

2-3 Constraints on the mechanical properties of an orthotropic materials

- Compliance matrix for orthotropic mat.

$$\begin{bmatrix} S_{11} & S_{12} & S_{13} & 0 & 0 & 0 \\ S_{12} & S_{22} & S_{23} & 0 & 0 & 0 \\ S_{13} & S_{23} & S_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & S_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & S_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & S_{66} \end{bmatrix}$$

We are interested to find the constraint on S_{ij} 's

$$\Delta_1 = S_{11} > 0 \quad (2-3-3) \quad \Delta_2 = \begin{vmatrix} S_{11} & S_{12} \\ S_{12} & S_{22} \end{vmatrix} = S_{11}S_{22} - S_{12}^2 > 0 \quad (2-3-4)$$

$$\Delta_3 = \begin{vmatrix} S_{11} & S_{12} & S_{13} \\ S_{12} & S_{22} & S_{23} \\ S_{13} & S_{23} & S_{33} \end{vmatrix} > 0 \quad (2-3-5) \quad \Delta_4 = S_{44}\Delta_3 > 0 \quad (2-3-6)$$

$$\Delta_5 = S_{44}S_{55}\Delta_3 > 0 \quad (2-3-7) \quad \Delta_6 = S_{44}S_{55}S_{66}\Delta_3 > 0 \quad (2-3-8)$$

From (2-3-3) and (2-3-4): $S_{22} > 0 \quad (2-3-9)$

Condition (2-3-5):

$$\Delta_3 = \frac{1}{S_{11}} [(S_{11}S_{22} - S_{12}^2)(S_{11}S_{33} - S_{13}^2) - (S_{11}S_{23} - S_{12}S_{13})^2] > 0 \quad (2-3-10)$$

$$\Delta_3 = \frac{1}{S_{11}} [(S_{22}S_{33} - S_{23}^2)(S_{11}S_{22} - S_{12}^2) - (S_{22}S_{13} - S_{23}S_{12})^2] > 0 \quad (2-3-11)$$

From (2-3-3) and (2-3-4), (2-3-10):

$$S_{11}S_{33}-S_{13}^2>0 \quad (2-3-12)$$

From (2-3-3) and (2-3-12):

$$S_{33}>0 \quad (2-3-13)$$

From (2-3-4) and (2-3-11):

$$S_{22}S_{33}-S_{23}^2>0 \quad (2-3-14)$$

Fro (2-3-5) and (2-3-6) and (2-3-7):

$$S_{44}>0 \quad \& \quad S_{55}>0 \quad \& \quad S_{66}>0 \quad (2-3-15)$$

Compliance matrix in terms of Eng. Const.

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$$\begin{bmatrix} \frac{1}{E_1} & \frac{-\nu_{21}}{E_2} & \frac{-\nu_{31}}{E_3} & 0 & 0 & 0 \\ \frac{-\nu_{12}}{E_1} & \frac{1}{E_2} & \frac{-\nu_{32}}{E_3} & 0 & 0 & 0 \\ \frac{-\nu_{13}}{E_1} & \frac{-\nu_{23}}{E_2} & \frac{1}{E_3} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{23}} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{13}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{12}} \end{bmatrix}$$

(2-3-16)

$$\frac{v_{ij}}{E_i} = \frac{v_{ji}}{E_j} \quad i,j=1,2,3 \quad (2-3-17)$$

$$E_1 > 0 \quad \& \quad E_2 > 0 \quad \& \quad E_3 > 0 \quad \& \quad G_{12} > 0 \quad \& \quad G_{13} > 0 \quad \& \quad G_{23} > 0 \quad (2-3-18)$$

$$1 - v_{12}v_{21} > 0 \quad \& \quad 1 - v_{13}v_{31} > 0 \quad \& \quad 1 - v_{32}v_{23} > 0$$

Also,

$$v_{12} < \left(\frac{E_1}{E_2}\right)^{1/2} \quad \& \quad v_{13} < \left(\frac{E_1}{E_3}\right)^{1/2} \quad \& \quad v_{23} < \left(\frac{E_2}{E_3}\right)^{1/2}$$

From (2-3-5):

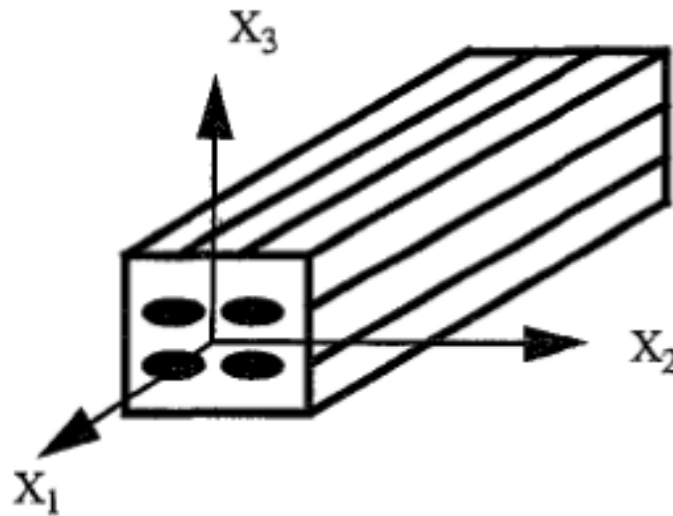
$$\Delta_3 = \frac{1}{E_1 E_2 E_3} (1 - v_{12}v_{21} - v_{13}v_{31} - v_{32}v_{23} - 2v_{21}v_{32}v_{13}) > 0 \quad (2-3-19)$$

From (2-3-18) and (2-3-19):

$$1 - v_{12}v_{21} - v_{13}v_{31} - v_{32}v_{23} - 2v_{21}v_{32}v_{13} > 0 \quad (2-3-20)$$

2-4-On-Axis constitutive law of a orthotropic materials

Consider X_1 - X_2 - X_3 coordinate attached to a lamina as shown here, this coordinate is called the principle material coordinate of orthotropic Mat.



Additional simplification of the stress-strain relationship can be realized through simplifying the matrix notation for stresses and strains.

→ We can replace the indices as follows:

$$11 \rightarrow 1 \qquad 23 \rightarrow 4$$

$$22 \rightarrow 2 \qquad 13 \rightarrow 5$$

$$33 \rightarrow 3 \qquad 12 \rightarrow 6$$

$$\begin{array}{c} \text{Notation I} \end{array} \left(\begin{array}{ccc} 11 & 12 & 13 \\ & 22 & 23 \\ & & 33 \end{array} \right) = \left(\begin{array}{ccc} 1 & 6 & 5 \\ & 2 & 4 \\ & & 3 \end{array} \right) \begin{array}{c} \text{Notation II} \end{array}$$

- The foregoing transformation is easy to remember: In order to obtain notation II, one must proceed first along the diagonal (1 → 2 → 3) and then back (4 → 5 → 6).
- Notation II method makes life very easy when correlating the stresses and strains for general case, in which the elastic properties of a material are dependent on its orientations.

We now have the stress and strain, in general form, as

$$\begin{pmatrix} \sigma_1 & \sigma_6 & \sigma_5 \\ \sigma_6 & \sigma_2 & \sigma_4 \\ \sigma_5 & \sigma_4 & \sigma_3 \end{pmatrix} \text{ and } \begin{pmatrix} \varepsilon_1 & \frac{\varepsilon_6}{2} & \frac{\varepsilon_5}{2} \\ \frac{\varepsilon_6}{2} & \varepsilon_2 & \frac{\varepsilon_4}{2} \\ \frac{\varepsilon_5}{2} & \frac{\varepsilon_4}{2} & \varepsilon_3 \end{pmatrix}$$

It should be noted that $\varepsilon_{11} = \varepsilon_{22} = \varepsilon_{33}$,
and $\varepsilon_3 = \varepsilon_{33}$, but

$$\varepsilon_4 = 2 \varepsilon_{23} = \gamma_{23}$$

$$\varepsilon_5 = 2 \varepsilon_{13} = \gamma_{13}$$

$$\varepsilon_6 = 2 \varepsilon_{12} = \gamma_{12}$$

(7-5)

The generalized Hook's law in the principal Mat. Coor.

$$\begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \gamma_{23} \\ \gamma_{13} \\ \gamma_{12} \end{Bmatrix} = \begin{bmatrix} S_{11} & S_{12} & S_{13} & 0 & 0 & 0 \\ S_{12} & S_{22} & S_{23} & 0 & 0 & 0 \\ S_{13} & S_{23} & S_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & S_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & S_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & S_{66} \end{bmatrix} \begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \tau_{23} \\ \tau_{13} \\ \tau_{12} \end{Bmatrix}$$

On-Axis constitutive law of a orthotropic Mat.

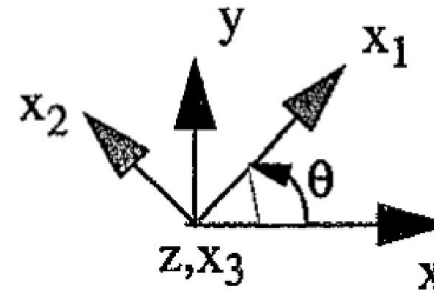
By inverting recent relationship:

$$\begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \tau_{23} \\ \tau_{13} \\ \tau_{12} \end{Bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ C_{12} & C_{22} & C_{23} & 0 & 0 & 0 \\ C_{13} & C_{23} & C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & C_{66} \end{bmatrix} \begin{Bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \gamma_{23} \\ \gamma_{13} \\ \gamma_{12} \end{Bmatrix}$$

[C] is called the on-axis stiffness Matrix.

2-4-Off-Axis constitutive law of a orthotropic materials

$m = \cos\theta$ and $n = \sin\theta$



$$\{\sigma\}_1 = [T_1]\{\sigma\}_x$$

$$\{\epsilon\}_1 = [T_2]\{\epsilon\}_x$$

where the transformation matrix $[T_1]$ is

$$[T_1] = \begin{bmatrix} m^2 & n^2 & 0 & 0 & 0 & 2mn \\ n^2 & m^2 & 0 & 0 & 0 & -2mn \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & m & -n & 0 \\ 0 & 0 & 0 & n & m & 0 \\ -mn & mn & 0 & 0 & 0 & m^2 - n^2 \end{bmatrix}$$

$$[T_2] = \begin{bmatrix} m^2 & n^2 & 0 & 0 & 0 & mn \\ n^2 & m^2 & 0 & 0 & 0 & -mn \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & m & -n & 0 \\ 0 & 0 & 0 & n & m & 0 \\ -2mn & 2mn & 0 & 0 & 0 & m^2 - n^2 \end{bmatrix}$$

$$\begin{aligned}\{\sigma\}_1 &= [C]\{\epsilon\}_1 \\ [T_1]\{\sigma\}_x &= [C][T_2]\{\epsilon\}_x \\ \{\sigma\}_x &= [T_1]^{-1}[C][T_2]\{\epsilon\}_x \\ \{\sigma\}_x &= [\bar{C}]\{\epsilon\}_x \\ [\bar{C}] &\equiv [T_1]^{-1}[C][T_2]\end{aligned}$$

$$\bar{C}_{11} = m^4 C_{11} + 2m^2 n^2 (C_{12} + 2C_{66}) + n^4 C_{22}$$

$$\bar{C}_{12} = n^2 m^2 (C_{11} + C_{22} - 4C_{66}) + (n^4 + m^4) C_{12}$$

$$\bar{C}_{13} = m^2 C_{13} + n^2 C_{23}$$

$$\bar{C}_{16} = nm [m^2 (C_{11} - C_{12} - 2C_{66}) + n^2 (C_{12} - C_{22} + 2C_{66})]$$

$$\bar{C}_{22} = n^4 C_{11} + 2m^2 n^2 (C_{12} + 2C_{66}) + m^4 C_{22}$$

$$\bar{C}_{23} = n^2 C_{13} + m^2 C_{23}$$

$$\bar{C}_{26} = nm [n^2 (C_{11} - C_{12} - 2C_{66}) + m^2 (C_{12} - C_{22} + 2C_{66})]$$

$$\bar{C}_{33} = C_{33}$$

$$\bar{C}_{36} = mn (C_{13} - C_{23})$$

$$\bar{C}_{44} = m^2 C_{44} + n^2 C_{55}$$

$$\bar{C}_{45} = mn (C_{55} - C_{44})$$

$$\bar{C}_{55} = n^2 C_{44} + m^2 C_{55}$$

$$\bar{C}_{66} = n^2 m^2 (C_{11} - 2C_{12} + C_{22}) + (n^2 - m^2)^2 C_{66}$$

$$\{\epsilon\}_x = [\bar{S}]\{\sigma\}_x$$

where the compliance $[\bar{S}]$ is the inverse of stiffness and

$$[\bar{S}] = [\bar{C}]^{-1} = ([T_1]^{-1}[C][T_2])^{-1}$$

$$[\bar{S}] = [T_2]^{-1}[C]^{-1}([T_1]^{-1})^{-1}$$

$$[\bar{S}] = [T_2]^{-1}[S][T_1]$$

The transformed compliance matrix then has the same symmetric form as the transformed stiffness matrix:

$$[\bar{S}] = \begin{bmatrix} \bar{S}_{11} & \bar{S}_{12} & \bar{S}_{13} & 0 & 0 & \bar{S}_{16} \\ \bar{S}_{12} & \bar{S}_{22} & \bar{S}_{23} & 0 & 0 & \bar{S}_{26} \\ \bar{S}_{13} & \bar{S}_{23} & \bar{S}_{33} & 0 & 0 & \bar{S}_{36} \\ 0 & 0 & 0 & \bar{S}_{44} & \bar{S}_{45} & 0 \\ 0 & 0 & 0 & \bar{S}_{45} & \bar{S}_{55} & 0 \\ \bar{S}_{16} & \bar{S}_{26} & \bar{S}_{36} & 0 & 0 & \bar{S}_{66} \end{bmatrix}$$

$$\bar{S}_{11} = m^4 S_{11} + m^2 n^2 (2S_{12} + S_{66}) + n^4 S_{22}$$

$$\bar{S}_{12} = n^2 m^2 (S_{11} + S_{22} - S_{66}) + (n^4 + m^4) S_{12}$$

$$\bar{S}_{13} = m^2 S_{13} + n^2 S_{23}$$

$$\bar{S}_{16} = nm[m^2(2S_{11} - 2S_{12} - S_{66}) + n^2(2S_{12} - 2S_{22} + S_{66})]$$

$$\bar{S}_{22} = n^4 S_{11} + m^2 n^2 (2S_{12} + S_{66}) + m^4 S_{22}$$

$$\bar{S}_{23} = n^2 S_{13} + m^2 S_{23}$$

$$\bar{S}_{26} = nm[n^2(2S_{11} - 2S_{12} - S_{66}) + m^2(2S_{12} - 2S_{22} + S_{66})]$$

$$\bar{S}_{33} = S_{33}$$

$$\bar{S}_{36} = 2mn(S_{13} - S_{23})$$

$$\bar{S}_{44} = m^2 S_{44} + n^2 S_{55}$$

$$\bar{S}_{45} = mn(S_{55} - S_{44})$$

$$\bar{S}_{55} = n^2 S_{44} + m^2 S_{55}$$

$$\bar{S}_{66} = 4n^2 m^2 (S_{11} - 2S_{12} + S_{22}) + (n^2 - m^2)^2 S_{66}$$

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_z \\ \gamma_{yz} \\ \gamma_{zx} \\ \gamma_{xy} \end{Bmatrix} = \begin{bmatrix} \bar{S}_{11} & \bar{S}_{12} & \bar{S}_{13} & 0 & 0 & \bar{S}_{16} \\ \bar{S}_{12} & \bar{S}_{22} & \bar{S}_{23} & 0 & 0 & \bar{S}_{26} \\ \bar{S}_{13} & \bar{S}_{23} & \bar{S}_{33} & 0 & 0 & \bar{S}_{36} \\ 0 & 0 & 0 & \bar{S}_{44} & \bar{S}_{45} & 0 \\ 0 & 0 & 0 & \bar{S}_{45} & \bar{S}_{55} & 0 \\ \bar{S}_{16} & \bar{S}_{26} & \bar{S}_{36} & 0 & 0 & \bar{S}_{66} \end{bmatrix} \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{yz} \\ \tau_{zx} \\ \tau_{xy} \end{Bmatrix}$$