

Chapter 1

1. **THINK** In this problem we're given the radius of Earth, and asked to compute its circumference, surface area and volume.

EXPRESS Assuming Earth to be a sphere of radius

$$R_E = (6.37 \times 10^6 \text{ m})(10^{-3} \text{ km/m}) = 6.37 \times 10^3 \text{ km},$$

the corresponding circumference, surface area and volume are:

$$C = 2\pi R_E, \quad A = 4\pi R_E^2, \quad V = \frac{4\pi}{3} R_E^3.$$

The geometric formulas are given in Appendix E.

ANALYZE (a) Using the formulas given above, we find the circumference to be

$$C = 2\pi R_E = 2\pi(6.37 \times 10^3 \text{ km}) = 4.00 \times 10^4 \text{ km}.$$

(b) Similarly, the surface area of Earth is

$$A = 4\pi R_E^2 = 4\pi(6.37 \times 10^3 \text{ km})^2 = 5.10 \times 10^8 \text{ km}^2,$$

(c) and its volume is

$$V = \frac{4\pi}{3} R_E^3 = \frac{4\pi}{3} (6.37 \times 10^3 \text{ km})^3 = 1.08 \times 10^{12} \text{ km}^3.$$

LEARN From the formulas given, we see that $C \sim R_E$, $A \sim R_E^2$, and $V \sim R_E^3$. The ratios of volume to surface area, and surface area to circumference are $V/A = R_E/3$ and $A/C = 2R_E$.

2. The conversion factors are: 1 gry = 1/10 line, 1 line = 1/12 inch and 1 point = 1/72 inch. The factors imply that

$$1 \text{ gry} = (1/10)(1/12)(72 \text{ points}) = 0.60 \text{ point}.$$

Thus, $1 \text{ gry}^2 = (0.60 \text{ point})^2 = 0.36 \text{ point}^2$, which means that $0.50 \text{ gry}^2 = 0.18 \text{ point}^2$.

3. The metric prefixes (micro, pico, nano, ...) are given for ready reference on the inside front cover of the textbook (see also Table 1-2).

(a) Since $1 \text{ km} = 1 \times 10^3 \text{ m}$ and $1 \text{ m} = 1 \times 10^6 \mu\text{m}$,

$$1 \text{ km} = 10^3 \text{ m} = (10^3 \text{ m})(10^6 \mu\text{m/m}) = 10^9 \mu\text{m}.$$

The given measurement is 1.0 km (two significant figures), which implies our result should be written as $1.0 \times 10^9 \mu\text{m}$.

(b) We calculate the number of microns in 1 centimeter. Since $1 \text{ cm} = 10^{-2} \text{ m}$,

$$1 \text{ cm} = 10^{-2} \text{ m} = (10^{-2} \text{ m})(10^6 \mu\text{m/m}) = 10^4 \mu\text{m}.$$

We conclude that the fraction of one centimeter equal to $1.0 \mu\text{m}$ is 1.0×10^{-4} .

(c) Since $1 \text{ yd} = (3 \text{ ft})(0.3048 \text{ m/ft}) = 0.9144 \text{ m}$,

$$1.0 \text{ yd} = (0.91 \text{ m})(10^6 \mu\text{m/m}) = 9.1 \times 10^5 \mu\text{m}.$$

4. (a) Using the conversion factors $1 \text{ inch} = 2.54 \text{ cm}$ exactly and $6 \text{ picas} = 1 \text{ inch}$, we obtain

$$0.80 \text{ cm} = (0.80 \text{ cm}) \left(\frac{1 \text{ inch}}{2.54 \text{ cm}} \right) \left(\frac{6 \text{ picas}}{1 \text{ inch}} \right) \approx 1.9 \text{ picas}.$$

(b) With $12 \text{ points} = 1 \text{ pica}$, we have

$$0.80 \text{ cm} = (0.80 \text{ cm}) \left(\frac{1 \text{ inch}}{2.54 \text{ cm}} \right) \left(\frac{6 \text{ picas}}{1 \text{ inch}} \right) \left(\frac{12 \text{ points}}{1 \text{ pica}} \right) \approx 23 \text{ points}.$$

5. **THINK** This problem deals with conversion of furlongs to rods and chains, all of which are units for distance.

EXPRESS Given that $1 \text{ furlong} = 201.168 \text{ m}$, $1 \text{ rod} = 5.0292 \text{ m}$ and $1 \text{ chain} = 20.117 \text{ m}$, the relevant conversion factors are

$$1.0 \text{ furlong} = 201.168 \text{ m} = (201.168 \cancel{\text{ m}}) \frac{1 \text{ rod}}{5.0292 \cancel{\text{ m}}} = 40 \text{ rods},$$

and

$$1.0 \text{ furlong} = 201.168 \text{ m} = (201.168 \cancel{\text{ m}}) \frac{1 \text{ chain}}{20.117 \cancel{\text{ m}}} = 10 \text{ chains}.$$

Note the cancellation of m (meters), the unwanted unit.

ANALYZE Using the above conversion factors, we find

(a) the distance d in *rods* to be $d = 4.0 \text{ furlongs} = (4.0 \text{ furlongs}) \frac{40 \text{ rods}}{1 \text{ furlong}} = 160 \text{ rods}$,

(b) and in *chains* to be $d = 4.0 \text{ furlongs} = (4.0 \text{ furlongs}) \frac{10 \text{ chains}}{1 \text{ furlong}} = 40 \text{ chains}$.

LEARN Since 4 furlongs is about 800 m, this distance is approximately equal to 160 rods (1 rod \approx 5 m) and 40 chains (1 chain \approx 20 m). So our results make sense.

6. We make use of Table 1-6.

(a) We look at the first (“cahiz”) column: 1 fanega is equivalent to what amount of cahiz? We note from the already completed part of the table that 1 cahiz equals a dozen fanega. Thus, $1 \text{ fanega} = \frac{1}{12} \text{ cahiz}$, or $8.33 \times 10^{-2} \text{ cahiz}$. Similarly, “1 cahiz = 48 cuartilla” (in the already completed part) implies that $1 \text{ cuartilla} = \frac{1}{48} \text{ cahiz}$, or $2.08 \times 10^{-2} \text{ cahiz}$. Continuing in this way, the remaining entries in the first column are 6.94×10^{-3} and 3.47×10^{-3} .

(b) In the second (“fanega”) column, we find 0.250, 8.33×10^{-2} , and 4.17×10^{-2} for the last three entries.

(c) In the third (“cuartilla”) column, we obtain 0.333 and 0.167 for the last two entries.

(d) Finally, in the fourth (“almude”) column, we get $\frac{1}{2} = 0.500$ for the last entry.

(e) Since the conversion table indicates that 1 almude is equivalent to 2 medios, our amount of 7.00 almudes must be equal to 14.0 medios.

(f) Using the value ($1 \text{ almude} = 6.94 \times 10^{-3} \text{ cahiz}$) found in part (a), we conclude that 7.00 almudes is equivalent to $4.86 \times 10^{-2} \text{ cahiz}$.

(g) Since each decimeter is 0.1 meter, then 55.501 cubic decimeters is equal to 0.055501 m^3 or 55501 cm^3 . Thus, $7.00 \text{ almudes} = \frac{7.00}{12} \text{ fanega} = \frac{7.00}{12} (55501 \text{ cm}^3) = 3.24 \times 10^4 \text{ cm}^3$.

7. We use the conversion factors found in Appendix D.

$$1 \text{ acre} \cdot \text{ft} = (43,560 \text{ ft}^2) \cdot \text{ft} = 43,560 \text{ ft}^3$$

Since 2 in. = (1/6) ft, the volume of water that fell during the storm is

$$V = (26 \text{ km}^2)(1/6 \text{ ft}) = (26 \text{ km}^2)(3281 \text{ ft/km})^2(1/6 \text{ ft}) = 4.66 \times 10^7 \text{ ft}^3.$$

Thus,

$$V = \frac{4.66 \times 10^7 \text{ ft}^3}{4.3560 \times 10^4 \text{ ft}^3/\text{acre} \cdot \text{ft}} = 1.1 \times 10^3 \text{ acre} \cdot \text{ft}.$$

8. From Fig. 1-4, we see that 212 S is equivalent to 258 W and $212 - 32 = 180$ S is equivalent to $216 - 60 = 156$ Z. The information allows us to convert S to W or Z.

(a) In units of W, we have

$$50.0 \text{ S} = (50.0 \text{ S}) \left(\frac{258 \text{ W}}{212 \text{ S}} \right) = 60.8 \text{ W}$$

(b) In units of Z, we have

$$50.0 \text{ S} = (50.0 \text{ S}) \left(\frac{156 \text{ Z}}{180 \text{ S}} \right) = 43.3 \text{ Z}$$

9. The volume of ice is given by the product of the semicircular surface area and the thickness. The area of the semicircle is $A = \pi r^2/2$, where r is the radius. Therefore, the volume is

$$V = \frac{\pi}{2} r^2 z$$

where z is the ice thickness. Since there are 10^3 m in 1 km and 10^2 cm in 1 m, we have

$$r = (2000 \text{ km}) \left(\frac{10^3 \text{ m}}{1 \text{ km}} \right) \left(\frac{10^2 \text{ cm}}{1 \text{ m}} \right) = 2000 \times 10^5 \text{ cm}.$$

In these units, the thickness becomes

$$z = 3000 \text{ m} = (3000 \text{ m}) \left(\frac{10^2 \text{ cm}}{1 \text{ m}} \right) = 3000 \times 10^2 \text{ cm}$$

which yields $V = \frac{\pi}{2} (2000 \times 10^5 \text{ cm})^2 (3000 \times 10^2 \text{ cm}) = 1.9 \times 10^{22} \text{ cm}^3$.

10. Since a change of longitude equal to 360° corresponds to a 24 hour change, then one expects to change longitude by $360^\circ/24 = 15^\circ$ before resetting one's watch by 1.0 h.

11. (a) Presuming that a French decimal day is equivalent to a regular day, then the ratio of weeks is simply $10/7$ or (to 3 significant figures) 1.43.

(b) In a regular day, there are 86400 seconds, but in the French system described in the problem, there would be 10^5 seconds. The ratio is therefore 0.864.

12. A day is equivalent to 86400 seconds and a meter is equivalent to a million micrometers, so

$$\frac{(3.7 \text{ m})(10^6 \mu\text{m/m})}{(14 \text{ day})(86400 \text{ s/day})} = 3.1 \mu\text{m/s}.$$

13. The time on any of these clocks is a straight-line function of that on another, with slopes $\neq 1$ and y -intercepts $\neq 0$. From the data in the figure we deduce

$$t_C = \frac{2}{7}t_B + \frac{594}{7}, \quad t_B = \frac{33}{40}t_A - \frac{662}{5}.$$

These are used in obtaining the following results.

(a) We find

$$t'_B - t_B = \frac{33}{40}(t'_A - t_A) = 495 \text{ s}$$

when $t'_A - t_A = 600 \text{ s}$.

(b) We obtain $t'_C - t_C = \frac{2}{7}(t'_B - t_B) = \frac{2}{7}(495) = 141 \text{ s}$.

(c) Clock B reads $t_B = (33/40)(400) - (662/5) \approx 198 \text{ s}$ when clock A reads $t_A = 400 \text{ s}$.

(d) From $t_C = 15 = (2/7)t_B + (594/7)$, we get $t_B \approx -245 \text{ s}$.

14. The metric prefixes (micro (μ), pico, nano, ...) are given for ready reference on the inside front cover of the textbook (also Table 1-2).

$$(a) 1 \mu\text{century} = (10^{-6} \text{ century}) \left(\frac{100 \text{ y}}{1 \text{ century}} \right) \left(\frac{365 \text{ day}}{1 \text{ y}} \right) \left(\frac{24 \text{ h}}{1 \text{ day}} \right) \left(\frac{60 \text{ min}}{1 \text{ h}} \right) = 52.6 \text{ min}.$$

(b) The percent difference is therefore

$$\frac{52.6 \text{ min} - 50 \text{ min}}{52.6 \text{ min}} = 4.9\%.$$

15. A week is 7 days, each of which has 24 hours, and an hour is equivalent to 3600 seconds. Thus, two weeks (a fortnight) is 1209600 s. By definition of the micro prefix, this is roughly $1.21 \times 10^{12} \mu\text{s}$.

16. We denote the pulsar rotation rate f (for frequency).

$$f = \frac{1 \text{ rotation}}{1.55780644887275 \times 10^{-3} \text{ s}}$$

(a) Multiplying f by the time-interval $t = 7.00$ days (which is equivalent to 604800 s, if we ignore *significant figure* considerations for a moment), we obtain the number of rotations:

$$N = \left(\frac{1 \text{ rotation}}{1.55780644887275 \times 10^{-3} \text{ s}} \right) (604800 \text{ s}) = 388238218.4$$

which should now be rounded to 3.88×10^8 rotations since the time-interval was specified in the problem to three significant figures.

(b) We note that the problem specifies the *exact* number of pulsar revolutions (one million). In this case, our unknown is t , and an equation similar to the one we set up in part (a) takes the form $N = ft$, or

$$1 \times 10^6 = \left(\frac{1 \text{ rotation}}{1.55780644887275 \times 10^{-3} \text{ s}} \right) t$$

which yields the result $t = 1557.80644887275$ s (though students who do this calculation on their calculator might not obtain those last several digits).

(c) Careful reading of the problem shows that the time-uncertainty *per revolution* is $\pm 3 \times 10^{-17}$ s. We therefore expect that as a result of one million revolutions, the uncertainty should be $(\pm 3 \times 10^{-17})(1 \times 10^6) = \pm 3 \times 10^{-11}$ s.

17. THINK In this problem we are asked to rank 5 clocks, based on their performance as timekeepers.

EXPRESS We first note that none of the clocks advance by exactly 24 h in a 24-h period but this is not the most important criterion for judging their quality for measuring time intervals. What is important here is that the clock advance by the same (or nearly the same) amount in each 24-h period. The clock reading can then easily be adjusted to give the correct interval.

ANALYZE The chart below gives the corrections (in seconds) that must be applied to the reading on each clock for each 24-h period. The entries were determined by subtracting the clock reading at the end of the interval from the clock reading at the beginning.

Clocks C and D are both good timekeepers in the sense that each is consistent in its daily drift (relative to WWF time); thus, C and D are easily made “perfect” with simple and predictable corrections. The correction for clock C is less than the correction for clock D, so we judge clock C to be the best and clock D to be the next best. The correction that must be applied to clock A is in the range from 15 s to 17s. For clock B it is the range from -5 s to $+10$ s, for clock E it is in the range from -70 s to -2 s. After C and D, A has

the smallest range of correction, B has the next smallest range, and E has the greatest range. From best to worst, the ranking of the clocks is C, D, A, B, E.

CLOCK	Sun. -Mon.	Mon. -Tues.	Tues. -Wed.	Wed. -Thurs.	Thurs. -Fri.	Fri. -Sat.
A	-16	-16	-15	-17	-15	-15
B	-3	+5	-10	+5	+6	-7
C	-58	-58	-58	-58	-58	-58
D	+67	+67	+67	+67	+67	+67
E	+70	+55	+2	+20	+10	+10

LEARN Of the five clocks, the readings in clocks A, B and E jump around from one 24-h period to another, making it difficult to correct them.

18. The last day of the 20 centuries is longer than the first day by

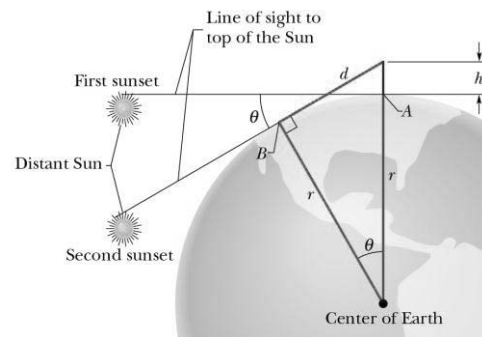
$$(20 \text{ century}) (0.001 \text{ s/century}) = 0.02 \text{ s.}$$

The average day during the 20 centuries is $(0 + 0.02)/2 = 0.01 \text{ s}$ longer than the first day. Since the increase occurs uniformly, the cumulative effect T is

$$\begin{aligned} T &= (\text{average increase in length of a day})(\text{number of days}) \\ &= \left(\frac{0.01 \text{ s}}{\text{day}} \right) \left(\frac{365.25 \text{ day}}{\text{y}} \right) (2000 \text{ y}) \\ &= 7305 \text{ s} \end{aligned}$$

or roughly two hours.

19. When the Sun first disappears while lying down, your line of sight to the top of the Sun is tangent to the Earth's surface at point A shown in the figure. As you stand, elevating your eyes by a height h , the line of sight to the Sun is tangent to the Earth's surface at point B .



Let d be the distance from point B to your eyes. From the Pythagorean theorem, we have

$$d^2 + r^2 = (r + h)^2 = r^2 + 2rh + h^2$$

or $d^2 = 2rh + h^2$, where r is the radius of the Earth. Since $r \gg h$, the second term can be dropped, leading to $d^2 \approx 2rh$. Now the angle between the two radii to the two tangent points A and B is θ , which is also the angle through which the Sun moves about Earth during the time interval $t = 11.1$ s. The value of θ can be obtained by using

$$\frac{\theta}{360^\circ} = \frac{t}{24 \text{ h}}.$$

This yields

$$\theta = \frac{(360^\circ)(11.1 \text{ s})}{(24 \text{ h})(60 \text{ min/h})(60 \text{ s/min})} = 0.04625^\circ.$$

Using $d = r \tan \theta$, we have $d^2 = r^2 \tan^2 \theta = 2rh$, or

$$r = \frac{2h}{\tan^2 \theta}$$

Using the above value for θ and $h = 1.7$ m, we have $r = 5.2 \times 10^6$ m.

20. (a) We find the volume in cubic centimeters

$$193 \text{ gal} = (193 \text{ gal}) \left(\frac{231 \text{ in}^3}{1 \text{ gal}} \right) \left(\frac{2.54 \text{ cm}}{1 \text{ in}} \right)^3 = 7.31 \times 10^5 \text{ cm}^3$$

and subtract this from $1 \times 10^6 \text{ cm}^3$ to obtain $2.69 \times 10^5 \text{ cm}^3$. The conversion $\text{gal} \rightarrow \text{in}^3$ is given in Appendix D (immediately below the table of Volume conversions).

(b) The volume found in part (a) is converted (by dividing by $(100 \text{ cm/m})^3$) to 0.731 m^3 , which corresponds to a mass of

$$(1000 \text{ kg/m}^3) (0.731 \text{ m}^3) = 731 \text{ kg}$$

using the density given in the problem statement. At a rate of 0.0018 kg/min , this can be filled in

$$\frac{731 \text{ kg}}{0.0018 \text{ kg/min}} = 4.06 \times 10^5 \text{ min} = 0.77 \text{ y}$$

after dividing by the number of minutes in a year $(365 \text{ days})(24 \text{ h/day})(60 \text{ min/h})$.

21. If M_E is the mass of Earth, m is the average mass of an atom in Earth, and N is the number of atoms, then $M_E = Nm$ or $N = M_E/m$. We convert mass m to kilograms using Appendix D ($1 \text{ u} = 1.661 \times 10^{-27} \text{ kg}$). Thus,

$$N = \frac{M_E}{m} = \frac{5.98 \times 10^{24} \text{ kg}}{(40 \text{ u})(1.661 \times 10^{-27} \text{ kg/u})} = 9.0 \times 10^{49}.$$

22. The density of gold is

$$\rho = \frac{m}{V} = \frac{19.32 \text{ g}}{1 \text{ cm}^3} = 19.32 \text{ g/cm}^3.$$

(a) We take the volume of the leaf to be its area A multiplied by its thickness z . With density $\rho = 19.32 \text{ g/cm}^3$ and mass $m = 27.63 \text{ g}$, the volume of the leaf is found to be

$$V = \frac{m}{\rho} = 1.430 \text{ cm}^3.$$

We convert the volume to SI units:

$$V = (1.430 \text{ cm}^3) \left(\frac{1 \text{ m}}{100 \text{ cm}} \right)^3 = 1.430 \times 10^{-6} \text{ m}^3.$$

Since $V = Az$ with $z = 1 \times 10^{-6} \text{ m}$ (metric prefixes can be found in Table 1–2), we obtain

$$A = \frac{1.430 \times 10^{-6} \text{ m}^3}{1 \times 10^{-6} \text{ m}} = 1.430 \text{ m}^2.$$

(b) The volume of a cylinder of length ℓ is $V = A\ell$ where the cross-section area is that of a circle: $A = \pi r^2$. Therefore, with $r = 2.500 \times 10^{-6} \text{ m}$ and $V = 1.430 \times 10^{-6} \text{ m}^3$, we obtain

$$\ell = \frac{V}{\pi r^2} = 7.284 \times 10^4 \text{ m} = 72.84 \text{ km}.$$

23. **THINK** This problem consists of two parts: in the first part, we are asked to find the mass of water, given its volume and density; the second part deals with the mass flow rate of water, which is expressed as kg/s in SI units.

EXPRESS From the definition of density: $\rho = m/V$, we see that mass can be calculated as $m = \rho V$, the product of the volume of water and its density. With $1 \text{ g} = 1 \times 10^{-3} \text{ kg}$ and $1 \text{ cm}^3 = (1 \times 10^{-2} \text{ m})^3 = 1 \times 10^{-6} \text{ m}^3$, the density of water in SI units (kg/m^3) is

$$\rho = 1 \text{ g/cm}^3 = \left(\frac{1 \text{ g}}{\text{cm}^3} \right) \left(\frac{10^{-3} \text{ kg}}{\text{g}} \right) \left(\frac{\text{cm}^3}{10^{-6} \text{ m}^3} \right) = 1 \times 10^3 \text{ kg/m}^3.$$

To obtain the flow rate, we simply divide the total mass of the water by the time taken to drain it.

ANALYZE (a) Using $m = \rho V$, the mass of a cubic meter of water is

$$m = \rho V = (1 \times 10^3 \text{ kg/m}^3)(1 \text{ m}^3) = 1000 \text{ kg}.$$

(b) The total mass of water in the container is

$$M = \rho V = (1 \times 10^3 \text{ kg/m}^3)(5700 \text{ m}^3) = 5.70 \times 10^6 \text{ kg},$$

and the time elapsed is $t = (10 \text{ h})(3600 \text{ s/h}) = 3.6 \times 10^4 \text{ s}$. Thus, the mass flow rate R is

$$R = \frac{M}{t} = \frac{5.70 \times 10^6 \text{ kg}}{3.6 \times 10^4 \text{ s}} = 158 \text{ kg/s}.$$

LEARN In terms of volume, the drain rate can be expressed as

$$R' = \frac{V}{t} = \frac{5700 \text{ m}^3}{3.6 \times 10^4 \text{ s}} = 0.158 \text{ m}^3/\text{s} \approx 42 \text{ gal/s}.$$

The greater the flow rate, the less time required to drain a given amount of water.

24. The metric prefixes (micro (μ), pico, nano, ...) are given for ready reference on the inside front cover of the textbook (see also Table 1–2). The surface area A of each grain of sand of radius $r = 50 \text{ } \mu\text{m} = 50 \times 10^{-6} \text{ m}$ is given by $A = 4\pi(50 \times 10^{-6})^2 = 3.14 \times 10^{-8} \text{ m}^2$ (Appendix E contains a variety of geometry formulas). We introduce the notion of density, $\rho = m/V$, so that the mass can be found from $m = \rho V$, where $\rho = 2600 \text{ kg/m}^3$. Thus, using $V = 4\pi r^3/3$, the mass of each grain is

$$m = \rho V = \rho \left(\frac{4\pi r^3}{3} \right) = \left(2600 \frac{\text{kg}}{\text{m}^3} \right) \frac{4\pi (50 \times 10^{-6} \text{ m})^3}{3} = 1.36 \times 10^{-9} \text{ kg}.$$

We observe that (because a cube has six equal faces) the indicated surface area is 6 m^2 . The number of spheres (the grains of sand) N that have a total surface area of 6 m^2 is given by

$$N = \frac{6 \text{ m}^2}{3.14 \times 10^{-8} \text{ m}^2} = 1.91 \times 10^8.$$

Therefore, the total mass M is $M = Nm = (1.91 \times 10^8) (1.36 \times 10^{-9} \text{ kg}) = 0.260 \text{ kg}$.

25. The volume of the section is $(2500 \text{ m})(800 \text{ m})(2.0 \text{ m}) = 4.0 \times 10^6 \text{ m}^3$. Letting “ d ” stand for the thickness of the mud after it has (uniformly) distributed in the valley, then its volume there would be $(400 \text{ m})(400 \text{ m})d$. Requiring these two volumes to be equal, we can solve for d . Thus, $d = 25 \text{ m}$. The volume of a small part of the mud over a patch of area of 4.0 m^2 is $(4.0)d = 100 \text{ m}^3$. Since each cubic meter corresponds to a mass of

1900 kg (stated in the problem), then the mass of that small part of the mud is 1.9×10^5 kg.

26. (a) The volume of the cloud is $(3000 \text{ m})\pi(1000 \text{ m})^2 = 9.4 \times 10^9 \text{ m}^3$. Since each cubic meter of the cloud contains from 50×10^6 to 500×10^6 water drops, then we conclude that the entire cloud contains from 4.7×10^{18} to 4.7×10^{19} drops. Since the volume of each drop is $\frac{4}{3}\pi(10 \times 10^{-6} \text{ m})^3 = 4.2 \times 10^{-15} \text{ m}^3$, then the total volume of water in a cloud is from 2×10^3 to $2 \times 10^4 \text{ m}^3$.

(b) Using the fact that $1 \text{ L} = 1 \times 10^3 \text{ cm}^3 = 1 \times 10^{-3} \text{ m}^3$, the amount of water estimated in part (a) would fill from 2×10^6 to 2×10^7 bottles.

(c) At 1000 kg for every cubic meter, the mass of water is from 2×10^6 to 2×10^7 kg. The coincidence in numbers between the results of parts (b) and (c) of this problem is due to the fact that each liter has a mass of one kilogram when water is at its normal density (under standard conditions).

27. We introduce the notion of density, $\rho = m/V$, and convert to SI units: $1000 \text{ g} = 1 \text{ kg}$, and $100 \text{ cm} = 1 \text{ m}$.

(a) The density ρ of a sample of iron is

$$\rho = (7.87 \text{ g/cm}^3) \left(\frac{1 \text{ kg}}{1000 \text{ g}} \right) \left(\frac{100 \text{ cm}}{1 \text{ m}} \right)^3 = 7870 \text{ kg/m}^3.$$

If we ignore the empty spaces between the close-packed spheres, then the density of an individual iron atom will be the same as the density of any iron sample. That is, if M is the mass and V is the volume of an atom, then

$$V = \frac{M}{\rho} = \frac{9.27 \times 10^{-26} \text{ kg}}{7.87 \times 10^3 \text{ kg/m}^3} = 1.18 \times 10^{-29} \text{ m}^3.$$

(b) We set $V = 4\pi R^3/3$, where R is the radius of an atom (Appendix E contains several geometry formulas). Solving for R , we find

$$R = \left(\frac{3V}{4\pi} \right)^{1/3} = \left(\frac{3(1.18 \times 10^{-29} \text{ m}^3)}{4\pi} \right)^{1/3} = 1.41 \times 10^{-10} \text{ m}.$$

The center-to-center distance between atoms is twice the radius, or $2.82 \times 10^{-10} \text{ m}$.

28. If we estimate the “typical” large domestic cat mass as 10 kg, and the “typical” atom (in the cat) as $10 \text{ u} \approx 2 \times 10^{-26} \text{ kg}$, then there are roughly $(10 \text{ kg}) / (2 \times 10^{-26} \text{ kg}) \approx 5 \times 10^{26}$ atoms. This is close to being a factor of a thousand greater than Avogadro’s number. Thus this is roughly a kilomole of atoms.

29. The mass in kilograms is

$$(28.9 \text{ piculs}) \left(\frac{100 \text{ gin}}{1 \text{ picul}} \right) \left(\frac{16 \text{ tahlil}}{1 \text{ gin}} \right) \left(\frac{10 \text{ chee}}{1 \text{ tahlil}} \right) \left(\frac{10 \text{ hoon}}{1 \text{ chee}} \right) \left(\frac{0.3779 \text{ g}}{1 \text{ hoon}} \right)$$

which yields $1.747 \times 10^6 \text{ g}$ or roughly $1.75 \times 10^3 \text{ kg}$.

30. To solve the problem, we note that the first derivative of the function with respect to time gives the rate. Setting the rate to zero gives the time at which an extreme value of the variable mass occurs; here that extreme value is a maximum.

(a) Differentiating $m(t) = 5.00t^{0.8} - 3.00t + 20.00$ with respect to t gives

$$\frac{dm}{dt} = 4.00t^{-0.2} - 3.00.$$

The water mass is the greatest when $dm/dt = 0$, or at $t = (4.00/3.00)^{1/0.2} = 4.21 \text{ s}$.

(b) At $t = 4.21 \text{ s}$, the water mass is

$$m(t = 4.21 \text{ s}) = 5.00(4.21)^{0.8} - 3.00(4.21) + 20.00 = 23.2 \text{ g}.$$

(c) The rate of mass change at $t = 2.00 \text{ s}$ is

$$\begin{aligned} \left. \frac{dm}{dt} \right|_{t=2.00 \text{ s}} &= [4.00(2.00)^{-0.2} - 3.00] \text{ g/s} = 0.48 \text{ g/s} = 0.48 \frac{\text{g}}{\text{s}} \cdot \frac{1 \text{ kg}}{1000 \text{ g}} \cdot \frac{60 \text{ s}}{1 \text{ min}} \\ &= 2.89 \times 10^{-2} \text{ kg/min.} \end{aligned}$$

d Similarly the rate of mass change at $t = 5.00 \text{ s}$ is

$$\begin{aligned} \left. \frac{dm}{dt} \right|_{t=5.00 \text{ s}} &= [4.00(5.00)^{-0.2} - 3.00] \text{ g/s} = -0.101 \text{ g/s} = -0.101 \frac{\text{g}}{\text{s}} \cdot \frac{1 \text{ kg}}{1000 \text{ g}} \cdot \frac{60 \text{ s}}{1 \text{ min}} \\ &= -6.05 \times 10^{-3} \text{ kg/min.} \end{aligned}$$

31. The mass density of the candy is

$$\rho = \frac{m}{V} = \frac{0.0200 \text{ g}}{50.0 \text{ mm}^3} = 4.00 \times 10^{-4} \text{ g mm}^3 = 4.00 \times 10^{-4} \text{ kg cm}^3.$$

If we neglect the volume of the empty spaces between the candies then the total mass of the candies in the container when filled to height h is $M = \rho Ah$ here $A = 14.0 \text{ cm} \times 17.0 \text{ cm} = 238 \text{ cm}^2$ is the base area of the container that remains unchanged. Thus the rate of mass change is given by

$$\begin{aligned} \frac{dM}{dt} &= \frac{d(\rho Ah)}{dt} = \rho A \frac{dh}{dt} = 4.00 \times 10^{-4} \text{ kg cm}^3 \times 238 \text{ cm}^2 \times 0.250 \text{ cm s} \\ &= 0.0238 \text{ kg s} = 1.43 \text{ kg min.} \end{aligned}$$

32. The total volume V of the real house is that of a triangular prism of height $h = 3.0 \text{ m}$ and base area $A = 20 \times 12 = 240 \text{ m}^2$ in addition to a rectangular box of height $h' = 6.0 \text{ m}$ and same base. Therefore

$$V = \frac{1}{2} hA + h'A = \left(\frac{h}{2} + h' \right) A = 1800 \text{ m}^3.$$

a Each dimension is reduced by a factor of $\frac{1}{12}$ and we find

$$V_{\text{doll}} = (1800 \text{ m}^3) \left(\frac{1}{12} \right)^3 \approx 1.0 \text{ m}^3.$$

b In this case each dimension relative to the real house is reduced by a factor of $\frac{1}{144}$. Therefore

$$V_{\text{miniature}} = (1800 \text{ m}^3) \left(\frac{1}{144} \right)^3 \approx 6.0 \times 10^{-4} \text{ m}^3.$$

33. **THINK** In this problem we are asked to differentiate between three types of tons: *displacement* ton, *freight* ton and *register* ton, all of which are units of volume.

EXPRESS The three different tons are defined in terms of *barrel bulk* with $1 \text{ barrel bulk} = 0.1415 \text{ m}^3 = 4.0155 \text{ . . bushels}$ using $1 \text{ m}^3 = 28.378 \text{ . . bushels}$. Thus in terms of . . bushels we have

$$1 \text{ displacement ton} = 7 \text{ barrels bulk} \times \left(\frac{4.0155 \text{ . . bushels}}{1 \text{ barrel bulk}} \right) = 28.108 \text{ . . bushels}$$

$$1 \text{ freight ton} = 8 \text{ barrels bulk} \times \left(\frac{4.0155 \text{ . . bushels}}{1 \text{ barrel bulk}} \right) = 32.124 \text{ . . bushels}$$

$$1 \text{ register ton} = 20 \text{ barrels bulk} \times \left(\frac{4.0155 \text{ . . bushels}}{1 \text{ barrel bulk}} \right) = 80.31 \text{ . . bushels}$$

ANALYZE a The difference between 73 “freight” tons and 73 “displacement” tons is

$$\Delta V = 73 \text{ freight tons} - \text{displacement tons} = 73 \text{ } 32.124 \text{ } . . \text{ bushels} - 28.108 \text{ } . . \text{ bushels} \\ = 293.168 \text{ } . . \text{ bushels} \approx 293 \text{ } . . \text{ bushels}$$

(b) Similarly, the difference between 73 “register” tons and 73 “displacement” tons is

$$\Delta V = 73 \text{ register tons} - \text{displacement tons} = 73 \text{ } 80.31 \text{ } . . \text{ bushels} - 28.108 \text{ } . . \text{ bushels} \\ = 3810.746 \text{ } . . \text{ bushels} \approx 3.81 \times 10^3 \text{ } . . \text{ bushels}$$

LEARN ith 1 register ton > 1 freight ton > 1 displacement ton e e pect the difference found in b to be greater than that in a . his is indeed the case.

34. he customer e pects a volume $V_1 = 20 \times 7056 \text{ in}^3$ and receives $V_2 = 20 \times 5826 \text{ in}^3$ the difference being $\Delta V = V_1 - V_2 = 24600 \text{ in}^3$ or

$$\Delta V = (24600 \text{ in}^3) \left(\frac{2.54 \text{ cm}}{1 \text{ inch}} \right)^3 \left(\frac{1}{1000 \text{ cm}^3} \right) = 403$$

here ppendi has been used.

35. he first t o conversions are easy enough that a *formal* conversion is not especially called for but in the interest of *practice makes perfect* e go ahead and proceed formally

$$\text{a } 11 \text{ tuffets} = (11 \text{ tuffets}) \left(\frac{2 \text{ peck}}{1 \text{ tuffet}} \right) = 22 \text{ pecks}.$$

$$\text{b } 11 \text{ tuffets} = (11 \text{ tuffets}) \left(\frac{0.50 \text{ mperial bushel}}{1 \text{ tuffet}} \right) = 5.5 \text{ mperial bushels}.$$

$$\text{c } 11 \text{ tuffets} = (5.5 \text{ mperial bushel}) \left(\frac{36.3687}{1 \text{ mperial bushel}} \right) \approx 200 .$$

36. able 7 can be completed as follo s

a It should be clear that the first column (under “wey”) is the reciprocal of the first row – so that $\frac{9}{10} = 0.900$ $\frac{3}{40} = 7.50 \times 10^{-2}$ and so forth. hus 1 pottle = 1.56×10^{-3} ey and 1 gill = 8.32×10^{-6} ey are the last t o entries in the first column.

b In the second column (under “chaldron”), clearly we have 1 chaldron = 1 chaldron (that is, the entries along the “diagonal” in the table must be 1’s). To find out how many

chaldron are equivalent to one bag. We note that $1 \text{ ley} = 10^9 \text{ chaldron} = 40^3 \text{ bag}$ so that $\frac{1}{12} \text{ chaldron} = 1 \text{ bag}$. Thus the next entry in that second column is $\frac{1}{12} = 8.33 \times 10^{-2}$.

Similarly $1 \text{ pottle} = 1.74 \times 10^{-3} \text{ chaldron}$ and $1 \text{ gill} = 9.24 \times 10^{-6} \text{ chaldron}$.

Converting the third column under “bag” we have $1 \text{ chaldron} = 12.0 \text{ bag}$, $1 \text{ bag} = 1 \text{ bag}$, $1 \text{ pottle} = 2.08 \times 10^{-2} \text{ bag}$ and $1 \text{ gill} = 1.11 \times 10^{-4} \text{ bag}$.

Converting the fourth column under “pottle” we find $1 \text{ chaldron} = 576 \text{ pottle}$, $1 \text{ bag} = 48 \text{ pottle}$, $1 \text{ pottle} = 1 \text{ pottle}$ and $1 \text{ gill} = 5.32 \times 10^{-3} \text{ pottle}$.

Converting the last column under “gill” we obtain $1 \text{ chaldron} = 1.08 \times 10^5 \text{ gill}$, $1 \text{ bag} = 9.02 \times 10^3 \text{ gill}$, $1 \text{ pottle} = 188 \text{ gill}$ and of course $1 \text{ gill} = 1 \text{ gill}$.

Using the information from part c, $1.5 \text{ chaldron} = 1.5 \cdot 12.0 = 18.0 \text{ bag}$. And since each bag is 0.1091 m^3 we conclude $1.5 \text{ chaldron} = 18.0 \cdot 0.1091 = 1.96 \text{ m}^3$.

37. The volume of one unit is $1 \text{ cm}^3 = 1 \times 10^{-6} \text{ m}^3$ so the volume of a mole of them is $6.02 \times 10^{23} \text{ cm}^3 = 6.02 \times 10^{17} \text{ m}^3$. The cube root of this number gives the edge length $8.4 \times 10^5 \text{ m}^3$. This is equivalent to roughly $8 \times 10^2 \text{ km}$.

38. a Using the fact that the area A of a rectangle is width \times (length we find

$$\begin{aligned} A_{\text{total}} &= (3.00 \text{ acre}) + (25.0 \text{ perch})(4.00 \text{ perch}) \\ &= (3.00 \text{ acre}) \left(\frac{(40 \text{ perch})(4 \text{ perch})}{1 \text{ acre}} \right) + 100 \text{ perch}^2 \\ &= 580 \text{ perch}^2. \end{aligned}$$

We multiply this by the $\text{perch}^2 \rightarrow \text{rood}$ conversion factor $1 \text{ rood} = 40 \text{ perch}^2$ to obtain the answer $A_{\text{total}} = 14.5 \text{ roods}$.

b We convert our intermediate result in part a

$$A_{\text{total}} = (580 \text{ perch}^2) \left(\frac{16.5 \text{ ft}}{1 \text{ perch}} \right)^2 = 1.58 \times 10^5 \text{ ft}^2.$$

or We use the feet \rightarrow meters conversion given in Appendix to obtain

$$A_{\text{total}} = (1.58 \times 10^5 \text{ ft}^2) \left(\frac{1 \text{ m}}{3.281 \text{ ft}} \right)^2 = 1.47 \times 10^4 \text{ m}^2.$$

39. **THINK** This problem compares the U.S. gallon with the U.K. gallon to non-SI units for volume. The interpretation of the type of gallons—whether U.S. or U.K.—affects the amount of gasoline one calculates for traveling a given distance.

EXPRESS If the fuel consumption rate is R in miles/gallon, then the amount of gasoline in gallons needed for a trip of distance d in miles could be

$$V \text{ gallon} = \frac{d \text{ miles}}{R \text{ miles/gallon}}$$

Since the car was manufactured in the U.K., the fuel consumption rate is calibrated based on U.K. gallon, and the correct interpretation should be “40 miles per U.K. gallon.” In U.K., one would think of gallon as U.K. gallon; however, in the U.S., the word “gallon” would naturally be interpreted as U.S. gallon. Note also that since $1 \text{ U.S. gallon} = 4.5460900$ and $1 \text{ U.K. gallon} = 3.7854118$, the relationship between the two is

$$1 \text{ U.S. gallon} = 4.5460900 \left(\frac{1 \text{ U.K. gallon}}{3.7854118} \right) = 1.20095 \text{ U.K. gallons}$$

ANALYZE a The amount of gasoline actually required is

$$V' = \frac{750 \text{ miles}}{40 \text{ miles/U.K. gallon}} = 18.75 \text{ U.K. gallons} \approx 18.8 \text{ U.K. gallons}$$

This means that the driver mistakenly believes that the car should need 18.8 U.K. gallons.

b Using the conversion factor found above, this is equivalent to

$$V' = (18.75 \text{ U.K. gallons}) \times \left(\frac{1.20095 \text{ U.S. gallons}}{1 \text{ U.K. gallon}} \right) \approx 22.5 \text{ U.S. gallons}$$

LEARN The U.S. gallon is greater than one U.K. gallon by roughly a factor of 1.2 in volume. Therefore, 40 mi/U.K. gallon is less fuel efficient than 40 mi/U.S. gallon.

40. Equation 1-9 gives to very high precision the conversion from atomic mass units to kilograms. Since this problem deals with the ratio of total mass (1.0 kg) divided by the mass of one atom (1.0 u) but converted to kilograms, then the computation reduces to simply taking the reciprocal of the number given in Eq. 1-9 and rounding off appropriately. Thus the answer is 6.0×10^{26} .

41. **THINK** This problem involves converting *cord*, a non-SI unit for volume, to SI unit.

EXPRESS Using the exact conversion $1 \text{ in.} = 2.54 \text{ cm} = 0.0254 \text{ m}$ for length, we have

$$1 \text{ ft} = 12 \text{ in} = 12 \text{ in.} \times \left(\frac{0.0254 \text{ m}}{1 \text{ in}} \right) = 0.3048 \text{ m}.$$

thus $1 \text{ ft}^3 = 0.3048 \text{ m}^3 = 0.0283 \text{ m}^3$ for volume these results also can be found in ppendi .

ANALYZE he volume of a cord of wood is $V = 8 \text{ ft} \times 4 \text{ ft} \times 4 \text{ ft} = 128 \text{ ft}^3$. sing the conversion factor found above e obtain

$$V = 1 \text{ cord} = 128 \text{ ft}^3 = 128 \text{ ft}^3 \times \left(\frac{0.0283 \text{ m}^3}{1 \text{ ft}^3} \right) = 3.625 \text{ m}^3$$

hich implies that $1 \text{ m}^3 = \left(\frac{1}{3.625} \right) \text{ cord} = 0.276 \text{ cord} \approx 0.3 \text{ cord}$.

LEARN he un anted units ft^3 all cancel out as they should. n conversions units obey the same algebraic rules as variables and numbers.

42. a n atomic mass units the mass of one molecule is $16 \text{ } ^1_1\text{u} = 18 \text{ u}$. sing .
1 9 e find

$$18 \text{ u} = (18 \text{ u}) \left(\frac{1.6605402 \times 10^{-27} \text{ kg}}{1 \text{ u}} \right) = 3.0 \times 10^{-26} \text{ kg}.$$

b e divide the total mass by the mass of each molecule and obtain the appo imate number of ater molecules

$$N \approx \frac{1.4 \times 10^{21}}{3.0 \times 10^{-26}} \approx 5 \times 10^{46}.$$

43. million milligrams comprise a kilogram so 2.3 kg eek is $2.3 \times 10^6 \text{ mg}$ eek. iguring 7 days a eek 24 hours per day 3600 second per hour e find 604800 seconds are e uivalent to one eek. hus $2.3 \times 10^6 \text{ mg}$ eek 604800 s eek $= 3.8 \text{ mg}$ s.

44. he volume of the ater that fell is

$$\begin{aligned} V &= (26 \text{ km}^2) (2.0 \text{ in.}) = (26 \text{ km}^2) \left(\frac{1000 \text{ m}}{1 \text{ km}} \right)^2 (2.0 \text{ in.}) \left(\frac{0.0254 \text{ m}}{1 \text{ in.}} \right) \\ &= (26 \times 10^6 \text{ m}^2) (0.0508 \text{ m}) \\ &= 1.3 \times 10^6 \text{ m}^3. \end{aligned}$$

e rite the mass per unit volume density of the ater as $\rho = \frac{m}{V} = 1 \times 10^3 \text{ kg/m}^3$.

he mass of the ater that fell is therefore given by $m = \rho V$

$$m = (1 \times 10^3 \text{ kg/m}^3) (1.3 \times 10^6 \text{ m}^3) = 1.3 \times 10^9 \text{ kg}.$$

45. The number of seconds in a year is 3.156×10^7 . This is listed in Appendix and results from the product

$$365.25 \text{ day y} \quad 24 \text{ h day} \quad 60 \text{ min h} \quad 60 \text{ s min}.$$

a. The number of shakes in a second is 10^8 therefore there are indeed more shakes per second than there are seconds per year.

b. Denoting the age of the universe as 1 u day or 86400 u sec then the time during which humans have existed is given by

$$\frac{10^6}{10^{10}} = 10^{-4} \text{ u day}$$

which may also be expressed as $(10^{-4} \text{ u day}) \left(\frac{86400 \text{ u sec}}{1 \text{ u day}} \right) = 8.6 \text{ u sec}.$

46. The volume removed in one year is $V = 75 \times 10^4 \text{ m}^2 \cdot 26 \text{ m} \approx 2 \times 10^7 \text{ m}^3$

which we convert to cubic kilometers $V = (2 \times 10^7 \text{ m}^3) \left(\frac{1 \text{ km}}{1000 \text{ m}} \right)^3 = 0.020 \text{ km}^3.$

47. **THINK** This problem involves expressing the speed of light in astronomical units per minute.

EXPRESS We first convert meters to astronomical units and seconds to minutes using

$$1000 \text{ m} = 1 \text{ km} \quad 1 \text{ au} = 1.50 \times 10^8 \text{ km} \quad 60 \text{ s} = 1 \text{ min}.$$

ANALYZE Using the conversion factors above the speed of light can be rewritten as

$$c = 3.0 \times 10^8 \text{ m s}^{-1} = \left(\frac{3.0 \times 10^8 \text{ m}}{\text{s}} \right) \left(\frac{1 \text{ km}}{1000 \text{ m}} \right) \left(\frac{1 \text{ au}}{1.50 \times 10^8 \text{ km}} \right) \left(\frac{60 \text{ s}}{\text{min}} \right) = 0.12 \text{ au/min}.$$

LEARN When we expressed the speed of light c in au/min we readily see that it takes about $8.3 = 1/0.12$ minutes for sunlight to reach the earth i.e. to travel a distance of 1 au.

48. Since one atomic mass unit is $1 \text{ u} = 1.66 \times 10^{-24} \text{ g}$ see Appendix the mass of one mole of atoms is about $m = 1.66 \times 10^{-24} \text{ g} \cdot 6.02 \times 10^{23} = 1 \text{ g}$. On the other hand the mass of one mole of atoms in the common SI system is

$$m' = \frac{75 \text{ g}}{7.5} = 10 \text{ g}$$

herefore in atomic mass units the average mass of one atom in the common astern mole is

$$\frac{m'}{N_A} = \frac{10 \text{ g}}{6.02 \times 10^{23}} = 1.66 \times 10^{-23} \text{ g} = 10 \text{ u}.$$

49. a uaring the relation 1 ken = 1.97 m and setting up the ratio e obtain

$$\frac{1 \text{ ken}^2}{1 \text{ m}^2} = \frac{1.97^2 \text{ m}^2}{1 \text{ m}^2} = 3.88.$$

b imilarly e find

$$\frac{1 \text{ ken}^3}{1 \text{ m}^3} = \frac{1.97^3 \text{ m}^3}{1 \text{ m}^3} = 7.65.$$

c he volume of a cylinder is the circular area of its base multiplied by its height. hus

$$\pi r^2 h = \pi (3.00)^2 (5.50) = 156 \text{ ken}^3.$$

d f e multiply this by the result of part b e determine the volume in cubic meters
 $155.5 \cdot 7.65 = 1.19 \times 10^3 \text{ m}^3.$

50. ccording to ppendi a nautical mile is 1.852 km so 24.5 nautical miles ould be 45.374 km. Iso according to ppendi a mile is 1.609 km so 24.5 miles is 39.4205 km. he difference is 5.95 km.

51. a or the minimum 43 cm case 9 cubits converts as follo s

$$9 \text{ cubits} = (9 \text{ cubits}) \left(\frac{0.43 \text{ m}}{1 \text{ cubit}} \right) = 3.9 \text{ m}.$$

$$\text{nd for the ma imum 53 cm case e have } 9 \text{ cubits} = (9 \text{ cubits}) \left(\frac{0.53 \text{ m}}{1 \text{ cubit}} \right) = 4.8 \text{ m}.$$

b imilarly ith $0.43 \text{ m} \rightarrow 430 \text{ mm}$ and $0.53 \text{ m} \rightarrow 530 \text{ mm}$ e find $3.9 \times 10^3 \text{ mm}$ and $4.8 \times 10^3 \text{ mm}$ respectively.

c e can convert length and diameter first and then compute the volume or first compute the volume and then convert. e proceed using the latter approach here d is diameter and ℓ is length .

$$V_{\text{cylinder min}} = \frac{\pi}{4} \ell d^2 = 28 \text{ cubit}^3 = (28 \text{ cubit}^3) \left(\frac{0.43 \text{ m}}{1 \text{ cubit}} \right)^3 = 2.2 \text{ m}^3.$$

imilarly with 0.43 m replaced by 0.53 m we obtain $V_{\text{cylinder ma}} = 4.2 \text{ m}^3$.

52. Abbreviating wapentake as “wp” and assuming a hide to be 110 acres, we set up the ratio 25 wp 11 barn along with appropriate conversion factors

$$\frac{(25 \text{ wp}) \left(\frac{100 \text{ hide}}{1 \text{ wp}} \right) \left(\frac{110 \text{ acre}}{1 \text{ hide}} \right) \left(\frac{4047 \text{ m}^2}{1 \text{ acre}} \right)}{(11 \text{ barn}) \left(\frac{1 \times 10^{-28} \text{ m}^2}{1 \text{ barn}} \right)} \approx 1 \times 10^{36}.$$

53. **THINK** The objective of this problem is to convert the earth-sun distance 1 AU to parsecs and light years.

EXPRESS To relate parsec (pc) to AU, we note that when θ is measured in radians, it is equal to the arc length s divided by the radius R . For a very large radius circle and small value of θ , the arc may be approximated as the straight line segment of length 1 AU. Thus

$$\theta = 1 \text{ arcsec} = (1 \text{ arcsec}) \left(\frac{1 \text{ arcmin}}{60 \text{ arcsec}} \right) \left(\frac{1^\circ}{60 \text{ arcmin}} \right) \left(\frac{2\pi \text{ radian}}{360^\circ} \right) = 4.85 \times 10^{-6} \text{ rad}.$$

Therefore, one parsec is

$$1 \text{ pc} = \frac{s}{\theta} = \frac{1 \text{ AU}}{4.85 \times 10^{-6}} = 2.06 \times 10^5 \text{ AU}.$$

We then relate AU to light year (ly). Since a year is about $3.16 \times 10^7 \text{ s}$,

$$1 \text{ ly} = (186,000 \text{ mi/s}) (3.16 \times 10^7 \text{ s}) = 5.9 \times 10^{12} \text{ mi}.$$

ANALYZE a) Since $1 \text{ pc} = 2.06 \times 10^5 \text{ AU}$, inverting the relation gives

$$1 \text{ AU} = (1 \text{ pc}) \left(\frac{1 \text{ pc}}{2.06 \times 10^5} \right) = 4.9 \times 10^{-6} \text{ pc}.$$

b) Given that $1 \text{ AU} = 92.9 \times 10^6 \text{ mi}$ and $1 \text{ ly} = 5.9 \times 10^{12} \text{ mi}$, the two expressions together lead to

$$1 \text{ AU} = 92.9 \times 10^6 \text{ mi} = 92.9 \times 10^6 \text{ mi} \left(\frac{1 \text{ ly}}{5.9 \times 10^{12} \text{ mi}} \right) = 1.57 \times 10^{-5} \text{ ly}.$$

LEARN Our results can be further combined to give $1 \text{ pc} = 3.2 \text{ ly}$. From the above expression we readily see that it takes $1.57 \times 10^{-5} \text{ y}$, or about 8.3 min for sunlight to travel a distance of 1 pc to reach the earth.

54. a. Since we have $1 \text{ ft} = 0.3048 \text{ m}$, $1 \text{ gal} = 231 \text{ in.}^3$ and $1 \text{ in.}^3 = 1.639 \times 10^{-2} \text{ m}^3$. From the latter two items we find that $1 \text{ gal} = 3.79 \text{ m}^3$. Thus the quantity $460 \text{ ft}^2 \text{ gal}$ becomes

$$460 \text{ ft}^2 \text{ gal} = \left(\frac{460 \text{ ft}^2}{\text{gal}} \right) \left(\frac{1 \text{ m}}{3.28 \text{ ft}} \right)^2 \left(\frac{1 \text{ gal}}{3.79} \right) = 11.3 \text{ m}^2/.$$

b. Also since 1 m^3 is equivalent to 1000 L our result from part a becomes

$$11.3 \text{ m}^2 = \left(\frac{11.3 \text{ m}^2}{\text{m}^3} \right) \left(\frac{1000}{1 \text{ m}^3} \right) = 1.13 \times 10^4 \text{ m}^{-1}.$$

c. The inverse of the original quantity is $460 \text{ ft}^2 \text{ gal}^{-1} = 2.17 \times 10^{-3} \text{ gal ft}^2$.

d. The answer in c represents the volume of the paint in gallons needed to cover a square foot of area. From this we could also figure the paint thickness; it turns out to be about a tenth of a millimeter as one sees by taking the reciprocal of the answer in part b.

55. a. The receptacle is a volume of $40 \text{ cm} \times 40 \text{ cm} \times 30 \text{ cm} = 48000 \text{ cm}^3 = 48 \text{ L} = 48/16 = 3.0 \text{ standard bottles}$. Which is a little more than 3 nebuchadnechans, the largest bottle indicated. The remainder 0.63 standard bottles is just a little less than 1 methuselah. Thus the answer to part a is 3 nebuchadnechans and 1 methuselah.

b. Since $1 \text{ methuselah} = 8 \text{ standard bottles}$ then the extra amount is $8 - 7.63 = 0.37 \text{ standard bottle}$.

c. Using the conversion factor $16 \text{ standard bottles} = 11.356 \text{ L}$ we have

$$0.37 \text{ standard bottle} = 0.37 \text{ standard bottle} \left(\frac{11.356}{16 \text{ standard bottles}} \right) = 0.26 \text{ L}.$$

56. The mass of the pig is $3.108 \text{ slugs} \times 14.59 = 45.346 \text{ kg}$. Referring now to the corn a bushel is 35.238 liters. Thus a value of 1 for the *corn-hog ratio* could be equivalent to $35.238/45.346 = 0.7766$ in the indicated metric units. Therefore a value of 5.7 for the *ratio* corresponds to $5.7 \times 0.777 \approx 4.4$ in the indicated metric units.

57. The number of peppers have spiciness = 8000 and this amount multiplied by 400 the number of people is 3.2×10^6 which is roughly ten times the value for a

single habanero pepper. More precisely 10.7 habanero peppers will provide that total required value.

58. In the simplest approach we set up a ratio for the total increase in *horizontal depth* x here $\Delta x = 0.05$ m is the increase in horizontal depth per step

$$x = N_{\text{steps}} \Delta x = \left(\frac{4.57}{0.19} \right) (0.05 \text{ m}) = 1.2 \text{ m.}$$

However we can approach this more carefully by noting that if there are $N = 4.57 / .19 \approx 24$ rises then under normal circumstances we could expect $N - 1 = 23$ horizontal pieces in that staircase. This would yield $23 (0.05 \text{ m}) = 1.15 \text{ m}$ which to two significant figures agrees with our first result.

59. The volume of the filled container is $24000 \text{ cm}^3 = 24$ liters which using the conversion given in the problem is equivalent to 50.7 pints. . . . The expected number is therefore in the range from 1317 to 1927 Atlantic oysters. Instead the number received is in the range from 406 to 609 Pacific oysters. This represents a shortage in the range of roughly 700 to 1500 oysters the answer to the problem. Note that the minimum value in our answer corresponds to the minimum Atlantic minus the maximum Pacific and the maximum value corresponds to the maximum Atlantic minus the minimum Pacific.

60. a. We reduce the stock amount to British teaspoons

$$1 \text{ breakfastcup} = 2 \times 8 \times 2 \times 2 = 64 \text{ teaspoons}$$

$$1 \text{ teacup} = 8 \times 2 \times 2 = 32 \text{ teaspoons}$$

$$6 \text{ tablespoons} = 6 \times 2 \times 2 = 24 \text{ teaspoons}$$

$$1 \text{ dessertspoon} = 2 \text{ teaspoons}$$

which totals to 122 British teaspoons or 122 . . . teaspoons since liquid measure is being used. . . . With one . . . cup equal to 48 teaspoons upon dividing $122 / 48 \approx 2.54$ we find this amount corresponds to 2.5 . . . cups plus a remainder of precisely 2 teaspoons. In other words

$$122 \text{ . . . teaspoons} = 2.5 \text{ . . . cups} + 2 \text{ . . . teaspoons.}$$

b. For the nettle tops one half quart is still one half quart.

c. For the rice one British tablespoon is 4 British teaspoons which since dry goods measure is being used corresponds to 2 . . . teaspoons.

d. British saltspoon is $\frac{1}{2}$ British teaspoon which corresponds since dry goods measure is again being used to 1 . . . teaspoon.

Chapter

1. The speed assumed constant is $v = 90 \text{ km/h} = 1000 \text{ m/km} / 3600 \text{ s/h} = 25 \text{ m/s}$.
 Thus in 0.50 s the car travels a distance $d = vt = 25 \text{ m/s} \cdot 0.50 \text{ s} \approx 13 \text{ m}$.

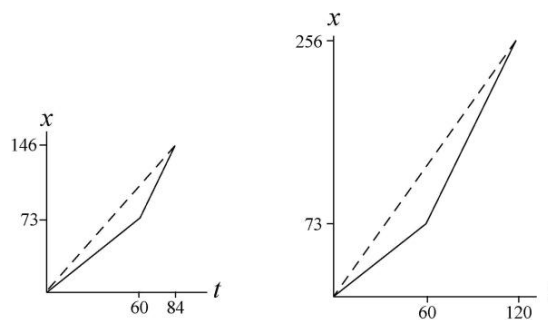
2. a Using the fact that time = distance/velocity while the velocity is constant we find

$$v_{\text{avg}} = \frac{73.2 \text{ m} + 73.2 \text{ m}}{\frac{73.2 \text{ m}}{1.22 \text{ m/s}} + \frac{73.2 \text{ m}}{3.05 \text{ m/s}}} = 1.74 \text{ m/s}.$$

b Using the fact that distance = vt while the velocity v is constant we find

$$v_{\text{avg}} = \frac{1.22 \text{ m/s} \cdot 60 \text{ s} + 3.05 \text{ m/s} \cdot 60 \text{ s}}{120 \text{ s}} = 2.14 \text{ m/s}.$$

c The graphs are shown below with meters and seconds understood. The first consists of two solid line segments the first having a slope of 1.22 and the second having a slope of 3.05. The slope of the dashed line represents the average velocity in both graphs. The second graph also consists of two solid line segments having the same slopes as before — the main difference compared to the first graph being that the stage involving higher speed motion lasts much longer.



3. **THINK** This one dimensional kinematics problem consists of two parts and we are asked to solve for the average velocity and average speed of the car.

EXPRESS Since the trip consists of two parts let the displacements during first and second parts of the motion be Δx_1 and Δx_2 and the corresponding time intervals be Δt_1 and Δt_2 respectively. So because the problem is one dimensional and both displacements are in the same direction the total displacement is simply $\Delta x = \Delta x_1 + \Delta x_2$ and the total time for the trip is $\Delta t = \Delta t_1 + \Delta t_2$. Using the definition of average velocity given in 2.2 we have

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{\Delta x_1 + \Delta x_2}{\Delta t_1 + \Delta t_2}.$$

o find the average speed we note that during a time Δt if the velocity remains a positive constant then the speed is equal to the magnitude of velocity and the distance is equal to the magnitude of displacement with $d = \Delta x = v\Delta t$.

ANALYZE

a During the first part of the motion the displacement is $\Delta x_1 = 40$ km and the time taken is

$$t_1 = \frac{40 \text{ km}}{30 \text{ km/h}} = 1.33 \text{ h.}$$

imilarly during the second part of the trip the displacement is $\Delta x_2 = 40$ km and the time interval is

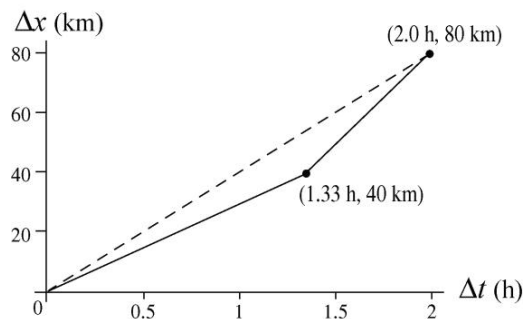
$$t_2 = \frac{40 \text{ km}}{60 \text{ km/h}} = 0.67 \text{ h.}$$

he total displacement is $\Delta x = \Delta x_1 + \Delta x_2 = 40 \text{ km} + 40 \text{ km} = 80 \text{ km}$ and the total time elapsed is $\Delta t = \Delta t_1 + \Delta t_2 = 2.00 \text{ h}$. Consequently the average velocity is

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{80 \text{ km}}{2.0 \text{ h}} = 40 \text{ km/h.}$$

b In this case the average speed is the same as the magnitude of the average velocity $s_{\text{avg}} = 40 \text{ km/h}$.

c The graph of the entire trip shown below consists of two contiguous line segments the first having a slope of 30 km/h and connecting the origin to $(\Delta t_1, \Delta x_1) = (1.33 \text{ h}, 40 \text{ km})$ and the second having a slope of 60 km/h and connecting $(\Delta t_1, \Delta x_1)$ to $(\Delta t, \Delta x) = (2.00 \text{ h}, 80 \text{ km})$.



From the graphical point of view the slope of the dashed line drawn from the origin to $(\Delta t, \Delta x)$ represents the average velocity.

LEARN The average velocity is a vector quantity that depends only on the net displacement also a vector between the starting and ending points.

4. Average speed as opposed to average velocity relates to the total distance as opposed to the net displacement. The distance D up the hill is of course the same as the distance down the hill and since the speed is constant during each stage of the

motion we have speed = D/t . Thus the average speed is

$$\frac{D_{\text{up}} + D_{\text{down}}}{t_{\text{up}} + t_{\text{down}}} = \frac{2D}{\frac{D}{v_{\text{up}}} + \frac{D}{v_{\text{down}}}}$$

which after canceling D and plugging in $v_{\text{up}} = 40 \text{ km/h}$ and $v_{\text{down}} = 60 \text{ km/h}$ yields 48 km/h for the average speed.

5. **THINK** In this one dimensional kinematics problem, we're given the position function $x(t)$ and asked to calculate the position and velocity of the object at a later time.

EXPRESS The position function is given as $x(t) = 3 \text{ m/s} t - 4 \text{ m/s}^2 t^2 + 1 \text{ m/s}^3 t^3$. The position of the object at some instant t_0 is simply given by $x(t_0)$. For the time interval $t_1 \leq t \leq t_2$ the displacement is $\Delta x = x(t_2) - x(t_1)$. Similarly using Eq. 2.2 the average velocity for this time interval is

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{x(t_2) - x(t_1)}{t_2 - t_1}.$$

ANALYZE a Plugging in $t = 1 \text{ s}$ into $x(t)$ yields

$$x(1 \text{ s}) = 3 \text{ m/s} (1 \text{ s}) - 4 \text{ m/s}^2 (1 \text{ s})^2 + 1 \text{ m/s}^3 (1 \text{ s})^3 = 0.$$

b With $t = 2 \text{ s}$ we get $x(2 \text{ s}) = 3 \text{ m/s} (2 \text{ s}) - 4 \text{ m/s}^2 (2 \text{ s})^2 + 1 \text{ m/s}^3 (2 \text{ s})^3 = -2 \text{ m}$.

c With $t = 3 \text{ s}$ we have $x(3 \text{ s}) = 3 \text{ m/s} (3 \text{ s}) - 4 \text{ m/s}^2 (3 \text{ s})^2 + 1 \text{ m/s}^3 (3 \text{ s})^3 = 0 \text{ m}$.

d Similarly plugging in $t = 4 \text{ s}$ gives

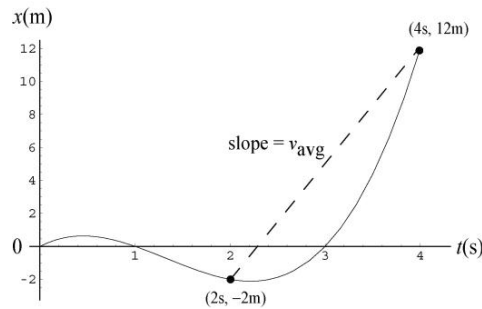
$$x(4 \text{ s}) = 3 \text{ m/s} (4 \text{ s}) - 4 \text{ m/s}^2 (4 \text{ s})^2 + 1 \text{ m/s}^3 (4 \text{ s})^3 = 12 \text{ m}.$$

e The position at $t = 0$ is $x = 0$. Thus the displacement between $t = 0$ and $t = 4 \text{ s}$ is $\Delta x = x(4 \text{ s}) - x(0) = 12 \text{ m} - 0 = 12 \text{ m}$.

f The position at $t = 2 \text{ s}$ is subtracted from the position at $t = 4 \text{ s}$ to give the displacement $\Delta x = x(4 \text{ s}) - x(2 \text{ s}) = 12 \text{ m} - (-2 \text{ m}) = 14 \text{ m}$. Thus the average velocity is

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{14 \text{ m}}{2 \text{ s}} = 7 \text{ m/s}.$$

g The position of the object for the interval $0 \leq t \leq 4$ is plotted below. The straight line drawn from the point at $t, x = 2 \text{ s}, -2 \text{ m}$ to $4 \text{ s}, 12 \text{ m}$ could represent the average velocity answer for part f.



LEARN ur graphical representation illustrates once again that the average velocity for a time interval depends only on the net displacement between the starting and ending points.

6. uber's speed is

$$v_0 = 200 \text{ m} / 6.509 \text{ s} = 30.72 \text{ m/s} = 110.6 \text{ km/h}$$

here we have used the conversion factor $1 \text{ m/s} = 3.6 \text{ km/h}$. Since hittingham beat uber by 19.0 km/h his speed is $v_1 = 110.6 \text{ km/h} + 19.0 \text{ km/h} = 129.6 \text{ km/h}$ or 36 m/s . $1 \text{ km/h} = 0.2778 \text{ m/s}$. Thus using v_1 the time through a distance of 200 m for hittingham is

$$\Delta t = \frac{\Delta x}{v_1} = \frac{200 \text{ m}}{36 \text{ m/s}} = 5.554 \text{ s}.$$

7. Recognizing that the gap between the trains is closing at a constant rate of 60 km/h the total time that elapses before they crash is $t = 60 \text{ km} / 60 \text{ km/h} = 1.0 \text{ h}$. During this time the bird travels a distance of $x = vt = 60 \text{ km/h} \cdot 1.0 \text{ h} = 60 \text{ km}$.

8. The amount of time it takes for each person to move a distance L with speed v_s is $\Delta t = L / v_s$. With each additional person the depth increases by one body depth d

a. The rate of increase of the layer of people is

$$R = \frac{d}{\Delta t} = \frac{d}{L / v_s} = \frac{dv_s}{L} = \frac{0.25 \text{ m} \cdot 3.50 \text{ m/s}}{1.75 \text{ m}} = 0.50 \text{ m/s}$$

b. The amount of time required to reach a depth of $D = 5.0 \text{ m}$ is

$$t = \frac{D}{R} = \frac{5.0 \text{ m}}{0.50 \text{ m/s}} = 10 \text{ s}$$

9. Converting to seconds the running times are $t_1 = 147.95 \text{ s}$ and $t_2 = 148.15 \text{ s}$ respectively. If the runners were equally fast then

$$s_{avg1} = s_{avg2} \Rightarrow \frac{L_1}{t_1} = \frac{L_2}{t_2}.$$

From this we obtain

$$L_2 - L_1 = \left(\frac{t_2}{t_1} - 1 \right) L_1 = \left(\frac{148.15}{147.95} - 1 \right) L_1 = 0.00135 L_1 \approx 1.4 \text{ m}$$

here we set $L_1 \approx 1000 \text{ m}$ in the last step. Thus if L_1 and L_2 are no different than about 1.4 m then runner 1 is indeed faster than runner 2. However if L_1 is shorter than L_2 by more than 1.4 m then runner 2 could actually be faster.

10. Let v_w be the speed of the wind and v_c be the speed of the car.

a. Suppose during time interval t_1 the car moves in the same direction as the wind. Then the effective speed of the car is given by $v_{\text{eff } 1} = v_c + v_w$ and the distance traveled is $d = v_{\text{eff } 1} t_1 = (v_c + v_w) t_1$. On the other hand for the return trip during time interval t_2 the car moves in the opposite direction of the wind and the effective speed could be $v_{\text{eff } 2} = v_c - v_w$. The distance traveled is $d = v_{\text{eff } 2} t_2 = (v_c - v_w) t_2$. The two expressions can be rewritten as

$$v_c + v_w = \frac{d}{t_1} \quad \text{and} \quad v_c - v_w = \frac{d}{t_2}$$

Adding the two equations and dividing by two we obtain $v_c = \frac{1}{2} \left(\frac{d}{t_1} + \frac{d}{t_2} \right)$. Thus method 1 gives the car's speed v_c in windless situation.

b. If method 2 is used the result could be

$$v'_c = \frac{d}{\frac{t_1 + t_2}{2}} = \frac{2d}{t_1 + t_2} = \frac{2d}{\frac{d}{v_c + v_w} + \frac{d}{v_c - v_w}} = \frac{v_c^2 - v_w^2}{v_c} = v_c \left[1 - \left(\frac{v_w}{v_c} \right)^2 \right].$$

The fractional difference is

$$\frac{v_c - v'_c}{v_c} = \left(\frac{v_w}{v_c} \right)^2 = 0.0240^2 = 5.76 \times 10^{-4}.$$

11. The values used in the problem statement make it easy to see that the first part of the trip at 100 km/h takes 1 hour and the second part at 40 km/h also takes 1 hour.

Expressed in decimal form the time left is 1.25 hour and the distance that remains is 160 km. Thus a speed $v = 160 \text{ km} / 1.25 \text{ h} = 128 \text{ km/h}$ is needed.

12. a. Let the fast and the slow cars be separated by a distance d at $t = 0$. If during the time interval $t = L/v_s = 12.0 \text{ m} / 5.0 \text{ m/s} = 2.40 \text{ s}$ in which the slow car has moved a distance of $L = 12.0 \text{ m}$ the fast car moves a distance of $vt = d + L$ to join the line of slow cars then the shock wave could remain stationary. The condition implies a separation of

$$d = vt - L = 25 \text{ m/s} \cdot 2.4 \text{ s} - 12.0 \text{ m} = 48.0 \text{ m}.$$

b. Let the initial separation at $t = 0$ be $d = 96.0 \text{ m}$. At a later time t the slow and

the fast cars have traveled $x = v_s t$ and the fast car joins the line by moving a distance $d + x$. From

$$t = \frac{x}{v_s} = \frac{d + x}{v}$$

we get

$$x = \frac{v_s}{v - v_s} d = \frac{5.00 \text{ m/s}}{25.0 \text{ m/s} - 5.00 \text{ m/s}} 96.0 \text{ m} = 24.0 \text{ m}$$

which in turn gives $t = (24.0 \text{ m} + 5.00 \text{ m/s}) / 25.0 \text{ m/s} = 4.80 \text{ s}$. Since the rear of the slow car pack has moved a distance of $\Delta x = x - L = 24.0 \text{ m} - 12.0 \text{ m} = 12.0 \text{ m}$ downstream the speed of the rear of the slow car pack (or equivalently the speed of the shock wave) is

$$v_{\text{shock}} = \frac{\Delta x}{t} = \frac{12.0 \text{ m}}{4.80 \text{ s}} = 2.50 \text{ m/s}.$$

c Since $x > L$ the direction of the shock wave is downstream.

13. a Denoting the travel time and distance from San Antonio to Houston as T and D respectively the average speed is

$$s_{\text{avg1}} = \frac{D}{T} = \frac{55 \text{ km/h} \cdot T/2 + 90 \text{ km/h} \cdot T/2}{T} = 72.5 \text{ km/h}$$

which should be rounded to 73 km/h.

b Using the fact that time = distance/speed while the speed is constant we find

$$s_{\text{avg2}} = \frac{D}{T} = \frac{D}{\frac{D/2}{55 \text{ km/h}} + \frac{D/2}{90 \text{ km/h}}} = 68.3 \text{ km/h}$$

which should be rounded to 68 km/h.

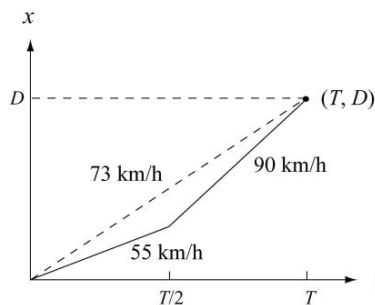
c The total distance traveled $2D$ must not be confused with the net displacement zero. We obtain for the total trip

$$s_{\text{avg}} = \frac{2D}{\frac{D}{72.5 \text{ km/h}} + \frac{D}{68.3 \text{ km/h}}} = 70 \text{ km/h}.$$

d Since the net displacement vanishes the average velocity for the trip in its entirety is zero.

e In asking for a *sketch* the problem is allowing the student to arbitrarily set the distance D the intent is *not* to make the student go to an atlas to look it up the student can just as easily arbitrarily set T instead of D as will be clear in the following discussion. We briefly describe the graph with kilometers per hour understood for the slopes of two contiguous line segments the first having a slope of 55 and connecting the origin to $(t_1, x_1) = (T/2, 55T/2)$ and the second having a slope of 90 and connecting (t_1, x_1) to (T, D) where $D = 55 \cdot 90 \cdot T/2$. The average velocity from the

graphical point of view is the slope of a line drawn from the origin to (T, D) . The graph (not drawn to scale) is depicted below.



14. Using the general property $\frac{d}{dx} e^{p \ln x} = e^{p \ln x} \cdot \frac{p}{x}$ write

$$v = \frac{dx}{dt} = \left(\frac{d}{dt} 19t \right) \cdot e^{-t} + 19t \cdot \left(\frac{de^{-t}}{dt} \right).$$

If a concern develops about the appearance of an argument of the exponential $-t$ apparently having units, then an explicit factor of $1/T$ (here $T = 1$ second) can be inserted and carried through the computation which does not change our answer. The result of this differentiation is

$$v = 16(1 - t)e^{-t}$$

With t and v in units s and m/s respectively, we see that this function is zero when $t = 1$ s. So that we know *when* it stops, we find out *where* it stops by plugging our result $t = 1$ into the given function $x = 16te^{-t}$ with x in meters. Therefore we find $x = 5.9$ m.

15. We use 2.4 to solve the problem.

a. The velocity of the particle is

$$v = \frac{dx}{dt} = \frac{d}{dt} (4 - 12t + 3t^2) = -12 + 6t.$$

Thus at $t = 1$ s the velocity is $v = -12 + 6(1) = -6$ m/s.

b. Since $v < 0$ it is moving in the $-x$ direction at $t = 1$ s.

c. At $t = 1$ s the *speed* is $|v| = 6$ m/s.

d. For $0 < t < 2$ s v decreases until it vanishes. For $2 < t < 3$ s v increases from zero to the value it had in part c. Then v is larger than that value for $t > 3$ s.

We see since v smoothly changes from negative values, consider the $t = 1$ result to positive, note that as $t \rightarrow \infty$ we have $v \rightarrow \infty$. We can check that $v = 0$ when $t = 2$ s.

f. In fact from $v = -12 - 6t$ we know that $v > 0$ for $t > 2$ s.

16. We use the functional notation $x(t)$, $v(t)$ and $a(t)$ in this solution. Here the latter two quantities are obtained by differentiation

$$v(t) = \frac{dx(t)}{dt} = -12t \quad \text{and} \quad a(t) = \frac{dv(t)}{dt} = -12$$

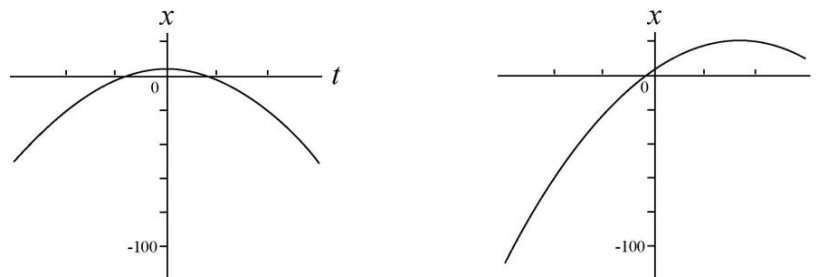
with units understood.

a. From $v(t) = 0$ we find it is momentarily at rest at $t = 0$.

b. We obtain $x(0) = 4.0$ m.

c. and d. We require $x(t) = 0$ in the expression $x(t) = 4.0 - 6.0t^2$ leads to $t = \pm 0.82$ s for the times when the particle can be found passing through the origin.

e. We show both the asked for graph (on the left) as well as the “shifted” graph that is relevant to part f. In both cases the time axis is given by $-3 \leq t \leq 3$ units understood.



f. We arrived at the graph on the right shown above by adding $20t$ to the $x(t)$ expression.

g. Examining here the slopes of the graphs become zero it is clear that the shift causes the $v = 0$ point to correspond to a larger value of x the top of the second curve shown in part e is higher than that of the first.

17. We use 2.2 for average velocity and 2.4 for instantaneous velocity and work with distances in centimeters and times in seconds.

a. We plug into the given equation for x for $t = 2.00$ s and $t = 3.00$ s and obtain $x_2 = 21.75$ cm and $x_3 = 50.25$ cm respectively. The average velocity during the time interval $2.00 \leq t \leq 3.00$ s is

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{50.25 \text{ cm} - 21.75 \text{ cm}}{3.00 \text{ s} - 2.00 \text{ s}}$$

which yields $v_{\text{avg}} = 28.5$ cm/s.

b. The instantaneous velocity is $v = \frac{dx}{dt} = 4.5t^2$ which at time $t = 2.00$ s yields $v = 4.5(2.00)^2 = 18.0$ cm/s.

c At $t = 3.00$ s the instantaneous velocity is $v = 4.5 \cdot 3.00^2 = 40.5$ cm/s.

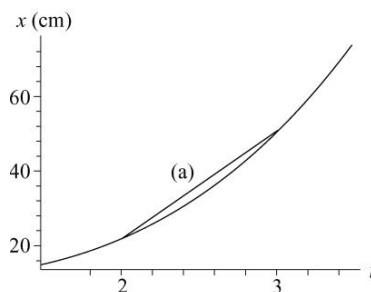
d At $t = 2.50$ s the instantaneous velocity is $v = 4.5 \cdot 2.50^2 = 28.1$ cm/s.

e Let t_m stand for the moment when the particle is midway between x_2 and x_3 that is when the particle is at $x_m = (x_2 + x_3)/2 = 36$ cm. Therefore

$$x_m = 9.75 + 1.5t_m^3 \Rightarrow t_m = 2.596$$

in seconds. Thus the instantaneous speed at this time is $v = 4.5 \cdot 2.596^2 = 30.3$ cm/s.

f The answer to part a is given by the slope of the straight line between $t = 2$ and $t = 3$ in this x vs t plot. The answers to parts b, c, d and e correspond to the slopes of tangent lines (not shown but easily imagined) to the curve at the appropriate points.



18. a Taking derivatives of $x(t) = 12t^2 - 2t^3$ we obtain the velocity and the acceleration functions

$$v(t) = 24t - 6t^2 \quad \text{and} \quad a(t) = 24 - 12t$$

With length in meters and time in seconds. Plugging in the value $t = 3$ yields $x(3) = 54$ m.

b Similarly plugging in the value $t = 3$ yields $v(3) = 18$ m/s.

c For $t = 3$ $a(3) = -12$ m/s².

d At the maximum x we must have $v = 0$ eliminating the $t = 0$ root the velocity equation reveals $t = 24/6 = 4$ s for the time of maximum x . Plugging $t = 4$ into the equation for x leads to $x = 64$ m for the largest x value reached by the particle.

e From d we see that the x reaches its maximum at $t = 4.0$ s.

f Maximum v requires $a = 0$ which occurs when $t = 24/12 = 2.0$ s. This inserted into the velocity equation gives $v_{\text{ma}} = 24$ m/s.

g From f we see that the maximum of v occurs at $t = 24/12 = 2.0$ s.

h In part e the particle was momentarily motionless at $t = 4$ s. The acceleration at that time is readily found to be $24 - 12(4) = -24$ m/s².

the *average velocity* is defined by $v_{\text{avg}} = \frac{\Delta x}{\Delta t}$ so we see that the values of x at $t = 0$ and $t = 3$ s are needed these are respectively $x = 0$ and $x = 54$ m found in part (a). Thus

$$v_{\text{avg}} = \frac{54 - 0}{3 - 0} = 18 \text{ m/s}.$$

19. THINK In this one dimensional kinematics problem, we're given the speed of a particle at two instants and asked to calculate its average acceleration.

EXPRESS We represent the initial direction of motion as the x direction. The average acceleration over a time interval $t_1 \leq t \leq t_2$ is given by $a_{\text{avg}} = \frac{\Delta v}{\Delta t}$.

$$a_{\text{avg}} = \frac{\Delta v}{\Delta t} = \frac{v(t_2) - v(t_1)}{t_2 - t_1}.$$

ANALYZE Let $v_1 = 18$ m/s at $t_1 = 0$ and $v_2 = -30$ m/s at $t_2 = 2.4$ s. Using $a_{\text{avg}} = \frac{\Delta v}{\Delta t}$ we find

$$a_{\text{avg}} = \frac{v(t_2) - v(t_1)}{t_2 - t_1} = \frac{-30 \text{ m/s} - 18 \text{ m/s}}{2.4 \text{ s} - 0} = -20 \text{ m/s}^2.$$

LEARN The average acceleration has magnitude 20 m/s^2 and is in the opposite direction to the particle's initial velocity. This makes sense because the velocity of the particle is decreasing over the time interval. With $t_1 = 0$ the velocity of the particle as a function of time can be written as

$$v = v_0 + at = 18 \text{ m/s} - 20 \text{ m/s}^2 t.$$

20. We use the functional notation $x(t)$, $v(t)$ and $a(t)$ and find the latter two quantities by differentiating

$$v(t) = \frac{dx(t)}{dt} = -15t^2 + 20 \quad \text{and} \quad a(t) = \frac{dv(t)}{dt} = -30t$$

with units understood. These expressions are used in the parts that follow.

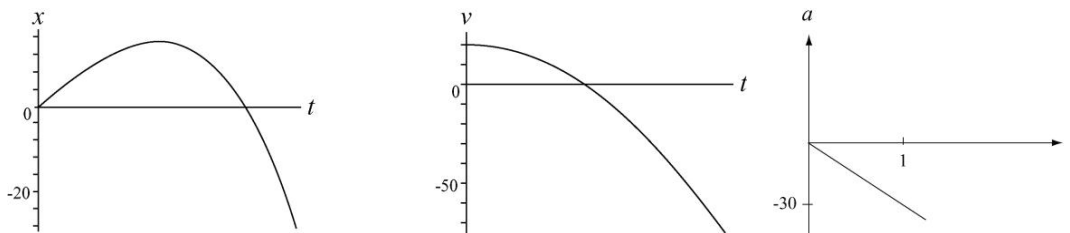
(a) From $0 = -15t^2 + 20$ we see that the only positive value of t for which the particle is momentarily stopped is $t = \sqrt{20/15} = 1.2$ s.

(b) From $0 = -30t$ we find $a(0) = 0$ that is it vanishes at $t = 0$.

(c) It is clear that $a(t) = -30t$ is negative for $t > 0$.

(d) The acceleration $a(t) = -30t$ is positive for $t < 0$.

(e) The graphs are shown below. Units are understood.



21. We use 2.2 average velocity and 2.7 average acceleration. Regarding our coordinate choices the initial position of the man is taken as the origin and his direction of motion during $5 \text{ min} \leq t \leq 10 \text{ min}$ is taken to be the positive x direction. We also use the fact that $\Delta x = v\Delta t$ when the velocity is constant during a time interval Δt .

a The entire interval considered is $\Delta t = 8 - 2 = 6 \text{ min}$ which is equivalent to 360 s whereas the sub interval in which he is *moving* is only $\Delta t' = 8 - 5 = 3 \text{ min} = 180 \text{ s}$. His position at $t = 2 \text{ min}$ is $x = 0$ and his position at $t = 8 \text{ min}$ is $x = v\Delta t' = 2.2 \cdot 180 = 396 \text{ m}$. Therefore

$$v_{\text{avg}} = \frac{396 \text{ m} - 0}{360 \text{ s}} = 1.10 \text{ m/s}.$$

b The man is at rest at $t = 2 \text{ min}$ and has velocity $v = 2.2 \text{ m/s}$ at $t = 8 \text{ min}$. Thus keeping the answer to 3 significant figures

$$a_{\text{avg}} = \frac{2.2 \text{ m/s} - 0}{360 \text{ s}} = 0.00611 \text{ m/s}^2.$$

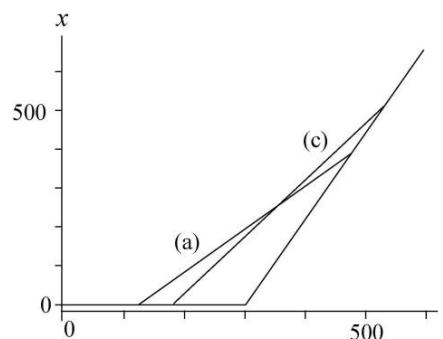
c For the entire interval considered is $\Delta t = 9 - 3 = 6 \text{ min} = 360 \text{ s}$ again whereas the sub interval in which he is moving is $\Delta t' = 9 - 5 = 4 \text{ min} = 240 \text{ s}$. His position at $t = 3 \text{ min}$ is $x = 0$ and his position at $t = 9 \text{ min}$ is $x = v\Delta t' = 2.2 \cdot 240 = 528 \text{ m}$. Therefore

$$v_{\text{avg}} = \frac{528 \text{ m} - 0}{360 \text{ s}} = 1.47 \text{ m/s}.$$

d The man is at rest at $t = 3 \text{ min}$ and has velocity $v = 2.2 \text{ m/s}$ at $t = 9 \text{ min}$. Consequently $a_{\text{avg}} = 2.2/360 = 0.00611 \text{ m/s}^2$ just as in part b.

e The horizontal line near the bottom of this x vs t graph represents the man standing at $x = 0$ for $0 \leq t < 300 \text{ s}$ and the linearly rising line for $300 \leq t \leq 600 \text{ s}$ represents his constant velocity motion. The lines represent the answers to part a and c in the sense that their slopes yield those results.

The graph of v vs t is not shown here but could consist of two horizontal “steps” (one at $v = 0$ for $0 \leq t < 300 \text{ s}$ and the next at $v = 2.2 \text{ m/s}$ for $300 \leq$



$t \leq 600 \text{ s}$. The indications of the average accelerations found in parts b and d would be dotted lines connecting the “steps” at the appropriate t values. The slopes of the dotted lines representing the values of a_{avg} .

22. In this solution we make use of the notation $x(t)$ for the value of x at a particular t . The notations $v(t)$ and $a(t)$ have similar meanings.

a. Since the unit of ct^2 is that of length, the unit of c must be that of length/time² or m/s^2 in the SI system.

b. Since bt^3 has a unit of length, b must have a unit of length/time³ or m/s^3 .

c. When the particle reaches its maximum or its minimum coordinate its velocity is zero. Since the velocity is given by $v = dx/dt = 2ct - 3bt^2$, $v = 0$ occurs for $t = 0$ and for

$$t = \frac{2c}{3b} = \frac{2(3.0 \text{ m/s}^2)}{3(2.0 \text{ m/s}^3)} = 1.0 \text{ s}.$$

For $t = 0$, $x = x_0 = 0$ and for $t = 1.0 \text{ s}$, $x = 1.0 \text{ m}$. Since we seek the maximum, we reject the first root $t = 0$ and accept the second $t = 1 \text{ s}$.

d. In the first 4 s the particle moves from the origin to $x = 1.0 \text{ m}$, turns around, and goes back to

$$x(4 \text{ s}) = 3.0 \text{ m/s}^2 (4.0 \text{ s})^2 - 2.0 \text{ m/s}^3 (4.0 \text{ s})^3 = -80 \text{ m}.$$

The total path length it travels is $1.0 \text{ m} + 1.0 \text{ m} + 80 \text{ m} = 82 \text{ m}$.

e. Its displacement is $\Delta x = x_2 - x_1$, where $x_1 = 0$ and $x_2 = -80 \text{ m}$. Thus $\Delta x = -80 \text{ m}$.

The velocity is given by $v = 2ct - 3bt^2 = 6.0 \text{ m/s}^2 t - 6.0 \text{ m/s}^3 t^2$.

f. Plugging in $t = 1 \text{ s}$, we obtain

$$v(1 \text{ s}) = 6.0 \text{ m/s}^2 (1.0 \text{ s}) - 6.0 \text{ m/s}^3 (1.0 \text{ s})^2 = 0.$$

g. Similarly, $v(2 \text{ s}) = 6.0 \text{ m/s}^2 (2.0 \text{ s}) - 6.0 \text{ m/s}^3 (2.0 \text{ s})^2 = -12 \text{ m/s}$.

h. $v(3 \text{ s}) = 6.0 \text{ m/s}^2 (3.0 \text{ s}) - 6.0 \text{ m/s}^3 (3.0 \text{ s})^2 = -36 \text{ m/s}$.

i. $v(4 \text{ s}) = 6.0 \text{ m/s}^2 (4.0 \text{ s}) - 6.0 \text{ m/s}^3 (4.0 \text{ s})^2 = -72 \text{ m/s}$.

The acceleration is given by $a = dv/dt = 2c - 6b = 6.0 \text{ m/s}^2 - 12.0 \text{ m/s}^3 t$.

Plugging in $t = 1 \text{ s}$, we obtain $a(1 \text{ s}) = 6.0 \text{ m/s}^2 - 12.0 \text{ m/s}^3 (1.0 \text{ s}) = -6.0 \text{ m/s}^2$.

k. $a(2 \text{ s}) = 6.0 \text{ m/s}^2 - 12.0 \text{ m/s}^3 (2.0 \text{ s}) = -18 \text{ m/s}^2$.

$$l \quad a \, 3 \, \text{s} = 6.0 \, \text{m/s}^2 - 12.0 \, \text{m/s}^3 \, 3.0 \, \text{s} = -30 \, \text{m/s}^2.$$

$$m \quad a \, 4 \, \text{s} = 6.0 \, \text{m/s}^2 - 12.0 \, \text{m/s}^3 \, 4.0 \, \text{s} = -42 \, \text{m/s}^2.$$

23. **THINK** The electron undergoes a constant acceleration. Given the final speed of the electron and the distance it has traveled, we can calculate its acceleration.

EXPRESS Since the problem involves constant acceleration, the motion of the electron can be readily analyzed using the equations given in Table 2-1.

$$v = v_0 + at \quad 2-11$$

$$x - x_0 = v_0 t + \frac{1}{2} at^2 \quad 2-15$$

$$v^2 = v_0^2 + 2a(x - x_0) \quad 2-16$$

The acceleration can be found by solving Eq. 2-16.

ANALYZE With $v_0 = 1.50 \times 10^5 \, \text{m/s}$, $v = 5.70 \times 10^6 \, \text{m/s}$, $x_0 = 0$ and $x = 0.010 \, \text{m}$, we find the average acceleration to be

$$a = \frac{v^2 - v_0^2}{2x} = \frac{5.7 \times 10^6 \, \text{m/s}^2 - 1.5 \times 10^5 \, \text{m/s}^2}{2(0.010 \, \text{m})} = 1.62 \times 10^{15} \, \text{m/s}^2.$$

LEARN It is always a good idea to apply other equations in Table 2-1 not used for solving the problem as a consistency check. For example, since we now know the value of the acceleration, using Eq. 2-11, the time it takes for the electron to reach its final speed would be

$$t = \frac{v - v_0}{a} = \frac{5.70 \times 10^6 \, \text{m/s} - 1.5 \times 10^5 \, \text{m/s}}{1.62 \times 10^{15} \, \text{m/s}^2} = 3.426 \times 10^{-9} \, \text{s}$$

Substituting the value of t into Eq. 2-15, the distance the electron travels is

$$x = x_0 + v_0 t + \frac{1}{2} at^2 = 0 + (1.5 \times 10^5 \, \text{m/s})(3.426 \times 10^{-9} \, \text{s}) + \frac{1}{2} (1.62 \times 10^{15} \, \text{m/s}^2)(3.426 \times 10^{-9} \, \text{s})^2 = 0.010 \, \text{m}$$

This is what was given in the problem statement. So we know the problem has been solved correctly.

24. In this problem we are given the initial and final speeds and the displacement and are asked to find the acceleration. We use the constant acceleration equation given in Eq. 2-16, $v^2 = v_0^2 + 2a(x - x_0)$.

Given that $v_0 = 0$, $v = 1.6 \, \text{m/s}$ and $\Delta x = 5.0 \, \mu\text{m}$, the acceleration of the spores during the launch is

$$a = \frac{v^2 - v_0^2}{2x} = \frac{1.6 \text{ m s}^{-2}}{2 \cdot 5.0 \times 10^{-6} \text{ m}} = 2.56 \times 10^5 \text{ m s}^{-2} = 2.6 \times 10^4 g$$

b During the speed reduction stage the acceleration is

$$a = \frac{v^2 - v_0^2}{2x} = \frac{0 - 1.6 \text{ m s}^{-2}}{2 \cdot 1.0 \times 10^{-3} \text{ m}} = -1.28 \times 10^3 \text{ m s}^{-2} = -1.3 \times 10^2 g$$

The negative sign means that the spores are decelerating.

25. We separate the motion into two parts and take the direction of motion to be positive. In part 1 the vehicle accelerates from rest to its highest speed. We are given $v_0 = 0$, $v = 20 \text{ m s}^{-1}$ and $a = 2.0 \text{ m s}^{-2}$. In part 2 the vehicle decelerates from its highest speed to a halt. We are given $v_0 = 20 \text{ m s}^{-1}$, $v = 0$ and $a = -1.0 \text{ m s}^{-2}$ (negative because the acceleration vector points opposite to the direction of motion).

a From Table 2.1 we find t_1 the duration of part 1 from $v = v_0 + at$. In this case $20 = 0 + 2.0 t_1$ yields $t_1 = 10 \text{ s}$. We obtain the duration t_2 of part 2 from the same equation. Thus $0 = 20 - 1.0 t_2$ leads to $t_2 = 20 \text{ s}$ and the total is $t = t_1 + t_2 = 30 \text{ s}$.

b For part 1 taking $x_0 = 0$ we use the equation $v^2 = v_0^2 + 2a(x - x_0)$ from Table 2.1 and find

$$x = \frac{v^2 - v_0^2}{2a} = \frac{20^2 \text{ m s}^{-2} - 0^2}{2 \cdot 2.0 \text{ m s}^{-2}} = 100 \text{ m}.$$

This position is then the *initial* position for part 2 so that when the same equation is used in part 2 we obtain

$$x - 100 \text{ m} = \frac{v^2 - v_0^2}{2a} = \frac{0^2 - 20^2 \text{ m s}^{-2}}{2 \cdot -1.0 \text{ m s}^{-2}}.$$

Thus the final position is $x = 300 \text{ m}$. That this is also the total distance traveled should be evident: the vehicle did not backtrack or reverse its direction of motion.

26. The constant acceleration condition permits the use of Table 2.1.

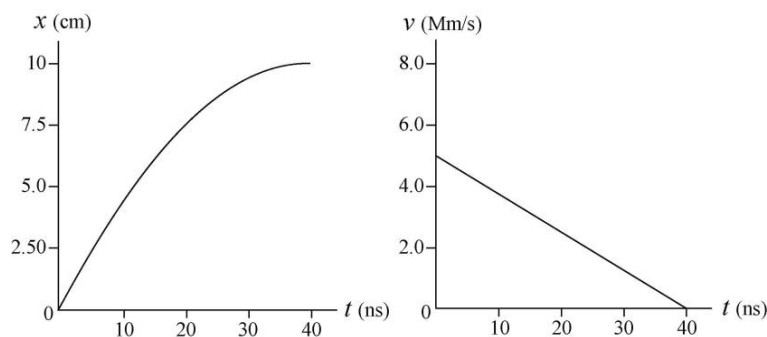
a Setting $v = 0$ and $x_0 = 0$ in $v^2 = v_0^2 + 2a(x - x_0)$ we find

$$x = -\frac{1}{2} \frac{v_0^2}{a} = -\frac{1}{2} \frac{5.00 \times 10^6 \text{ m}^2 \text{ s}^{-2}}{-1.25 \times 10^{14} \text{ m s}^{-2}} = 0.100 \text{ m}.$$

Since the muon is slowing the initial velocity and the acceleration must have opposite signs.

b Below are the time plots of the position x and velocity v of the muon from the moment it enters the field to the time it stops. The computation in part a made no reference to t so that other equations from Table 2.1 such as $v = v_0 + at$ and

$x = v_0 t + \frac{1}{2} a t^2$ are used in making these plots.



27. We use $v = v_0 + at$ with $t = 0$ as the instant when the velocity equals 9.6 m/s .

a. Since we wish to calculate the velocity for a time *before* $t = 0$ we set $t = -2.5 \text{ s}$. This gives

$$v = 9.6 \text{ m/s} + (3.2 \text{ m/s}^2)(-2.5 \text{ s}) = 1.6 \text{ m/s}.$$

b. At $t = 2.5 \text{ s}$ and we find $v = 9.6 \text{ m/s} + (3.2 \text{ m/s}^2)(2.5 \text{ s}) = 18 \text{ m/s}$.

28. We take x in the direction of motion so $v_0 = 24.6 \text{ m/s}$ and $a = -4.92 \text{ m/s}^2$. We also take $x_0 = 0$.

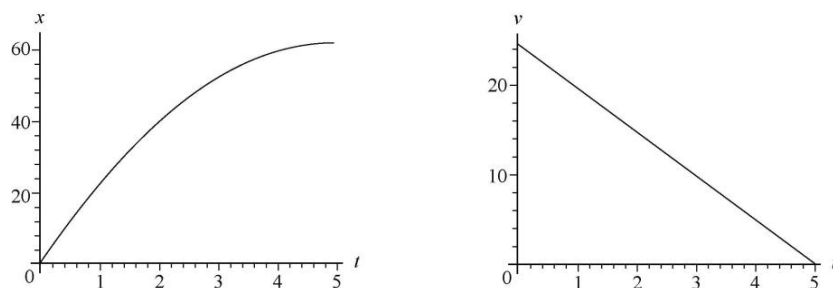
a. The time to come to a halt is found using 2.11

$$0 = v_0 + at \Rightarrow t = \frac{24.6 \text{ m/s}}{-4.92 \text{ m/s}^2} = 5.00 \text{ s}.$$

b. Although several of the equations in Table 2.1 will yield the result we choose 2.16 since it does not depend on our answer to part a.

$$0 = v_0^2 + 2ax \Rightarrow x = -\frac{24.6^2 \text{ m}^2/\text{s}^2}{2(-4.92 \text{ m/s}^2)} = 61.5 \text{ m}.$$

c. Using these results we plot $v_0 t + \frac{1}{2} a t^2$ the x graph shown next on the left and $v_0 + at$ the v graph on the right over $0 \leq t \leq 5 \text{ s}$ with units understood.



29. We assume the periods of acceleration duration t_1 and deceleration duration t_2 are periods of constant a so that Table 2.1 can be used. Taking the direction of motion to be x then $a_1 = 1.22 \text{ m/s}^2$ and $a_2 = -1.22 \text{ m/s}^2$. We use SI units so the velocity at $t = t_1$ is $v = 305.60 = 5.08 \text{ m/s}$.

a We denote Δx as the distance moved during t_1 and use Eq. 2.16

$$v^2 = v_0^2 + 2a_1\Delta x \Rightarrow \Delta x = \frac{5.08 \text{ m/s}^2}{2 \cdot 1.22 \text{ m/s}^2} = 10.59 \text{ m} \approx 10.6 \text{ m}.$$

b Using Eq. 2.11 we have

$$t_1 = \frac{v - v_0}{a_1} = \frac{5.08 \text{ m/s}}{1.22 \text{ m/s}^2} = 4.17 \text{ s}.$$

The deceleration time t_2 turns out to be the same so that $t_1 = t_2 = 8.33 \text{ s}$. The distances traveled during t_1 and t_2 are the same so that they total to $2 \cdot 10.59 \text{ m} = 21.18 \text{ m}$. This implies that for a distance of $190 \text{ m} - 21.18 \text{ m} = 168.82 \text{ m}$ the elevator is traveling at constant velocity. This time of constant velocity motion is

$$t_3 = \frac{168.82 \text{ m}}{5.08 \text{ m/s}} = 33.21 \text{ s}.$$

Therefore the total time is $8.33 \text{ s} + 33.21 \text{ s} \approx 41.5 \text{ s}$.

30. We choose the positive direction to be that of the initial velocity of the car implying that $a < 0$ since it is slowing down. We assume the acceleration is constant and use Table 2.1.

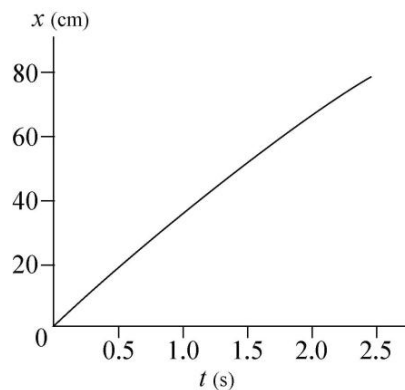
a Substituting $v_0 = 137 \text{ km/h} = 38.1 \text{ m/s}$, $v = 90 \text{ km/h} = 25 \text{ m/s}$ and $a = -5.2 \text{ m/s}^2$ into $v = v_0 + at$ we obtain

$$t = \frac{25 \text{ m/s} - 38 \text{ m/s}}{-5.2 \text{ m/s}^2} = 2.5 \text{ s}.$$

b We take the car to be at $x = 0$ when the brakes are applied at time $t = 0$. Thus the coordinate of the car as a function of time is given by

$$x = (38 \text{ m/s})t + \frac{1}{2}(-5.2 \text{ m/s}^2)t^2$$

in SI units. This function is plotted from $t = 0$ to $t = 2.5 \text{ s}$ on the graph to the right. We have not shown the v vs t graph here; it is a descending straight line from v_0 to v .



31. **THINK** The rocket ship undergoes a constant acceleration from rest and we want to know the time elapsed and the distance traveled when the rocket reaches a certain speed.

EXPRESS Since the problem involves constant acceleration the motion of the rocket can be readily analyzed using the equations in Table 2-11

$$v = v_0 + at \quad 2-11$$

$$x - x_0 = v_0 t + \frac{1}{2} at^2 \quad 2-15$$

$$v^2 = v_0^2 + 2a(x - x_0) \quad 2-16$$

ANALYZE a Given that $a = 9.8 \text{ m/s}^2$, $v_0 = 0$ and $v = 0.1c = 3.0 \times 10^7 \text{ m/s}$ we can solve $v = v_0 + at$ for the time

$$t = \frac{v - v_0}{a} = \frac{3.0 \times 10^7 \text{ m/s} - 0}{9.8 \text{ m/s}^2} = 3.1 \times 10^6 \text{ s}$$

which is about 1.2 months. So it takes 1.2 months for the rocket to reach a speed of $0.1c$ starting from rest with a constant acceleration of 9.8 m/s^2 .

b To calculate the distance traveled during this time interval we evaluate $x = x_0 + v_0 t + \frac{1}{2} at^2$ with $x_0 = 0$ and $v_0 = 0$. The result is

$$x = \frac{1}{2} (9.8 \text{ m/s}^2) (3.1 \times 10^6 \text{ s})^2 = 4.6 \times 10^{13} \text{ m}.$$

LEARN In solving parts a and b we did not use Eq. 2-16 $v^2 = v_0^2 + 2a(x - x_0)$. This equation can be used to check our answers. The final velocity based on this equation is

$$v = \sqrt{v_0^2 + 2a(x - x_0)} = \sqrt{0 + 2(9.8 \text{ m/s}^2)(4.6 \times 10^{13} \text{ m} - 0)} = 3.0 \times 10^7 \text{ m/s}$$

which is that as given in the problem statement. So we know the problems have been solved correctly.

32. The acceleration is found from Eq. 2-11 or suitably interpreted Eq. 2-7.

$$a = \frac{\Delta v}{\Delta t} = \frac{(1020 \text{ km/h}) \left(\frac{1000 \text{ m}}{3600 \text{ s}} \right)}{1.4 \text{ s}} = 202.4 \text{ m/s}^2.$$

In terms of the gravitational acceleration g this is expressed as a multiple of 9.8 m/s^2 as follows

$$a = \left(\frac{202.4 \text{ m/s}^2}{9.8 \text{ m/s}^2} \right) g = 21g.$$

33. **THINK** The car undergoes a constant negative acceleration to avoid impacting a barrier. Given its initial speed we want to know the distance it has traveled and the time elapsed prior to the impact.

EXPRESS Since the problem involves constant acceleration the motion of the car can be readily analysed using the equations in Table 2.1

$$v = v_0 + at \quad 2-11$$

$$x - x_0 = v_0 t + \frac{1}{2} at^2 \quad 2-15$$

$$v^2 = v_0^2 + 2a(x - x_0) \quad 2-16$$

We take $x_0 = 0$ and $v_0 = 56.0 \text{ km/h} = 15.55 \text{ m/s}$ to be the initial position and speed of the car. Solving 2.15 with $t = 2.00 \text{ s}$ gives the acceleration a . Since a is known the speed of the car upon impact can be found by using 2.11.

ANALYZE Using 2.15 we find the acceleration to be

$$a = \frac{2(x - v_0 t)}{t^2} = \frac{2[24.0 \text{ m} - 15.55 \text{ m/s} \cdot 2.00 \text{ s}]}{2.00 \text{ s}^2} = -3.56 \text{ m/s}^2$$

or $a = 3.56 \text{ m/s}^2$. The negative sign indicates that the acceleration is opposite to the direction of motion of the car the car is slowing down.

b The speed of the car at the instant of impact is

$$v = v_0 + at = 15.55 \text{ m/s} + (-3.56 \text{ m/s}^2)(2.00 \text{ s}) = 8.43 \text{ m/s}$$

which can also be converted to 30.3 km/h .

LEARN In solving parts a and b we did not use 2.16. This equation can be used as a consistency check. The final velocity based on this equation is

$$v = \sqrt{v_0^2 + 2a(x - x_0)} = \sqrt{15.55 \text{ m/s}^2 + 2(-3.56 \text{ m/s}^2)(24 \text{ m} - 0)} = 8.43 \text{ m/s}$$

which is what was calculated in b. This indicates that the problems have been solved correctly.

34. Let d be the 220 m distance between the cars at $t = 0$ and v_1 be the $20 \text{ km/h} = 5.56 \text{ m/s}$ speed corresponding to a passing point of $x_1 = 44.5 \text{ m}$ and v_2 be the $40 \text{ km/h} = 11.1 \text{ m/s}$ speed corresponding to a passing point of $x_2 = 76.6 \text{ m}$ of the red car. We have two equations based on 2.17

$$d - x_1 = v_0 t_1 + \frac{1}{2} a t_1^2 \quad \text{here } t_1 = x_1 / v_1$$

$$d - x_2 = v_0 t_2 + \frac{1}{2} a t_2^2 \quad \text{here } t_2 = x_2 / v_2$$

We simultaneously solve these equations and obtain the following results

a the initial velocity of the green car is $v_0 = -13.9 \text{ m/s}$ or roughly -50 km/h the negative sign means that it's along the $-x$ direction.

b the corresponding acceleration of the car is $a = -2.0 \text{ m/s}^2$ the negative sign means that it's along the $-x$ direction.

35. the positions of the cars as a function of time are given by

$$x_r(t) = x_{r0} + \frac{1}{2}a_r t^2 = -35.0 \text{ m} + \frac{1}{2}a_r t^2$$

$$x_g(t) = x_{g0} + v_g t = 270 \text{ m} - 20 \text{ m/s } t$$

here we have substituted the velocity and not the speed for the green car. the two cars pass each other at $t = 12.0 \text{ s}$ when the graphed lines cross. this implies that

$$270 \text{ m} - 20 \text{ m/s } 12.0 \text{ s} = 30 \text{ m} = -35.0 \text{ m} + \frac{1}{2}a_r 12.0 \text{ s}^2$$

which can be solved to give $a_r = 0.90 \text{ m/s}^2$.

36. a equation 2.15 is used for part 1 of the trip and 2.18 is used for part 2

$$\Delta x_1 = v_{01} t_1 + \frac{1}{2} a_1 t_1^2 \quad \text{here } a_1 = 2.25 \text{ m/s}^2 \text{ and } \Delta x_1 = \frac{900}{4} \text{ m}$$

$$\Delta x_2 = v_2 t_2 + \frac{1}{2} a_2 t_2^2 \quad \text{here } a_2 = -0.75 \text{ m/s}^2 \text{ and } \Delta x_2 = \frac{3 \cdot 900}{4} \text{ m}$$

In addition $v_{01} = v_2 = 0$. solving these equations for the times and adding the results gives $t = t_1 + t_2 = 56.6 \text{ s}$.

b equation 2.16 is used for part 1 of the trip

$$v^2 = v_{01}^2 + 2a_1 \Delta x_1 = 0 + 2 \cdot 2.25 \left(\frac{900}{4} \right) = 1013 \text{ m}^2/\text{s}^2$$

which leads to $v = 31.8 \text{ m/s}$ for the maximum speed.

37. a from the figure we see that $x_0 = -2.0 \text{ m}$. from table 2.1 we can apply

$$x - x_0 = v_0 t + \frac{1}{2} a t^2$$

with $t = 1.0 \text{ s}$ and then again with $t = 2.0 \text{ s}$. this yields two equations for the two unknowns v_0 and a

$$0.0 - (-2.0 \text{ m}) = v_0(1.0 \text{ s}) + \frac{1}{2}a(1.0 \text{ s})^2$$

$$6.0 \text{ m} - (-2.0 \text{ m}) = v_0(2.0 \text{ s}) + \frac{1}{2}a(2.0 \text{ s})^2.$$

Solving these simultaneous equations yields the results $v_0 = 0$ and $a = 4.0 \text{ m/s}^2$.

b The fact that the answer is positive tells us that the acceleration vector points in the x direction.

38. We assume the train accelerates from rest $v_0 = 0$ and $x_0 = 0$ at $a_1 = +1.34 \text{ m/s}^2$ until the midway point and then decelerates at $a_2 = -1.34 \text{ m/s}^2$ until it comes to a stop ($v_2 = 0$) at the next station. The velocity at the midpoint is v_1 which occurs at $x_1 = 806/2 = 403 \text{ m}$.

a Equation 2-16 leads to

$$v_1^2 = v_0^2 + 2a_1x_1 \Rightarrow v_1 = \sqrt{2(1.34 \text{ m/s}^2)(403 \text{ m})} = 32.9 \text{ m/s}.$$

b The time t_1 for the accelerating stage is using 2-15

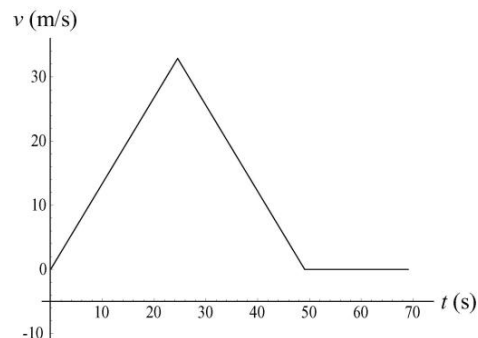
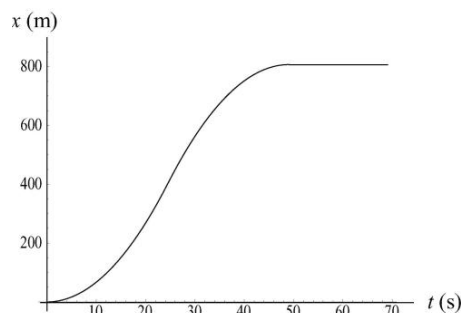
$$x_1 = v_0t_1 + \frac{1}{2}a_1t_1^2 \Rightarrow t_1 = \sqrt{\frac{2(403 \text{ m})}{1.34 \text{ m/s}^2}} = 24.53 \text{ s}.$$

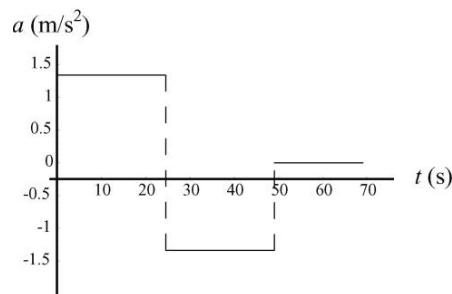
Since the time interval for the decelerating stage turns out to be the same we double this result and obtain $t = 49.1 \text{ s}$ for the travel time between stations.

(c) With a “dead time” of 20 s, we have $T = t + 20 = 69.1 \text{ s}$ for the total time between start-ups. Thus 2-2 gives

$$v_{\text{avg}} = \frac{806 \text{ m}}{69.1 \text{ s}} = 11.7 \text{ m/s}.$$

d The graphs for x , v and a as a function of t are shown below. The third graph a vs t consists of three horizontal “steps” — one at 1.34 m/s^2 during $0 \leq t < 24.53 \text{ s}$ and the next at -1.34 m/s^2 during $24.53 \text{ s} \leq t < 49.1 \text{ s}$ and the last at zero during the “dead time” $49.1 \text{ s} \leq t \leq 69.1 \text{ s}$.





39. a. We note that $v = 12.6 = 2 \text{ m/s}$ with two significant figures understood. Therefore, with an initial x value of 20 m, car A will be at $x = 28 \text{ m}$ when $t = 4 \text{ s}$. This must be the value of x for car B at that time. We use $a = -2.5$.

$$28 \text{ m} = 12 \text{ m/s} \cdot t + \frac{1}{2} a t^2 \quad \text{here } t = 4.0 \text{ s}.$$

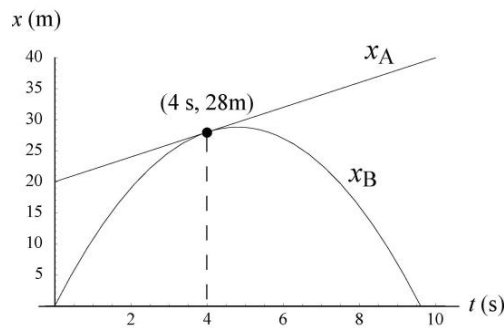
This yields $a = -2.5 \text{ m/s}^2$.

b. The question is: using the value obtained for a in part a, are there other values of t besides $t = 4 \text{ s}$ such that $x_A = x_B$? The requirement is

$$20 + 2t = 12t + \frac{1}{2} a t^2$$

here $a = -5/2$. There are two distinct roots unless the discriminant $\sqrt{10^2 - 2(-20)a}$ is zero. In our case it is zero – which means there is only one root. The cars are side by side only once at $t = 4 \text{ s}$.

c. The sketch is shown below. It consists of a straight line x_A tangent to a parabola x_B at $t = 4$.



d. We only care about real roots, which means $10^2 - 2(-20)a \geq 0$. If $a = 5/2$, then there are no real solutions to the equation; the cars are never side by side.

e. Here we have $10^2 - 2(-20)a > 0 \Rightarrow$ two real roots. The cars are side by side at two different times.

40. We take the direction of motion as x , so $a = -5.18 \text{ m/s}^2$ and we use units so $v_0 = 55 \cdot 1000 / 3600 = 15.28 \text{ m/s}$.

a The velocity is constant during the reaction time T so the distance traveled during it is

$$d_r = v_0 T = 15.28 \text{ m/s} \cdot 0.75 \text{ s} = 11.46 \text{ m}.$$

Use Eq. 2-16 with $v = 0$ to find the distance d_b traveled during braking

$$v^2 = v_0^2 + 2ad_b \Rightarrow d_b = -\frac{15.28 \text{ m/s}^2}{2(-5.18 \text{ m/s}^2)}$$

which yields $d_b = 22.53 \text{ m}$. Thus the total distance is $d_r + d_b = 34.0 \text{ m}$ which means that the driver *is* able to stop in time. And if the driver were to continue at v_0 the car could enter the intersection in $t = 40 \text{ m} / 15.28 \text{ m/s} = 2.6 \text{ s}$ which is barely enough time to enter the intersection before the light turns which many people could consider an acceptable situation.

b In this case the total distance to stop found in part a to be 34 m is greater than the distance to the intersection so the driver cannot stop without the front end of the car being a couple of meters into the intersection. And the time to reach it at constant speed is $32 / 15.28 = 2.1 \text{ s}$ which is too long the light turns in 1.8 s . The driver is caught between a rock and a hard place.

41. The displacement (Δx) for each train is the “area” in the graph (since the displacement is the integral of the velocity). Each area is triangular and the area of a triangle is $\frac{1}{2} \text{ base} \cdot \text{height}$. Thus the absolute value of the displacement for one train is $\frac{1}{2} (40 \text{ m/s}) (5 \text{ s}) = 100 \text{ m}$ and that of the other train is $\frac{1}{2} (30 \text{ m/s}) (4 \text{ s}) = 60 \text{ m}$. The initial “gap” between the trains was 200 m , and according to our displacement computations the gap has narrowed by 160 m . Thus the answer is $200 - 160 = 40 \text{ m}$.

42. a Note that 110 km/h is equivalent to 30.56 m/s . Using a 2.0 s second interval you travel 61.11 m . The decelerating police car travels using Eq. 2-15 51.11 m . In light of the fact that the initial “gap” between cars was 25 m , this means the gap has narrowed by 10.0 m – that is to a distance of 15.0 m between cars.

b First we add 0.4 s to the considerations of part a. Using a 2.4 s interval you travel 73.33 m . The decelerating police car travels using Eq. 2-15 58.93 m during that time. The initial distance between cars of 25 m has therefore narrowed by 14.4 m .

Thus at the start of your braking call it t_0 the gap between the cars is 10.6 m . The speed of the police car at t_0 is $30.56 - 5(2.4) = 18.56 \text{ m/s}$. Collision occurs at time t when $x_{\text{you}} = x_{\text{police}}$. We choose coordinates such that your position is $x = 0$ and the police car’s position is $x = 10.6 \text{ m}$ at t_0 . Eq. 2-15 becomes for each car

$$x_{\text{police}} - 10.6 = 18.56(t - t_0) - \frac{1}{2}(5)(t - t_0)^2$$

$$x_{\text{you}} = 30.56(t - t_0) - \frac{1}{2}(5)(t - t_0)^2.$$

Subtracting equations we find

$$10.6 = 30.56 - 18.56(t - t_0) \Rightarrow 0.883 \text{ s} = t - t_0.$$

at that time your speed is 30.56 m/s $a(t - t_0) = 30.56 - 5(0.883) \approx 26 \text{ m/s}$ or 94 km/h .

43. In this solution we elect to wait until the last step to convert to SI units. Constant acceleration is indicated so use of Table 2.1 is permitted. We start with Eq. 2.17 and denote the train's initial velocity as v_i and the locomotive's velocity as v_ℓ which is also the final velocity of the train if the rear end collision is barely avoided. We note that the distance Δx consists of the original gap between them D as well as the forward distance traveled during this time by the locomotive $v_\ell t$. Therefore

$$\frac{v_i + v_\ell}{2} = \frac{\Delta x}{t} = \frac{D + v_\ell t}{t} = \frac{D}{t} + v_\ell.$$

We now use Eq. 2.11 to eliminate time from the equation. Thus

$$\frac{v_i + v_\ell}{2} = \frac{D}{(v_\ell - v_i)/a} + v_\ell$$

which leads to

$$a = \left(\frac{v_i + v_\ell}{2} - v_\ell \right) \left(\frac{v_\ell - v_i}{D} \right) = -\frac{1}{2D} (v_\ell - v_i)^2.$$

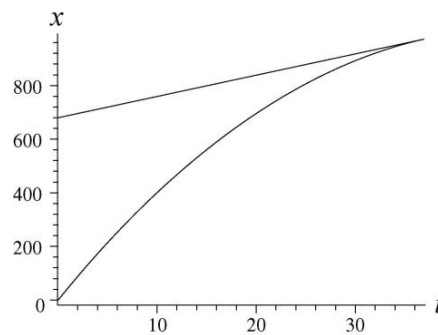
hence

$$a = -\frac{1}{2(0.676 \text{ km})} \left(29 \frac{\text{km}}{\text{h}} - 161 \frac{\text{km}}{\text{h}} \right)^2 = -12888 \text{ km/h}^2$$

which we convert as follows

$$a = (-12888 \text{ km/h}^2) \left(\frac{1000 \text{ m}}{1 \text{ km}} \right) \left(\frac{1 \text{ h}}{3600 \text{ s}} \right)^2 = -0.994 \text{ m/s}^2$$

so that its *magnitude* is $a = 0.994 \text{ m/s}^2$. The graph is shown here for the case where a collision is just avoided. x along the vertical axis is in meters and t along the horizontal axis is in seconds. The top straight line shows the motion of the locomotive and the bottom curve shows the motion of the passenger train.



The other case where the collision is not quite avoided could be similar except that the slope of the bottom curve could be greater than that of the top line at the point where they meet.

44. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking *down* as the $-y$ direction for the duration of the motion. We are allowed to use Table 2.1 with Δy replacing Δx because this is constant acceleration motion. The ground level is taken to correspond to the origin of the y axis.

Assuming $y = v_0 t - \frac{1}{2} g t^2$ with $y = 0.544 \text{ m}$ and $t = 0.200 \text{ s}$ we find

$$v_0 = \frac{y + gt^2}{t} = \frac{0.544 \text{ m} + 9.8 \text{ m/s}^2 \cdot 0.200 \text{ s}^2}{0.200 \text{ s}} = 3.70 \text{ m/s}.$$

b The velocity at $y = 0.544 \text{ m}$ is

$$v = v_0 - gt = 3.70 \text{ m/s} - 9.8 \text{ m/s}^2 \cdot 0.200 \text{ s} = 1.74 \text{ m/s}.$$

c Using $v^2 = v_0^2 - 2gy$ with different values for y and v than before we solve for the value of y corresponding to maximum height where $v = 0$.

$$y = \frac{v_0^2}{2g} = \frac{3.7 \text{ m/s}^2}{2 \cdot 9.8 \text{ m/s}^2} = 0.698 \text{ m}.$$

thus the armadillo goes $0.698 - 0.544 = 0.154 \text{ m}$ higher.

45. **THINK** As the ball travels vertically upward its motion is under the influence of gravitational acceleration. The kinematics is one dimensional.

EXPRESS We neglect air resistance for the duration of the motion between “launching” and “landing”, so $a = -g = -9.8 \text{ m/s}^2$. We take downward to be the $-y$ direction. We use the equations in Table 2-1 with Δy replacing Δx because this is $a = \text{constant}$ motion

$$v = v_0 - gt \quad 2-11$$

$$y - y_0 = v_0 t - \frac{1}{2} gt^2 \quad 2-15$$

$$v^2 = v_0^2 - 2g(y - y_0) \quad 2-16$$

We set $y_0 = 0$. Upon reaching the maximum height y the speed of the ball is momentarily zero $v = 0$. Therefore we can relate its initial speed v_0 to y via the equation $0 = v^2 = v_0^2 - 2gy$. The time it takes for the ball to reach maximum height is given by $v = v_0 - gt = 0$ or $t = v_0/g$. Therefore for the entire trip from the time it leaves the ground until the time it returns to the ground the total flight time is $T = 2t = 2v_0/g$.

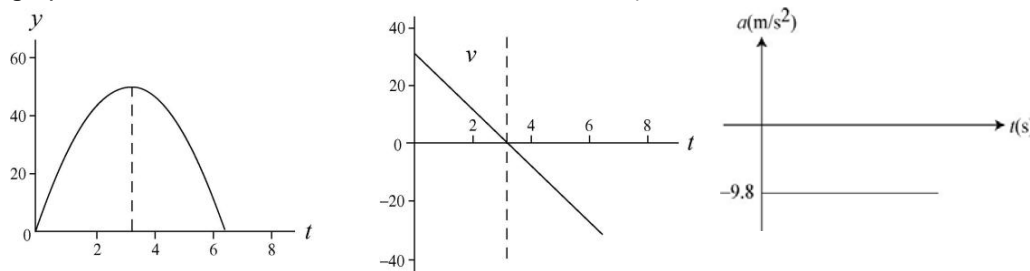
ANALYZE At the highest point $v = 0$ and $v_0 = \sqrt{2gy}$. With $y = 50 \text{ m}$ we find the initial speed of the ball to be

$$v_0 = \sqrt{2gy} = \sqrt{2 \cdot 9.8 \text{ m/s}^2 \cdot 50 \text{ m}} = 31.3 \text{ m/s}.$$

b Using the result from a for v_0 the total flight time of the ball is

$$T = \frac{2v_0}{g} = \frac{2 \cdot 31.3 \text{ m/s}}{9.8 \text{ m/s}^2} = 6.39 \text{ s}$$

c The plots of y , v and a as a function of time are shown below. The acceleration graph is a horizontal line at -9.8 m/s^2 . At $t = 3.19 \text{ s}$, $y = 50 \text{ m}$.



LEARN In calculating the total flight time of the ball we could have used Eq. 2-15. At $t = T > 0$ the ball returns to its original position ($y = 0$). Therefore

$$y = v_0 T - \frac{1}{2} g T^2 = 0 \Rightarrow T = \frac{2v_0}{g}$$

46. Neglect of air resistance justifies setting $a = -g = -9.8 \text{ m/s}^2$ (here *down* is our $-y$ direction) for the duration of the fall. This is constant acceleration motion and we may use Table 2-1 with Δy replacing Δx .

a Using Eq. 2-16 and taking the negative root (since the final velocity is down) and we have

$$v = -\sqrt{v_0^2 - 2g\Delta y} = -\sqrt{0 - 2(9.8 \text{ m/s}^2)(-1700 \text{ m})} = -183 \text{ m/s}.$$

Its magnitude is therefore 183 m/s.

b No, but it is hard to make a convincing case without more analysis. We estimate the mass of a raindrop to be about a gram or less, so that its mass and speed (from part a) could be less than that of a typical bullet (which is good news). But the fact that one is dealing with *many* raindrops leads us to suspect that this scenario poses an unhealthy situation. If the factor in air resistance, the final speed is smaller, of course, and we return to the relatively healthy situation with which we are familiar.

47. **THINK** The wrench is in free fall with an acceleration $a = -g = -9.8 \text{ m/s}^2$.

EXPRESS We neglect air resistance, which justifies setting $a = -g = -9.8 \text{ m/s}^2$ (taking *down* as the $-y$ direction) for the duration of the fall. This is constant acceleration motion, which justifies the use of Table 2-1 with Δy replacing Δx .

$$v = v_0 - gt \quad 2-11$$

$$y - y_0 = v_0 t - \frac{1}{2} g t^2 \quad 2-15$$

$$v^2 = v_0^2 - 2g(y - y_0) \quad 2-16$$

Since the wrench had an initial speed $v_0 = 0$, knowing its speed of impact allows us to apply Eq. 2-16 to calculate the height from which it was dropped.

ANALYZE a Using $v^2 = v_0^2 + 2a\Delta y$ we find the initial height to be

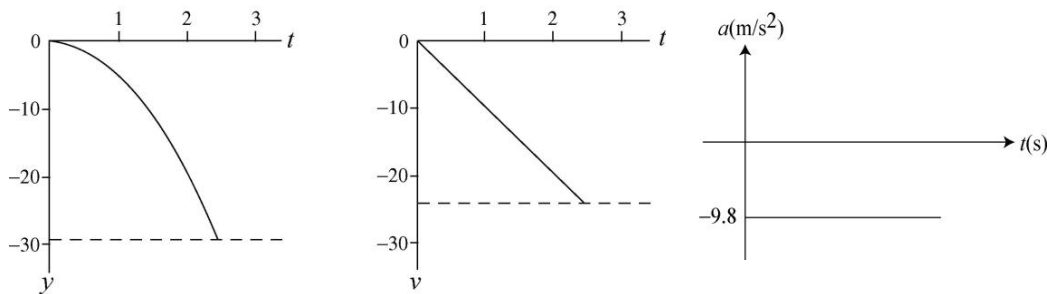
$$\Delta y = \frac{v_0^2 - v^2}{2a} = \frac{0 - (-24 \text{ m/s})^2}{2(-9.8 \text{ m/s}^2)} = 29.4 \text{ m}.$$

so that it fell through a height of 29.4 m.

b Solving $v = v_0 - gt$ for time we obtain a flight time of

$$t = \frac{v_0 - v}{g} = \frac{0 - (-24 \text{ m/s})}{9.8 \text{ m/s}^2} = 2.45 \text{ s}.$$

c Units are used in the graphs and the initial position is taken as the coordinate origin. The acceleration graph is a horizontal line at -9.8 m/s^2 .



LEARN As the object falls with $a = -g < 0$ its speed increases but its velocity becomes more negative as indicated by the second graph above.

48. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking *down* as the $-y$ direction for the duration of the fall. This is constant acceleration motion which justifies the use of Table 2.1 with Δy replacing Δx .

a Noting that $\Delta y = y - y_0 = -30 \text{ m}$ we apply Eq. 2.15 and the quadratic formula Appendix A to compute t

$$\Delta y = v_0 t - \frac{1}{2} g t^2 \Rightarrow t = \frac{v_0 \pm \sqrt{v_0^2 - 2g\Delta y}}{g}$$

which with $v_0 = -12 \text{ m/s}$ since it is downward leads upon choosing the positive root so that $t > 0$ to the result

$$t = \frac{-12 \text{ m/s} + \sqrt{(-12 \text{ m/s})^2 - 2(-9.8 \text{ m/s}^2)(-30 \text{ m})}}{9.8 \text{ m/s}^2} = 1.54 \text{ s}.$$

b Enough information is now known that any of the equations in Table 2.1 can be used to obtain v however the one equation that does *not* use our result from part a is Eq. 2.16

$$v = \sqrt{v_0^2 - 2g\Delta y} = 27.1 \text{ m/s}$$

here the positive root has been chosen in order to give *speed* which is the magnitude of the velocity vector.

49. **THINK** In this problem a package is dropped from a hot air balloon which is ascending vertically upward. We analyze the motion of the package under the influence of gravity.

EXPRESS We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking *down* as the $-y$ direction for the duration of the motion. This allows us to use Table 2-11 with Δy replacing Δx

$$v = v_0 - gt \quad 2-11$$

$$y - y_0 = v_0 t - \frac{1}{2} g t^2 \quad 2-15$$

$$v^2 = v_0^2 - 2g(y - y_0) \quad 2-16$$

We place the coordinate origin on the ground and note that the initial velocity of the package is the same as the velocity of the balloon $v_0 = 12 \text{ m/s}$ and that its initial coordinate is $y_0 = 80 \text{ m}$. The time it takes for the package to hit the ground can be found by solving Eq. 2-15 with $y = 0$.

ANALYZE (a) We solve $0 = y = y_0 + v_0 t - \frac{1}{2} g t^2$ for time using the quadratic formula choosing the positive root to yield a positive value for t

$$t = \frac{v_0 + \sqrt{v_0^2 + 2gy_0}}{g} = \frac{12 \text{ m/s} + \sqrt{12^2 \text{ m}^2/\text{s}^2 + 2(9.8 \text{ m/s}^2)(80 \text{ m})}}{9.8 \text{ m/s}^2} = 5.45 \text{ s}.$$

(b) The speed of the package when it hits the ground can be calculated using Eq. 2-11. The result is

$$v = v_0 - gt = 12 \text{ m/s} - 9.8 \text{ m/s}^2 (5.447 \text{ s}) = -41.38 \text{ m/s}.$$

Its final *speed* is 41.38 m/s .

LEARN Our answers can be readily verified by using Eq. 2-16 which was not used in either (a) or (b). The equation leads to

$$v = -\sqrt{v_0^2 - 2g(y - y_0)} = -\sqrt{12^2 \text{ m}^2/\text{s}^2 - 2(9.8 \text{ m/s}^2)(0 - 80 \text{ m})} = -41.38 \text{ m/s}$$

which agrees with that calculated in (b).

50. The y coordinate of particle 1 obeys $y - y_{01} = -\frac{1}{2} g t^2$ where $y = 0$ when $t = 2.0 \text{ s}$. This allows us to solve for y_{01} and we find $y_{01} = 19.6 \text{ m}$.

The graph for the coordinate of particle 2 which is thrown apparently at $t = 1.0 \text{ s}$ with

velocity v_2 is

$$y - y_{02} = v_2 t - 1.0 - \frac{1}{2} g t - 1.0^2$$

here $y_{02} = y_{01} = 19.6$ m and here $y = 0$ when $t = 2.25$ s. thus we obtain $|v_2| = 9.6$ m/s approximately.

51. a. With up and chosen as the y direction we use Eq. 2.11 to find the initial velocity of the package

$$v = v_0 - at \Rightarrow 0 = v_0 - 9.8 \text{ m/s}^2 (2.0 \text{ s})$$

which leads to $v_0 = 19.6$ m/s. so we use Eq. 2.15

$$\Delta y = 19.6 \text{ m/s} (2.0 \text{ s}) - \frac{1}{2} (9.8 \text{ m/s}^2) (2.0 \text{ s})^2 \approx 20 \text{ m}.$$

We note that the “2.0 s” in this second computation refers to the time interval $2 < t < 4$ in the graph (whereas the “2.0 s” in the first computation referred to the $0 < t < 2$ time interval shown in the graph).

b. In our computation for part (b), the time interval (“6.0 s”) refers to the $2 < t < 8$ portion of the graph

$$\Delta y = 19.6 \text{ m/s} (6.0 \text{ s}) - \frac{1}{2} (9.8 \text{ m/s}^2) (6.0 \text{ s})^2 \approx -59 \text{ m}$$

or $|\Delta y| = 59 \text{ m}$.

52. The full extent of the bolt’s fall is given by

$$y - y_0 = -\frac{1}{2} g t^2$$

here $y - y_0 = -90$ m if up and is chosen as the positive y direction. thus the time for the full fall is found to be $t = 4.29$ s. the first 80% of its free fall distance is given by $-72 = -g\tau^2/2$ which requires time $\tau = 3.83$ s.

a. thus the final 20% of its fall takes $t - \tau = 0.45$ s.

b. we can find that speed using $v = -g\tau$. therefore $v = 38$ m/s approximately.

c. similarly $v_{final} = -g t \Rightarrow v_{final} = 42$ m/s.

53. **THINK** This problem involves two objects: a key dropped from a bridge and a boat moving at a constant speed. we look for conditions such that the key will fall into the boat.

EXPRESS the speed of the boat is constant given by $v_b = d/t$ here d is the distance of the boat from the bridge when the key is dropped 12 m and t is the time the key takes in falling.

o calculate t we take the time to be zero at the instant the key is dropped we compute the time t when $y = 0$ using $y = y_0 + v_0 t - \frac{1}{2} g t^2$ with $y_0 = 45 \text{ m}$. Once t is known the speed of the boat can be readily calculated.

ANALYZE Since the initial velocity of the key is zero the coordinate of the key is

given by $y_0 = \frac{1}{2} g t^2$. Thus the time it takes for the key to drop into the boat is

$$t = \sqrt{\frac{2y_0}{g}} = \sqrt{\frac{2(45 \text{ m})}{9.8 \text{ m/s}^2}} = 3.03 \text{ s}.$$

herefore the speed of the boat is $v_b = \frac{12 \text{ m}}{3.03 \text{ s}} = 4.0 \text{ m/s}$.

LEARN From the general expression $v_b = \frac{d}{dt} = \frac{d}{\sqrt{2y_0/g}} = d \sqrt{\frac{g}{2y_0}}$ we see that

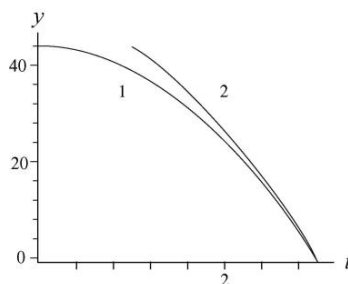
$v_b \sim 1/\sqrt{y_0}$. This agrees with our intuition that the lower the height from which the key is dropped the greater the speed of the boat in order to catch it.

54. a. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking down as the $-y$ direction for the duration of the motion. We are allowed to use Δy with Δy replacing Δx because this is constant acceleration motion. We use primed variables with the first stone which has zero initial velocity and unprimed variables with the second stone with initial downward velocity $-v_0$ so that v_0 is being used for the initial speed. SI units are used throughout.

$$\Delta y' = 0(t) - \frac{1}{2} g t^2$$

$$\Delta y = (-v_0)(t-1) - \frac{1}{2} g (t-1)^2$$

Since the problem indicates $\Delta y' = \Delta y = -43.9 \text{ m}$ we solve the first equation for t finding $t = 2.99 \text{ s}$ and use this result to solve the second equation for the initial speed of the second stone



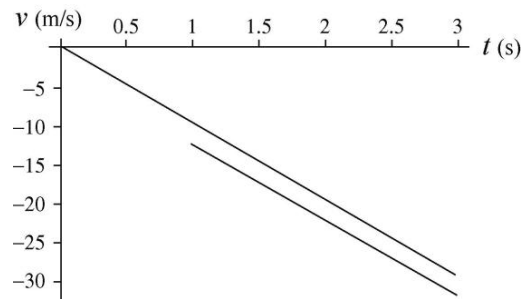
$$-43.9 \text{ m} = (-v_0)(1.99 \text{ s}) - \frac{1}{2}(9.8 \text{ m/s}^2)(1.99 \text{ s})^2$$

which leads to $v_0 = 12.3 \text{ m/s}$.

b. The velocity of the stones are given by

$$v'_y = \frac{d \Delta y'}{dt} = -gt \quad v_y = \frac{d \Delta y}{dt} = -v_0 - g t - 1$$

he plot is shown below



55. **THINK** The free falling moist clay ball strikes the ground with a non-zero speed and it undergoes deceleration before coming to rest.

EXPRESS During contact with the ground its average acceleration is given by

$a_{\text{avg}} = \frac{\Delta v}{\Delta t}$ where Δv is the change in its velocity during contact with the ground and $\Delta t = 20.0 \times 10^{-3}$ s is the duration of contact. Thus we must first find the velocity of the ball just before it hits the ground $y = 0$.

ANALYZE Also to find the velocity just before contact we take $t = 0$ to be when it is dropped. Using Eq. 2.16 with $y_0 = 15.0$ m we obtain

$$v = -\sqrt{v_0^2 - 2g(y - y_0)} = -\sqrt{0 - 2(9.8 \text{ m/s}^2)(0 - 15 \text{ m})} = -17.15 \text{ m/s}$$

Here the negative sign is chosen since the ball is traveling downward at the moment of contact. Consequently the average acceleration during contact with the ground is

$$a_{\text{avg}} = \frac{\Delta v}{\Delta t} = \frac{0 - (-17.1 \text{ m/s})}{20.0 \times 10^{-3} \text{ s}} = 857 \text{ m/s}^2.$$

Because the fact that the result is positive indicates that this acceleration vector points upward.

LEARN Since Δt is very small it is not surprising to have a very large acceleration to stop the motion of the ball. In later chapters we shall see that the acceleration is directly related to the magnitude and direction of the force exerted by the ground on the ball during the course of collision.

56. We use Eq. 2.16

$$v^2 = v_0^2 + 2a(y - y_0)$$

With $a = -9.8 \text{ m/s}^2$, $y - y_0 = 0.40 \text{ m}$ and $v = \frac{1}{3} v_0$, it is then straightforward to solve $v_0 = 3.0 \text{ m/s}$ approximately.

57. The average acceleration during contact with the floor is $a_{\text{avg}} = \frac{v_2 - v_1}{\Delta t}$

here v_1 is its velocity just before striking the floor v_2 is its velocity just as it leaves the floor and Δt is the duration of contact with the floor $12 \times 10^{-3} \text{ s}$.

Taking the y axis to be positively up and placing the origin at the point where the ball is dropped we first find the velocity just before striking the floor using $v_1^2 = v_0^2 - 2gy$. With $v_0 = 0$ and $y = -4.00 \text{ m}$ the result is

$$v_1 = -\sqrt{-2gy} = -\sqrt{-2(9.8 \text{ m/s}^2)(-4.00 \text{ m})} = -8.85 \text{ m/s}$$

here the negative root is chosen because the ball is traveling down. To find the velocity just after hitting the floor as it ascends without air friction to a height of 2.00 m we use $v^2 = v_2^2 - 2g(y - y_0)$ with $v = 0$, $y = -2.00 \text{ m}$ it ends up 2.00 m below its initial drop height and $y_0 = -4.00 \text{ m}$. therefore

$$v_2 = \sqrt{2g(y - y_0)} = \sqrt{2(9.8 \text{ m/s}^2)(-2.00 \text{ m} + 4.00 \text{ m})} = 6.26 \text{ m/s}.$$

Consequently the average acceleration is

$$a_{\text{avg}} = \frac{v_2 - v_1}{\Delta t} = \frac{6.26 \text{ m/s} - (-8.85 \text{ m/s})}{12.0 \times 10^{-3} \text{ s}} = 1.26 \times 10^3 \text{ m/s}^2.$$

The positive nature of the result indicates that the acceleration vector points up. In a later chapter this will be directly related to the magnitude and direction of the force exerted by the ground on the ball during the collision.

58. We choose *down* as the y direction and set the coordinate origin at the point where it is dropped which is when we start the clock. We denote the 1.00 s duration mentioned in the problem as $t - t'$ where t is the value of time when it lands and t' is one second prior to that. The corresponding distance is $y - y' = 0.50h$ where y denotes the location of the ground. In these terms y is the same as h so we have $h - y' = 0.50h$ or $0.50h = y'$.

a We find t' and t from $y = \frac{1}{2}gt^2$ with $v_0 = 0$

$$y' = \frac{1}{2}gt'^2 \Rightarrow t' = \sqrt{\frac{2y'}{g}}$$

$$y = \frac{1}{2}gt^2 \Rightarrow t = \sqrt{\frac{2y}{g}}.$$

Plugging in $y = h$ and $y' = 0.50h$ and dividing these two equations we obtain

$$\frac{t'}{t} = \sqrt{\frac{2(0.50h)/g}{2h/g}} = \sqrt{0.50}.$$

Setting $t' = t - 1.00$ units understood and cross multiplying we find

$$t - 1.00 = t\sqrt{0.50} \Rightarrow t = \frac{1.00}{1 - \sqrt{0.50}}$$

which yields $t = 3.41$ s.

b Plugging this result into $y = \frac{1}{2}gt^2$ we find $h = 57$ m.

(c) In our approach, we did not use the quadratic formula, but we did “choose a root” when we assumed in the last calculation in part a that $\sqrt{0.50} = 0.707$ instead of -0.707 . If we had instead let $\sqrt{0.50} = -0.707$ then our answer for t could have been roughly 0.6 s which could imply that $t' = t - 1$ could equal a negative number indicating a time *before* it was dropped which certainly does not fit with the physical situation described in the problem.

59. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking *down* as the $-y$ direction for the duration of the motion. We are allowed to use Table 2.1 with Δy replacing Δx because this is constant acceleration motion. The ground level is taken to correspond to the origin of the y axis.

a The time drop 1 leaves the nozzle is taken as $t = 0$ and its time of landing on the floor t_1 can be computed from Eq. 2.15 with $v_0 = 0$ and $y_1 = -2.00$ m.

$$y_1 = -\frac{1}{2}gt_1^2 \Rightarrow t_1 = \sqrt{\frac{-2y}{g}} = \sqrt{\frac{-2(-2.00 \text{ m})}{9.8 \text{ m/s}^2}} = 0.639 \text{ s}.$$

At that moment the fourth drop begins to fall and from the regularity of the dripping we conclude that drop 2 leaves the nozzle at $t = 0.639/3 = 0.213$ s and drop 3 leaves the nozzle at $t = 2(0.213 \text{ s}) = 0.426$ s. Therefore the time in free fall up to the moment drop 1 lands for drop 2 is $t_2 = t_1 - 0.213 \text{ s} = 0.426$ s. Its position at the moment drop 1 strikes the floor is

$$y_2 = -\frac{1}{2}gt_2^2 = -\frac{1}{2}(9.8 \text{ m/s}^2)(0.426 \text{ s})^2 = -0.889 \text{ m}$$

or about 89 cm below the nozzle.

b The time in free fall up to the moment drop 1 lands for drop 3 is $t_3 = t_1 - 0.426 \text{ s} = 0.213$ s. Its position at the moment drop 1 strikes the floor is

$$y_3 = -\frac{1}{2}gt_3^2 = -\frac{1}{2}(9.8 \text{ m/s}^2)(0.213 \text{ s})^2 = -0.222 \text{ m}$$

or about 22 cm below the nozzle.

60. To find the “launch” velocity of the rock, we apply Eq. 2.11 to the maximum height where the speed is momentarily zero

$$v = v_0 - gt \Rightarrow 0 = v_0 - (9.8 \text{ m s}^{-2})(2.5 \text{ s})$$

so that $v_0 = 24.5 \text{ m s}^{-1}$ with y up. So we use Eq. 2.15 to find the height of the tower taking $y_0 = 0$ at the ground level

$$y - y_0 = v_0 t + \frac{1}{2} a t^2 \Rightarrow y - 0 = (24.5 \text{ m s}^{-1})(1.5 \text{ s}) - \frac{1}{2} (9.8 \text{ m s}^{-2})(1.5 \text{ s})^2.$$

thus we obtain $y = 26 \text{ m}$.

61. We choose *down* as the y direction and place the coordinate origin at the top of the building which has height H . During its fall the ball passes with velocity v_1 the top of the window which is at y_1 at time t_1 and passes the bottom which is at y_2 at time t_2 . We are told $y_2 - y_1 = 1.20 \text{ m}$ and $t_2 - t_1 = 0.125 \text{ s}$. So Eq. 2.15 we have

$$y_2 - y_1 = v_1(t_2 - t_1) + \frac{1}{2} g(t_2 - t_1)^2$$

which immediately yields

$$v_1 = \frac{1.20 \text{ m} - \frac{1}{2} (9.8 \text{ m s}^{-2})(0.125 \text{ s})^2}{0.125 \text{ s}} = 8.99 \text{ m s}^{-1}.$$

From this Eq. 2.16 with $v_0 = 0$ reveals the value of y_1

$$v_1^2 = 2gy_1 \Rightarrow y_1 = \frac{(8.99 \text{ m s}^{-1})^2}{2 \cdot 9.8 \text{ m s}^{-2}} = 4.12 \text{ m}.$$

It reaches the ground $y_3 = H$ at t_3 . Because of the symmetry we pressed in the problem ("upward flight is a reverse of the fall") we know that $t_3 - t_2 = 2.00 \text{ s} - 1.00 \text{ s} = 1.00 \text{ s}$. And this means $t_3 - t_1 = 1.00 \text{ s} + 0.125 \text{ s} = 1.125 \text{ s}$. So Eq. 2.15 produces

$$y_3 - y_1 = v_1(t_3 - t_1) + \frac{1}{2} g(t_3 - t_1)^2$$

$$y_3 - 4.12 \text{ m} = (8.99 \text{ m s}^{-1})(1.125 \text{ s}) + \frac{1}{2} (9.8 \text{ m s}^{-2})(1.125 \text{ s})^2$$

which yields $y_3 = H = 20.4 \text{ m}$.

62. The height reached by the player is $y = 0.76 \text{ m}$ where we have taken the origin of the y axis at the floor and y to be upward.

a. The initial velocity v_0 of the player is

$$v_0 = \sqrt{2gy} = \sqrt{2 \cdot 9.8 \text{ m s}^{-2} \cdot 0.76 \text{ m}} = 3.86 \text{ m s}^{-1}.$$

This is a consequence of Eq. 2.16 where velocity v vanishes. As the player reaches y_1

$= 0.76 \text{ m} - 0.15 \text{ m} = 0.61 \text{ m}$ his speed v_1 satisfies $v_0^2 - v_1^2 = 2gy_1$ which yields

$$v_1 = \sqrt{v_0^2 - 2gy_1} = \sqrt{3.86 \text{ m s}^{-2} - 2(9.80 \text{ m s}^{-2})(0.61 \text{ m})} = 1.71 \text{ m s}^{-1}$$

The time t_1 that the player spends *ascending* in the top $\Delta y_1 = 0.15 \text{ m}$ of the jump can now be found from Eq. 2-17

$$\Delta y_1 = \frac{1}{2}(v_1 + v)t_1 \Rightarrow t_1 = \frac{2(0.15 \text{ m})}{1.71 \text{ m s}^{-1} + 0} = 0.175 \text{ s}$$

which means that the total time spent in that top 15 cm both ascending and descending is $2(0.175 \text{ s}) = 0.35 \text{ s} = 350 \text{ ms}$.

(b) The time t_2 when the player reaches a height of 0.15 m is found from Eq. 2-15

$$0.15 \text{ m} = v_0 t_2 - \frac{1}{2} g t_2^2 = 3.86 \text{ m s}^{-1} t_2 - \frac{1}{2} (9.8 \text{ m s}^{-2}) t_2^2$$

which yields, using the quadratic formula, taking the smaller of the two positive roots $t_2 = 0.041 \text{ s} = 41 \text{ ms}$ which implies that the total time spent in that bottom 15 cm both ascending and descending is $2(41 \text{ ms}) = 82 \text{ ms}$.

63. The time t the pot spends passing in front of the window of length $L = 2.0 \text{ m}$ is 0.25 s each way. We use v for its velocity as it passes the top of the window going up. Then with $a = -g = -9.8 \text{ m s}^{-2}$ taking *down* to be the $-y$ direction, Eq. 2-18 yields

$$L = vt - \frac{1}{2} g t^2 \Rightarrow v = \frac{L}{t} - \frac{1}{2} g t.$$

The distance H the pot goes above the top of the window is therefore, using Eq. 2-16 with the *final velocity* being zero to indicate the highest point

$$H = \frac{v^2}{2g} = \frac{(L/t - \frac{1}{2} g t)^2}{2g} = \frac{(2.00 \text{ m} - 0.25 \text{ s} - 9.80 \text{ m s}^{-2} \cdot 0.25 \text{ s})^2}{2(9.80 \text{ m s}^{-2})} = 2.34 \text{ m}.$$

64. The graph shows $y = 25 \text{ m}$ to be the highest point (here the speed momentarily vanishes). The neglect of “air friction” (or whatever passes for that on the distant planet) is certainly reasonable due to the symmetry of the graph.

(a) To find the acceleration due to gravity g_p on that planet we use Eq. 2-15 with y up

$$y - y_0 = vt + \frac{1}{2} g_p t^2 \Rightarrow 25 \text{ m} - 0 = (0)(2.5 \text{ s}) + \frac{1}{2} g_p (2.5 \text{ s})^2$$

so that $g_p = 8.0 \text{ m s}^{-2}$.

(b) That same maximum point on the graph can be used to find the initial velocity.

$$y - y_0 = \frac{1}{2}(v_0 + v)t \Rightarrow 25 \text{ m} - 0 = \frac{1}{2}(v_0 + 0)(2.5 \text{ s})$$

herefore $v_0 = 20 \text{ m/s}$.

65. The key idea here is that the speed of the head and the torso as well at any given time can be calculated by finding the area on the graph of the head's acceleration versus time as shown in Fig. 2.26

$$v_1 - v_0 = \left(\begin{array}{l} \text{area between the acceleration curve} \\ \text{and the time axis from } t_0 \text{ to } t_1 \end{array} \right)$$

From Fig. 2.15a we see that the head begins to accelerate from rest $v_0 = 0$ at $t_0 = 110 \text{ ms}$ and reaches a maximum value of 90 m/s^2 at $t_1 = 160 \text{ ms}$. The area of this region is

$$\text{area} = \frac{1}{2} (160 - 110) \times 10^{-3} \text{ s} \cdot (90 \text{ m/s}^2) = 2.25 \text{ m/s}$$

which is equal to v_1 the speed at t_1 .

Now to compute the speed of the torso at $t_1 = 160 \text{ ms}$ we divide the area into 4 regions from 0 to 40 ms region has zero area. From 40 ms to 100 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.0600 \text{ s}) (50.0 \text{ m/s}^2) = 1.50 \text{ m/s}$$

From 100 to 120 ms region has the shape of a rectangle with area

$$\text{area} = (0.0200 \text{ s}) (50.0 \text{ m/s}^2) = 1.00 \text{ m/s}$$

From 120 to 160 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.0400 \text{ s}) (50.0 + 20.0 \text{ m/s}^2) = 1.40 \text{ m/s}$$

Substituting these values into Eq. 2.26 with $v_0 = 0$ then gives

$$v_1 - 0 = 0 + 1.50 \text{ m/s} + 1.00 \text{ m/s} + 1.40 \text{ m/s} = 3.90 \text{ m/s}$$

or $v_1 = 3.90 \text{ m/s}$.

66. The key idea here is that the position of an object at any given time can be calculated by finding the area on the graph of the object's velocity versus time as shown in Fig. 2.30

$$x_1 - x_0 = \left(\begin{array}{l} \text{area between the velocity curve} \\ \text{and the time axis from } t_0 \text{ to } t_1 \end{array} \right)$$

Now to compute the position of the fist at $t = 50 \text{ ms}$ we divide the area in Fig. 2.37 into two regions. From 0 to 10 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.010 \text{ s}) (2 \text{ m/s}) = 0.01 \text{ m}.$$

From 10 to 50 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.040 \text{ s}) (2 + 4 \text{ m/s}) = 0.12 \text{ m}.$$

Substituting these values into Eq. 2-30 with $x_0 = 0$ then gives

$$x_1 - 0 = 0 + 0.01 \text{ m} + 0.12 \text{ m} = 0.13 \text{ m}$$

or $x_1 = 0.13 \text{ m}$.

(b) The speed of the fist reaches a maximum at $t_1 = 120 \text{ ms}$. From 50 to 90 ms region C has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.040 \text{ s}) (4 + 5 \text{ m/s}) = 0.18 \text{ m}.$$

From 90 to 120 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.030 \text{ s}) (5 + 7.5 \text{ m/s}) = 0.19 \text{ m}.$$

Substituting these values into Eq. 2-30 with $x_0 = 0$ then gives

$$x_1 - 0 = 0 + 0.01 \text{ m} + 0.12 \text{ m} + 0.18 \text{ m} + 0.19 \text{ m} = 0.50 \text{ m}$$

or $x_1 = 0.50 \text{ m}$.

67. The problem is solved using Eq. 2-31

$$v_1 - v_0 = \left(\begin{array}{l} \text{area between the acceleration curve} \\ \text{and the time axis from } t_0 \text{ to } t_1 \end{array} \right)$$

To compute the speed of the unhelmeted bare head at $t_1 = 7.0 \text{ ms}$ we divide the area under the a vs. t graph into 4 regions. From 0 to 2 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.0020 \text{ s}) (120 \text{ m/s}^2) = 0.12 \text{ m/s}.$$

From 2 ms to 4 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.0020 \text{ s}) (120 + 140 \text{ m/s}^2) = 0.26 \text{ m/s}.$$

rom 4 to 6 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.0020 \text{ s} \cdot 140 + 200) \text{ m s}^2 = 0.34 \text{ m s}.$$

rom 6 to 7 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.0010 \text{ s} \cdot 200) \text{ m s}^2 = 0.10 \text{ m s}.$$

substituting these values into Eq. 2-31 with $v_0=0$ then gives

$$v_{\text{unhelmeted}} = 0.12 \text{ m s} + 0.26 \text{ m s} + 0.34 \text{ m s} + 0.10 \text{ m s} = 0.82 \text{ m s}.$$

Carrying out similar calculations for the helmeted head we have the following results. rom 0 to 3 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.0030 \text{ s} \cdot 40) \text{ m s}^2 = 0.060 \text{ m s}.$$

rom 3 ms to 4 ms region has the shape of a rectangle with area

$$\text{area} = (0.0010 \text{ s} \cdot 40) \text{ m s}^2 = 0.040 \text{ m s}.$$

rom 4 to 6 ms region has the shape of a trapezoid with area

$$\text{area} = \frac{1}{2} (0.0020 \text{ s} \cdot 40 + 80) \text{ m s}^2 = 0.12 \text{ m s}.$$

rom 6 to 7 ms region has the shape of a triangle with area

$$\text{area} = \frac{1}{2} (0.0010 \text{ s} \cdot 80) \text{ m s}^2 = 0.040 \text{ m s}.$$

substituting these values into Eq. 2-31 with $v_0 = 0$ then gives

$$v_{\text{helmeted}} = 0.060 \text{ m s} + 0.040 \text{ m s} + 0.12 \text{ m s} + 0.040 \text{ m s} = 0.26 \text{ m s}.$$

thus the difference in the speed is

$$\Delta v = v_{\text{unhelmeted}} - v_{\text{helmeted}} = 0.82 \text{ m s} - 0.26 \text{ m s} = 0.56 \text{ m s}.$$

68. This problem can be solved by noting that velocity can be determined by the graphical integration of acceleration versus time. The speed of the tongue of the salamander is simply equal to the area under the acceleration curve

$$\begin{aligned} v &= \text{area} = \frac{1}{2} (10^{-2} \text{ s} \cdot 100 \text{ m s}^2) + \frac{1}{2} (10^{-2} \text{ s} \cdot 100 \text{ m s}^2 + 400 \text{ m s}^2) + \frac{1}{2} (10^{-2} \text{ s} \cdot 400 \text{ m s}^2) \\ &= 5.0 \text{ m s}. \end{aligned}$$

69. Since $v = dx/dt$, then $\Delta x = \int v dt$ which corresponds to the area under the v vs t graph. Dividing the total area A into rectangular (base \times height) and triangular ($\frac{1}{2}$ base \times height) areas we have

$$\begin{aligned} A &= A_{0 < t < 2} + A_{2 < t < 10} + A_{10 < t < 12} + A_{12 < t < 16} \\ &= \frac{1}{2}(2)(8) + (8)(8) + \left((2)(4) + \frac{1}{2}(2)(4) \right) + (4)(4) \end{aligned}$$

With units understood, in this way we obtain $\Delta x = 100$ m.

70. To solve this problem we note that velocity is equal to the time derivative of a position function as well as the time integral of an acceleration function with the integration constant being the initial velocity. Thus the velocity of particle 1 can be written as

$$v_1 = \frac{dx_1}{dt} = \frac{d}{dt}(6.00t^2 + 3.00t + 2.00) = 12.0t + 3.00.$$

Similarly the velocity of particle 2 is

$$v_2 = v_{20} + \int a_2 dt = 20.0 + \int -8.00t dt = 20.0 - 4.00t^2.$$

The condition that $v_1 = v_2$ implies

$$12.0t + 3.00 = 20.0 - 4.00t^2 \Rightarrow 4.00t^2 + 12.0t - 17.0 = 0$$

which can be solved to give taking positive root $t = \frac{-3 + \sqrt{26}}{2} = 1.05$ s. Thus the velocity at this time is $v_1 = v_2 = 12.0(1.05) + 3.00 = 15.6$ m/s.

71. a. The derivative with respect to time of the given expression for x yields the “velocity” of the spot:

$$v(t) = 9 - \frac{9}{4}t^2$$

With 3 significant figures understood, it is easy to see that $v = 0$ when $t = 2.00$ s.

b. At $t = 2$ s $x = 9(2) - \frac{9}{4}(2)^3 = 12$. Thus the location of the spot when $v = 0$ is 12.0 cm from left edge of screen.

c. The derivative of the velocity is $a = -\frac{9}{2}t$ which gives an acceleration of -9.00 cm/s² (negative sign indicating left) and when the spot is 12 cm from the left edge of screen.

d. Since $v > 0$ for times less than $t = 2$ s then the spot had been moving right and.

is implied by our answer to part (c) it moves leftward for times immediately after $t = 2$ s. In fact, the expression found in part (a) guarantees that for all $t \geq 2$ s, $v < 0$ (that is, until the clock is “reset” by reaching an edge).

For the discussion in part (e) shows the edge that it reaches at some $t \geq 2$ s cannot be the right edge; it is the left edge $x = 0$. Solving the expression given in the problem statement with $x = 0$ for positive t yields the answer: the spot reaches the left edge at $t = \sqrt{12}$ s ≈ 3.46 s.

72. We adopt the convention frequently used in the text that up is the positive y direction.

(a) At the highest point in the trajectory $v = 0$. Thus, with $t = 1.60$ s, the equation $v = v_0 - gt$ yields $v_0 = 15.7$ m/s.

(b) The equation that is not dependent on our result from part (a) is $y - y_0 = v_0 t - \frac{1}{2}gt^2$. This readily gives $y_{\text{max}} - y_0 = 12.5$ m for the highest maximum point measured relative to where it started—the top of the building.

(c) Once we use our result from part (a) and plug into $y - y_0 = v_0 t - \frac{1}{2}gt^2$ with $t = 6.00$ s and $y = 0$ (the ground level), we have

$$0 - y_0 = 15.68 \text{ m/s} \cdot 6.00 \text{ s} - \frac{1}{2} \cdot 9.8 \text{ m/s}^2 \cdot 6.00 \text{ s}^2.$$

Therefore, y_0 (the height of the building) is equal to 82.3 m.

73. We denote the required time as t assuming the light turns green when the clock reads zero. By this time, the distances traveled by the two vehicles must be the same.

(a) Denoting the acceleration of the automobile as a and the constant speed of the truck as v then

$$\Delta x = \left(\frac{1}{2}at^2 \right)_{\text{car}} = (vt)_{\text{truck}}$$

which leads to

$$t = \frac{2v}{a} = \frac{2(9.5 \text{ m/s})}{2.2 \text{ m/s}^2} = 8.6 \text{ s}.$$

Therefore

$$\Delta x = vt = (9.5 \text{ m/s})(8.6 \text{ s}) = 82 \text{ m}.$$

(b) The speed of the car at that moment is

$$v_{\text{car}} = at = (2.2 \text{ m/s}^2)(8.6 \text{ s}) = 19 \text{ m/s}.$$

74. If the plane with velocity v maintains its present course and if the terrain continues its upward slope of 4.3°, then the plane will strike the ground after traveling

$$\Delta x = \frac{h}{\tan \theta} = \frac{35 \text{ m}}{\tan 4.3^\circ} = 465.5 \text{ m} \approx 0.465 \text{ km}.$$

this corresponds to a time of flight found from $v^2 = v_{\text{avg}}^2$ since it is constant

$$t = \frac{\Delta x}{v} = \frac{0.465 \text{ km}}{1300 \text{ km/h}} = 0.000358 \text{ h} \approx 1.3 \text{ s}.$$

his then estimates the time available to the pilot to make his correction.

75. We denote t_r as the reaction time and t_b as the braking time. The motion during t_r is of the constant velocity call it v_0 type. Then the position of the car is given by

$$x = v_0 t_r + v_0 t_b + \frac{1}{2} a t_b^2$$

here v_0 is the initial velocity and a is the acceleration which we expect to be negative valued since we are taking the velocity in the positive direction and we know the car is decelerating. After the brakes are applied the velocity of the car is given by $v = v_0 + a t_b$. Using this equation with $v = 0$ we eliminate t_b from the first equation and obtain

$$x = v_0 t_r - \frac{v_0^2}{a} + \frac{1}{2} \frac{v_0^2}{a} = v_0 t_r - \frac{1}{2} \frac{v_0^2}{a}.$$

We write this equation for each of the initial velocities

$$x_1 = v_{01} t_r - \frac{1}{2} \frac{v_{01}^2}{a} \quad x_2 = v_{02} t_r - \frac{1}{2} \frac{v_{02}^2}{a}.$$

Solving these equations simultaneously for t_r and a we get

$$t_r = \frac{v_{02}^2 x_1 - v_{01}^2 x_2}{v_{01} v_{02} (v_{02} - v_{01})}$$

and

$$a = -\frac{1}{2} \frac{v_{02} v_{01}^2 - v_{01} v_{02}^2}{v_{02} x_1 - v_{01} x_2}.$$

a. Substituting $x_1 = 56.7 \text{ m}$, $v_{01} = 80.5 \text{ km/h} = 22.4 \text{ m/s}$, $x_2 = 24.4 \text{ m}$ and $v_{02} = 48.3 \text{ km/h} = 13.4 \text{ m/s}$ we find

$$\begin{aligned} t_r &= \frac{v_{02}^2 x_1 - v_{01}^2 x_2}{v_{01} v_{02} (v_{02} - v_{01})} = \frac{13.4 \text{ m/s}^2 \cdot 56.7 \text{ m} - 22.4 \text{ m/s}^2 \cdot 24.4 \text{ m}}{22.4 \text{ m/s} \cdot 13.4 \text{ m/s} \cdot 13.4 \text{ m/s} - 22.4 \text{ m/s}} \\ &= 0.74 \text{ s}. \end{aligned}$$

b. Similarly substituting $x_1 = 56.7 \text{ m}$, $v_{01} = 80.5 \text{ km/h} = 22.4 \text{ m/s}$, $x_2 = 24.4 \text{ m}$ and

$v_{02} = 48.3 \text{ km/h} = 13.4 \text{ m/s}$ gives

$$a = -\frac{1}{2} \frac{v_{02}^2 - v_{01}^2}{v_{02}x_1 - v_{01}x_2} = -\frac{1}{2} \frac{(13.4 \text{ m/s})^2 - (22.4 \text{ m/s})^2}{13.4 \text{ m/s} \cdot 56.7 \text{ m} - 22.4 \text{ m/s} \cdot 24.4 \text{ m}} = -6.2 \text{ m/s}^2.$$

The *magnitude* of the deceleration is therefore 6.2 m/s^2 . Although rounded off values are displayed in the above substitutions that we have input into our calculators are the “exact” values (such as $v_{02} = \frac{161}{12} \text{ m/s}$).

76. a. A constant velocity is equal to the ratio of displacement to elapsed time. Thus for the vehicle to be traveling at a constant speed v_p over a distance D_{23} the time delay should be $t = D_{23}/v_p$.

b. The time required for the car to accelerate from rest to a cruising speed v_p is $t_0 = v_p/a$. During this time interval the distance traveled is $\Delta x_0 = at_0^2/2 = v_p^2/2a$.

The car then moves at a constant speed v_p over a distance $D_{12} - \Delta x_0 - d$ to reach intersection 2 and the time elapsed is $t_1 = (D_{12} - \Delta x_0 - d)/v_p$. Thus the time delay at intersection 2 should be set to

$$\begin{aligned} t_{\text{total}} &= t_r + t_0 + t_1 = t_r + \frac{v_p}{a} + \frac{D_{12} - \Delta x_0 - d}{v_p} = t_r + \frac{v_p}{a} + \frac{D_{12} - \frac{v_p^2}{2a} - d}{v_p} \\ &= t_r + \frac{1}{2} \frac{v_p}{a} + \frac{D_{12} - d}{v_p} \end{aligned}$$

77. **THINK** The speed of the rod changes due to a nonzero acceleration.

EXPRESS Since the problem involves constant acceleration the motion of the rod can be readily analyzed using the equations given in Table 2.1. We take x to be in the direction of motion so

$$v = (60 \text{ km/h}) \left(\frac{1000 \text{ m}}{3600 \text{ s}} \frac{\text{km}}{\text{h}} \right) = +16.7 \text{ m/s}$$

and $a = 0$. The location where the rod starts from rest $v_0 = 0$ is taken to be $x_0 = 0$.

ANALYZE a. Using Eqs. 2.7 we find the average acceleration to be

$$a_{\text{avg}} = \frac{\Delta v}{\Delta t} = \frac{v - v_0}{t - t_0} = \frac{16.7 \text{ m/s} - 0}{5.4 \text{ s} - 0} = 3.09 \text{ m/s}^2.$$

b. Assuming constant acceleration $a = a_{\text{avg}} = 3.09 \text{ m/s}^2$ the total distance traveled during the 5.4 s time interval is

$$x = x_0 + v_0 t + \frac{1}{2} a t^2 = 0 + 0 + \frac{1}{2} (3.09 \text{ m/s}^2) (5.4 \text{ s})^2 = 45 \text{ m}$$

c. Using Eq. 2.15 the time required to travel a distance of $x = 250 \text{ m}$ is

$$x = \frac{1}{2} a t^2 \Rightarrow t = \sqrt{\frac{2x}{a}} = \sqrt{\frac{2(250 \text{ m})}{3.1 \text{ m/s}^2}} = 12.73 \text{ s}$$

LEARN The displacement of the rod as a function of time can be written as

$x(t) = \frac{1}{2} (3.09 \text{ m/s}^2) t^2$. Note that we could have chosen Eq. 2.17 to solve for t because

$$x = \frac{1}{2} (v_0 + v) t = \frac{1}{2} (16.7 \text{ m/s})(5.4 \text{ s}) = 45 \text{ m}.$$

78. We take the moment of applying brakes to be $t = 0$. The deceleration is constant so that Table 2.1 can be used. Our primed variables such as $v'_0 = 72 \text{ km/h} = 20 \text{ m/s}$ refer to one train moving in the $+x$ direction and located at the origin when $t = 0$ and unprimed variables refer to the other moving in the $-x$ direction and located at $x_0 = 950 \text{ m}$ when $t = 0$. We note that the acceleration vector of the unprimed train points in the *positive* direction even though the train is slowing down its initial velocity is $v_0 = -144 \text{ km/h} = -40 \text{ m/s}$. Since the primed train has the lower initial speed it should stop sooner than the other train would were it not for the collision. Using Eq. 2.16 it should stop meaning $v' = 0$ at

$$x' = \frac{(v')^2 - (v'_0)^2}{2a'} = \frac{0 - (20 \text{ m/s})^2}{-2 \text{ m/s}^2} = 200 \text{ m}.$$

The speed of the other train when it reaches that location is

$$v = \sqrt{v_0^2 + 2a\Delta x} = \sqrt{(-40 \text{ m/s})^2 + 2(1.0 \text{ m/s}^2)(200 \text{ m} - 950 \text{ m})} \\ = 10 \text{ m/s}$$

using Eq. 2.16 again. Specifically its velocity at that moment would be -10 m/s since it is still traveling in the $-x$ direction when it crashes. If the computation of v had failed meaning that a negative number would have been inside the square root then we could have looked at the possibility that there was no collision and we aimed how far apart they finally were. A concern that can be brought up is whether the primed train collides before it comes to rest this can be studied by computing the time it stops. Eq. 2.11 yields $t = 20 \text{ s}$ and seeing where the unprimed train is at that moment Eq. 2.18 yields $x = 350 \text{ m}$ still a good distance away from contact.

79. The y coordinate of object 1 obeys $y - y_{01} = -\frac{1}{2} g t^2$ where $y = 0$ when $t = 3.0 \text{ s}$.

This allows us to solve for y_{01} and we find $y_{01} = 44.1 \text{ m}$. The graph for the coordinate of object 2 which is thrown apparently at $t = 1.0 \text{ s}$ with velocity v_1 is

$$y - y_{02} = v_1 t - 1.0 - \frac{1}{2} g t - 1.0^2$$

here $y_{02} = y_{01} - 1.0 = 54.1 \text{ m}$ and here again $y = 0$ when $t = 3.0 \text{ s}$. thus we obtain $|v_1| = 17 \text{ m/s}$ approximately.

80. we take x in the direction of motion. we use subscripts 1 and 2 for the data. thus $v_1 = 30 \text{ m/s}$, $v_2 = 50 \text{ m/s}$ and $x_2 - x_1 = 160 \text{ m}$.

a. using these subscripts . 2 16 leads to

$$a = \frac{v_2^2 - v_1^2}{2(x_2 - x_1)} = \frac{50^2 - 30^2}{2(160)} = 5.0 \text{ m/s}^2.$$

b. we find the time interval corresponding to the displacement $x_2 - x_1$ using . 2 17

$$t_2 - t_1 = \frac{2(x_2 - x_1)}{v_1 + v_2} = \frac{2(160)}{30 + 50} = 4.0 \text{ s}.$$

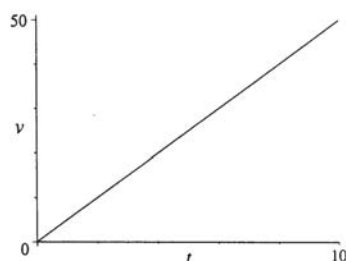
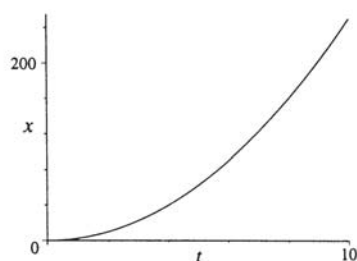
c. since the train is at rest $v_0 = 0$ when the clock starts we find the value of t_1 from . 2 11

$$v_1 = v_0 + at_1 \Rightarrow t_1 = \frac{30}{5.0} = 6.0 \text{ s}.$$

d. the coordinate origin is taken to be the location at which the train was initially at rest so $x_0 = 0$. thus we are asked to find the value of x_1 . Although any of several equations could be used we choose . 2 17

$$x_1 = \frac{1}{2}(v_0 + v_1)t_1 = \frac{1}{2}(30)(6.0) = 90 \text{ m}.$$

e. the graphs are shown below with units understood.



81. **THINK** the particle undergoes a *non-constant* acceleration along the x axis. Integration is required to calculate velocity.

EXPRESS with a non constant acceleration $a = dv/dt$ the velocity of the

particle at time t_1 is given by $v_1 = v_0 + \int_{t_0}^{t_1} a \, dt$ here v_0 is the velocity at time t_0 . In our situation we have $a = 5.0t$. In addition we also know that $v_0 = 17 \text{ m/s}$ at $t_0 = 2.0 \text{ s}$.

ANALYZE Integrating from $t = 2 \text{ s}$ to variable $t = 4 \text{ s}$ the acceleration to get the velocity and using the values given in the problem leads to

$$v = v_0 + \int_{t_0}^t a \, dt = v_0 + \int_{2.0}^t 5.0t \, dt = v_0 + \frac{1}{2} (5.0) (t^2 - t_0^2) = 17 + \frac{1}{2} (5.0) (4^2 - 2^2) = 47 \text{ m/s}.$$

LEARN The velocity of the particle as a function of t is

$$v(t) = v_0 + \frac{1}{2} (5.0) (t^2 - t_0^2) = 17 + \frac{1}{2} (5.0) (t^2 - 4) = 7 + 2.5t^2$$

in units m/s . Since the acceleration is linear in t we expect the velocity to be quadratic in t and the displacement to be cubic in t .

82. The velocity v at $t = 6$ units and to significant figures understood is $v_{\text{given}} + \int_{-2}^6 a \, dt$. A quick way to implement this is to recall the area of a triangle $\frac{1}{2} \text{ base} \times \text{height}$. The result is $v = 7 \text{ m/s} + 32 \text{ m/s} = 39 \text{ m/s}$.

83. The object once it is dropped $v_0 = 0$ is in free fall $a = -g = -9.8 \text{ m/s}^2$ if we take down as the $-y$ direction and we use 2.15 repeatedly.

a. The positive distance D from the lower dot to the mark corresponding to a certain reaction time t is given by $\Delta y = -D = -\frac{1}{2}gt^2$ or $D = \frac{1}{2}gt^2$. Thus for $t_1 = 50.0 \text{ ms}$

$$D_1 = \frac{(9.8 \text{ m/s}^2)(50.0 \times 10^{-3} \text{ s})^2}{2} = 0.0123 \text{ m} = 1.23 \text{ cm}.$$

$$\text{b. or } t_2 = 100 \text{ ms} \quad D_2 = \frac{(9.8 \text{ m/s}^2)(100 \times 10^{-3} \text{ s})^2}{2} = 0.049 \text{ m} = 4D_1.$$

$$\text{c. or } t_3 = 150 \text{ ms} \quad D_3 = \frac{(9.8 \text{ m/s}^2)(150 \times 10^{-3} \text{ s})^2}{2} = 0.11 \text{ m} = 9D_1.$$

$$\text{d. or } t_4 = 200 \text{ ms} \quad D_4 = \frac{(9.8 \text{ m/s}^2)(200 \times 10^{-3} \text{ s})^2}{2} = 0.196 \text{ m} = 16D_1.$$

$$\text{e. or } t_5 = 250 \text{ ms} \quad D_5 = \frac{(9.8 \text{ m/s}^2)(250 \times 10^{-3} \text{ s})^2}{2} = 0.306 \text{ m} = 25D_1.$$

84. We take the direction of motion as x . Take $x_0 = 0$ and use SI units so $v = 1600 \text{ m/s}$, 1000 m/s , $3600 \text{ m/s} = 444 \text{ m/s}$.

a. Equation 2.11 gives $444 = a(1.8)$ or $a = 247 \text{ m/s}^2$. We express this as a multiple of g by setting up a ratio

$$a = \left(\frac{247 \text{ m/s}^2}{9.8 \text{ m/s}^2} \right) g = 25g.$$

b. Equation 2.17 readily yields

$$x = \frac{1}{2}(v_0 + v)t = \frac{1}{2}(444 \text{ m/s})(1.8 \text{ s}) = 400 \text{ m}.$$

85. Let D be the distance up the hill. Then

$$\text{average speed} = \frac{\text{total distance traveled}}{\text{total time of travel}} = \frac{2D}{\frac{D}{20 \text{ km/h}} + \frac{D}{35 \text{ km/h}}} \approx 25 \text{ km/h}.$$

86. We obtain the velocity by integration of the acceleration

$$v - v_0 = \int_0^t (6.1 - 1.2t') dt'.$$

Lengths are in meters and times are in seconds. The student is encouraged to look at the discussion in Section 2.7 to better understand the manipulations here.

a. The result of the above calculation is $v = v_0 + 6.1t - 0.6t^2$. Here the problem states that $v_0 = 2.7 \text{ m/s}$. The maximum of this function is found by knowing when its derivative (the acceleration) is zero: $a = 0$ when $t = 6.1/1.2 = 5.1 \text{ s}$, and plugging that value of t into the velocity equation above. Thus we find $v = 18 \text{ m/s}$.

b. We integrate again to find x as a function of t

$$x - x_0 = \int_0^t v dt' = \int_0^t (v_0 + 6.1t' - 0.6t'^2) dt' = v_0 t + 3.05t^2 - 0.2t^3.$$

With $x_0 = 7.3 \text{ m}$ we obtain $x = 83 \text{ m}$ for $t = 6$. This is the correct answer but one has the right to worry that it might not be: after all, the problem asks for the total distance traveled and $x - x_0$ is just the *displacement*. If the cyclist backtracked then his total distance would be greater than his displacement. Thus we might ask: did he backtrack? To do so would require that his velocity be momentarily zero at some point as he reversed his direction of motion. We could solve the above quadratic equation for velocity for a positive value of t here: $v = 0$ if we did we would find that at $t = 10.6 \text{ s}$ a reversal does indeed happen. However in the time interval we are concerned with in our problem ($0 \leq t \leq 6 \text{ s}$), there is no reversal and the displacement is the same as the total distance traveled.

87. **THINK** In this problem we're given two different speeds, and asked to find the difference in their travel times.

EXPRESS The time it takes to travel a distance d with a speed v_1 is $t_1 = d/v_1$. Similarly, with a speed v_2 the time would be $t_2 = d/v_2$. The two speeds in this problem are

$$v_1 = 55 \text{ mi/h} = 55 \text{ mi/h} \frac{1609 \text{ m}}{1 \text{ mi}} \frac{1 \text{ h}}{3600 \text{ s}} = 24.58 \text{ m/s}$$

$$v_2 = 65 \text{ mi/h} = 65 \text{ mi/h} \frac{1609 \text{ m}}{1 \text{ mi}} \frac{1 \text{ h}}{3600 \text{ s}} = 29.05 \text{ m/s}$$

ANALYZE With $d = 700 \text{ km} = 7.0 \times 10^5 \text{ m}$ the time difference between the two is

$$\Delta t = t_1 - t_2 = d \left(\frac{1}{v_1} - \frac{1}{v_2} \right) = 7.0 \times 10^5 \text{ m} \left(\frac{1}{24.58 \text{ m/s}} - \frac{1}{29.05 \text{ m/s}} \right) = 4383 \text{ s}$$

$$= 73 \text{ min}$$

or about 1.2 h.

LEARN The travel time was reduced from 7.9 h to 6.9 h. Driving at higher speed within the legal limit reduces travel time.

88. The acceleration is constant and we may use the equations in Table 2.1.

a. Taking the first point as coordinate origin and time to be zero when the car is there we apply Eq. 2.17

$$x = \frac{1}{2} (v + v_0) t = \frac{1}{2} (15.0 \text{ m/s} + v_0) (6.00 \text{ s}).$$

With $x = 60.0 \text{ m}$ which takes the direction of motion as the x direction we solve for the initial velocity $v_0 = 5.00 \text{ m/s}$.

b. Substituting $v = 15.0 \text{ m/s}$, $v_0 = 5.00 \text{ m/s}$ and $t = 6.00 \text{ s}$ into $a = (v - v_0)/t$ (Eq. 2.11) we find $a = 1.67 \text{ m/s}^2$.

c. Substituting $v = 0$ in $v^2 = v_0^2 + 2ax$ and solving for x we obtain

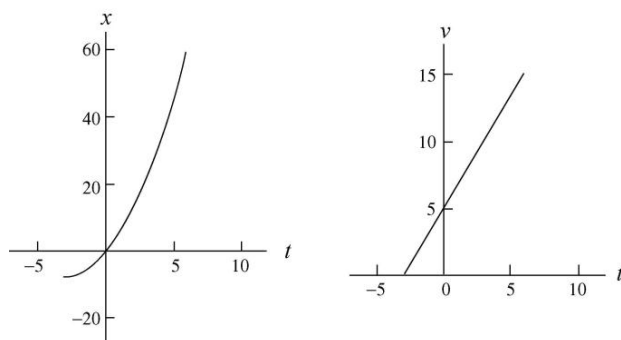
$$x = -\frac{v_0^2}{2a} = -\frac{5.00 \text{ m/s}^2}{2(1.67 \text{ m/s}^2)} = -7.50 \text{ m}$$

or $|x| = 7.50 \text{ m}$.

d. The graphs require computing the time when $v = 0$ in which case we use $v = v_0 + at'$. Thus

$$t' = \frac{-v_0}{a} = \frac{-5.00 \text{ m/s}}{1.67 \text{ m/s}^2} = -3.0 \text{ s}$$

indicates the moment the car was at rest. Units are understood.



89. **THINK** In this problem we explore the connection between the maximum height an object reaches under the influence of gravity and the total amount of time it stays in air.

EXPRESS Neglecting air resistance and setting $a = -g = -9.8 \text{ m/s}^2$ taking *down* as the $-y$ direction for the duration of the motion we analyze the motion of the ball using Table 2.1 with Δy replacing Δx . We set $y_0 = 0$. Upon reaching the maximum height H the speed of the ball is momentarily zero $v = 0$. Therefore we can relate its initial speed v_0 to H via the equation

$$0 = v^2 = v_0^2 - 2gH \Rightarrow v_0 = \sqrt{2gH}.$$

The time it takes for the ball to reach maximum height is given by $v = v_0 - gt = 0$ or $t = v_0/g = \sqrt{2H/g}$.

ANALYZE For the ball to spend twice as much time in air as before i.e. $t' = 2t$ then the new maximum height H' it must reach is such that $t' = \sqrt{2H'/g}$. Solving for H' we obtain

$$H' = \frac{1}{2}gt'^2 = \frac{1}{2}g(2t)^2 = 4\left(\frac{1}{2}gt^2\right) = 4H.$$

LEARN Since $H \sim t^2$ doubling t means that H must increase fourfold. Note also that for $t' = 2t$ the initial speed must be twice the original speed $v'_0 = 2v_0$.

90. a. Using the fact that the area of a triangle is $\frac{1}{2}$ base \times height and the fact that the integral corresponds to the area under the curve we find from $t = 0$ through $t = 5$ s the integral of v with respect to t is 15 m. Since we are told that $x_0 = 0$ then we conclude that $x = 15$ m when $t = 5.0$ s.

b. We see directly from the graph that $v = 2.0 \text{ m/s}$ when $t = 5.0$ s.

c. Since $a = dv/dt = \text{slope of the graph}$ we find that the acceleration during the interval $4 \leq t \leq 6$ is uniformly equal to -2.0 m/s^2 .

d. Thinking of $x(t)$ in terms of accumulated area on the graph we note that $x(1) = 1$ m using this and the value found in part a $\frac{1}{2} \times 2 \times 2$ produces

$$v_{\text{avg}} = \frac{x_5 - x_1}{5 - 1} = \frac{15 \text{ m} - 1 \text{ m}}{4 \text{ s}} = 3.5 \text{ m/s}.$$

e. From 2.7 and the values v and t we read directly from the graph we find

$$a_{\text{avg}} = \frac{v_5 - v_1}{5 - 1} = \frac{2 \text{ m/s} - 2 \text{ m/s}}{4 \text{ s}} = 0.$$

91. Taking the y direction *downward* and $y_0 = 0$ we have $y = v_0 t + \frac{1}{2} g t^2$ which with $v_0 = 0$ yields $t = \sqrt{2y/g}$.

a. For this part of the motion $y_1 = 50 \text{ m}$ so that $t_1 = \sqrt{\frac{2(50 \text{ m})}{9.8 \text{ m/s}^2}} = 3.2 \text{ s}$.

b. For this next part of the motion we note that the total displacement is $y_2 = 100 \text{ m}$. Therefore the total time is

$$t_2 = \sqrt{\frac{2(100 \text{ m})}{9.8 \text{ m/s}^2}} = 4.5 \text{ s}.$$

The difference between this and the answer to part a is the time required to fall through that second 50 m distance $\Delta t = t_2 - t_1 = 4.5 \text{ s} - 3.2 \text{ s} = 1.3 \text{ s}$.

92. Direction of x is implicit in the problem statement. The initial position when the clock starts is $x_0 = 0$ where $v_0 = 0$. The end of the speeding up motion occurs at $x_1 = 1100/2 = 550 \text{ m}$ and the subway train comes to a halt $v_2 = 0$ at $x_2 = 1100 \text{ m}$.

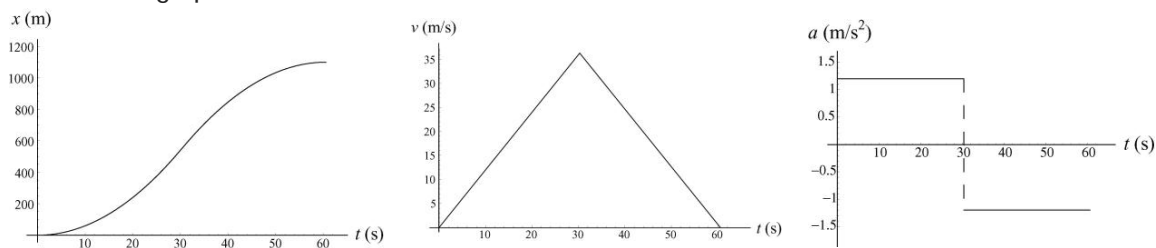
a. Using 2.15 the subway train reaches x_1 at

$$t_1 = \sqrt{\frac{2x_1}{a_1}} = \sqrt{\frac{2(550 \text{ m})}{1.2 \text{ m/s}^2}} = 30.3 \text{ s}.$$

The time interval $t_2 - t_1$ turns out to be the same value most easily seen using 2.18 so the total time is $t_2 = 2(30.3) = 60.6 \text{ s}$.

b. Its maximum speed occurs at t_1 and equals $v_1 = v_0 + a_1 t_1 = 36.3 \text{ m/s}$.

c. The graphs are shown below



93. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ (taking *down* as the $-y$ direction) for the duration of the stone's motion. We are allowed to use Table 2.1 with Δx replaced by y because the ball has constant acceleration motion and we choose $y_0 = 0$.

a. We apply 2.16 to both measurements with units understood.

$$v_B^2 = v_0^2 - 2gy_B \Rightarrow \left(\frac{1}{2}v\right)^2 + 2g(y_A + 3) = v_0^2$$

$$v_A^2 = v_0^2 - 2gy_A \Rightarrow v^2 + 2gy_A = v_0^2$$

We equate the two expressions that each equal v_0^2 and obtain

$$\frac{1}{4}v^2 + 2gy_A + 2g(3) = v^2 + 2gy_A \Rightarrow 2g(3) = \frac{3}{4}v^2$$

which yields $v = \sqrt{2g(4)} = 8.85 \text{ m/s}$.

b. An object moving upward at A with speed $v = 8.85 \text{ m/s}$ will reach a maximum height $y - y_A = v^2/2g = 4.00 \text{ m}$ above point A (this is again a consequence of 2.16 now with the "final" velocity set to zero to indicate the highest point). Thus the top of its motion is 1.00 m above point B .

94. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ (taking *down* as the $-y$ direction) for the duration of the motion. We are allowed to use Table 2.1 with Δy replacing Δx because this is constant acceleration motion. The ground level is taken to correspond to the origin of the y axis. The total time of fall can be computed from 2.15 using the quadratic formula.

$$\Delta y = v_0 t - \frac{1}{2}gt^2 \Rightarrow t = \frac{v_0 + \sqrt{v_0^2 - 2g\Delta y}}{g}$$

With the positive root chosen. With $y = 0$, $v_0 = 0$ and $y_0 = h = 60 \text{ m}$ we obtain

$$t = \frac{\sqrt{2gh}}{g} = \sqrt{\frac{2h}{g}} = 3.5 \text{ s}.$$

Thus, "1.2 s earlier" means we are examining where the rock is at $t = 2.3 \text{ s}$

$$y - h = v_0(2.3 \text{ s}) - \frac{1}{2}g(2.3 \text{ s})^2 \Rightarrow y = 34 \text{ m}$$

here we again use the fact that $h = 60 \text{ m}$ and $v_0 = 0$.

95. **THINK** This problem involves analyzing a plot describing the position of an iceboat as function of time. The boat has a non-zero acceleration due to the wind.

EXPRESS Since we are told that the acceleration of the boat is constant the equations of Table 2.1 can be applied. However the challenge here is that v_0 , v and a are not explicitly given. Our strategy to deduce these values is to apply the kinematic equation $x - x_0 = v_0 t + \frac{1}{2} a t^2$ to a variety of points on the graph and solve for the unknowns from the simultaneous equations.

ANALYZE a From the graph we pick two points on the curve $(t, x) = (2.0 \text{ s}, 16 \text{ m})$ and $(3.0 \text{ s}, 27 \text{ m})$. The corresponding simultaneous equations are

$$\begin{aligned} 16 \text{ m} - 0 &= v_0 (2.0 \text{ s}) + \frac{1}{2} a (2.0 \text{ s})^2 \\ 27 \text{ m} - 0 &= v_0 (3.0 \text{ s}) + \frac{1}{2} a (3.0 \text{ s})^2 \end{aligned}$$

Solving the equations lead to the values $v_0 = 6.0 \text{ m/s}$ and $a = 2.0 \text{ m/s}^2$.

b From Table 2.1

$$x - x_0 = v t + \frac{1}{2} a t^2 \Rightarrow 27 \text{ m} - 0 = v (3.0 \text{ s}) + \frac{1}{2} (2.0 \text{ m/s}^2) (3.0 \text{ s})^2$$

which leads to $v = 12 \text{ m/s}$.

c Assuming the wind continues during $3.0 \leq t \leq 6.0$, we apply $x - x_0 = v_0 t + \frac{1}{2} a t^2$ to this interval where $v_0 = 12.0 \text{ m/s}$ from part b to obtain

$$\Delta x = (12.0 \text{ m/s})(3.0 \text{ s}) + \frac{1}{2} (2.0 \text{ m/s}^2) (3.0 \text{ s})^2 = 45 \text{ m}.$$

LEARN By using the results obtained in a the position and velocity of the iceboat as a function of time can be written as

$$x(t) = 6.0 \text{ m/s} t + \frac{1}{2} (2.0 \text{ m/s}^2) t^2 \quad \text{and} \quad v(t) = 6.0 \text{ m/s} + 2.0 \text{ m/s}^2 t.$$

One can readily verify that the same answers are obtained for b and c using the above expressions for $x(t)$ and $v(t)$.

96. a Let the height of the diving board be h . We choose *down* as the y direction and set the coordinate origin at the point where it is dropped which is when we start the clock. Thus $y = h$ designates the location where the ball strikes the water. Let the depth of the lake be D and the total time for the ball to descend be T . The speed of the ball as it reaches the surface of the lake is then $v = \sqrt{2gh}$ from 2.16 and the time for the ball to fall from the board to the lake surface is $t_1 = \sqrt{2h/g}$ from 2.15. So the time it spends descending in the lake at constant velocity v is

$$t_2 = \frac{D}{v} = \frac{D}{\sqrt{2gh}}.$$

thus $T = t_1 + t_2 = \sqrt{\frac{2h}{g}} + \frac{D}{\sqrt{2gh}}$ which gives

$$D = T\sqrt{2gh} - 2h = (4.80 \text{ s})\sqrt{(2)(9.80 \text{ m/s}^2)(5.20 \text{ m})} - 2(5.20 \text{ m}) = 38.1 \text{ m}.$$

b. Since the magnitude of the average velocity is

$$v_{\text{avg}} = \frac{D + h}{T} = \frac{38.1 \text{ m} + 5.20 \text{ m}}{4.80 \text{ s}} = 9.02 \text{ m/s}$$

c. In our coordinate choices a positive sign for v_{avg} means that the ball is going down. If however up had been chosen as the positive direction then this answer in b would turn out negative valued.

d. We find v_0 from $\Delta y = v_0 t + \frac{1}{2}gt^2$ with $t = T$ and $\Delta y = h - D$. Thus

$$v_0 = \frac{h - D}{T} - \frac{gT}{2} = \frac{5.20 \text{ m} - 38.1 \text{ m}}{4.80 \text{ s}} - \frac{(9.8 \text{ m/s}^2)(4.80 \text{ s})}{2} = -14.5 \text{ m/s}$$

e. Here in our coordinate choices the negative sign means that the ball is being thrown up.

97. We choose *down* as the y direction and use the equations of Table 2-1 replacing x with y with $a = g$, $v_0 = 0$ and $y_0 = 0$. We use subscript 2 for the elevator reaching the ground and 1 for the half-way point.

a. Equation 2-16 $v_2^2 = v_0^2 + 2a(y_2 - y_0)$ leads to

$$v_2 = \sqrt{2gy_2} = \sqrt{2(9.8 \text{ m/s}^2)(120 \text{ m})} = 48.5 \text{ m/s}.$$

b. The time at which it strikes the ground is using Eq. 2-15

$$t_2 = \sqrt{\frac{2y_2}{g}} = \sqrt{\frac{2(120 \text{ m})}{9.8 \text{ m/s}^2}} = 4.95 \text{ s}.$$

c. Eq. 2-16 in the form $v_1^2 = v_0^2 + 2a(y_1 - y_0)$ leads to

$$v_1 = \sqrt{2gy_1} = \sqrt{2(9.8 \text{ m/s}^2)(60 \text{ m})} = 34.3 \text{ m/s}.$$

d. The time at which it reaches the half-way point is using Eq. 2-15

$$t_1 = \sqrt{\frac{2y_1}{g}} = \sqrt{\frac{2 \cdot 60 \text{ m}}{9.8 \text{ m/s}^2}} = 3.50 \text{ s}.$$

98. Taking y to be upward and placing the origin at the point from which the objects are dropped then the location of diamond 1 is given by $y_1 = -\frac{1}{2}gt^2$ and the location of diamond 2 is given by $y_2 = -\frac{1}{2}g(t-1)^2$. We are starting the clock when the first object is dropped. We want the time for which $y_2 - y_1 = 10 \text{ m}$. Therefore

$$-\frac{1}{2}g(t-1)^2 + \frac{1}{2}gt^2 = 10 \Rightarrow t = (10/g) + 0.5 = 1.5 \text{ s}.$$

99. With y upward we have $y_0 = 36.6 \text{ m}$ and $y = 12.2 \text{ m}$. Therefore using Eq. 2.18 the last equation in Table 2.1 we find

$$y - y_0 = vt + \frac{1}{2}gt^2 \Rightarrow v = -22.0 \text{ m/s}$$

at $t = 2.00 \text{ s}$. The term *speed* refers to the magnitude of the velocity vector so the answer is $v = 22.0 \text{ m/s}$.

100. During free fall we ignore the air resistance and set $a = -g = -9.8 \text{ m/s}^2$ where we are choosing *down* to be the $-y$ direction. The initial velocity is zero so that Eq. 2.15 becomes $\Delta y = -\frac{1}{2}gt^2$ where Δy represents the *negative* of the distance d she has fallen. Thus we can write the equation as $d = \frac{1}{2}gt^2$ for simplicity.

a. The time t_1 during which the parachutist is in free fall is using Eq. 2.15 given by

$$d_1 = 50 \text{ m} = \frac{1}{2}gt_1^2 = \frac{1}{2}(9.80 \text{ m/s}^2)t_1^2$$

which yields $t_1 = 3.2 \text{ s}$. The *speed* of the parachutist just before he opens the parachute is given by the positive root $v_1^2 = 2gd_1$ or

$$v_1 = \sqrt{2gh_1} = \sqrt{(2)(9.80 \text{ m/s}^2)(50 \text{ m})} = 31 \text{ m/s}.$$

If the final speed is v_2 then the time interval t_2 between the opening of the parachute and the arrival of the parachutist at the ground level is

$$t_2 = \frac{v_1 - v_2}{a} = \frac{31 \text{ m/s} - 3.0 \text{ m/s}}{2 \text{ m/s}^2} = 14 \text{ s}.$$

This is a result of Eq. 2.11 where *speeds* are used instead of the negative valued velocities so that final velocity minus initial velocity turns out to be equal initial speed minus final speed. We also note that the acceleration vector for this part of the motion is positive since it points upward opposite to the direction of motion — which makes it a deceleration. The total time of flight is therefore $t_1 + t_2 = 17 \text{ s}$.

b The distance through which the parachutist falls after the parachute is opened is given by

$$d = \frac{v_1^2 - v_2^2}{2a} = \frac{(31 \text{ m/s})^2 - (3.0 \text{ m/s})^2}{(2)(2.0 \text{ m/s}^2)} \approx 240 \text{ m.}$$

In the computation we have used Eq. 2-16 with both sides multiplied by -1 which changes the negative valued Δy into the positive d on the left hand side and switches the order of v_1 and v_2 on the right hand side. Thus the fall begins at a height of $h = 50 \text{ m}$, $d \approx 290 \text{ m}$.

101. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m/s}^2$ taking down as the $-y$ direction for the duration of the motion. We are allowed to use Table 2-1 with Δy replacing Δx because this is constant acceleration motion. The ground level is taken to correspond to $y = 0$.

a With $y_0 = h$ and v_0 replaced with $-v_0$, Eq. 2-16 leads to

$$v = \sqrt{-v_0^2 - 2g(y - y_0)} = \sqrt{v_0^2 + 2gh}.$$

The positive root is taken because the problem asks for the speed the *magnitude* of the velocity.

b We use the quadratic formula to solve Eq. 2-15 for t with v_0 replaced with $-v_0$

$$\Delta y = -v_0 t - \frac{1}{2}gt^2 \Rightarrow t = \frac{-v_0 + \sqrt{-v_0^2 - 2g\Delta y}}{g}$$

here the positive root is chosen to yield $t > 0$. With $y = 0$ and $y_0 = h$ this becomes

$$t = \frac{\sqrt{v_0^2 + 2gh} - v_0}{g}.$$

c If it were thrown up and with that speed from height h then in the absence of air friction it would return to height h with that same down and speed and would therefore yield the same final speed before hitting the ground as in part a. An important perspective related to this is treated later in the book in the context of energy conservation.

d Having to travel up before it starts its descent certainly requires more time than in part b. The calculation is quite similar however except for no v_0 in the equation here we had put in $-v_0$ in part b. The details follow

$$\Delta y = v_0 t - \frac{1}{2}gt^2 \Rightarrow t = \frac{v_0 + \sqrt{v_0^2 - 2g\Delta y}}{g}$$

with the positive root again chosen to yield $t \geq 0$. With $y = 0$ and $y_0 = h$ we obtain

$$t = \frac{\sqrt{v_0^2 + 2gh} + v_0}{g}.$$

102. We assume constant velocity motion and use $v_{\text{avg}} = v_0$. Therefore

$$\Delta x = v\Delta t = \left(303 \frac{\text{km}}{\text{h}} \left(\frac{1000 \text{ m}}{3600 \text{ s}} \frac{\text{km}}{\text{h}}\right)\right) (100 \times 10^{-3} \text{ s}) = 8.4 \text{ m}.$$

103. Assuming the horizontal velocity of the ball is constant the horizontal displacement is $\Delta x = v\Delta t$ where Δx is the horizontal distance traveled Δt is the time and v is the horizontal velocity. Converting v to meters per second we have $160 \text{ km/h} = 44.4 \text{ m/s}$. Thus

$$\Delta t = \frac{\Delta x}{v} = \frac{18.4 \text{ m}}{44.4 \text{ m/s}} = 0.414 \text{ s}.$$

The velocity unit conversion implemented above can be figured “from basics” ($1000 \text{ m} = 1 \text{ km}$, $3600 \text{ s} = 1 \text{ h}$) or found in Appendix .

104. In this solution we make use of the notation $x(t)$ for the value of x at a particular t . Thus $x(t) = 50t + 10t^2$ with units meters and seconds understood.

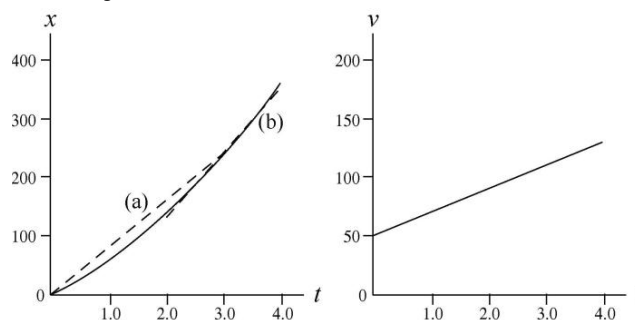
a The average velocity during the first 3 s is given by

$$v_{\text{avg}} = \frac{x(3) - x(0)}{\Delta t} = \frac{50(3) + 10(3)^2 - 0}{3} = 80 \text{ m/s}.$$

b The instantaneous velocity at time t is given by $v = dx/dt = 50 + 20t$ in units. At $t = 3.0 \text{ s}$, $v = 50 + 20(3.0) = 110 \text{ m/s}$.

c The instantaneous acceleration at time t is given by $a = dv/dt = 20 \text{ m/s}^2$. It is constant so the acceleration at any time is 20 m/s^2 .

d and e The graphs that follow show the coordinate x and velocity v as functions of time with units understood. The dashed line marked a in the first graph runs from $t = 0$, $x = 0$ to $t = 3.0 \text{ s}$, $x = 240 \text{ m}$. Its slope is the average velocity during the first 3 s of motion. The dashed line marked b is tangent to the x curve at $t = 3.0 \text{ s}$. Its slope is the instantaneous velocity at $t = 3.0 \text{ s}$.



105. We take x in the direction of motion so $v_0 = 30 \text{ m/s}$, $v_1 = 15 \text{ m/s}$ and $a = 0$. The acceleration is found from $a = \frac{v_1 - v_0}{t_1}$ here $t_1 = 3.0 \text{ s}$. This gives $a = -5.0 \text{ m/s}^2$. The displacement which in this situation is the same as the distance traveled to the point it stops $v_2 = 0$ is using $v_2^2 = v_0^2 + 2a\Delta x$

$$v_2^2 = v_0^2 + 2a\Delta x \Rightarrow \Delta x = -\frac{30^2 \text{ m}^2/\text{s}^2}{2(-5 \text{ m/s}^2)} = 90 \text{ m}.$$

106. The problem consists of two constant acceleration parts. Part 1 with $v_0 = 0$, $v = 6.0 \text{ m/s}$, $x = 1.8 \text{ m}$ and $x_0 = 0$ if we take its original position to be the coordinate origin and part 2 with $v_0 = 6.0 \text{ m/s}$, $v = 0$ and $a_2 = -2.5 \text{ m/s}^2$ negative because we are taking the positive direction to be the direction of motion.

a. We can use $x - x_0 = \frac{1}{2} v_0 t_1 + \frac{1}{2} a t_1^2$ to find the time for the first part

$$x - x_0 = \frac{1}{2} v_0 t_1 + \frac{1}{2} a t_1^2 \Rightarrow 1.8 \text{ m} - 0 = \frac{1}{2} (0) + \frac{1}{2} (6.0 \text{ m/s}) t_1$$

so that $t_1 = 0.6 \text{ s}$. and $v = v_0 + a t_1$ is used to obtain the time for the second part

$$v = v_0 + a_2 t_2 \Rightarrow 0 = 6.0 \text{ m/s} - 2.5 \text{ m/s}^2 t_2$$

from which $t_2 = 2.4 \text{ s}$ is computed. Thus the total time is $t_1 + t_2 = 3.0 \text{ s}$.

b. We already know the distance for part 1. We could find the distance for part 2 from several of the equations but the one that makes no use of our part a results is $v^2 = v_0^2 + 2a\Delta x$

$$v^2 = v_0^2 + 2a_2\Delta x_2 \Rightarrow 0 = 6.0^2 \text{ m}^2/\text{s}^2 - 2(2.5 \text{ m/s}^2)\Delta x_2$$

which leads to $\Delta x_2 = 7.2 \text{ m}$. Therefore the total distance traveled by the shuffleboard disk is $1.8 + 7.2 \text{ m} = 9.0 \text{ m}$.

107. The time required is found from $\Delta v = a \Delta t$ or suitably interpreted $\Delta t = \frac{\Delta v}{a}$. First we convert the velocity change to m/s units

$$\Delta v = 100 \text{ km/h} \left(\frac{1000 \text{ m}}{3600 \text{ s}} \frac{\text{km}}{\text{h}} \right) = 27.8 \text{ m/s}.$$

thus $\Delta t = \frac{\Delta v}{a} = \frac{27.8 \text{ m/s}}{50 \text{ m/s}^2} = 0.556 \text{ s}$.

108. From $v^2 - v_0^2 = 2a\Delta x$ is used to solve for a . Its minimum value is

$$a_{\min} = \frac{v^2 - v_0^2}{2\Delta x_{\max}} = \frac{360^2 \text{ km}^2/\text{h}^2}{2(1.80 \text{ km})} = 36000 \text{ km/h}^2$$

which converts to 2.78 m/s^2 .

109. a For the automobile $\Delta v = 55 - 25 = 30 \text{ km/h}$ which we convert to SI units

$$a = \frac{\Delta v}{\Delta t} = \frac{30 \text{ km/h} \left(\frac{1000 \text{ m}}{3600 \text{ s}} \right)}{0.50 \text{ min} \cdot 60 \text{ s/min}} = 0.28 \text{ m/s}^2.$$

b The change of velocity for the bicycle for the same time is identical to that of the car so its acceleration is also 0.28 m/s^2 .

110. Converting to SI units we have $v = 3400 \frac{1000}{3600} = 944 \text{ m/s}$ presumed constant and $\Delta t = 0.10 \text{ s}$. Thus $\Delta x = v\Delta t = 94.4 \text{ m}$.

111. This problem consists of two parts: part 1 with constant acceleration so that the equations in Table 2.1 apply: $v_0 = 0$, $v = 11.0 \text{ m/s}$, $x = 12.0 \text{ m}$ and $x_0 = 0$ adopting the starting line as the coordinate origin; and part 2 with constant velocity so that $x - x_0 = vt$ applies with $v = 11.0 \text{ m/s}$, $x_0 = 12.0$ and $x = 100.0 \text{ m}$.

a We obtain the time for part 1 from Eq. 2.17

$$x - x_0 = \frac{1}{2}(v_0 + v)t_1 \Rightarrow 12.0 - 0 = \frac{1}{2}(0 + 11.0)t_1$$

so that $t_1 = 2.2 \text{ s}$ and we find the time for part 2 simply from $88.0 = 11.0 t_2 \rightarrow t_2 = 8.0 \text{ s}$. Therefore the total time is $t_1 + t_2 = 10.2 \text{ s}$.

b Here the total time is required to be 10.0 s and we are to locate the point x_p where the runner switches from accelerating to proceeding at constant speed. The equations for parts 1 and 2 used above therefore become

$$\begin{aligned} x_p - 0 &= \frac{1}{2}(0 + 11.0 \text{ m/s})t_1 \\ 100.0 \text{ m} - x_p &= (11.0 \text{ m/s})(10.0 \text{ s} - t_1) \end{aligned}$$

here in the latter equation we use the fact that $t_2 = 10.0 - t_1$. Solving the equations for the two unknowns we find that $t_1 = 1.8 \text{ s}$ and $x_p = 10.0 \text{ m}$.

112. The bullet starts at rest $v_0 = 0$ and after traveling the length of the barrel $\Delta x = 1.2 \text{ m}$ emerges with the given velocity $v = 640 \text{ m/s}$ where the direction of motion is the positive direction. Turning to the constant acceleration equations in Table 2.1 we use $\Delta x = \frac{1}{2}v_0 + vt$. Thus we find $t = 0.00375 \text{ s}$ or 3.75 ms .

113. There is no air resistance which makes it quite accurate to set $a = -g = -9.8 \text{ m/s}^2$ where down is the $-y$ direction for the duration of the fall. We are allowed to use Table 2.1 with Δy replacing Δx because this is constant acceleration motion; in fact when the acceleration changes during the process of catching the ball we will again assume constant acceleration conditions; in this case we have $a_2 = 25g = 245 \text{ m/s}^2$.

a The time of fall is given by Eq. 2.15 with $v_0 = 0$ and $y = 0$. Thus

$$t = \sqrt{\frac{2y_0}{g}} = \sqrt{\frac{2 \cdot 145 \text{ m}}{9.8 \text{ m s}^{-2}}} = 5.44 \text{ s}.$$

b The final velocity for its free fall which becomes the initial velocity during the catching process is found from . 2 16 Other equations can be used but they could use the result from part a

$$v = -\sqrt{v_0^2 - 2g(y - y_0)} = -\sqrt{2gy_0} = -53.3 \text{ m s}^{-1}$$

here the negative root is chosen since this is a downward velocity. Thus the speed is $v = 53.3 \text{ m s}^{-1}$.

c For the catching process the answer to part b plays the role of an *initial* velocity $v_0 = -53.3 \text{ m s}^{-1}$ and the final velocity must become zero. Using . 2 16 we find

$$\Delta y_2 = \frac{v^2 - v_0^2}{2a_2} = \frac{0 - (-53.3 \text{ m s}^{-1})^2}{2(-245 \text{ m s}^{-2})} = -5.80 \text{ m}$$

or $\Delta y_2 = 5.80 \text{ m}$. The negative value of Δy_2 signifies that the distance traveled while arresting its motion is downward.

114. During T_r the velocity v_0 is constant in the direction we choose as x and obeys $v_0 = D_r T_r$ where we note that in units the velocity is $v_0 = 200 \frac{1000}{3600} = 55.6 \text{ m s}^{-1}$. During T_b the acceleration is opposite to the direction of v_0 hence for us $a < 0$ until the car is stopped $v = 0$.

a Using . 2 16 with $\Delta x_b = 170 \text{ m}$ we find

$$v^2 = v_0^2 + 2a\Delta x_b \Rightarrow a = -\frac{v_0^2}{2\Delta x_b}$$

which yields $a = -9.08 \text{ m s}^{-2}$.

b We express this as a multiple of g by setting up a ratio

$$a = \left(\frac{9.08 \text{ m s}^{-2}}{9.8 \text{ m s}^{-2}} \right) g = 0.926g.$$

c We use . 2 17 to obtain the braking time

$$\Delta x_b = \frac{1}{2}(v_0 + v)T_b \Rightarrow T_b = \frac{2(170 \text{ m})}{55.6 \text{ m s}} = 6.12 \text{ s}.$$

d We express our result for T_b as a multiple of the reaction time T_r by setting up a ratio

$$T_b = \left(\frac{6.12 \text{ s}}{400 \times 10^{-3} \text{ s}} \right) T_r = 15.3T_r.$$

Since $T_b > T_r$, most of the full time required to stop is spent in braking.

If we are only asked that the *increase* in distance D is due to $\Delta T_r = 0.100$ s, so we simply have

$$\Delta D = v_0 \Delta T_r = (55.6 \text{ m/s})(0.100 \text{ s}) = 5.56 \text{ m}.$$

115. The total time elapsed is $\Delta t = 2 \text{ h } 41 \text{ min} = 161 \text{ min}$ and the center point is displaced by $\Delta x = 3.70 \text{ m} = 370 \text{ cm}$. Thus the average velocity of the center point is

$$v_{\text{avg}} = \frac{\Delta x}{\Delta t} = \frac{370 \text{ cm}}{161 \text{ min}} = 2.30 \text{ cm/min}.$$

116. Using $v = v_0 + at$ we find the initial speed to be

$$v_0 = v - at = 0 - (-3400 \text{ m/s}^2)(6.5 \times 10^{-3} \text{ s}) = 216.6 \text{ m/s}$$

117. The total number of days walked is including the first and the last day and leap year

$$N = 340 + 365 + 365 + 366 + 365 + 365 + 261 = 2427$$

Thus the average speed of the walk is

$$s_{\text{avg}} = \frac{d}{\Delta t} = \frac{3.06 \times 10^7 \text{ m}}{2427 \text{ days} \cdot 86400 \text{ s/day}} = 0.146 \text{ m/s}.$$

118. a. Let d be the distance traveled. The average speed with and without rings set as sails are $v_s = d/t_s$ and $v_{ns} = d/t_{ns}$ respectively. Thus the ratio of the two speeds is

$$\frac{v_s}{v_{ns}} = \frac{d/t_s}{d/t_{ns}} = \frac{t_{ns}}{t_s} = \frac{25.0 \text{ s}}{7.1 \text{ s}} = 3.52$$

b. The difference in time expressed in terms of v_s is

$$\Delta t = t_{ns} - t_s = \frac{d}{v_{ns}} - \frac{d}{v_s} = \frac{d}{v_s} \left(\frac{1}{3.52} - 1 \right) = 2.52 \frac{d}{v_s} = 2.52 \frac{2.0 \text{ m}}{v_s} = \frac{5.04 \text{ m}}{v_s}$$

119. a. Differentiating $y(t) = 2.0 \text{ cm} \sin \pi t/4$ with respect to t we obtain

$$v_y(t) = \frac{dy}{dt} = \left(\frac{\pi}{2} \text{ cm/s} \right) \cos \pi t/4$$

The average velocity between $t = 0$ and $t = 2.0 \text{ s}$ is

$$\begin{aligned} v_{\text{avg}} &= \frac{1}{2.0 \text{ s}} \int_0^2 v_y dt = \frac{1}{2.0 \text{ s}} \left(\frac{\pi}{2} \text{ cm s} \right) \int_0^2 \cos \left(\frac{\pi t}{4} \right) dt \\ &= \frac{1}{2.0 \text{ s}} (2 \text{ cm}) \int_0^{\pi/2} \cos x dx = 1.0 \text{ cm s} \end{aligned}$$

b The instantaneous velocities of the particle at $t = 0$, 1.0 s and 2.0 s are respectively

$$\begin{aligned} v_y(0) &= \left(\frac{\pi}{2} \text{ cm s} \right) \cos 0 = \frac{\pi}{2} \text{ cm s} \\ v_y(1.0 \text{ s}) &= \left(\frac{\pi}{2} \text{ cm s} \right) \cos \frac{\pi}{4} = \frac{\pi\sqrt{2}}{4} \text{ cm s} \\ v_y(2.0 \text{ s}) &= \left(\frac{\pi}{2} \text{ cm s} \right) \cos \frac{\pi}{2} = 0 \end{aligned}$$

c Differentiating $v_y(t)$ with respect to t we obtain the following expression for acceleration

$$a_y(t) = \frac{dv_y}{dt} = \left(-\frac{\pi^2}{8} \text{ cm s}^2 \right) \sin \frac{\pi t}{4}$$

The average acceleration between $t = 0$ and $t = 2.0 \text{ s}$ is

$$\begin{aligned} a_{\text{avg}} &= \frac{1}{2.0 \text{ s}} \int_0^2 a_y dt = \frac{1}{2.0 \text{ s}} \left(-\frac{\pi^2}{8} \text{ cm s}^2 \right) \int_0^2 \sin \left(\frac{\pi t}{4} \right) dt \\ &= \frac{1}{2.0 \text{ s}} \left(-\frac{\pi}{2} \text{ cm s} \right) \int_0^{\pi/2} \sin x dx = \frac{1}{2.0 \text{ s}} \left(-\frac{\pi}{2} \text{ cm s} \right) = -\frac{\pi}{4} \text{ cm s}^2 \end{aligned}$$

d The instantaneous accelerations of the particle at $t = 0$, 1.0 s and 2.0 s are respectively

$$\begin{aligned} a_y(0) &= \left(-\frac{\pi^2}{8} \text{ cm s}^2 \right) \sin 0 = 0 \\ a_y(1.0 \text{ s}) &= \left(-\frac{\pi^2}{8} \text{ cm s}^2 \right) \sin \frac{\pi}{4} = -\frac{\pi^2\sqrt{2}}{16} \text{ cm s}^2 \\ a_y(2.0 \text{ s}) &= \left(-\frac{\pi^2}{8} \text{ cm s}^2 \right) \sin \frac{\pi}{2} = -\frac{\pi^2}{8} \text{ cm s}^2 \end{aligned}$$

Chapter

1. **THINK** In this problem we're given the magnitude and direction of a vector in two dimensions and asked to calculate its x and y components.

EXPRESS The x and the y components of a vector \vec{a} lying in the xy plane are given by

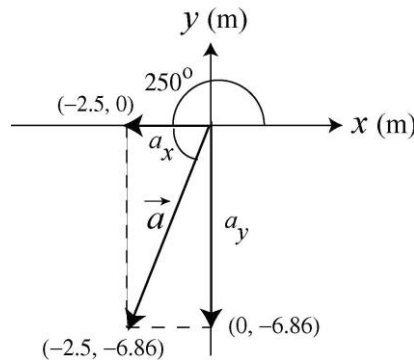
$$a_x = a \cos \theta \quad a_y = a \sin \theta$$

here $a = |\vec{a}| = \sqrt{a_x^2 + a_y^2}$ is the magnitude and $\theta = \tan^{-1} \frac{a_y}{a_x}$ is the angle between \vec{a} and the positive x axis. Given that $\theta = 250^\circ$ we see that the vector is in the third quadrant and we expect both the x and the y components of \vec{a} to be negative.

ANALYZE a) The x component of \vec{a} is

$$a_x = a \cos \theta = 7.3 \text{ m} \cos 250^\circ = -2.50 \text{ m}$$

b) and the y component is $a_y = a \sin \theta = 7.3 \text{ m} \sin 250^\circ = -6.86 \text{ m} \approx -6.9 \text{ m}$. The results are depicted in the figure below



LEARN In considering the variety of ways to compute these we note that the vector is 70° below the $-x$ axis so the components could also have been found from

$$a_x = -7.3 \text{ m} \cos 70^\circ = -2.50 \text{ m} \quad a_y = -7.3 \text{ m} \sin 70^\circ = -6.86 \text{ m}.$$

Similarly we note that the vector is 20° to the left from the $-y$ axis so one could also achieve the same results by using

$$a_x = -7.3 \text{ m} \sin 20^\circ = -2.50 \text{ m} \quad a_y = -7.3 \text{ m} \cos 20^\circ = -6.86 \text{ m}.$$

As a consistency check, we note that $\sqrt{a_x^2 + a_y^2} = \sqrt{(-2.50 \text{ m})^2 + (-6.86 \text{ m})^2} = 7.3 \text{ m}$ and $\tan^{-1}(a_y/a_x) = \tan^{-1}(-6.86 \text{ m} / -2.50 \text{ m}) = 250^\circ$, which are indeed the values given in the problem statement.

2. a. With $r = 15 \text{ m}$ and $\theta = 30^\circ$, the x component of \vec{r} is given by

$$r_x = r \cos \theta = 15 \text{ m} \cos 30^\circ = 13 \text{ m}.$$

b. Similarly, the y component is given by $r_y = r \sin \theta = 15 \text{ m} \sin 30^\circ = 7.5 \text{ m}$.

3. **THINK** In this problem we're given the x and y components of a vector \vec{A} in two dimensions and asked to calculate its magnitude and direction.

EXPRESS Vector \vec{A} can be represented in the *magnitude-angle* notation $A \angle \theta$, where

$$A = \sqrt{A_x^2 + A_y^2}$$

is the magnitude and

$$\theta = \tan^{-1}\left(\frac{A_y}{A_x}\right)$$

is the angle \vec{A} makes with the positive x axis. Given that $A_x = -25.0 \text{ m}$ and $A_y = 40.0 \text{ m}$, the above formulas can be readily used to calculate A and θ .

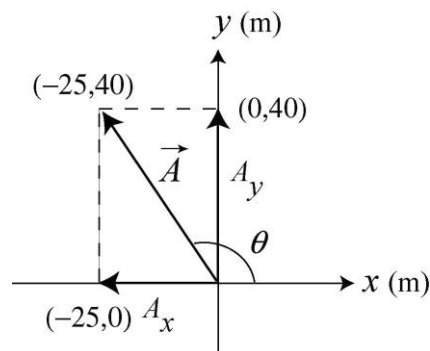
ANALYZE a. The magnitude of the vector \vec{A} is

$$A = \sqrt{A_x^2 + A_y^2} = \sqrt{(-25.0 \text{ m})^2 + (40.0 \text{ m})^2} = 47.2 \text{ m}$$

b. Recalling that $\tan \theta = \tan(\theta + 180^\circ)$,

$$\tan^{-1}(40.0 \text{ m} / -25.0 \text{ m}) = -58^\circ \text{ or } 122^\circ.$$

Noting that the vector is in the second quadrant by the signs of its x and y components, we see that 122° is the correct answer. The results are depicted in the figure to the right.



LEARN We can check our answers by noting that the x and the y components of \vec{A} can be written as

$$A_x = A \cos \theta \quad A_y = A \sin \theta.$$

substituting the results calculated above we obtain

$$A_x = 47.2 \text{ m} \cos 122^\circ = -25.0 \text{ m} \quad A_y = 47.2 \text{ m} \sin 122^\circ = +40.0 \text{ m}$$

which indeed are the values given in the problem statement.

4. The angle described by a full circle is $360^\circ = 2\pi \text{ rad}$ which is the basis of our conversion factor.

a $20.0^\circ = (20.0^\circ) \frac{2\pi \text{ rad}}{360^\circ} = 0.349 \text{ rad}.$

b $50.0^\circ = (50.0^\circ) \frac{2\pi \text{ rad}}{360^\circ} = 0.873 \text{ rad}.$

c $100^\circ = (100^\circ) \frac{2\pi \text{ rad}}{360^\circ} = 1.75 \text{ rad}.$

d $0.330 \text{ rad} = (0.330 \text{ rad}) \frac{360^\circ}{2\pi \text{ rad}} = 18.9^\circ.$

e $2.10 \text{ rad} = (2.10 \text{ rad}) \frac{360^\circ}{2\pi \text{ rad}} = 120^\circ.$

f $7.70 \text{ rad} = (7.70 \text{ rad}) \frac{360^\circ}{2\pi \text{ rad}} = 441^\circ.$

5. The vector sum of the displacements \vec{d}_{storm} and \vec{d}_{ne} must give the same result as its originally intended displacement $\vec{d}_o = 120 \text{ km} \hat{i}$ here east is \hat{i} north is \hat{j} . Thus we write

$$\vec{d}_{\text{storm}} = 100 \text{ km} (A\hat{i} + B\hat{j}) \quad \vec{d}_{\text{ne}} = A\hat{i} + B\hat{j}.$$

a The equation $\vec{d}_{\text{storm}} + \vec{d}_{\text{ne}} = \vec{d}_o$ readily yields $A = -100 \text{ km}$ and $B = 120 \text{ km}$. The magnitude of \vec{d}_{ne} is therefore equal to $|\vec{d}_{\text{ne}}| = \sqrt{A^2 + B^2} = 156 \text{ km}.$

b The direction is

$$\tan^{-1} \frac{B}{A} = -50.2^\circ \text{ or } 180^\circ - 50.2^\circ = 129.8^\circ.$$

We choose the latter value since it indicates a vector pointing in the second quadrant which is what we expect here. The answer can be phrased several equivalent ways: 129.8 counterclockwise from east or 39.8 west from north or 50.2 north from west.

6. a The height is $h = d \sin \theta$ here $d = 12.5 \text{ m}$ and $\theta = 20.0^\circ$. Therefore $h = 4.28 \text{ m}.$

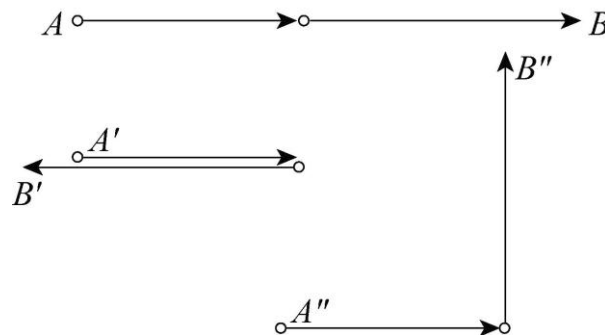
b The horizontal distance is $d \cos \theta = 11.7 \text{ m}.$

7. a the vectors should be parallel to achieve a resultant 7 m long the unprimed case shown below

b anti parallel in opposite directions to achieve a resultant 1 m long primed case shown

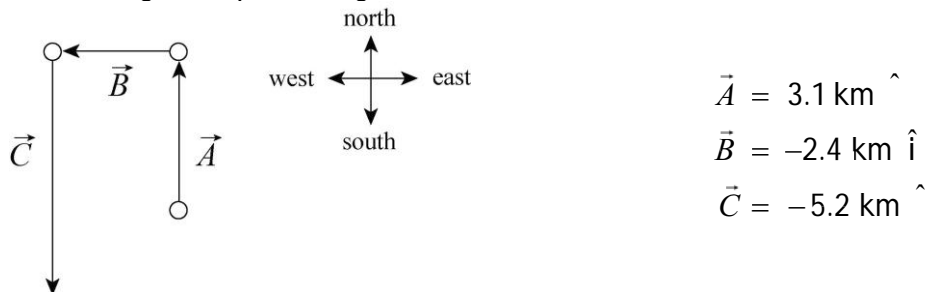
c and perpendicular to achieve a resultant $\sqrt{3^2 + 4^2} = 5$ m long the double primed case shown.

In each sketch the vectors are shown in a “head to tail” sketch but the resultant is not shown. The resultant could be a straight line drawn from beginning to end the beginning is indicated by A with or without primes as the case may be and the end is indicated by B .



8. We label the displacement vectors \vec{A} , \vec{B} and \vec{C} and denote the result of their vector sum as \vec{r} . We choose *east* as the \hat{i} direction (x direction) and *north* as the \hat{j} direction (y direction). All distances are understood to be in kilometers.

a the vector diagram representing the motion is shown next



b the final point is represented by

$$\vec{r} = \vec{A} + \vec{B} + \vec{C} = -2.4 \text{ km } \hat{i} + -2.1 \text{ km } \hat{j}$$

whose magnitude is

$$|\vec{r}| = \sqrt{(-2.4 \text{ km})^2 + (-2.1 \text{ km})^2} \approx 3.2 \text{ km}.$$

c there are two possibilities for the angle

$$\theta = \tan^{-1} \left(\frac{-2.1 \text{ km}}{-2.4 \text{ km}} \right) = 41^\circ \text{ or } 221^\circ.$$

we choose the latter possibility since \vec{r} is in the third quadrant. It should be noted that many graphical calculators have polar \leftrightarrow rectangular “shortcuts” that automatically produce the correct answer for angle measured counterclockwise from the x axis. We may phrase the angle then as 221° counterclockwise from east—a phrasing that sounds peculiar at best—or as 41° south from east or 49° east from south. The resultant \vec{r} is not shown in our sketch; it could be an arrow directed from the “tail” of \vec{A} to the “head” of \vec{C} .

9. All distances in this solution are understood to be in meters.

$$a \quad \vec{a} + \vec{b} = 4.0\hat{i} - 1.0\hat{j} + (-3.0\hat{i} + 1.0\hat{j}) + 1.0\hat{i} + 4.0\hat{k} = 3.0\hat{i} - 2.0\hat{j} + 5.0\hat{k} \text{ m.}$$

$$b \quad \vec{a} - \vec{b} = 4.0\hat{i} - 1.0\hat{j} - (-3.0\hat{i} - 1.0\hat{j}) + 1.0\hat{i} - 4.0\hat{k} = 5.0\hat{i} - 4.0\hat{j} - 3.0\hat{k} \text{ m.}$$

c The requirement $\vec{a} - \vec{b} + \vec{c} = 0$ leads to $\vec{c} = \vec{b} - \vec{a}$, which we note is the opposite of what we found in part b. Thus $\vec{c} = -5.0\hat{i} + 4.0\hat{j} + 3.0\hat{k} \text{ m.}$

10. The x , y and z components of $\vec{r} = \vec{c} + \vec{d}$ are respectively

$$a \quad r_x = c_x + d_x = 7.4 \text{ m} + 4.4 \text{ m} = 12 \text{ m}$$

$$b \quad r_y = c_y + d_y = -3.8 \text{ m} - 2.0 \text{ m} = -5.8 \text{ m} \text{ and}$$

$$c \quad r_z = c_z + d_z = -6.1 \text{ m} + 3.3 \text{ m} = -2.8 \text{ m.}$$

11. **THINK** This problem involves the addition of two vectors \vec{a} and \vec{b} . We want to find the magnitude and direction of the resulting vector.

EXPRESS In two dimensions a vector \vec{a} can be written as in unit vector notation

$$\vec{a} = a_x\hat{i} + a_y\hat{j}.$$

Similarly a second vector \vec{b} can be expressed as $\vec{b} = b_x\hat{i} + b_y\hat{j}$. Adding the two vectors gives

$$\vec{r} = \vec{a} + \vec{b} = a_x\hat{i} + b_x\hat{i} + a_y\hat{j} + b_y\hat{j} = r_x\hat{i} + r_y\hat{j}$$

ANALYZE We are given that $\vec{a} = 4.0 \text{ m}\hat{i} + 3.0 \text{ m}\hat{j}$ and $\vec{b} = -13.0 \text{ m}\hat{i} + 7.0 \text{ m}\hat{j}$. We find the x and the y components of \vec{r} to be

$$\begin{array}{rcl} r_x = a_x & b_x = 4.0 \text{ m} & -13 \text{ m} = -9.0 \text{ m} \\ r_y = a_y & b_y = 3.0 \text{ m} & 7.0 \text{ m} = 10.0 \text{ m}. \end{array}$$

thus $\vec{r} = -9.0 \text{ m } \hat{i} + 10 \text{ m } \hat{j}$.

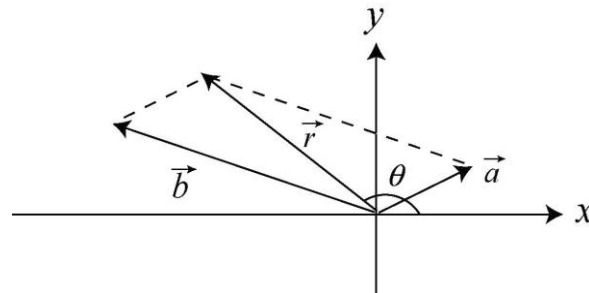
b the magnitude of \vec{r} is $r = |\vec{r}| = \sqrt{r_x^2 + r_y^2} = \sqrt{(-9.0 \text{ m})^2 + (10 \text{ m})^2} = 13 \text{ m}$.

c the angle between the resultant and the x axis is given by

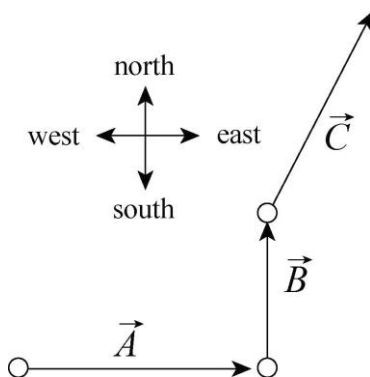
$$\theta = \tan^{-1}\left(\frac{r_y}{r_x}\right) = \tan^{-1}\left(\frac{10.0 \text{ m}}{-9.0 \text{ m}}\right) = -48^\circ \text{ or } 132^\circ.$$

Since the x component of the resultant is negative and the y component is positive characteristic of the second quadrant the angle is 132° measured counterclockwise from the x axis.

LEARN The addition of the two vectors is depicted in the figure below (not to scale). Indeed since $r_x < 0$ and $r_y > 0$ we expect \vec{r} to be in the second quadrant.



12. We label the displacement vectors \vec{A} , \vec{B} , and \vec{C} and denote the result of their vector sum as \vec{r} . We choose *east* as the \hat{i} direction (x direction) and *north* as the \hat{j} direction (y direction). We note that the angle between \vec{C} and the x axis is 60° . Thus



$$\vec{A} = 50 \text{ km } \hat{i}$$

$$\vec{B} = 30 \text{ km } \hat{j}$$

$$\vec{C} = 25 \text{ km } \cos(60^\circ) \hat{i} + 25 \text{ km } \sin(60^\circ) \hat{j}$$

a The total displacement of the car from its initial position is represented by

$$\vec{r} = \vec{A} + \vec{B} + \vec{C} = 62.5 \text{ km } \hat{i} + 51.7 \text{ km } \hat{j}$$

which means that its magnitude is

$$|\vec{r}| = \sqrt{62.5^2 + 51.7^2} = 81 \text{ km.}$$

b The angle counterclockwise from the x axis is $\tan^{-1} \frac{51.7 \text{ km}}{62.5 \text{ km}} = 40^\circ$ which is to say that it points 40° north of east. Although the resultant \vec{r} is shown in our sketch it could be a direct line from the “tail” of \vec{A} to the “head” of \vec{C} .

13. We find the components and then add them as scalars not vectors. With $d = 3.40$ km and $\theta = 35.0^\circ$ we find $d \cos \theta = 2.78$ km and $d \sin \theta = 1.94$ km.

14. a Summing the x components we have

$$20 \text{ m} + b_x - 20 \text{ m} - 60 \text{ m} = -140 \text{ m}$$

which gives $b_x = -80 \text{ m}$.

b Summing the y components we have

$$60 \text{ m} - 70 \text{ m} + c_y - 70 \text{ m} = 30 \text{ m}$$

which implies $c_y = 110 \text{ m}$.

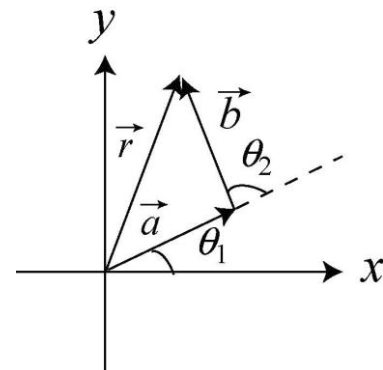
c Using the Pythagorean theorem the magnitude of the overall displacement is given by $\sqrt{(-140 \text{ m})^2 + (30 \text{ m})^2} \approx 143 \text{ m}$.

d The angle is given by $\tan^{-1} \frac{30}{-140} = -12^\circ$ which could be 12° measured clockwise from the $-x$ axis or 168° measured counterclockwise from the x axis.

15. **THINK** This problem involves the addition of two vectors \vec{a} and \vec{b} in two dimensions. We’re asked to find the components, magnitude and direction of the resulting vector.

EXPRESS In two dimensions a vector \vec{a} can be written as in unit vector notation

$$\vec{a} = a_x \hat{i} + a_y \hat{j} = a \cos \alpha \hat{i} + a \sin \alpha \hat{j}.$$



imilarly a second vector \vec{b} can be expressed as $\vec{b} = b_x \hat{i} + b_y \hat{j} = b \cos \beta \hat{i} + b \sin \beta \hat{j}$.
 From the figure we have $\alpha = \theta_1$ and $\beta = \theta_1 + \theta_2$ since the angles are measured from the x axis and the resulting vector is

$$\vec{r} = \vec{a} + \vec{b} = a \cos \theta_1 + b \cos (\theta_1 + \theta_2) \hat{i} + a \sin \theta_1 + b \sin (\theta_1 + \theta_2) \hat{j} = r_x \hat{i} + r_y \hat{j}$$

ANALYZE a Given that $a = b = 10$ m $\theta_1 = 30^\circ$ and $\theta_2 = 105^\circ$ the x component of \vec{r} is

$$r_x = a \cos \theta_1 + b \cos (\theta_1 + \theta_2) = 10 \text{ m} \cos 30^\circ + 10 \text{ m} \cos (30^\circ + 105^\circ) = 1.59 \text{ m}$$

b Similarly the y component of \vec{r} is

$$r_y = a \sin \theta_1 + b \sin (\theta_1 + \theta_2) = 10 \text{ m} \sin 30^\circ + 10 \text{ m} \sin (30^\circ + 105^\circ) = 12.1 \text{ m}.$$

c The magnitude of \vec{r} is $r = |\vec{r}| = \sqrt{1.59^2 + 12.1^2} = 12.2 \text{ m}.$

d The angle between \vec{r} and the x axis is

$$\theta = \tan^{-1} \left(\frac{r_y}{r_x} \right) = \tan^{-1} \left(\frac{12.1 \text{ m}}{1.59 \text{ m}} \right) = 82.5^\circ.$$

LEARN As depicted in the figure the resultant \vec{r} lies in the first quadrant. This is what we expect. Note that the magnitude of \vec{r} can also be calculated by using law of cosine \vec{a} , \vec{b} and \vec{r} form an isosceles triangle

$$r = \sqrt{a^2 + b^2 - 2ab \cos 180 - \theta_2} = \sqrt{10^2 + 10^2 - 2 \cdot 10 \cdot 10 \cos 75^\circ} = 12.2 \text{ m}.$$

16. a $\vec{a} + \vec{b} = 3.0 \hat{i} + 4.0 \hat{j} \text{ m} + 5.0 \hat{i} - 2.0 \hat{j} \text{ m} = 8.0 \text{ m} \hat{i} + 2.0 \text{ m} \hat{j}.$

b The magnitude of $\vec{a} + \vec{b}$ is

$$|\vec{a} + \vec{b}| = \sqrt{8.0^2 + 2.0^2} = 8.2 \text{ m}.$$

c The angle between this vector and the x axis is

$$\tan^{-1} \frac{2.0 \text{ m}}{8.0 \text{ m}} = 14^\circ.$$

d $\vec{b} - \vec{a} = 5.0 \hat{i} - 2.0 \hat{j} \text{ m} - 3.0 \hat{i} + 4.0 \hat{j} \text{ m} = 2.0 \text{ m} \hat{i} - 6.0 \text{ m} \hat{j}.$

e The magnitude of the difference vector $\vec{b} - \vec{a}$ is

$$\vec{b} - \vec{a} = \sqrt{2.0 \text{ m}^2 + -6.0 \text{ m}^2} = 6.3 \text{ m}.$$

f The angle between this vector and the x axis is $\tan^{-1} \frac{-6.0 \text{ m}}{2.0 \text{ m}} = -72^\circ$. The vector is 72° clockwise from the x axis defined by \hat{i} .

17. Many of the operations are done efficiently on most modern graphical calculators using their built in vector manipulation and rectangular \leftrightarrow polar “shortcuts.” In this solution we employ the “traditional” methods (such as Eq. 3-6). Here the length unit is not displayed; the unit meter should be understood.

a Using unit vector notation

$$\vec{a} = 50 \text{ m} \cos 30^\circ \hat{i} + 50 \text{ m} \sin 30^\circ \hat{j}$$

$$\vec{b} = 50 \text{ m} \cos 195^\circ \hat{i} + 50 \text{ m} \sin 195^\circ \hat{j}$$

$$\vec{c} = 50 \text{ m} \cos 315^\circ \hat{i} + 50 \text{ m} \sin 315^\circ \hat{j}$$

$$\vec{a} + \vec{b} + \vec{c} = 30.4 \text{ m} \hat{i} - 23.3 \text{ m} \hat{j}.$$

The magnitude of this result is $\sqrt{30.4 \text{ m}^2 + -23.3 \text{ m}^2} = 38 \text{ m}$.

b The two possibilities presented by a simple calculation for the angle between the vector described in part a and the x direction are $\tan^{-1} \frac{-23.2 \text{ m}}{30.4 \text{ m}} = -37.5^\circ$ and $180^\circ - 37.5^\circ = 142.5^\circ$. The former possibility is the correct answer since the vector is in the fourth quadrant indicated by the signs of its components. Thus the angle is -37.5° which is to say that it is 37.5° clockwise from the x axis. This is equivalent to 322.5° counterclockwise from x .

c We find

$$\vec{a} - \vec{b} + \vec{c} = 43.3 - -48.3 + 35.4 \hat{i} - 25 - -12.9 + -35.4 \hat{j} = 127 \hat{i} + 2.6 \hat{j} \text{ m}$$

in unit vector notation. The magnitude of this result is

$$\vec{a} - \vec{b} + \vec{c} = \sqrt{127 \text{ m}^2 + 2.6 \text{ m}^2} \approx 1.30 \times 10^2 \text{ m}.$$

d The angle between the vector described in part c and the x axis is $\tan^{-1} \frac{2.6 \text{ m}}{127 \text{ m}} \approx 1.2^\circ$.

Using unit vector notation \vec{d} is given by $\vec{d} = \vec{a} + \vec{b} - \vec{c} = -40.4 \hat{i} + 47.4 \hat{j}$ m which has a magnitude of $\sqrt{(-40.4 \text{ m})^2 + (47.4 \text{ m})^2} = 62 \text{ m}$.

The two possibilities presented by a simple calculation for the angle between the vector described in part e and the x axis are $\tan^{-1} \frac{47.4}{-40.4} = -50.0^\circ$ and $180^\circ + -50.0^\circ = 130^\circ$. We choose the latter possibility as the correct one since it indicates that \vec{d} is in the second quadrant indicated by the signs of its components.

18. If we wish to use 3.5 in an unmodified fashion we should note that the angle between \vec{C} and the x axis is $180^\circ - 20.0^\circ = 200^\circ$.

a The x and y components of \vec{B} are given by

$$\begin{aligned} B_x &= C_x - A_x = 15.0 \text{ m} \cos 200^\circ - 12.0 \text{ m} \cos 40^\circ = -23.3 \text{ m} \\ B_y &= C_y - A_y = 15.0 \text{ m} \sin 200^\circ - 12.0 \text{ m} \sin 40^\circ = -12.8 \text{ m}. \end{aligned}$$

Consequently its magnitude is $B = \sqrt{(-23.3 \text{ m})^2 + (-12.8 \text{ m})^2} = 26.6 \text{ m}$.

b The two possibilities presented by a simple calculation for the angle between \vec{B} and the x axis are $\tan^{-1} \frac{-12.8 \text{ m}}{-23.3 \text{ m}} = 28.9^\circ$ and $180^\circ - 28.9^\circ = 209^\circ$. We choose the latter possibility as the correct one since it indicates that \vec{B} is in the third quadrant indicated by the signs of its components. We note too that the answer can be equivalently stated as -151° .

19. a With i directed forward and j directed left and the resultant is $5.00 \hat{i} - 2.00 \hat{j}$ m. The magnitude is given by the Pythagorean theorem $\sqrt{(5.00 \text{ m})^2 + (2.00 \text{ m})^2} = 5.385 \text{ m} \approx 5.39 \text{ m}$.

b The angle is $\tan^{-1} \frac{2.00}{5.00} \approx 21.8^\circ$ left of forward.

20. The desired result is the displacement vector in units of km $\vec{A} = 5.6 \text{ km} \cdot 90^\circ$ measured counterclockwise from the x axis or $\vec{A} = 5.6 \text{ km} \hat{j}$ here \hat{j} is the unit vector along the positive y axis north. This consists of the sum of two displacements during the hikeout $\vec{B} = 7.8 \text{ km} \cdot 50^\circ$ or

$$\vec{B} = 7.8 \text{ km} (\cos 50^\circ \hat{i} + \sin 50^\circ \hat{j}) = 5.01 \text{ km} \hat{i} + 5.98 \text{ km} \hat{j}$$

and the unknown \vec{C} . Thus $\vec{A} = \vec{B} + \vec{C}$.

a The desired displacement is given by $\vec{C} = \vec{A} - \vec{B} = -5.01 \text{ km } \hat{i} - 0.38 \text{ km } \hat{j}$. The magnitude is $\sqrt{(-5.01 \text{ km})^2 + (-0.38 \text{ km})^2} = 5.0 \text{ km}$.

b The angle is $\tan^{-1} \frac{-0.38 \text{ km}}{-5.01 \text{ km}} = 4.3^\circ$ south of due west.

21. Reading carefully we see that the x , y specifications for each “dart” are to be interpreted as Δx , Δy descriptions of the corresponding displacement vectors. We combine the different parts of this problem into a single equation position.

a Along the x axis we have with the centimeter unit understood

$$30.0 + b_x - 20.0 - 80.0 = -140$$

which gives $b_x = -70.0 \text{ cm}$.

b Along the y axis we have

$$40.0 - 70.0 + c_y - 70.0 = -20.0$$

which yields $c_y = 80.0 \text{ cm}$.

c The magnitude of the final location -140 , -20.0 is $\sqrt{(-140)^2 + (-20.0)^2} = 141 \text{ cm}$.

d Since the displacement is in the third quadrant the angle of the overall displacement is given by $\pi - \tan^{-1} \frac{-20.0}{-140}$ or 188° counterclockwise from the x axis or -172° counterclockwise from the x axis.

22. Angles are given in ‘standard’ fashion so Eq. 3.5 applies directly. We use this to write the vectors in unit vector notation before adding them. However a very different looking approach using the special capabilities of most graphical calculators can be imagined. However the length unit is not displayed in the solution below the unit meter should be understood.

a Looking for the different angle units used in the problem statement we arrive at

$$\vec{E} = 3.73 \hat{i} + 4.70 \hat{j}$$

$$\vec{F} = 1.29 \hat{i} - 4.83 \hat{j}$$

$$\vec{G} = 1.45 \hat{i} + 3.73 \hat{j}$$

$$\vec{H} = -5.20 \hat{i} + 3.00 \hat{j}$$

$$\vec{E} + \vec{F} + \vec{G} + \vec{H} = 1.28 \hat{i} + 6.60 \hat{j}$$

b The magnitude of the vector sum found in part a is $\sqrt{(1.28 \text{ m})^2 + (6.60 \text{ m})^2} = 6.72 \text{ m}$.

c its angle measured counterclockwise from the x axis is $\tan^{-1} 6.60/1.28 = 79.0^\circ$.

d Using the conversion factor $\pi \text{ rad} = 180^\circ$ $79.0^\circ = 1.38 \text{ rad}$.

23. The resultant along the y axis with the same magnitude as \vec{C} forms along with \vec{C} a side of an isosceles triangle with \vec{B} forming the base. If the angle between \vec{C} and the y axis is $\theta = \tan^{-1} 3/4 = 36.87^\circ$ then it should be clear that referring to the magnitudes of the vectors $B = 2C \sin \theta$. Thus since $C = 5.0$ we find $B = 3.2$.

24. This is a vector addition problem. We express the situation described in the problem statement as $\vec{A} + \vec{B} = 3\vec{A}$ here $\vec{A} = A\hat{i}$ and $B = 7.0 \text{ m}$. Since $\hat{i} \perp \hat{j}$ we may use the Pythagorean theorem to express B in terms of the magnitudes of the other two vectors

$$B = \sqrt{3A^2 - A^2} \Rightarrow A = \frac{1}{\sqrt{10}} B = 2.2 \text{ m}.$$

25. The strategy is to find where the camel is \vec{C} by adding the two consecutive displacements described in the problem and then finding the difference between that location and the oasis \vec{B} . Using the magnitude-angle notation

$$\vec{C} = 24 \angle -15^\circ + 8.0 \angle 90^\circ = 23.25 \angle 4.41^\circ$$

so

$$\vec{B} - \vec{C} = 25 \angle 0^\circ - 23.25 \angle 4.41^\circ = 2.5 \angle -45^\circ$$

which is efficiently implemented using a vector capable calculator in polar mode. The distance is therefore 2.6 km.

26. The vector equation is $\vec{R} = \vec{A} + \vec{B} + \vec{C} + \vec{D}$. Expressing \vec{B} and \vec{D} in unit vector notation we have $1.69\hat{i} + 3.63\hat{j} \text{ m}$ and $-2.87\hat{i} + 4.10\hat{j} \text{ m}$ respectively. Here the length unit is not displayed in the solution below the unit meter should be understood.

a Adding corresponding components we obtain $\vec{R} = -3.18 \text{ m } \hat{i} + 4.72 \text{ m } \hat{j}$.

b Using 3.6 the magnitude is

$$R = \sqrt{(-3.18 \text{ m})^2 + (4.72 \text{ m})^2} = 5.69 \text{ m}.$$

c The angle is

$$\theta = \tan^{-1} \left(\frac{4.72 \text{ m}}{-3.18 \text{ m}} \right) = -56.0^\circ \quad \text{with } -x \text{ axis}.$$

If measured counterclockwise from the x -axis the angle is then $180^\circ - 56.0^\circ = 124^\circ$. Thus converting the result to polar coordinates we obtain

$$(-3.18, 4.72) \rightarrow (5.69 \angle 124^\circ)$$

27. Solving the simultaneous equations yields the answers

a $\vec{d}_1 = 4\vec{d}_3 = 8\hat{i} - 16\hat{j}$ and

b $\vec{d}_2 = \vec{d}_3 = 2\hat{i} - 4\hat{j}$.

28. Let \vec{A} represent the first part of Beetle 1's trip (0.50 m east or $0.5\hat{i}$) and \vec{C} represent the first part of Beetle 2's trip intended voyage (1.6 m at 50° north of east). For their respective second parts \vec{B} is 0.80 m at 30° north of east and \vec{D} is the unknown. The final position of Beetle 1 is

$$\vec{A} + \vec{B} = 0.5\text{ m}\hat{i} + 0.8\text{ m}\cos 30^\circ\hat{i} + \sin 30^\circ\hat{j} = 1.19\text{ m}\hat{i} + 0.40\text{ m}\hat{j}.$$

The equation relating these is $\vec{A} + \vec{B} = \vec{C} + \vec{D}$ here

$$\vec{C} = 1.60\text{ m}\cos 50.0^\circ\hat{i} + \sin 50.0^\circ\hat{j} = 1.03\text{ m}\hat{i} + 1.23\text{ m}\hat{j}$$

a We find $\vec{D} = \vec{A} + \vec{B} - \vec{C} = 0.16\text{ m}\hat{i} - 0.83\text{ m}\hat{j}$ and the magnitude is $D = 0.84\text{ m}$.

b The angle is $\tan^{-1} \frac{-0.83}{0.16} = -79^\circ$ which is interpreted to mean 79° south of east or 11° east of south.

29. Let $l_0 = 2.0\text{ cm}$ be the length of each segment. The nest is located at the endpoint of segment w .

a Using unit vector notation the displacement vector for point A is

$$\begin{aligned}\vec{d}_A &= \vec{w} + \vec{v} + \vec{i} + \vec{h} = l_0 \cos 60^\circ\hat{i} + \sin 60^\circ\hat{j} + (l_0\hat{j}) + l_0 \cos 120^\circ\hat{i} + \sin 120^\circ\hat{j} + (l_0\hat{i}) \\ &= (2 + \sqrt{3})l_0\hat{i}.\end{aligned}$$

Therefore the magnitude of \vec{d}_A is $d_A = (2 + \sqrt{3})2.0\text{ cm} = 7.5\text{ cm}$.

b The angle of \vec{d}_A is $\theta = \tan^{-1} \frac{d_{A,y}}{d_{A,x}} = \tan^{-1} \infty = 90^\circ$.

c Similarly the displacement for point B is

$$\begin{aligned}
 \vec{d}_B &= \vec{w} + \vec{v} + \vec{j} + \vec{p} + \vec{o} \\
 &= l_0 \cos 60^\circ \hat{i} + \sin 60^\circ \hat{j} + (l_0 \hat{j}) + l_0 \cos 60^\circ \hat{i} + \sin 60^\circ \hat{j} + l_0 \cos 30^\circ \hat{i} + \sin 30^\circ \hat{j} + (l_0 \hat{i}) \\
 &= 2 + \sqrt{3} \quad 2 l_0 \hat{i} + 3 \quad 2 + \sqrt{3} l_0 \hat{j}.
 \end{aligned}$$

herefore the magnitude of \vec{d}_B is

$$|\vec{d}_B| = l_0 \sqrt{(2 + \sqrt{3})^2 + (3 + 2 + \sqrt{3})^2} = 2.0 \text{ cm} \cdot 4.3 = 8.6 \text{ cm}.$$

d the direction of \vec{d}_B is

$$\theta_B = \tan^{-1} \left(\frac{d_{B,y}}{d_{B,x}} \right) = \tan^{-1} \left(\frac{3 + 2 + \sqrt{3}}{2 + \sqrt{3}} \right) = \tan^{-1} 1.13 = 48^\circ.$$

30. any of the operations are done efficiently on most modern graphical calculators using their built in vector manipulation and rectangular \leftrightarrow polar “shortcuts.” In this solution we employ the “traditional” methods (such as Eq. 3.6).

a the magnitude of \vec{a} is $a = \sqrt{4.0 \text{ m}^2 + (-3.0 \text{ m})^2} = 5.0 \text{ m}.$

b the angle between \vec{a} and the x axis is $\tan^{-1} \frac{-3.0 \text{ m}}{4.0 \text{ m}} = -37^\circ$. the vector is 37° clockwise from the x axis defined by \hat{i} .

c the magnitude of \vec{b} is $b = \sqrt{6.0 \text{ m}^2 + 8.0 \text{ m}^2} = 10 \text{ m}.$

d the angle between \vec{b} and the x axis is $\tan^{-1} \frac{8.0 \text{ m}}{6.0 \text{ m}} = 53^\circ.$

e $\vec{a} + \vec{b} = 4.0 \text{ m} \hat{i} + 6.0 \text{ m} \hat{j} - 3.0 \text{ m} \hat{i} + 8.0 \text{ m} \hat{j} = 1.0 \text{ m} \hat{i} + 14.0 \text{ m} \hat{j}$. the magnitude of this vector is $|\vec{a} + \vec{b}| = \sqrt{1.0^2 + 14.0^2} = 14.0 \text{ m}$ (round to two significant figures in our results).

f the angle between the vector described in part e and the x axis is $\tan^{-1} \frac{14.0 \text{ m}}{1.0 \text{ m}} = 86^\circ.$

g $\vec{b} - \vec{a} = 6.0 \text{ m} \hat{i} + 8.0 \text{ m} \hat{j} - 4.0 \text{ m} \hat{i} - 3.0 \text{ m} \hat{j} = 2.0 \text{ m} \hat{i} + 5.0 \text{ m} \hat{j}$. the magnitude of this vector is $|\vec{b} - \vec{a}| = \sqrt{2.0^2 + 5.0^2} = 5.4 \text{ m}$ which is interestingly the same result as in part e (we actually not just to 2 significant figures this curious coincidence is made possible by the fact that $\vec{a} \perp \vec{b}$).

h The angle between the vector described in part g and the x axis is $\tan^{-1} \frac{11 \text{ m}}{2.0 \text{ m}} = 80^\circ$.

i $\vec{a} - \vec{b} = 4.0 \text{ m} \hat{i} - 6.0 \text{ m} \hat{j} - 3.0 \text{ m} \hat{k} - 8.0 \text{ m} \hat{k} = -2.0 \text{ m} \hat{i} - 11 \text{ m} \hat{k}$. The magnitude of this vector is

$$|\vec{a} - \vec{b}| = \sqrt{(-2.0 \text{ m})^2 + (-11 \text{ m})^2} = 11 \text{ m}.$$

The two possibilities presented by a simple calculation for the angle between the vector described in part i and the x direction are $\tan^{-1} \frac{11 \text{ m}}{2.0 \text{ m}} = 80^\circ$ and $180^\circ - 80^\circ = 100^\circ$. The latter possibility is the correct answer (see part k for a further observation related to this result).

k Since $\vec{a} - \vec{b} = -(\vec{b} - \vec{a})$ they point in opposite (anti-parallel) directions the angle between them is 180° .

31. a With $a = 17.0 \text{ m}$ and $\theta = 56.0^\circ$ we find $a_x = a \cos \theta = 9.51 \text{ m}$.

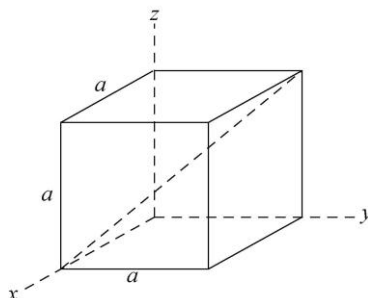
b Similarly $a_y = a \sin \theta = 14.1 \text{ m}$.

c The angle relative to the new coordinate system is $\theta' = 56.0^\circ - 18.0^\circ = 38.0^\circ$. Thus $a'_x = a \cos \theta' = 13.4 \text{ m}$.

d Similarly $a'_y = a \sin \theta' = 10.5 \text{ m}$.

32. a As can be seen from Figure 3-30 the point diametrically opposite the origin $(0, 0, 0)$ has position vector $a \hat{i} + a \hat{j} + a \hat{k}$ and this is the vector along the “body diagonal.”

b From the point $(a, 0, 0)$ which corresponds to the position vector $a \hat{i}$ the diametrically opposite point is $(0, a, a)$ with the position vector $a \hat{j} + a \hat{k}$. Thus the vector along the line is the difference $-a \hat{i} + a \hat{j} + a \hat{k}$.



c If the starting point is $(0, a, 0)$ with the corresponding position vector $a \hat{j}$ the diametrically opposite point is $(a, 0, a)$ with the position vector $a \hat{i} + a \hat{k}$. Thus the vector along the line is the difference $a \hat{i} - a \hat{j} + a \hat{k}$.

d If the starting point is $(a, a, 0)$ with the corresponding position vector $a\hat{i} + a\hat{j}$ the diametrically opposite point is $(0, 0, a)$ with the position vector $a\hat{k}$. Thus the vector along the line is the difference $-a\hat{i} - a\hat{j} + a\hat{k}$.

e Consider the vector from the back lower left corner to the front upper right corner. It is $a\hat{i} + a\hat{j} + a\hat{k}$. We may think of it as the sum of the vector $a\hat{i}$ parallel to the x axis and the vector $a\hat{j} + a\hat{k}$ perpendicular to the x axis. The tangent of the angle between the vector and the x axis is the perpendicular component divided by the parallel component.

Since the magnitude of the perpendicular component is $\sqrt{a^2 + a^2} = a\sqrt{2}$ and the magnitude of the parallel component is $a \tan \theta = (a\sqrt{2}) \Rightarrow a = \sqrt{2}$. Thus $\theta = 54.7^\circ$. The angle between the vector and each of the other two adjacent sides the y and z axes is the same as is the angle between any of the other diagonal vectors and any of the cube sides adjacent to them.

f The length of any of the diagonals is given by $\sqrt{a^2 + a^2 + a^2} = a\sqrt{3}$.

33. Examining the figure we see that $\vec{a} + \vec{b} + \vec{c} = 0$ here $\vec{a} \perp \vec{b}$.

a $|\vec{a} \times \vec{b}| = 3.0 \cdot 4.0 = 12$ since the angle between them is 90° .

b Using the right hand rule the vector $\vec{a} \times \vec{b}$ points in the $\hat{i} \times \hat{j} = \hat{k}$ or the z direction.

c $\vec{a} \times \vec{c} = \vec{a} \times (-\vec{a} - \vec{b}) = -(\vec{a} \times \vec{b}) = 12$.

d The vector $-\vec{a} \times \vec{b}$ points in the $-\hat{i} \times \hat{j} = -\hat{k}$ or the $-z$ direction.

e $\vec{b} \times \vec{c} = \vec{b} \times (-\vec{a} - \vec{b}) = -(\vec{b} \times \vec{a}) = (\vec{a} \times \vec{b}) = 12$.

f The vector points in the z direction as in part a.

34. We apply 3.23 and 3.27.

a $\vec{a} \times \vec{b} = a_x b_y - a_y b_x \hat{k}$ since all other terms vanish due to the fact that neither \vec{a} nor \vec{b} have any z components. Consequently we obtain $3.0 \cdot 4.0 - 5.0 \cdot 2.0 \hat{k} = 2.0 \hat{k}$.

b $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y$ yields $3.0 \cdot 2.0 + 5.0 \cdot 4.0 = 26$.

c $\vec{a} + \vec{b} = 3.0 + 2.0 \hat{i} + 5.0 + 4.0 \hat{j} \Rightarrow \vec{a} + \vec{b} \cdot \vec{b} = 5.0 \cdot 2.0 + 9.0 \cdot 4.0 = 46$.

Several approaches are available. In this solution we will construct a \hat{b} unit vector and “dot” it (take the scalar product of it with \vec{a}). In this case we make the desired unit vector by

$$\hat{b} = \frac{\vec{b}}{b} = \frac{2.0\hat{i} + 4.0\hat{j}}{\sqrt{2.0^2 + 4.0^2}}.$$

We therefore obtain

$$a_b = \vec{a} \cdot \hat{b} = \frac{3.0(2.0) + 5.0(4.0)}{\sqrt{2.0^2 + 4.0^2}} = 5.8.$$

35. a. The scalar or dot product is $4.50(7.30)\cos 320^\circ - 85.0 = -18.8$.

b. The vector or cross product is in the k direction by the right hand rule with magnitude $4.50(7.30)\sin 320^\circ - 85.0 = 26.9$.

36. First we rewrite the given expression as $4\vec{d}_{\text{plane}} \cdot \vec{d}_{\text{cross}}$ here $\vec{d}_{\text{plane}} = \vec{d}_1 \times \vec{d}_2$ and in the plane of \vec{d}_1 and \vec{d}_2 and $\vec{d}_{\text{cross}} = \vec{d}_1 \times \vec{d}_2$. Noting that \vec{d}_{cross} is perpendicular to the plane of \vec{d}_1 and \vec{d}_2 we see that the answer must be 0 the scalar or dot product of perpendicular vectors is zero.

37. We apply 3.23 and 3.27. If a vector capable calculator is used this makes a good exercise for getting familiar with those features. Here we briefly sketch the method.

a. We note that $\vec{b} \times \vec{c} = -8.0\hat{i} + 5.0\hat{j} + 6.0\hat{k}$. Thus

$$\vec{a} \cdot \vec{b} \times \vec{c} = 3.0(-8.0) + 3.0(5.0) + (-2.0)(6.0) = -21.$$

b. We note that $\vec{b} \cdot \vec{c} = 1.0\hat{i} - 2.0\hat{j} \cdot 3.0\hat{k}$. Thus

$$\vec{a} \cdot \vec{b} + \vec{c} = 3.0(1.0) + 3.0(-2.0) + (-2.0)(3.0) = -9.0.$$

c. Finally

$$\begin{aligned} \vec{a} \times (\vec{b} \cdot \vec{c}) &= 3.0(3.0) - (-2.0)(-2.0)\hat{i} + (-2.0)(1.0) - 3.0(3.0)\hat{j} \\ &\quad + 3.0(-2.0) - 3.0(1.0)\hat{k} \\ &= 5\hat{i} - 11\hat{j} - 9\hat{k} \end{aligned}$$

38. Using the fact that

$$\hat{i} \times \hat{j} = \hat{k} \quad \hat{j} \times \hat{k} = \hat{i} \quad \hat{k} \times \hat{i} = \hat{j}$$

We obtain

$$2\vec{A} \times \vec{B} = 2(2.00\hat{i} + 3.00\hat{j} - 4.00\hat{k}) \times (-3.00\hat{i} + 4.00\hat{j} + 2.00\hat{k})$$

$$= 44.0\hat{i} + 16.0\hat{j} + 34.0\hat{k}.$$

Using the making use of

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$$

we have

$$3\vec{C} \cdot (2\vec{A} \times \vec{B}) = 3(7.00\hat{i} - 8.00\hat{j}) \cdot (44.0\hat{i} + 16.0\hat{j} + 34.0\hat{k})$$

$$= 3(7.00 \cdot 44.0 - 8.00 \cdot 16.0 + 0 \cdot 34.0) = 540.$$

39. From the definition of the dot product between \vec{A} and \vec{B} , $\vec{A} \cdot \vec{B} = AB \cos \theta$ we have

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{AB}$$

With $A = 6.00$, $B = 7.00$ and $\vec{A} \cdot \vec{B} = 14.0$, $\cos \theta = 0.333$ or $\theta = 70.5^\circ$.

40. The displacement vectors can be written as in meters

$$\vec{d}_1 = 4.50 \text{ m} (\cos 63^\circ \hat{i} + \sin 63^\circ \hat{k}) = 2.04 \text{ m} \hat{i} + 4.01 \text{ m} \hat{k}$$

$$\vec{d}_2 = 1.40 \text{ m} (\cos 30^\circ \hat{i} + \sin 30^\circ \hat{k}) = 1.21 \text{ m} \hat{i} + 0.70 \text{ m} \hat{k}.$$

a. The dot product of \vec{d}_1 and \vec{d}_2 is

$$\vec{d}_1 \cdot \vec{d}_2 = 2.04 \hat{i} + 4.01 \hat{k} \cdot 1.21 \hat{i} + 0.70 \hat{k} = 4.01 \hat{k} \cdot 0.70 \hat{k} = 2.81 \text{ m}^2.$$

b. The cross product of \vec{d}_1 and \vec{d}_2 is

$$\vec{d}_1 \times \vec{d}_2 = 2.04 \hat{i} + 4.01 \hat{k} \times 1.21 \hat{i} + 0.70 \hat{k}$$

$$= 2.04 \cdot 1.21 (-\hat{k}) - 2.04 \cdot 0.70 \hat{i} + 4.01 \cdot 1.21 \hat{j}$$

$$= -1.43 \hat{i} + 4.86 \hat{j} - 2.48 \hat{k} \text{ m}^2.$$

c. The magnitudes of \vec{d}_1 and \vec{d}_2 are

$$d_1 = \sqrt{2.04^2 + 4.01^2} = 4.50 \text{ m}$$

$$d_2 = \sqrt{1.21^2 + 0.70^2} = 1.40 \text{ m}.$$

Thus the angle between the two vectors is

$$\theta = \cos^{-1} \left(\frac{\vec{d}_1 \cdot \vec{d}_2}{d_1 d_2} \right) = \cos^{-1} \left(\frac{2.81 \text{ m}^2}{4.50 \text{ m} \cdot 1.40 \text{ m}} \right) = 63.5^\circ.$$

41. **THINK** The angle between two vectors can be calculated using the definition of scalar product.

EXPRESS Since the scalar product of two vectors \vec{a} and \vec{b} is

$$\vec{a} \cdot \vec{b} = ab \cos \phi = a_x b_x + a_y b_y + a_z b_z$$

the angle between them is given by

$$\cos \phi = \frac{a_x b_x + a_y b_y + a_z b_z}{ab} \Rightarrow \phi = \cos^{-1} \left(\frac{a_x b_x + a_y b_y + a_z b_z}{ab} \right).$$

Since the magnitudes and components of the vectors are known, the angle ϕ can be readily calculated.

ANALYZE Given that $\vec{a} = 3.0 \hat{i} + 3.0 \hat{j} + 3.0 \hat{k}$ and $\vec{b} = 2.0 \hat{i} + 1.0 \hat{j} + 3.0 \hat{k}$, the magnitudes of the vectors are

$$a = |\vec{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2} = \sqrt{3.0^2 + 3.0^2 + 3.0^2} = 5.20$$

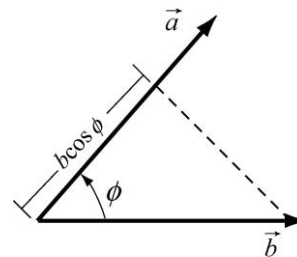
$$b = |\vec{b}| = \sqrt{b_x^2 + b_y^2 + b_z^2} = \sqrt{2.0^2 + 1.0^2 + 3.0^2} = 3.74.$$

The angle between them is found to be

$$\cos \phi = \frac{3.0 \cdot 2.0 + 3.0 \cdot 1.0 + 3.0 \cdot 3.0}{5.20 \cdot 3.74} = 0.926$$

or $\phi = 22^\circ$.

LEARN As the name implies, the scalar product or dot product between two vectors is a scalar quantity. It can be regarded as the product between the magnitude of one of the vectors and the scalar component of the second vector along the direction of the first one, as illustrated below (see also in Fig. 3-18 of the text).



$$\vec{a} \cdot \vec{b} = ab \cos \phi = a (b \cos \phi)$$

42. The two vectors are written as in unit of meters

$$\vec{d}_1 = 4.0\hat{i} - 5.0\hat{j} = d_{1x}\hat{i} + d_{1y}\hat{j} \quad \vec{d}_2 = -3.0\hat{i} + 4.0\hat{j} = d_{2x}\hat{i} + d_{2y}\hat{j}$$

a. The vector cross product gives

$$\vec{d}_1 \times \vec{d}_2 = d_{1x}d_{2y} - d_{1y}d_{2x} \hat{k} = (4.0)(4.0) - (-5.0)(-3.0) \hat{k} = 31 \hat{k}$$

b. The scalar dot product gives

$$\vec{d}_1 \cdot \vec{d}_2 = d_{1x}d_{2x} + d_{1y}d_{2y} = (4.0)(-3.0) + (-5.0)(4.0) = -8.0.$$

c.

$$\vec{d}_1 + \vec{d}_2 \cdot \vec{d}_2 = \vec{d}_1 \cdot \vec{d}_2 + d_2^2 = -8.0 + (-3.0)^2 + (4.0)^2 = 33.$$

d. Note that the magnitude of the d_1 vector is $\sqrt{16 + 25} = 6.4$. So the dot product is $6.4(-5.0) \cos \theta = -8$. Dividing both sides by 32 and taking the inverse cosine yields $\theta = 75.5^\circ$. Therefore the component of the d_1 vector along the direction of the d_2 vector is $6.4 \cos \theta \approx 1.6$.

43. **THINK** In this problem we are given three vectors \vec{a} , \vec{b} and \vec{c} on the xy plane and asked to calculate their components.

EXPRESS From the figure we note that $\vec{c} \perp \vec{b}$ which implies that the angle between \vec{c} and the x axis is $\theta + 90^\circ$. In unit vector notation the three vectors can be written as

$$\vec{a} = a_x \hat{i}$$

$$\vec{b} = b_x \hat{i} + b_y \hat{j} = b \cos \theta \hat{i} + b \sin \theta \hat{j}$$

$$\vec{c} = c_x \hat{i} + c_y \hat{j} = c \cos (\theta + 90^\circ) \hat{i} + c \sin (\theta + 90^\circ) \hat{j}.$$

The above expressions allow us to evaluate the components of the vectors.

ANALYZE a. The x component of \vec{a} is $a_x = a \cos 0^\circ = a = 3.00$ m.

b. Similarly the y component of \vec{a} is $a_y = a \sin 0^\circ = 0$.

c. The x component of \vec{b} is $b_x = b \cos 30^\circ = (4.00 \text{ m}) \cos 30^\circ = 3.46$ m

d. and the y component is $b_y = b \sin 30^\circ = (4.00 \text{ m}) \sin 30^\circ = 2.00$ m.

e. The x component of \vec{c} is $c_x = c \cos 120^\circ = (10.0 \text{ m}) \cos 120^\circ = -5.00$ m

f and the y component is $c_y = c \sin 30^\circ = 10.0 \text{ m} \sin 120^\circ = 8.66 \text{ m}$.

g The fact that $\vec{c} = p\vec{a} + q\vec{b}$ implies

$$\vec{c} = c_x \hat{i} + c_y \hat{j} = p(a_x \hat{i} + a_y \hat{j}) + q(b_x \hat{i} + b_y \hat{j}) = pa_x \hat{i} + qb_x \hat{i} + pb_y \hat{j} + qb_y \hat{j}$$

or

$$c_x = pa_x + qb_x \quad c_y = pb_y + qb_y.$$

Substituting the values found above we have

$$\begin{aligned} -5.00 \text{ m} &= p(3.00 \text{ m}) + q(3.46 \text{ m}) \\ 8.66 \text{ m} &= p(2.00 \text{ m}) + q(2.00 \text{ m}). \end{aligned}$$

Solving these equations we find $p = -6.67$.

Similarly $q = 4.33$ (note that it's easiest to solve for q first). The numbers p and q have no units.

LEARN This exercise shows that given two non parallel vectors in two dimensions the third vector can always be written as a linear combination of the first two.

44. Applying $\vec{F} = q\vec{v} \times \vec{B}$ here q is a scalar becomes

$$F_x \hat{i} + F_y \hat{j} + F_z \hat{k} = q(v_y B_z - v_z B_y) \hat{i} + q(v_z B_x - v_x B_z) \hat{j} + q(v_x B_y - v_y B_x) \hat{k}$$

which — plugging in values — leads to three equations

$$\begin{aligned} 4.0 &= 2(4.0 B_z - 6.0 B_y) \\ -20 &= 2(6.0 B_x - 2.0 B_z) \\ 12 &= 2(2.0 B_y - 4.0 B_x) \end{aligned}$$

Since we are told that $B_x = B_y$ the third equation leads to $B_y = -3.0$. Inserting this value into the first equation we find $B_z = -4.0$. Thus our answer is

$$\vec{B} = -3.0 \hat{i} - 3.0 \hat{j} - 4.0 \hat{k}.$$

45. The two vectors are given by

$$\begin{aligned} \vec{A} &= 8.00 \cos 130^\circ \hat{i} + 8.00 \sin 130^\circ \hat{j} = -5.14 \hat{i} + 6.13 \hat{j} \\ \vec{B} &= B_x \hat{i} + B_y \hat{j} = -7.72 \hat{i} - 9.20 \hat{j}. \end{aligned}$$

a The dot product of $5\vec{A} \cdot \vec{B}$ is

$$5\vec{A} \cdot \vec{B} = 5[-5.14\hat{i} + 6.13\hat{j}] \cdot [-7.72\hat{i} - 9.20\hat{j}] = 5[-5.14(-7.72) + 6.13(-9.20)] = -83.4.$$

b In unit vector notation

$$4\vec{A} \times 3\vec{B} = 12\vec{A} \times \vec{B} = 12[-5.14\hat{i} + 6.13\hat{j}] \times [-7.72\hat{i} - 9.20\hat{j}] = 12(94.6\hat{k}) = 1.14 \times 10^3 \hat{k}$$

c Note that the azimuthal angle is undefined for a vector along the z axis. Thus our result is " 1.14×10^3 θ not defined and $\phi = 0^\circ$."

d Since \vec{A} is in the xy plane and $\vec{A} \times \vec{B}$ is perpendicular to that plane then the answer is 90° .

e Clearly $\vec{A} + 3.00\hat{k} = -5.14\hat{i} + 6.13\hat{j} + 3.00\hat{k}$.

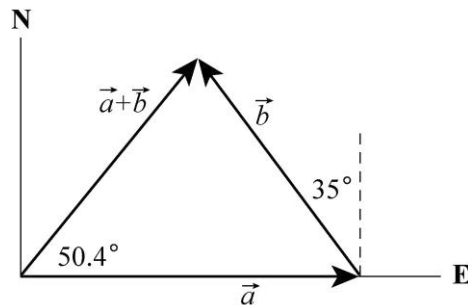
f The Pythagorean theorem yields magnitude $A = \sqrt{5.14^2 + 6.13^2 + 3.00^2} = 8.54$.

The azimuthal angle is $\theta = 130^\circ$ just as it was in the problem statement. \vec{A} is the projection onto the xy plane of the new vector created in part e. The angle measured from the z axis is

$$\phi = \cos^{-1} \frac{3.00}{8.54} = 69.4^\circ.$$

46. The vectors are shown on the diagram. The x axis runs from west to east and the y axis runs from south to north. Then $a_x = 5.0$ m, $a_y = 0$

$$b_x = -4.0 \text{ m} \sin 35^\circ = -2.29 \text{ m}, \quad b_y = 4.0 \text{ m} \cos 35^\circ = 3.28 \text{ m}.$$



a Let $\vec{c} = \vec{a} + \vec{b}$. Then $c_x = a_x + b_x = 5.00 \text{ m} - 2.29 \text{ m} = 2.71 \text{ m}$ and $c_y = a_y + b_y = 0 + 3.28 \text{ m} = 3.28 \text{ m}$. The magnitude of c is

$$c = \sqrt{c_x^2 + c_y^2} = \sqrt{(2.71 \text{ m})^2 + (3.28 \text{ m})^2} = 4.2 \text{ m}.$$

b The angle θ that $\vec{c} = \vec{a} + \vec{b}$ makes with the x axis is

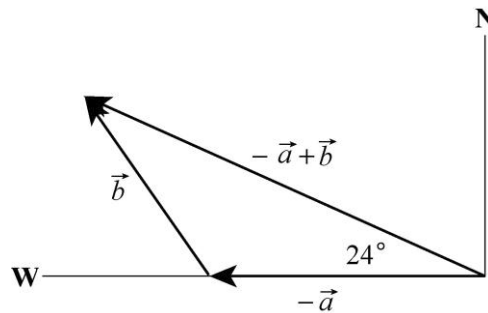
$$\theta = \tan^{-1}\left(\frac{c_y}{c_x}\right) = \tan^{-1}\left(\frac{3.28}{2.71}\right) = 50.5^\circ \approx 50^\circ.$$

The second possibility $\theta = 50.4^\circ + 180^\circ = 230.4^\circ$ is rejected because it would point in a direction opposite to \vec{c} .

c The vector $\vec{b} - \vec{a}$ is found by adding $-\vec{a}$ to \vec{b} . The result is shown on the diagram to the right. Let $\vec{c} = \vec{b} - \vec{a}$. The components are

$$\begin{aligned} c_x &= b_x - a_x = -2.29 \text{ m} - 5.00 \text{ m} = -7.29 \text{ m} \\ c_y &= b_y - a_y = 3.28 \text{ m}. \end{aligned}$$

The magnitude of \vec{c} is $c = \sqrt{c_x^2 + c_y^2} = 8.0 \text{ m}$.



d The tangent of the angle θ that \vec{c} makes with the x axis is

$$\tan \theta = \frac{c_y}{c_x} = \frac{3.28 \text{ m}}{-7.29 \text{ m}} = -4.50.$$

There are two solutions -24.2° and 155.8° . As the diagram shows, the second solution is correct. The vector $\vec{c} = -\vec{a} + \vec{b}$ is 24° north of west.

47. Noting that the given 130° is measured counterclockwise from the x axis, the two vectors can be written as

$$\begin{aligned} \vec{A} &= 8.00 \cos 130^\circ \hat{i} + \sin 130^\circ \hat{j} = -5.14 \hat{i} + 6.13 \hat{j} \\ \vec{B} &= B_x \hat{i} + B_y \hat{j} = -7.72 \hat{i} - 9.20 \hat{j}. \end{aligned}$$

a The angle between the negative direction of the y axis $-\hat{j}$ and the direction of \vec{A} is

$$\theta = \cos^{-1} \left(\frac{\vec{A} \cdot \hat{-y}}{A} \right) = \cos^{-1} \left(\frac{-6.13}{\sqrt{-5.14^2 + 6.13^2}} \right) = \cos^{-1} \left(\frac{-6.13}{8.00} \right) = 140^\circ.$$

Alternatively one may say that the $-y$ direction corresponds to an angle of 270° and the answer is simply given by $270^\circ - 130^\circ = 140^\circ$.

b Since the y axis is in the xy plane and $\vec{A} \times \vec{B}$ is perpendicular to that plane then the answer is 90.0° .

c The vector can be simplified as

$$\begin{aligned} \vec{A} \times \vec{B} + 3.00\hat{k} &= -5.14\hat{i} + 6.13\hat{j} \times -7.72\hat{i} - 9.20\hat{j} + 3.00\hat{k} \\ &= 18.39\hat{i} + 15.42\hat{j} + 94.61\hat{k} \end{aligned}$$

Its magnitude is $|\vec{A} \times \vec{B} + 3.00\hat{k}| = 97.6$. The angle between the negative direction of the y axis $-\hat{j}$ and the direction of the above vector is

$$\theta = \cos^{-1} \left(\frac{-15.42}{97.6} \right) = 99.1^\circ.$$

48. Here the length unit is not displayed the unit meter is understood.

a We first note that the magnitudes of the vectors are $a = |\vec{a}| = \sqrt{3.2^2 + 1.6^2} = 3.58$ and $b = |\vec{b}| = \sqrt{0.50^2 + 4.5^2} = 4.53$. So

$$\begin{aligned} \vec{a} \cdot \vec{b} &= a_x b_x + a_y b_y = ab \cos \phi \\ 3.2(0.50) + 1.6(4.5) &= 3.58(4.53) \cos \phi \end{aligned}$$

which leads to $\phi = 57^\circ$ the inverse cosine is double valued as is the inverse tangent but we know this is the right solution since both vectors are in the same quadrant.

b Since the angle measured from x for \vec{a} is $\tan^{-1} \frac{1.6}{3.2} = 26.6^\circ$ we know the angle for \vec{c} is $26.6^\circ - 90^\circ = -63.4^\circ$ the other possibility $26.6^\circ + 90^\circ$ would lead to a $c_x < 0$. Therefore

$$c_x = c \cos -63.4^\circ = 5.0(0.45) = 2.2 \text{ m.}$$

c So $c_y = c \sin -63.4^\circ = 5.0(-0.89) = -4.5 \text{ m.}$

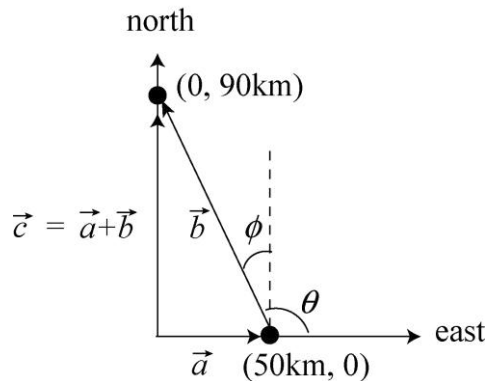
d And we know the angle for \vec{d} to be $26.6^\circ + 90^\circ = 116.6^\circ$ which leads to

$$d_x = d \cos 116.6 = 5.0 \cos 116.6 = -2.2 \text{ m.}$$

$$\text{e Finally } d_y = d \sin 116.6 = 5.0 \sin 116.6 = 4.5 \text{ m.}$$

49. **THINK** This problem deals with the displacement of a sailboat. We want to find the displacement vector between two locations.

EXPRESS The situation is depicted in the figure below. Let \vec{a} represent the first part of his actual voyage 50.0 km east and \vec{c} represent the intended voyage 90.0 km north. We look for a vector \vec{b} such that $\vec{c} = \vec{a} + \vec{b}$.



ANALYZE a Using the Pythagorean theorem the distance traveled by the sailboat is

$$b = \sqrt{50.0 \text{ km}^2 + 90.0 \text{ km}^2} = 103 \text{ km.}$$

b The direction is

$$\phi = \tan^{-1} \left(\frac{50.0 \text{ km}}{90.0 \text{ km}} \right) = 29.1^\circ$$

west of north which is equivalent to 60.9° north of due west.

LEARN This problem could also be solved by first expressing the vectors in unit vector notation $\vec{a} = 50.0 \text{ km} \hat{i}$, $\vec{c} = 90.0 \text{ km} \hat{j}$. This gives

$$\vec{b} = \vec{c} - \vec{a} = -50.0 \text{ km} \hat{i} + 90.0 \text{ km} \hat{j}.$$

The angle between \vec{b} and the x axis is

$$\theta = \tan^{-1} \left(\frac{90.0 \text{ km}}{-50.0 \text{ km}} \right) = 119.1^\circ.$$

The angle θ is related to ϕ by $\theta = 90^\circ + \phi$.

50. The two vectors \vec{d}_1 and \vec{d}_2 are given by $\vec{d}_1 = d_1 \hat{i}$ and $\vec{d}_2 = d_2 \hat{j}$.

a The vector $\vec{d}_2 = d_2 \hat{j}$ points in the y direction. The factor does not affect the result.

b The vector $\vec{d}_1 = d_1 \hat{i}$ points in the x direction. The minus sign (with the “-4”) does affect the direction $-x = -x$.

c $\vec{d}_1 \cdot \vec{d}_2 = 0$ since $\hat{i} \cdot \hat{j} = 0$. The two vectors are perpendicular to each other.

d $\vec{d}_1 \cdot \vec{d}_2 = d_1 d_2 \hat{i} \cdot \hat{j} = 0$ as in part c.

e $\vec{d}_1 \times \vec{d}_2 = d_1 d_2 \hat{i} \times \hat{j} = d_1 d_2 \hat{k}$ in the z direction.

f $\vec{d}_2 \times \vec{d}_1 = d_2 d_1 \hat{j} \times \hat{i} = -d_1 d_2 \hat{k}$ in the $-z$ direction.

g The magnitude of the vector in e is $d_1 d_2$.

h The magnitude of the vector in f is $d_1 d_2$.

i Since $\vec{d}_1 \times \vec{d}_2 = d_1 d_2 \hat{k}$ the magnitude is $d_1 d_2$.

The direction of $\vec{d}_1 \times \vec{d}_2 = d_1 d_2 \hat{k}$ is in the z direction.

51. Although we think of this as a three dimensional movement it is rendered effectively two dimensional by referring measurements to its well defined plane of the fault.

a The magnitude of the net displacement is

$$\vec{AB} = \sqrt{AD^2 + AC^2} = \sqrt{17.0 \text{ m}^2 + 22.0 \text{ m}^2} = 27.8 \text{ m}.$$

b The magnitude of the vertical component of \vec{AB} is $AD \sin 52.0^\circ = 13.4 \text{ m}$.

52. The three vectors are

$$\begin{aligned}\vec{d}_1 &= 4.0\hat{i} + 5.0\hat{j} - 6.0\hat{k} \\ \vec{d}_2 &= -1.0\hat{i} + 2.0\hat{j} + 3.0\hat{k} \\ \vec{d}_3 &= 4.0\hat{i} + 3.0\hat{j} - 2.0\hat{k}\end{aligned}$$

a $\vec{r} = \vec{d}_1 - \vec{d}_2 + \vec{d}_3 = 9.0 \text{ m } \hat{i} + 6.0 \text{ m } \hat{j} + -7.0 \text{ m } \hat{k}.$

b The magnitude of \vec{r} is $|\vec{r}| = \sqrt{9.0^2 + 6.0^2 + (-7.0)^2} = 12.9 \text{ m}.$ The angle between \vec{r} and the z axis is given by

$$\cos \theta = \frac{\vec{r} \cdot \hat{k}}{|\vec{r}|} = \frac{-7.0 \text{ m}}{12.9 \text{ m}} = -0.543$$

which implies $\theta = 123^\circ.$

c The component of \vec{d}_1 along the direction of \vec{d}_2 is given by $d_{\parallel} = \vec{d}_1 \cdot \hat{u} = d_1 \cos \phi$ where ϕ is the angle between \vec{d}_1 and \vec{d}_2 and \hat{u} is the unit vector in the direction of \vec{d}_2 . Using the properties of the scalar dot product we have

$$d_{\parallel} = d_1 \left(\frac{\vec{d}_1 \cdot \vec{d}_2}{d_1 d_2} \right) = \frac{\vec{d}_1 \cdot \vec{d}_2}{d_2} = \frac{4.0(-1.0) + 5.0(2.0) + (-6.0)(3.0)}{\sqrt{(-1.0)^2 + 2.0^2 + 3.0^2}} = \frac{-12}{\sqrt{14}} = -3.2 \text{ m}.$$

d So we are looking for d_{\perp} such that $d_1^2 = 4.0^2 + 5.0^2 + (-6.0)^2 = 77 = d_{\parallel}^2 + d_{\perp}^2.$ From c we have

$$d_{\perp} = \sqrt{77 \text{ m}^2 - (-3.2 \text{ m})^2} = 8.2 \text{ m}.$$

This gives the magnitude of the perpendicular component and is consistent with what one could get using Eq. 3-24 but if more information such as the direction or a full specification in terms of unit vectors is sought then more computation is needed.

53. **THINK** This problem involves finding scalar and vector products between two vectors \vec{a} and \vec{b} .

EXPRESS We apply Eqs. 3-20 and 3-24 to calculate the scalar and vector products between two vectors

$$\vec{a} \cdot \vec{b} = ab \cos \phi$$

$$\vec{a} \times \vec{b} = ab \sin \phi.$$

ANALYZE a Given that $a = |\vec{a}| = 10$, $b = |\vec{b}| = 6.0$ and $\phi = 60^\circ$ the scalar dot product of \vec{a} and \vec{b} is

$$\vec{a} \cdot \vec{b} = ab \cos \phi = 10(6.0) \cos 60^\circ = 30.$$

b Similarly the magnitude of the vector cross product of the two vectors is

$$\vec{a} \times \vec{b} = ab \sin \phi = 10 \cdot 6.0 \sin 60^\circ = 52.$$

LEARN When two vectors \vec{a} and \vec{b} are parallel $\phi = 0$ their scalar and vector products are $\vec{a} \cdot \vec{b} = ab \cos \phi = ab$ and $\vec{a} \times \vec{b} = ab \sin \phi = 0$ respectively. However when they are perpendicular $\phi = 90^\circ$ we have $\vec{a} \cdot \vec{b} = ab \cos \phi = 0$ and $\vec{a} \times \vec{b} = ab \sin \phi = ab$.

54. From the figure it is clear that $\vec{a} \cdot \vec{b} \cdot \vec{c} = 0$ here $\vec{a} \perp \vec{b}$.

a $\vec{a} \cdot \vec{b} = 0$ since the angle between them is 90° .

b $\vec{a} \cdot \vec{c} = \vec{a} \cdot (\vec{a} - \vec{b}) = |\vec{a}|^2 = 16$.

c Similarly $\vec{b} \cdot \vec{c} = -9.0$.

55. We choose x east and y north and measure all angles in the “standard” way positive ones are counterclockwise from x . Thus vector \vec{d}_1 has magnitude $d_1 = 4.00$ m with the unit meter and direction $\theta_1 = 225^\circ$. Also \vec{d}_2 has magnitude $d_2 = 5.00$ m and direction $\theta_2 = 0^\circ$ and vector \vec{d}_3 has magnitude $d_3 = 6.00$ m and direction $\theta_3 = 60^\circ$.

a The x component of \vec{d}_1 is $d_{1x} = d_1 \cos \theta_1 = -2.83$ m.

b The y component of \vec{d}_1 is $d_{1y} = d_1 \sin \theta_1 = -2.83$ m.

c The x component of \vec{d}_2 is $d_{2x} = d_2 \cos \theta_2 = 5.00$ m.

d The y component of \vec{d}_2 is $d_{2y} = d_2 \sin \theta_2 = 0$.

e The x component of \vec{d}_3 is $d_{3x} = d_3 \cos \theta_3 = 3.00$ m.

f The y component of \vec{d}_3 is $d_{3y} = d_3 \sin \theta_3 = 5.20$ m.

g The sum of x components is

$$d_x = d_{1x} + d_{2x} + d_{3x} = -2.83 \text{ m} + 5.00 \text{ m} + 3.00 \text{ m} = 5.17 \text{ m}.$$

h The sum of y components is

$$d_y = d_{1y} + d_{2y} + d_{3y} = -2.83 \text{ m} + 0 + 5.20 \text{ m} = 2.37 \text{ m}.$$

i The magnitude of the resultant displacement is

$$d = \sqrt{d_x^2 + d_y^2} = \sqrt{5.17 \text{ m}^2 + 2.37 \text{ m}^2} = 5.69 \text{ m}.$$

and its angle is

$$\theta = \tan^{-1} \frac{2.37}{5.17} = 24.6^\circ$$

which, recalling our coordinate choices, means it points at about 25° north of east.

Now, if we add this net displacement (the direct line home) when vectorially added to the previous net displacement must give zero. Thus the net displacement is the negative or opposite of the previous net displacement. That is, it has the same magnitude (5.69 m) but points in the opposite direction (25° south of east).

56. If we wish to use Eqs. 3-5 directly, we should note that the angles for \vec{Q} , \vec{R} , and \vec{S} are 100° , 250° , and 310° respectively if they are measured counterclockwise from the x axis.

a. Using unit vector notation (with the unit meter understood), we have

$$\vec{P} = 10.0 \cos(25.0^\circ) \hat{i} + 10.0 \sin(25.0^\circ) \hat{j}$$

$$\vec{Q} = 12.0 \cos(100^\circ) \hat{i} + 12.0 \sin(100^\circ) \hat{j}$$

$$\vec{R} = 8.00 \cos(250^\circ) \hat{i} + 8.00 \sin(250^\circ) \hat{j}$$

$$\vec{S} = 9.00 \cos(310^\circ) \hat{i} + 9.00 \sin(310^\circ) \hat{j}$$

$$\vec{P} + \vec{Q} + \vec{R} + \vec{S} = 10.0 \text{ m} \hat{i} + 1.63 \text{ m} \hat{j}$$

b. The magnitude of the vector sum is $\sqrt{10.0 \text{ m}^2 + 1.63 \text{ m}^2} = 10.2 \text{ m}$.

c. The angle is $\tan^{-1} \frac{1.63 \text{ m}}{10.0 \text{ m}} \approx 9.24^\circ$ measured counterclockwise from the x axis.

57. **THINK** This problem deals with addition and subtraction of two vectors.

EXPRESS From the problem statement, we have

$$\vec{A} + \vec{B} = 6.0 \hat{i} + 1.0 \hat{j} \quad \vec{A} - \vec{B} = -4.0 \hat{i} + 7.0 \hat{j}$$

Solving the simultaneous equations gives \vec{A} and \vec{B} .

ANALYZE Adding the above equations and dividing by 2 leads to $\vec{A} = 1.0 \hat{i} + 4.0 \hat{j}$.

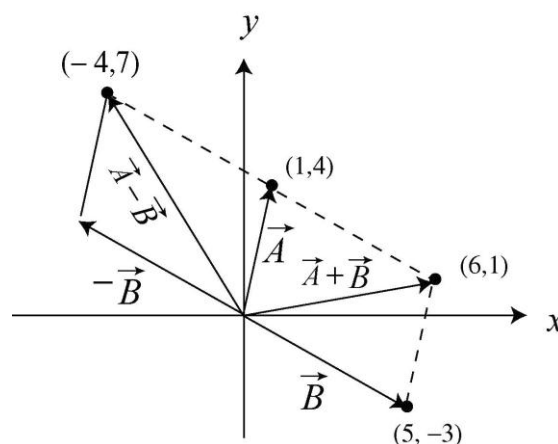
The magnitude of \vec{A} is

$$A = |\vec{A}| = \sqrt{A_x^2 + A_y^2} = \sqrt{1.0^2 + 4.0^2} = 4.1$$

LEARN The vector \vec{B} is $\vec{B} = 5.0 \hat{i} + -3.0 \hat{j}$ and its magnitude is

$$B = |\vec{B}| = \sqrt{B_x^2 + B_y^2} = \sqrt{5.0^2 + -3.0^2} = 5.8.$$

The results are summarized in the figure to the right.



58. The vector can be written as $\vec{d} = 2.5 \hat{j}$ where we have taken \hat{j} to be the unit vector pointing north.

a The magnitude of the vector $\vec{a} = 4.0 \vec{d}$ is $4.0 \cdot 2.5 \text{ m} = 10 \text{ m}$.

b The direction of the vector $\vec{a} = 4.0 \vec{d}$ is the same as the direction of \vec{d} north.

c The magnitude of the vector $\vec{c} = -3.0 \vec{d}$ is $3.0 \cdot 2.5 \text{ m} = 7.5 \text{ m}$.

d The direction of the vector $\vec{c} = -3.0 \vec{d}$ is the opposite of the direction of \vec{d} . Thus the direction of \vec{c} is south.

59. Reference to figure 3.18 and the accompanying material in that section is helpful. If we convert \vec{B} to the magnitude-angle notation as \vec{A} already is we have $\vec{B} = (14.4 \angle 33.7^\circ)$ appropriate notation especially if we are using a vector capable calculator in polar mode. Here the length unit is not displayed in the solution the unit meter should be understood. In the magnitude-angle notation rotating the axis by 20° amounts to subtracting that angle from the angles previously specified. Thus $\vec{A} = (12.0 \angle 40.0^\circ)'$ and $\vec{B} = (14.4 \angle 13.7^\circ)'$ where the 'prime' notation indicates that the description is in terms of the new coordinates. Converting these results to x, y representations we obtain

a $\vec{A} = 9.19 \text{ m } \hat{i}' + 7.71 \text{ m } \hat{j}'$.

b Similarly $\vec{B} = 14.0 \text{ m } \hat{i} + 3.41 \text{ m } \hat{j}$.

60. The two vectors can be found by solving the simultaneous equations.

a If we add the equations we obtain $2\vec{a} = 6\vec{c}$ which leads to $\vec{a} = 3\vec{c} = 9\hat{i} + 12\hat{j}$.

b Plugging this result back in we find $\vec{b} = \vec{c} = 3\hat{i} + 4\hat{j}$.

61. The three vectors given are

$$\vec{a} = 5.0\hat{i} + 4.0\hat{j} - 6.0\hat{k}$$

$$\vec{b} = -2.0\hat{i} + 2.0\hat{j} + 3.0\hat{k}$$

$$\vec{c} = 4.0\hat{i} + 3.0\hat{j} + 2.0\hat{k}$$

a The vector equation $\vec{r} = \vec{a} - \vec{b} + \vec{c}$ is

$$\begin{aligned}\vec{r} &= 5.0 - (-2.0) + 4.0\hat{i} + 4.0 - 2.0 + 3.0\hat{j} + -6.0 - 3.0 + 2.0\hat{k} \\ &= 11\hat{i} + 5.0\hat{j} - 7.0\hat{k}.\end{aligned}$$

b We find the angle from z by “dotting” (taking the scalar product) \vec{r} with \hat{k} . Noting that

$$r = |\vec{r}| = \sqrt{11.0^2 + 5.0^2 + (-7.0)^2} = 14$$

and $\hat{k} \cdot \hat{k} = 1$ leads to

$$\vec{r} \cdot \hat{k} = -7.0 = (14)(1)\cos\phi \Rightarrow \phi = 120^\circ.$$

c To find the component of a vector in a certain direction it is efficient to “dot” it (take the scalar product of it) with a unit vector in that direction. In this case we make the desired unit vector by

$$\hat{b} = \frac{\vec{b}}{b} = \frac{-2.0\hat{i} + 2.0\hat{j} + 3.0\hat{k}}{\sqrt{(-2.0)^2 + 2.0^2 + 3.0^2}}.$$

We therefore obtain

$$a_b = \vec{a} \cdot \hat{b} = \frac{(5.0)(-2.0) + (4.0)(2.0) + (-6.0)(3.0)}{\sqrt{(-2.0)^2 + 2.0^2 + 3.0^2}} = -4.9.$$

d One approach if all we require is the magnitude is to use the vector cross product as the problem suggests another which supplies more information is to subtract the result in part c multiplied by \hat{b} from \vec{a} . We briefly illustrate both methods. We note that if

$a \cos \theta$ here θ is the angle between \vec{a} and \vec{b} gives a_b the component along \hat{b} then expect $a \sin \theta$ to yield the orthogonal component

$$a \sin \theta = \frac{|\vec{a} \times \vec{b}|}{b} = 7.3$$

alternatively one might compute θ from part c and proceed more directly. The second method proceeds as follows

$$\begin{aligned}\vec{a} - a_b \hat{b} &= (5.0 - 2.35)\hat{i} + (4.0 - (-2.35))\hat{j} + ((-6.0) - (-3.53))\hat{k} \\ &= 2.65\hat{i} + 6.35\hat{j} - 2.47\hat{k}\end{aligned}$$

this describes the perpendicular part of \vec{a} completely. To find the magnitude of this part we compute

$$\sqrt{2.65^2 + 6.35^2 + (-2.47)^2} = 7.3$$

which agrees with the first method.

62. We choose x east and y north and measure all angles in the “standard” way positive ones counterclockwise from x negative ones clockwise. Thus vector \vec{d}_1 has magnitude $d_1 = 3.66$ with the unit meter and three significant figures assumed and direction $\theta_1 = 90^\circ$. Also \vec{d}_2 has magnitude $d_2 = 1.83$ and direction $\theta_2 = -45^\circ$ and vector \vec{d}_3 has magnitude $d_3 = 0.91$ and direction $\theta_3 = -135^\circ$. We add the x and y components respectively

$$x: d_1 \cos \theta_1 + d_2 \cos \theta_2 + d_3 \cos \theta_3 = 0.65 \text{ m}$$

$$y: d_1 \sin \theta_1 + d_2 \sin \theta_2 + d_3 \sin \theta_3 = 1.7 \text{ m.}$$

a. The magnitude of the direct displacement the vector sum $\vec{d}_1 + \vec{d}_2 + \vec{d}_3$ is $\sqrt{0.65^2 + 1.7^2} = 1.8 \text{ m.}$

b. The angle understood in the sense described above is $\tan^{-1} \frac{1.7}{0.65} = 69^\circ$. That is the first putt must aim in the direction 69° north of east.

63. The three vectors are

$$\vec{d}_1 = -3.0\hat{i} + 3.0\hat{j} + 2.0\hat{k}$$

$$\vec{d}_2 = -2.0\hat{i} - 4.0\hat{j} + 2.0\hat{k}$$

$$\vec{d}_3 = 2.0\hat{i} + 3.0\hat{j} + 1.0\hat{k}.$$

a Since $\vec{d}_2 + \vec{d}_3 = 0\hat{i} - 1.0\hat{j} + 3.0\hat{k}$ we have

$$\begin{aligned}\vec{d}_1 \cdot \vec{d}_2 + \vec{d}_3 &= -3.0\hat{i} + 3.0\hat{j} + 2.0\hat{k} \cdot 0\hat{i} - 1.0\hat{j} + 3.0\hat{k} \\ &= 0 - 3.0 + 6.0 = 3.0 \text{ m}^2.\end{aligned}$$

b Using Eq. 3-27 we obtain $\vec{d}_2 \times \vec{d}_3 = -10\hat{i} + 6.0\hat{j} + 2.0\hat{k}$. Thus

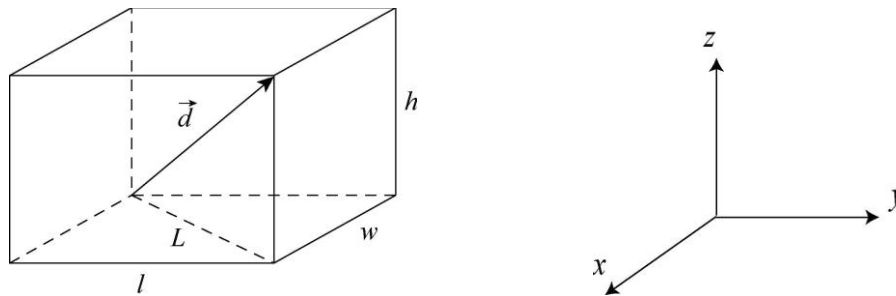
$$\begin{aligned}\vec{d}_1 \cdot \vec{d}_2 \times \vec{d}_3 &= -3.0\hat{i} + 3.0\hat{j} + 2.0\hat{k} \cdot -10\hat{i} + 6.0\hat{j} + 2.0\hat{k} \\ &= 30 + 18 + 4.0 = 52 \text{ m}^3.\end{aligned}$$

c We found \vec{d}_2 and \vec{d}_3 in part a. Use of Eq. 3-27 then leads to

$$\begin{aligned}\vec{d}_1 \times \vec{d}_2 + \vec{d}_3 &= -3.0\hat{i} + 3.0\hat{j} + 2.0\hat{k} \times 0\hat{i} - 1.0\hat{j} + 3.0\hat{k} \\ &= 11\hat{i} - 9.0\hat{j} - 3.0\hat{k} \text{ m}^2\end{aligned}$$

64. **THINK** This problem deals with the displacement and distance traveled by a fly from one corner of a room to the diagonally opposite corner. The displacement vector is three dimensional.

EXPRESS The displacement of the fly is illustrated in the figure below



A coordinate system such as the one shown above right allows us to express the displacement as a three dimensional vector.

ANALYZE The magnitude of the displacement from one corner to the diagonally opposite corner is

$$d = |\vec{d}| = \sqrt{w^2 + l^2 + h^2}$$

Substituting the values given we obtain

$$d = |\vec{d}| = \sqrt{w^2 + l^2 + h^2} = \sqrt{3.70^2 \text{ m}^2 + 4.30^2 \text{ m}^2 + 3.00^2 \text{ m}^2} = 6.42 \text{ m}.$$

b The displacement vector is along the straight line from the beginning to the end point of the trip. Since a straight line is the shortest distance between two points the length of the path cannot be less than d the magnitude of the displacement.

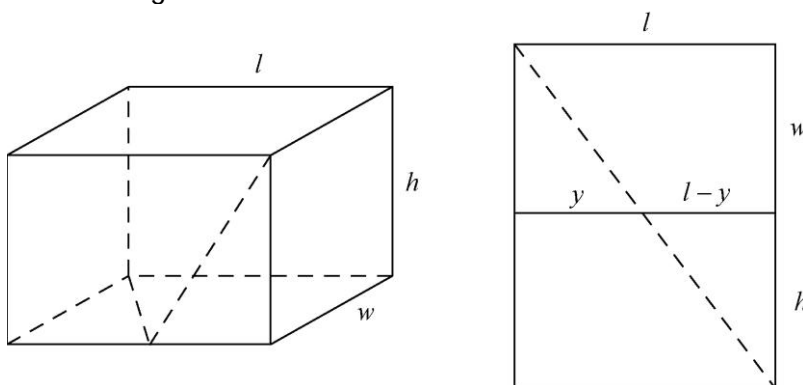
c The length of the path of the fly can be greater than d however. The fly might for example crawl along the edges of the room. Its displacement could be the same but the path length could be $\ell + w + h = 11.0$ m.

d The path length is the same as the magnitude of the displacement if the fly flies along the displacement vector.

e We take the x axis to be out of the page the y axis to be to the right and the z axis to be up and as shown in the figure above. Then the x component of the displacement is $w = 3.70$ m the y component of the displacement is 4.30 m and the z component is 3.00 m. Thus the displacement vector can be written as

$$\vec{d} = 3.70 \text{ m } \hat{i} + 4.30 \text{ m } \hat{j} + 3.00 \text{ m } \hat{k}.$$

f Suppose the path of the fly is as shown by the dotted lines on the diagram below left. Pretend there is a hinge here the front wall of the room joins the floor and lay the wall down as shown above right.



The shortest walking distance between the lower left back of the room and the upper right front corner is the dotted straight line shown on the diagram. Its length is

$$s_{\min} = \sqrt{(w + h)^2 + l^2} = \sqrt{(3.70 \text{ m} + 3.00 \text{ m})^2 + (4.30 \text{ m})^2} = 7.96 \text{ m}.$$

LEARN To show that the shortest path is indeed given by s_{\min} we write the length of the path as

$$s = \sqrt{y^2 + w^2} + \sqrt{(l - y)^2 + h^2}.$$

The condition for minimum is given by

$$\frac{ds}{dy} = \frac{y}{\sqrt{y^2 + w^2}} - \frac{l-y}{\sqrt{l-y^2 + h^2}} = 0.$$

little algebra shows that the condition is satisfied when $y = lw / (w + h)$ which gives

$$s_{\min} = \sqrt{w^2 \left(1 + \frac{l^2}{w+h^2} \right)} + \sqrt{h^2 \left(1 + \frac{l^2}{w+h^2} \right)} = \sqrt{w+h^2 + l^2}.$$

any other path could be longer than 7.96 m.

65. a. This is one example of an answer $-40\mathbf{i} - 20\mathbf{j} + 25\mathbf{k}$ m with \mathbf{i} directed anti parallel to the first path, \mathbf{j} directed anti parallel to the second path and \mathbf{k} directed up and in order to have a right handed coordinate system. Other examples include $40\mathbf{i} + 20\mathbf{j} - 25\mathbf{k}$ m and $40\mathbf{i} - 20\mathbf{j} - 25\mathbf{k}$ m with slightly different interpretations for the unit vectors. Note that the product of the components is positive in each example.

b. Using the Pythagorean theorem we have $\sqrt{40^2 + 20^2} = 44.7 \text{ m} \approx 45 \text{ m}$.

66. The vectors can be written as $\vec{a} = a\hat{a}$ and $\vec{b} = b\hat{b}$ where $a, b > 0$.

a. We are asked to consider

$$\frac{\vec{b}}{d} = \left(\frac{b}{d} \right) \hat{b}$$

in the case $d > 0$. Since the coefficient of \hat{b} is positive then the vector points in the \hat{b} direction.

b. If however $d < 0$ then the coefficient is negative and the vector points in the $-\hat{b}$ direction.

c. Since $\cos 90^\circ = 0$ then $\vec{a} \cdot \vec{b} = 0$ using 3.20.

d. Since \vec{b}/d is along the y axis then by the same reasoning as in the previous part $\vec{a} \cdot \vec{b}/d = 0$.

e. By the right hand rule $\vec{a} \times \vec{b}$ points in the z direction.

f. By the same rule $\vec{b} \times \vec{a}$ points in the $-z$ direction. Note that $\vec{b} \times \vec{a} = -\vec{a} \times \vec{b}$ is true in this case and quite generally.

g Since $\sin 90^\circ = 1$. 3 24 gives $\vec{a} \times \vec{b} = ab$ here a is the magnitude of \vec{a} .

h Iso $\vec{a} \times \vec{b} = \vec{b} \times \vec{a} = ab$.

i ith $d = 0$ e find that $\vec{a} \times \vec{b} \cdot \vec{d}$ has magnitude $ab d$.

he vector $\vec{a} \times \vec{b} \cdot \vec{d}$ points in the z direction.

67. e note that the set of choices for unit vector directions has correct orientation for a right handed coordinate system). Students sometimes confuse “north” with “up”, so it might be necessary to emphasise that these are being treated as the mutually perpendicular directions of our real world, not just some “on the paper” or “on the blackboard” representation of it. Once the terminology is clear, these questions are basic to the definitions of the scalar dot and vector cross products.

a $\hat{i} \cdot \hat{k} = 0$ since $\hat{i} \perp \hat{k}$

b $-\hat{k} \cdot -\hat{j} = 0$ since $\hat{k} \perp \hat{j}$.

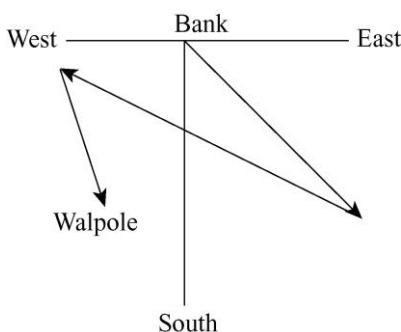
c $\hat{j} \cdot -\hat{j} = -1$.

d $\hat{k} \times \hat{j} = -\hat{i}$ est .

e $-\hat{i} \times -\hat{j} = +\hat{k}$ up ard .

f $-\hat{k} \times -\hat{j} = -\hat{i}$ est .

68. sketch of the displacements is shown. The resultant not shown could be a straight line from start bank to finish Walpole. With a careful drawing one should find that the resultant vector has length 29.5 km at 35° east of south.



69. The point P is displaced vertically by $2R$ where R is the radius of the wheel. It is displaced horizontally by half the circumference of the wheel or πR . Since $R = 0.450$ m

the horizontal component of the displacement is 1.414 m and the vertical component of the displacement is 0.900 m. If the x axis is horizontal and the y axis is vertical the vector displacement in meters is $\vec{r} = (1.414 \hat{i} + 0.900 \hat{j})$. The displacement has a magnitude of

$$|\vec{r}| = \sqrt{(\pi R)^2 + (2R)^2} = R\sqrt{\pi^2 + 4} = 1.68 \text{ m}$$

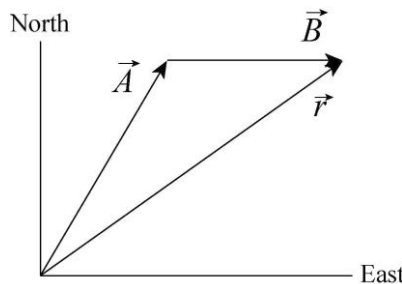
and an angle of

$$\tan^{-1}\left(\frac{2R}{\pi R}\right) = \tan^{-1}\left(\frac{2}{\pi}\right) = 32.5^\circ$$

above the floor. In physics there are no “exact” measurements, yet that angle computation seemed to yield something *exact*. However there has to be some uncertainty in the observation that the wheel rolled half of a revolution which introduces some indefiniteness in our result.

70. The diagram shows the displacement vectors for the two segments of her walk labeled \vec{A} and \vec{B} and the total “final” displacement vector, labeled \vec{r} . We take east to be the x direction and north to be the y direction. We observe that the angle between \vec{A} and the x axis is 60° . Here the units are not explicitly shown the distances are understood to be in meters. Thus the components of \vec{A} are $A_x = 250 \cos 60^\circ = 125$ and $A_y = 250 \sin 60^\circ = 216.5$. The components of \vec{B} are $B_x = 175$ and $B_y = 0$. The components of the total displacement are

$$\begin{aligned} r_x &= A_x + B_x = 125 + 175 = 300 \\ r_y &= A_y + B_y = 216.5 + 0 = 216.5. \end{aligned}$$



a The magnitude of the resultant displacement is

$$r = \sqrt{r_x^2 + r_y^2} = \sqrt{(300 \text{ m})^2 + (216.5 \text{ m})^2} = 370 \text{ m}.$$

b The angle the resultant displacement makes with the x axis is

$$\tan^{-1}\left(\frac{r_y}{r_x}\right) = \tan^{-1}\left(\frac{216.5 \text{ m}}{300 \text{ m}}\right) = 36^\circ.$$

he direction is 36° north of due east.

c the total *distance* walked is $d = 250 \text{ m} + 175 \text{ m} = 425 \text{ m}$.

d the total distance walked is greater than the magnitude of the resultant displacement. the diagram shows why \vec{A} and \vec{B} are not collinear.

71. the vector \vec{d} measured in meters can be represented as $\vec{d} = 3.0 \text{ m } -\hat{y}$ here $-\hat{y}$ is the unit vector pointing south. therefore $5.0\vec{d} = 5.0 \times 3.0 \text{ m } -\hat{y} = -15 \text{ m } \hat{y}$.

a the positive scalar factor 5.0 affects the magnitude but not the direction. the magnitude of $5.0\vec{d}$ is 15 m.

b the new direction of $5\vec{d}$ is the same as the old south.

the vector $-2.0\vec{d}$ can be written as $-2.0\vec{d} = 6.0 \text{ m } \hat{y}$.

c the absolute value of the scalar factor $-2.0 = 2.0$ affects the magnitude. the new magnitude is 6.0 m.

d the minus sign carried by this scalar factor reverses the direction so the new direction is $+\hat{y}$ or north.

72. The ant's trip consists of three displacements:

$$\vec{d}_1 = 0.40 \text{ m } \cos 225^\circ \hat{i} + \sin 225^\circ \hat{j} = -0.28 \text{ m } \hat{i} + -0.28 \text{ m } \hat{j}$$

$$\vec{d}_2 = 0.50 \text{ m } \hat{i}$$

$$\vec{d}_3 = 0.60 \text{ m } \cos 60^\circ \hat{i} + \sin 60^\circ \hat{j} = 0.30 \text{ m } \hat{i} + 0.52 \text{ m } \hat{j}$$

here the angle is measured with respect to the positive x axis. we have taken the positive x and y directions to correspond to east and north respectively.

a the x component of \vec{d}_1 is $d_{1x} = 0.40 \text{ m } \cos 225^\circ = -0.28 \text{ m}$.

b the y component of \vec{d}_1 is $d_{1y} = 0.40 \text{ m } \sin 225^\circ = -0.28 \text{ m}$.

c the x component of \vec{d}_2 is $d_{2x} = 0.50 \text{ m}$.

d the y component of \vec{d}_2 is $d_{2y} = 0 \text{ m}$.

e The x component of \vec{d}_3 is $d_{3x} = 0.60 \text{ m} \cos 60^\circ = 0.30 \text{ m}$.

f The y component of \vec{d}_3 is $d_{3y} = 0.60 \text{ m} \sin 60^\circ = 0.52 \text{ m}$.

g The x component of the net displacement \vec{d}_{net} is

$$d_{\text{net } x} = d_{1x} + d_{2x} + d_{3x} = -0.28 \text{ m} + 0.50 \text{ m} + 0.30 \text{ m} = 0.52 \text{ m}.$$

h The y component of the net displacement \vec{d}_{net} is

$$d_{\text{net } y} = d_{1y} + d_{2y} + d_{3y} = -0.28 \text{ m} + 0 \text{ m} + 0.52 \text{ m} = 0.24 \text{ m}.$$

i The magnitude of the net displacement is

$$d_{\text{net}} = \sqrt{d_{\text{net } x}^2 + d_{\text{net } y}^2} = \sqrt{0.52 \text{ m}^2 + 0.24 \text{ m}^2} = 0.57 \text{ m}.$$

The direction of the net displacement is

$$\theta = \tan^{-1} \left(\frac{d_{\text{net } y}}{d_{\text{net } x}} \right) = \tan^{-1} \left(\frac{0.24 \text{ m}}{0.52 \text{ m}} \right) = 25^\circ \text{ north of east}$$

f The ant has to return directly to the starting point the displacement could be $-\vec{d}_{\text{net}}$.

k The distance the ant has to travel is $-\vec{d}_{\text{net}} = 0.57 \text{ m}$.

l The direction the ant has to travel is 25° south of east.

73. We apply 3.23 and 3.27.

a $\vec{a} \times \vec{b} = a_x b_y - a_y b_x \hat{k}$ since all other terms vanish due to the fact that neither \vec{a} nor \vec{b} have any z components. Consequently we obtain $3.0(4.0) - 5.0(2.0) \hat{k} = 2.0 \hat{k}$.

b $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y$ yields $3.0(2.0) + 5.0(4.0) = 26$.

c $\vec{a} + \vec{b} = 3.0 \hat{i} + 2.0 \hat{j} + 5.0 \hat{i} + 4.0 \hat{j} \Rightarrow \vec{a} + \vec{b} = 8.0 \hat{i} + 6.0 \hat{j}$ and $|\vec{a} + \vec{b}| = \sqrt{8.0^2 + 6.0^2} = 10.0$.

d Several approaches are available. In this solution we will construct a \hat{b} unit vector and “dot” it with \vec{a} . In this case we make the desired unit vector by

$$\hat{b} = \frac{\vec{b}}{b} = \frac{2.0 \hat{i} + 4.0 \hat{j}}{\sqrt{2.0^2 + 4.0^2}}.$$

e therefore obtain

$$a_b = \vec{a} \cdot \hat{b} = \frac{3.0 \cdot 2.0 + 5.0 \cdot 4.0}{\sqrt{2.0^2 + 4.0^2}} = 5.81.$$

74. The two vectors \vec{a} and \vec{b} are given by

$$\vec{a} = 3.20 \cos 63^\circ \hat{i} + \sin 63^\circ \hat{k} = 1.45 \hat{i} + 2.85 \hat{k}$$

$$\vec{b} = 1.40 \cos 48^\circ \hat{i} + \sin 48^\circ \hat{k} = 0.937 \hat{i} + 1.04 \hat{k}$$

The components of \vec{a} are $a_x = 0$, $a_y = 3.20 \cos 63^\circ = 1.45$ and $a_z = 3.20 \sin 63^\circ = 2.85$.

The components of \vec{b} are $b_x = 1.40 \cos 48^\circ = 0.937$, $b_y = 0$ and $b_z = 1.40 \sin 48^\circ = 1.04$.

a The scalar dot product is therefore

$$\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z = (0)(0.937) + (1.45)(0) + (2.85)(1.04) = 2.97.$$

b The vector cross product is

$$\begin{aligned} \vec{a} \times \vec{b} &= (a_y b_z - a_z b_y) \hat{i} - (a_x b_z - a_z b_x) \hat{j} + (a_x b_y - a_y b_x) \hat{k} \\ &= ((1.45)(1.04) - 0) \hat{i} - ((2.85)(0.937) - 0) \hat{j} + (0 - (1.45)(0.937)) \hat{k} \\ &= 1.51 \hat{i} - 2.67 \hat{j} - 1.36 \hat{k}. \end{aligned}$$

c The angle θ between \vec{a} and \vec{b} is given by

$$\theta = \cos^{-1} \left(\frac{\vec{a} \cdot \vec{b}}{ab} \right) = \cos^{-1} \left(\frac{2.97}{(3.20)(1.40)} \right) = 48.5^\circ.$$

75. We orient \hat{i} east, \hat{j} north, and \hat{k} up, and use the following fundamental products

$$\begin{aligned} \hat{i} \times \hat{j} &= \hat{k} & \hat{j} \times \hat{i} &= -\hat{k} \\ \hat{j} \times \hat{k} &= \hat{i} & \hat{k} \times \hat{j} &= -\hat{i} \\ \hat{k} \times \hat{i} &= \hat{j} & \hat{i} \times \hat{k} &= -\hat{j} \end{aligned}$$

(a) “north cross west” = $\hat{j} \times -\hat{i} = \hat{k}$ = “up.”

(b) “down dot south” = $-\hat{k} \cdot -\hat{j} = 0$.

(c) “east cross up” = $\hat{i} \times \hat{k} = -\hat{j}$ = “south.”

(d) “west dot west” = $-\hat{i} \cdot -\hat{i} = 1$.

(e) “south cross south” = $-\hat{j} \times -\hat{j} = 0$.

76. Let A denote the magnitude of \vec{A} similarly for the other vectors. The vector equation is $\vec{A} + \vec{B} = \vec{C}$ here $B = 8.0$ m and $C = 2A$. We are also told that the angle measured in the ‘standard’ sense for \vec{A} is 0° and the angle for \vec{C} is 90° which makes this a right triangle (then drawn in a “head to tail” fashion) where B is the side of the hypotenuse. Using the Pythagorean theorem

$$B = \sqrt{A^2 + C^2} \Rightarrow 8.0 = \sqrt{A^2 + 4A^2}$$

which leads to $A = 8/\sqrt{5} = 3.6$ m.

77. We orient \hat{i} east and \hat{j} north and \hat{k} up and

a the displacement is $\vec{d} = 1300 \text{ m } \hat{i} + 2200 \text{ m } \hat{j} + -410 \text{ m } \hat{k}$.

b the displacement for the return portion is $\vec{d}' = -1300 \text{ m } \hat{i} - 2200 \text{ m } \hat{j}$ and the magnitude is $d' = \sqrt{(-1300 \text{ m})^2 + (-2200 \text{ m})^2} = 2.56 \times 10^3 \text{ m}$.

The net displacement is zero since his final position matches his initial position.

78. Let $\vec{c} = \vec{b} \times \vec{a}$. Then the magnitude of \vec{c} is $c = ab \sin \phi$ since \vec{c} is perpendicular to \vec{a} the magnitude of $\vec{a} \times \vec{c}$ is ac . The magnitude of $\vec{a} \times \vec{b} \times \vec{a}$ is consequently

$$\vec{a} \times \vec{b} \times \vec{a} = ac = a^2 b \sin \phi.$$

Substituting the values given we obtain

$$\vec{a} \times \vec{b} \times \vec{a} = a^2 b \sin \phi = (3.90)^2 (2.70) \sin 63.0^\circ = 36.6.$$

79. The area of a triangle is half the product of its base and altitude. The base is the side formed by vector \vec{a} . Then the altitude is $b \sin \phi$ and the area is $A = \frac{1}{2} ab \sin \phi = \frac{1}{2} \vec{a} \times \vec{b}$.

Substituting the values given we have

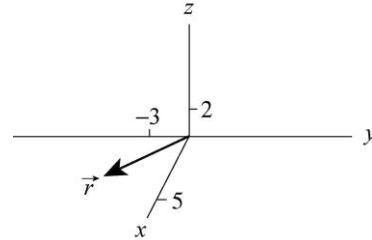
$$A = \frac{1}{2} ab \sin \phi = \frac{1}{2} (4.3)(5.4) \sin 46^\circ \approx 8.4.$$

Chapter

1. a the magnitude of \vec{r} is

$$\vec{r} = \sqrt{5.0 \text{ m}^2 + (-3.0 \text{ m})^2 + 2.0 \text{ m}^2} = 6.2 \text{ m}.$$

- b sketch is shown. The coordinate values are in meters.



2. a the position vector according to 3.4.1 is $\vec{r} = -5.0 \text{ m} \hat{i} + 8.0 \text{ m} \hat{j}$.

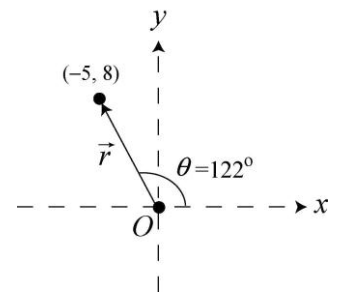
- b the magnitude is $\vec{r} = \sqrt{x^2 + y^2 + z^2} = \sqrt{(-5.0 \text{ m})^2 + (8.0 \text{ m})^2 + 0 \text{ m}^2} = 9.4 \text{ m}.$

- c many calculators have polar \leftrightarrow rectangular conversion capabilities that make this computation more efficient than what is shown below. Noting that the vector lies in the xy plane and using 3.6 we obtain

$$\theta = \tan^{-1}\left(\frac{8.0 \text{ m}}{-5.0 \text{ m}}\right) = -58^\circ \text{ or } 122^\circ$$

- here the latter possibility 122° measured counterclockwise from the x direction is chosen since the signs of the components imply the vector is in the second quadrant.

- d the sketch is shown to the right. The vector is 122° counterclockwise from the x direction.



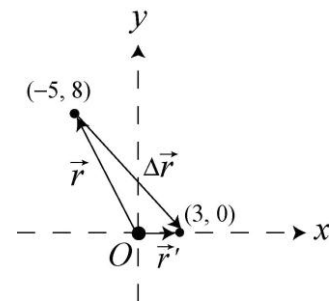
- e the displacement is $\Delta\vec{r} = \vec{r}' - \vec{r}$ here \vec{r} is given in part a and $\vec{r}' = 3.0 \text{ m} \hat{i}$. therefore $\Delta\vec{r} = 8.0 \text{ m} \hat{i} - 8.0 \text{ m} \hat{j}$.

- f the magnitude of the displacement is

$$\Delta\vec{r} = \sqrt{8.0 \text{ m}^2 + (-8.0 \text{ m})^2} = 11 \text{ m}.$$

- g the angle for the displacement using 3.6 is

$$\tan^{-1}\left(\frac{8.0 \text{ m}}{-8.0 \text{ m}}\right) = -45^\circ \text{ or } 135^\circ$$



here we choose the former possibility -45° or 45° measured *clockwise* from x since the signs of the components imply the vector is in the fourth quadrant. sketch of $\Delta\vec{r}$ is shown on the right.

3. the initial position vector \vec{r}_0 satisfies $\vec{r} - \vec{r}_0 = \Delta\vec{r}$ which results in

$$\vec{r}_0 = \vec{r} - \Delta\vec{r} = (3.0\hat{i} - 4.0\hat{k}) \text{ m} - (2.0\hat{i} - 3.0\hat{j} + 6.0\hat{k}) \text{ m} = -2.0\text{ m}\hat{i} + 3.0\text{ m}\hat{j} - 10\text{ m}\hat{k}.$$

4. we choose a coordinate system with origin at the clock center and x rightward (toward the “3:00” position) and $+y$ upward (toward “12:00”).

a. in unit vector notation we have $\vec{r}_1 = 10\text{ cm}\hat{i}$ and $\vec{r}_2 = -10\text{ cm}\hat{i}$. thus $\Delta\vec{r} = \vec{r}_2 - \vec{r}_1$ gives

$$\Delta\vec{r} = \vec{r}_2 - \vec{r}_1 = -10\text{ cm}\hat{i} - 10\text{ cm}\hat{i} = -20\text{ cm}\hat{i}.$$

the magnitude is given by $|\Delta\vec{r}| = \sqrt{(-20\text{ cm})^2} = 20\text{ cm}$.

b. since $\Delta\vec{r}$ is along the $-x$ axis the angle is

$$\theta = \tan^{-1}\left(\frac{-10\text{ cm}}{-10\text{ cm}}\right) = 45^\circ \text{ or } -135^\circ.$$

we choose -135° since the desired angle is in the third quadrant. in terms of the magnitude-angle notation one may write

$$\Delta\vec{r} = \vec{r}_2 - \vec{r}_1 = -10\text{ cm}\hat{i} - 10\text{ cm}\hat{i} \rightarrow 20\text{ cm} \angle -135^\circ.$$

c. in this case we have $\vec{r}_1 = -10\text{ cm}\hat{i}$ and $\vec{r}_2 = 10\text{ cm}\hat{i}$ and $\Delta\vec{r} = 20\text{ cm}\hat{i}$. thus $|\Delta\vec{r}| = 20\text{ cm}$.

d. since $\Delta\vec{r}$ is along the $+x$ axis the angle is given by

$$\theta = \tan^{-1}\left(\frac{0\text{ cm}}{20\text{ cm}}\right) = 0^\circ.$$

e. in a full hour sweep the hand returns to its starting position and the displacement is zero.

f. the corresponding angle for a full hour sweep is also zero.

5. **THINK** This problem deals with the motion of a train in two dimensions. The entire trip consists of three parts, and we're interested in the overall average velocity.

EXPRESS The average velocity of the entire trip is given by $\vec{v}_{\text{avg}} = \Delta \vec{r} / \Delta t$ where the total displacement $\Delta \vec{r} = \Delta \vec{r}_1 + \Delta \vec{r}_2 + \Delta \vec{r}_3$ is the sum of three displacements each result of a constant velocity during a given time and $\Delta t = \Delta t_1 + \Delta t_2 + \Delta t_3$ is the total amount of time for the trip. We use a coordinate system with x for east and y for north.

ANALYZE In unit vector notation the first displacement is given by

$$\Delta \vec{r}_1 = \left(60.0 \frac{\text{km}}{\text{h}} \right) \left(\frac{40.0 \text{ min}}{60 \text{ min h}} \right) \hat{i} = 40.0 \text{ km } \hat{i}.$$

The second displacement has a magnitude of $60.0 \frac{\text{km}}{\text{h}} \cdot \frac{20.0 \text{ min}}{60 \text{ min h}} = 20.0 \text{ km}$ and its direction is 40° north of east. Therefore

$$\Delta \vec{r}_2 = 20.0 \text{ km } \cos 40.0^\circ \hat{i} + 20.0 \text{ km } \sin 40.0^\circ \hat{j} = 15.3 \text{ km } \hat{i} + 12.9 \text{ km } \hat{j}.$$

Similarly the third displacement is

$$\Delta \vec{r}_3 = - \left(60.0 \frac{\text{km}}{\text{h}} \right) \left(\frac{50.0 \text{ min}}{60 \text{ min h}} \right) \hat{i} = -50.0 \text{ km } \hat{i}.$$

Thus the total displacement is

$$\begin{aligned} \Delta \vec{r} &= \Delta \vec{r}_1 + \Delta \vec{r}_2 + \Delta \vec{r}_3 = 40.0 \text{ km } \hat{i} + 15.3 \text{ km } \hat{i} + 12.9 \text{ km } \hat{j} - 50.0 \text{ km } \hat{i} \\ &= 5.30 \text{ km } \hat{i} + 12.9 \text{ km } \hat{j}. \end{aligned}$$

The time for the trip is $\Delta t = 40.0 + 20.0 + 50.0 \text{ min} = 110 \text{ min}$ which is equivalent to 1.83 h. Then yields

$$\vec{v}_{\text{avg}} = \frac{5.30 \text{ km } \hat{i} + 12.9 \text{ km } \hat{j}}{1.83 \text{ h}} = 2.90 \text{ km h}^{-1} \hat{i} + 7.01 \text{ km h}^{-1} \hat{j}.$$

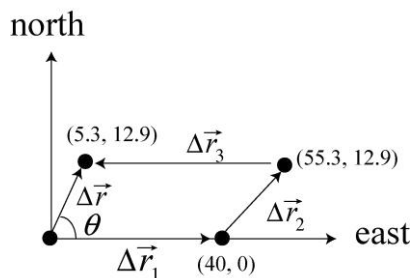
The magnitude of \vec{v}_{avg} is $v_{\text{avg}} = \sqrt{(2.90 \text{ km h}^{-1})^2 + (7.01 \text{ km h}^{-1})^2} = 7.59 \text{ km h}^{-1}$.

(b) The angle is given by

$$\theta = \tan^{-1} \left(\frac{v_{\text{avg } y}}{v_{\text{avg } x}} \right) = \tan^{-1} \left(\frac{7.01 \text{ km h}^{-1}}{2.90 \text{ km h}^{-1}} \right) = 67.5^\circ \text{ north of east}$$

or 22.5° east of due north.

LEARN The displacement of the train is depicted in the figure below



Note that the net displacement $\Delta \vec{r}$ is found by adding $\Delta \vec{r}_1$, $\Delta \vec{r}_2$ and $\Delta \vec{r}_3$ vectorially.

6. To emphasize the fact that the velocity is a function of time we adopt the notation $\vec{v}(t)$ for $\frac{d\vec{x}}{dt}$.

a. Equation 4.10 leads to

$$\vec{v}(t) = \frac{d}{dt} (3.00t\hat{i} - 4.00t^2\hat{j} + 2.00\hat{k}) = 3.00 \text{ m/s } \hat{i} - 8.00 \text{ m/s}^2 t \hat{j}$$

b. Evaluating this result at $t = 2.00 \text{ s}$ produces $\vec{v} = 3.00\hat{i} - 16.0\hat{j} \text{ m/s}$.

c. The speed at $t = 2.00 \text{ s}$ is $v = |\vec{v}| = \sqrt{(3.00 \text{ m/s})^2 + (-16.0 \text{ m/s})^2} = 16.3 \text{ m/s}$.

d. The angle of \vec{v} at that moment is

$$\tan^{-1} \left(\frac{-16.0 \text{ m/s}}{3.00 \text{ m/s}} \right) = -79.4^\circ \text{ or } 101^\circ$$

Here we choose the first possibility 79.4° measured *clockwise* from the x direction or 281° counterclockwise from x since the signs of the components imply the vector is in the fourth quadrant.

7. Using $\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$ and $\Delta t = 10 \text{ s}$ we have

$$\vec{v}_{\text{avg}} = \frac{-2.0\hat{i} - 8.0\hat{j} - 2.0\hat{k} \text{ m} - (-5.0\hat{i} - 6.0\hat{j} - 2.0\hat{k} \text{ m})}{10 \text{ s}} = -0.70\hat{i} - 1.40\hat{j} - 0.40\hat{k} \text{ m/s}$$

8. Our coordinate system has \hat{i} pointed east and \hat{j} pointed north. The first displacement is $\vec{r}_{AB} = 483 \text{ km } \hat{i}$ and the second is $\vec{r}_{BC} = -966 \text{ km } \hat{j}$.

a the net displacement is

$$\vec{r}_{AC} = \vec{r}_{AB} + \vec{r}_{BC} = 483 \text{ km } \hat{i} - 966 \text{ km } \hat{j}$$

which yields $\vec{r}_{AC} = \sqrt{483^2 + (-966)^2} = 1.08 \times 10^3 \text{ km}$.

b the angle is given by

$$\theta = \tan^{-1} \left(\frac{-966 \text{ km}}{483 \text{ km}} \right) = -63.4^\circ.$$

We observe that the angle can be alternatively expressed as 63.4° south of east or 26.6° east of south.

c dividing the magnitude of \vec{r}_{AC} by the total time 2.25 h gives

$$\vec{v}_{\text{avg}} = \frac{483 \text{ km } \hat{i} - 966 \text{ km } \hat{j}}{2.25 \text{ h}} = 215 \text{ km/h } \hat{i} - 429 \text{ km/h } \hat{j}$$

with a magnitude $|\vec{v}_{\text{avg}}| = \sqrt{215^2 + (-429)^2} = 480 \text{ km/h}$.

d the direction of \vec{v}_{avg} is 26.6° east of south same as in part b. In magnitude-angle notation we could have $\vec{v}_{\text{avg}} = 480 \text{ km/h } \angle -63.4^\circ$.

e Assuming the AB trip as a straight one and similarly for the BC trip then \vec{r}_{AB} is the distance traveled during the AB trip and \vec{r}_{BC} is the distance traveled during the BC trip. Since the average speed is the total distance divided by the total time it equals

$$\frac{483 \text{ km} + 966 \text{ km}}{2.25 \text{ h}} = 644 \text{ km/h}.$$

9. The x, y coordinates in meters of the points are $A = (15, -15)$, $B = (30, -45)$, $C = (20, -15)$ and $D = (45, 45)$. The respective times are $t_A = 0$, $t_B = 300 \text{ s}$, $t_C = 600 \text{ s}$ and $t_D = 900 \text{ s}$. Average velocity is defined by $\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$. Each displacement $\Delta \vec{r}$ is understood to originate at point A .

a the average velocity having the least magnitude 5.0 m/600 s is for the displacement ending at point C $\vec{v}_{\text{avg}} = 0.0083 \text{ m/s}$.

b the direction of \vec{v}_{avg} is 0° measured counterclockwise from the x axis.

c The average velocity having the greatest magnitude $\sqrt{15 \text{ m}^2 + 30 \text{ m}^2} / 300 \text{ s}$ is for the displacement ending at point B $\vec{v}_{avg} = 0.11 \text{ m/s}$.

d The direction of \vec{v}_{avg} is 297° counterclockwise from x or -63° which is equivalent to measuring 63° clockwise from the x axis.

10. We differentiate $\vec{r} = 5.00t\hat{i} + et + ft^2\hat{j}$.

a The particle's motion is indicated by the derivative of \vec{r} $\vec{v} = 5.00\hat{i} + e + 2ft\hat{j}$. The angle of its direction of motion is consequently

$$\theta = \tan^{-1} v_y / v_x = \tan^{-1} (e + 2ft) / 5.00.$$

The graph indicates $\theta_0 = 35.0^\circ$ which determines the parameter e

$$e = 5.00 \text{ m/s} \tan 35.0^\circ = 3.50 \text{ m/s}.$$

b We note from the graph that $\theta = 0$ when $t = 14.0 \text{ s}$. Thus $e + 2ft = 0$ at that time. This determines the parameter f

$$f = \frac{-e}{2t} = \frac{-3.5 \text{ m/s}}{2(14.0 \text{ s})} = -0.125 \text{ m/s}^2.$$

11. In parts b and c we use 4.10 and 4.16. For part d we find the direction of the velocity computed in part b since that represents the asked-for tangent line.

a Plugging into the given expression we obtain

$$\vec{r}|_{t=2.00} = (2.00\hat{i} - 5.00\hat{j}) + (6.00 - 7.00(16))\hat{j} = 6.00\hat{i} - 106\hat{j} \text{ m}$$

b Taking the derivative of the given expression produces

$$\vec{v}(t) = 6.00t^2\hat{i} - 5.00\hat{j} - 28.0t^3\hat{j}$$

Here we have written $v(t)$ to emphasize its dependence on time. This becomes at $t = 2.00 \text{ s}$ $\vec{v} = 19.0\hat{i} - 224\hat{j} \text{ m/s}$.

c Differentiating the $\vec{v}(t)$ found above with respect to t produces $12.0t\hat{i} - 84.0t^2\hat{j}$ which yields $\vec{a} = 24.0\hat{i} - 336\hat{j} \text{ m/s}^2$ at $t = 2.00 \text{ s}$.

d The angle of \vec{v} measured from x is either

$$\tan^{-1}\left(\frac{-224 \text{ m/s}}{19.0 \text{ m/s}}\right) = -85.2^\circ \text{ or } 94.8^\circ$$

here we settle on the first choice -85.2° which is equivalent to 275° measured counterclockwise from the x axis since the signs of its components imply that it is in the fourth quadrant.

12. We adopt a coordinate system with \hat{i} pointed east and \hat{j} pointed north; the coordinate origin is the flagpole. We “translate” the given information into unit vector notation as follows

$$\begin{aligned}\vec{r}_0 &= 40.0 \text{ m } \hat{i} & \text{and} & & \vec{v}_0 &= -10.0 \text{ m/s } \hat{j} \\ \vec{r} &= 40.0 \text{ m } \hat{j} & \text{and} & & \vec{v} &= 10.0 \text{ m/s } \hat{i}.\end{aligned}$$

a. Using Eq. 4-2 the displacement $\Delta\vec{r}$ is

$$\Delta\vec{r} = \vec{r} - \vec{r}_0 = -40.0 \text{ m } \hat{i} + 40.0 \text{ m } \hat{j}$$

with a magnitude $|\Delta\vec{r}| = \sqrt{(-40.0 \text{ m})^2 + (40.0 \text{ m})^2} = 56.6 \text{ m}$.

b. The direction of $\Delta\vec{r}$ is

$$\theta = \tan^{-1}\left(\frac{\Delta y}{\Delta x}\right) = \tan^{-1}\left(\frac{40.0 \text{ m}}{-40.0 \text{ m}}\right) = -45.0^\circ \text{ or } 135^\circ.$$

Since the desired angle is in the second quadrant we pick 135° (45° north of due west). Note that the displacement can be written as $\Delta\vec{r} = \vec{r} - \vec{r}_0 = (56.6 \angle 135^\circ)$ in terms of the magnitude-angle notation.

c. The magnitude of \vec{v}_{avg} is simply the magnitude of the displacement divided by the time $\Delta t = 30.0 \text{ s}$. Thus the average velocity has magnitude $56.6 \text{ m} / 30.0 \text{ s} = 1.89 \text{ m/s}$.

d. Equation 4-8 shows that \vec{v}_{avg} points in the same direction as $\Delta\vec{r}$ that is 135° (45° north of due west).

e. Using Eq. 4-15 we have

$$\vec{a}_{\text{avg}} = \frac{\vec{v} - \vec{v}_0}{\Delta t} = 0.333 \text{ m/s}^2 \hat{i} + 0.333 \text{ m/s}^2 \hat{j}.$$

The magnitude of the average acceleration vector is therefore equal to $|\vec{a}_{\text{avg}}| = \sqrt{(0.333 \text{ m/s}^2)^2 + (0.333 \text{ m/s}^2)^2} = 0.471 \text{ m/s}^2$.

find the direction of \vec{a}_{avg} is

$$\theta = \tan^{-1} \left(\frac{0.333 \text{ m s}^{-2}}{0.333 \text{ m s}^{-2}} \right) = 45^\circ \text{ or } -135^\circ.$$

Since the desired angle is not in the first quadrant we choose 45° and \vec{a}_{avg} points north of due east.

13. THINK Knowing the position of a particle as function of time allows us to calculate its corresponding velocity and acceleration by taking time derivatives.

EXPRESS From the position vector $\vec{r}(t)$ the velocity and acceleration of the particle can be found by differentiating $\vec{r}(t)$ with respect to time

$$\vec{v} = \frac{d\vec{r}}{dt} \quad \vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2}.$$

ANALYZE Taking the derivative of the position vector $\vec{r}(t) = \hat{i} + 4t^2\hat{j} + t\hat{k}$ with respect to time we have in units m/s

$$\vec{v} = \frac{d}{dt} (\hat{i} + 4t^2\hat{j} + t\hat{k}) = 8t\hat{j} + \hat{k}.$$

Taking another derivative with respect to time leads to in units m/s^2

$$\vec{a} = \frac{d}{dt} (8t\hat{j} + \hat{k}) = 8\hat{j}.$$

LEARN The particle undergoes constant acceleration in the y direction. This can be seen by noting that the y component of $\vec{r}(t)$ is $4t^2$ which is quadratic in t .

14. We use 4.15 with \vec{v}_1 designating the initial velocity and \vec{v}_2 designating the later one.

a The average acceleration during the $\Delta t = 4 \text{ s}$ interval is

$$\vec{a}_{\text{avg}} = \frac{-2.0\hat{i} - 2.0\hat{j} + 5.0\hat{k} \text{ m/s} - (-4.0\hat{i} - 22\hat{j} + 3.0\hat{k}) \text{ m/s}}{4 \text{ s}} = -1.5 \text{ m/s}^2 \hat{i} + 0.5 \text{ m/s}^2 \hat{j}.$$

b The magnitude of \vec{a}_{avg} is $\sqrt{(-1.5 \text{ m/s}^2)^2 + (0.5 \text{ m/s}^2)^2} = 1.6 \text{ m/s}^2$.

c Its angle in the xz plane measured from the x axis is one of these possibilities

$$\tan^{-1}\left(\frac{0.5 \text{ m s}^2}{-1.5 \text{ m s}^2}\right) = -18^\circ \text{ or } 162^\circ$$

here we settle on the second choice since the signs of its components imply that it is in the second quadrant.

15. THINK Given the initial velocity and acceleration of a particle, we're interested in finding its velocity and position at a later time.

EXPRESS Since the acceleration $\vec{a} = a_x \hat{i} + a_y \hat{j} = -1.0 \text{ m s}^{-2} \hat{i} + -0.50 \text{ m s}^{-2} \hat{j}$ is constant in both x and y directions we may use Table 2.1 for the motion along each direction. This can be handled individually for x and y or together with the unit vector notation for $\Delta \vec{r}$.

Since the particle started at the origin the coordinates of the particle at any time t are given by $\vec{r} = \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$. The velocity of the particle at any time t is given by $\vec{v} = \vec{v}_0 + \vec{a} t$ where \vec{v}_0 is the initial velocity and \vec{a} is the constant acceleration. Along the x direction we have

$$x(t) = v_{0x} t + \frac{1}{2} a_x t^2 \quad v_x(t) = v_{0x} + a_x t$$

Similarly along the y direction we get

$$y(t) = v_{0y} t + \frac{1}{2} a_y t^2 \quad v_y(t) = v_{0y} + a_y t.$$

Known $v_{0x} = 3.0 \text{ m s}^{-1}$ $v_{0y} = 0$ $a_x = -1.0 \text{ m s}^{-2}$ $a_y = -0.5 \text{ m s}^{-2}$.

ANALYZE a) Substituting the values given the components of the velocity are

$$v_x(t) = v_{0x} + a_x t = 3.0 \text{ m s}^{-1} - 1.0 \text{ m s}^{-2} t$$

$$v_y(t) = v_{0y} + a_y t = -0.50 \text{ m s}^{-2} t$$

When the particle reaches its maximum x coordinate at $t = t_m$ we must have $v_x = 0$. Therefore $3.0 - 1.0 t_m = 0$ or $t_m = 3.0 \text{ s}$. The y component of the velocity at this time is

$$v_y(t) = 3.0 \text{ s} = -0.50 \text{ m s}^{-2} (3.0) = -1.5 \text{ m s}^{-1}$$

thus $\vec{v}_m = -1.5 \text{ m s}^{-1} \hat{j}$.

b) At $t = 3.0 \text{ s}$ the components of the position are

$$x(t=3.0\text{ s}) = v_{0x}t + \frac{1}{2}a_x t^2 = 3.0\text{ m/s} \cdot 3.0\text{ s} + \frac{1}{2}(-1.0\text{ m/s}^2) \cdot 3.0\text{ s}^2 = 4.5\text{ m}$$

$$y(t=3.0\text{ s}) = v_{0y}t + \frac{1}{2}a_y t^2 = 0 + \frac{1}{2}(-0.5\text{ m/s}^2) \cdot 3.0\text{ s}^2 = -2.25\text{ m}$$

Using unit vector notation the results can be written as $\vec{r}_m = 4.50\text{ m} \hat{i} - 2.25\text{ m} \hat{j}$.

LEARN The motion of the particle in this problem is two dimensional and the kinematics in the x and y directions can be analysed separately.

16. We make use of Eq. 4-16.

a. The acceleration as a function of time is

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d}{dt}((6.0t - 4.0t^2)\hat{i} + 8.0\hat{j}) = (6.0 - 8.0t)\hat{i}$$

in m/s^2 units. Specifically we find the acceleration vector at $t = 3.0\text{ s}$ to be $(6.0 - 8.0 \cdot 3.0)\hat{i} = -18\text{ m/s}^2 \hat{i}$.

b. The equation is $\vec{a} = (6.0 - 8.0t)\hat{i} = 0$ we find $t = 0.75\text{ s}$.

c. Since the y component of the velocity $v_y = 8.0\text{ m/s}$ is never zero the velocity cannot vanish.

d. Since speed is the magnitude of the velocity we have

$$v = |\vec{v}| = \sqrt{(6.0t - 4.0t^2)^2 + (8.0)^2} = 10$$

in m/s units. To solve for t we first square both sides of the above equation followed by some rearrangement

$$(6.0t - 4.0t^2)^2 + 64 = 100 \Rightarrow (6.0t - 4.0t^2)^2 = 36$$

Taking the square root of the new expression and making further simplification lead to

$$6.0t - 4.0t^2 = \pm 6.0 \Rightarrow 4.0t^2 - 6.0t \pm 6.0 = 0$$

Finally using the quadratic formula we obtain

$$t = \frac{6.0 \pm \sqrt{36 - 4(4.0)(\pm 6.0)}}{2(8.0)}$$

here the requirement of a real positive result leads to the unique answer $t = 2.2$ s.

17. We find t by applying Eq. 2-11 to motion along the y axis with $v_y = 0$ characterizing $y = y_{\text{ma}}$

$$0 = 12 \text{ m/s} - 2.0 \text{ m/s}^2 t \Rightarrow t = 6.0 \text{ s.}$$

then Eq. 2-11 applies to motion along the x axis to determine the answer

$$v_x = 8.0 \text{ m/s} + 4.0 \text{ m/s}^2 (6.0 \text{ s}) = 32 \text{ m/s.}$$

therefore the velocity of the cart when it reaches $y = y_{\text{ma}}$ is 32 m/s .

18. We find t by solving $\Delta x = x_0 + v_{0x}t + \frac{1}{2}a_x t^2$

$$12.0 \text{ m} = 0 + 4.00 \text{ m/s} t + \frac{1}{2} 5.00 \text{ m/s}^2 t^2$$

here we have used $\Delta x = 12.0 \text{ m}$, $v_x = 4.00 \text{ m/s}$ and $a_x = 5.00 \text{ m/s}^2$. We use the quadratic formula and find $t = 1.53 \text{ s}$. Then Eq. 2-11 actually its analog in two dimensions applies with this value of t . Therefore its velocity when $\Delta x = 12.00 \text{ m}$ is

$$\begin{aligned} \vec{v} &= \vec{v}_0 + \vec{a}t = 4.00 \text{ m/s} \hat{i} + 5.00 \text{ m/s}^2 (1.53 \text{ s}) \hat{i} + 7.00 \text{ m/s}^2 (1.53 \text{ s}) \hat{j} \\ &= 11.7 \text{ m/s} \hat{i} + 10.7 \text{ m/s} \hat{j}. \end{aligned}$$

thus the magnitude of \vec{v} is $v = \sqrt{11.7^2 + 10.7^2} = 15.8 \text{ m/s}$.

b. The angle of \vec{v} measured from x is

$$\tan^{-1} \left(\frac{10.7 \text{ m/s}}{11.7 \text{ m/s}} \right) = 42.6^\circ.$$

19. We make use of Eqs. 4-16 and 4-10.

Since $\vec{a} = 3t\hat{i} + 4t\hat{j}$ we have in m/s

$$\vec{v}(t) = \vec{v}_0 + \int_0^t \vec{a} dt = 5.00\hat{i} + 2.00\hat{j} + \int_0^t (3t\hat{i} + 4t\hat{j}) dt = (5.00 + 3t^2/2)\hat{i} + (2.00 + 2t^2)\hat{j}$$

Integrating using Eq. 4-10 then yields in meters

$$\begin{aligned}
 \vec{r}(t) &= \vec{r}_0 + \int_0^t \vec{v} dt = 20.0\hat{i} + 40.0\hat{j} + \int_0^t (5.00 + 3t^2)\hat{i} + (2.00 + 2t^2)\hat{j} dt \\
 &= 20.0\hat{i} + 40.0\hat{j} + 5.00t + t^3)\hat{i} + (2.00t + 2t^3)\hat{j} \\
 &= (20.0 + 5.00t + t^3)\hat{i} + (40.0 + 2.00t + 2t^3)\hat{j}
 \end{aligned}$$

a At $t = 4.00 \text{ s}$ we have $\vec{r}(t = 4.00 \text{ s}) = 72.0 \text{ m } \hat{i} + 90.7 \text{ m } \hat{j}$.

b $\vec{v}(t = 4.00 \text{ s}) = 29.0 \text{ m/s } \hat{i} + 34.0 \text{ m/s } \hat{j}$. Thus the angle between the direction of travel and x measured counterclockwise is $\theta = \tan^{-1} \frac{34.0 \text{ m/s}}{29.0 \text{ m/s}} = 49.5^\circ$.

20. The acceleration is constant so that use of Table 2-1 for both the x and y motions is permitted. Here units are not shown; units are to be understood. Collision between particles A and B requires two things. First the y motion of B must satisfy Eq. 2-15 and noting that θ is measured from the y axis

$$y = \frac{1}{2} a_y t^2 \Rightarrow 30 \text{ m} = \frac{1}{2} [0.40 \text{ m/s}^2 \cos \theta] t^2.$$

Second the x motions of A and B must coincide

$$vt = \frac{1}{2} a_x t^2 \Rightarrow 3.0 \text{ m/s } t = \frac{1}{2} [0.40 \text{ m/s}^2 \sin \theta] t^2.$$

We eliminate a factor of t in the last relationship and formally solve for time

$$t = \frac{2v}{a_x} = \frac{2(3.0 \text{ m/s})}{0.40 \text{ m/s}^2 \sin \theta}.$$

This is then plugged into the previous equation to produce

$$30 \text{ m} = \frac{1}{2} [0.40 \text{ m/s}^2 \cos \theta] \left(\frac{2(3.0 \text{ m/s})}{0.40 \text{ m/s}^2 \sin \theta} \right)^2$$

which with the use of $\sin^2 \theta = 1 - \cos^2 \theta$ simplifies to

$$30 = \frac{9.0}{0.20} \frac{\cos \theta}{1 - \cos^2 \theta} \Rightarrow 1 - \cos^2 \theta = \frac{9.0}{(0.20)(30)} \cos \theta.$$

We use the quadratic formula (choosing the positive root) to solve for $\cos \theta$

$$\cos \theta = \frac{-1.5 + \sqrt{1.5^2 - 4(1.0)(-1.0)}}{2} = \frac{1}{2}$$

hich yields $\theta = \cos^{-1}\left(\frac{1}{2}\right) = 60^\circ$.

21. We adopt the positive direction choices used in the textbook so that the equations such as . 4 22 are directly applicable. The initial velocity is horizontal so that $v_{0,y} = 0$ and $v_{0,x} = v_0 = 10 \text{ m/s}$.

(a) With the origin at the initial point (where the dart leaves the thrower's hand), the y coordinate of the dart is given by $y = -\frac{1}{2}gt^2$ so that with $y = -PQ$ we have $PQ = \frac{1}{2}(9.8 \text{ m/s}^2)(0.19 \text{ s})^2 = 0.18 \text{ m}$.

b From $x = v_0t$ we obtain $x = 10 \text{ m/s} \cdot 0.19 \text{ s} = 1.9 \text{ m}$.

22. We adopt the positive direction choices used in the textbook so that the equations such as . 4 22 are directly applicable.

a With the origin at the initial point (edge of table) the y coordinate of the ball is given by $y = -\frac{1}{2}gt^2$. If t is the time of flight and $y = -1.20 \text{ m}$ indicates the level at which the ball hits the floor then

$$t = \sqrt{\frac{2(-1.20 \text{ m})}{-9.80 \text{ m/s}^2}} = 0.495 \text{ s}.$$

b The initial horizontal velocity of the ball is $\vec{v} = v_0 \hat{i}$. Since $x = 1.52 \text{ m}$ is the horizontal position of its impact point with the floor we have $x = v_0t$. Thus

$$v_0 = \frac{x}{t} = \frac{1.52 \text{ m}}{0.495 \text{ s}} = 3.07 \text{ m/s}.$$

23. a From . 4 22 with $\theta_0 = 0$ the time of flight is

$$t = \sqrt{\frac{2h}{g}} = \sqrt{\frac{2(45.0 \text{ m})}{9.80 \text{ m/s}^2}} = 3.03 \text{ s}.$$

b The horizontal distance traveled is given by . 4 21

$$\Delta x = v_0t = 250 \text{ m/s} \cdot 3.03 \text{ s} = 758 \text{ m}.$$

c And from . 4 23 we find

$$|v_y| = gt = 9.80 \text{ m/s}^2 \cdot 3.03 \text{ s} = 29.7 \text{ m/s}.$$

24. Use Eq. 4-26

$$R_{\text{ma}} = \left(\frac{v_0^2}{g} \sin 2\theta_0 \right)_{\text{ma}} = \frac{v_0^2}{g} = \frac{(9.50 \text{ m/s})^2}{9.80 \text{ m/s}^2} = 9.209 \text{ m} \approx 9.21 \text{ m}$$

to compare with Joel's long jump; the difference from R_{ma} is only $\Delta R = 9.21 \text{ m} - 8.95 \text{ m} = 0.259 \text{ m}$.

25. Using Eq. 4-26 the take off speed of the jumper is

$$v_0 = \sqrt{\frac{gR}{\sin 2\theta_0}} = \sqrt{\frac{9.80 \text{ m/s}^2 \cdot 77.0 \text{ m}}{\sin 2 \cdot 12.0^\circ}} = 43.1 \text{ m/s}$$

26. We adopt the positive direction choices used in the textbook so that equations such as Eq. 4-22 are directly applicable. The coordinate origin is the throwing point (the stone's initial position). The x component of its initial velocity is given by $v_{0x} = v_0 \cos \theta_0$ and the y component is given by $v_{0y} = v_0 \sin \theta_0$ here $v_0 = 20 \text{ m/s}$ is the initial speed and $\theta_0 = 40.0^\circ$ is the launch angle.

a. At $t = 1.10 \text{ s}$ its x coordinate is

$$x = v_0 t \cos \theta_0 = (20.0 \text{ m/s})(1.10 \text{ s}) \cos 40.0^\circ = 16.9 \text{ m}$$

b. Its y coordinate at that instant is

$$y = v_0 t \sin \theta_0 - \frac{1}{2} g t^2 = (20.0 \text{ m/s})(1.10 \text{ s}) \sin 40.0^\circ - \frac{1}{2} (9.80 \text{ m/s}^2)(1.10 \text{ s})^2 = 8.21 \text{ m}.$$

c. At $t' = 1.80 \text{ s}$ its x coordinate is $x = (20.0 \text{ m/s})(1.80 \text{ s}) \cos 40.0^\circ = 27.6 \text{ m}$.

d. Its y coordinate at t' is

$$y = (20.0 \text{ m/s})(1.80 \text{ s}) \sin 40.0^\circ - \frac{1}{2} (9.80 \text{ m/s}^2)(1.80 \text{ s})^2 = 7.26 \text{ m}.$$

e. The stone hits the ground earlier than $t = 5.0 \text{ s}$. To find the time when it hits the ground solve $y = v_0 t \sin \theta_0 - \frac{1}{2} g t^2 = 0$ for t . We find

$$t = \frac{2v_0}{g} \sin \theta_0 = \frac{2(20.0 \text{ m/s})}{9.8 \text{ m/s}^2} \sin 40^\circ = 2.62 \text{ s}.$$

ts x coordinate on landing is

$$x = v_0 t \cos \theta_0 = (20.0 \text{ m/s})(2.62 \text{ s}) \cos 40^\circ = 40.2 \text{ m}.$$

f Assuming it stays there it lands its vertical component at $t = 5.00 \text{ s}$ is $y = 0$.

27. We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at ground level directly below the release point. We write $\theta_0 = -30.0^\circ$ since the angle shown in the figure is measured clockwise from horizontal. We note that the initial speed of the decoy is the plane's speed at the moment of release $v_0 = 290 \text{ km/h}$ which we convert to SI units $290 \frac{1000}{3600} = 80.6 \text{ m/s}$.

a We use 4.12 to solve for the time

$$\Delta x = v_0 \cos \theta_0 t \Rightarrow t = \frac{700 \text{ m}}{80.6 \text{ m/s} \cos -30.0^\circ} = 10.0 \text{ s}.$$

b And we use 4.22 to solve for the initial height y_0

$$y - y_0 = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow 0 - y_0 = -40.3 \text{ m/s} \cdot 10.0 \text{ s} - \frac{1}{2} (9.80 \text{ m/s}^2) (10.0 \text{ s})^2$$

which yields $y_0 = 897 \text{ m}$.

28. a Using the same coordinate system assumed in 4.22 we solve for $y = h$

$$h = y_0 + v_0 \sin \theta_0 t - \frac{1}{2} g t^2$$

which yields $h = 51.8 \text{ m}$ for $y_0 = 0$, $v_0 = 42.0 \text{ m/s}$, $\theta_0 = 60.0^\circ$ and $t = 5.50 \text{ s}$.

b The horizontal motion is steady so $v_x = v_{0x} = v_0 \cos \theta_0$ but the vertical component of velocity varies according to 4.23. Thus the speed at impact is

$$v = \sqrt{(v_0 \cos \theta_0)^2 + (v_0 \sin \theta_0 - g t)^2} = 27.4 \text{ m/s}.$$

c We use 4.24 with $v_y = 0$ and $y = H$

$$H = \frac{(v_0 \sin \theta_0)^2}{2g} = 67.5 \text{ m}.$$

29. We adopt the positive direction choices used in the textbook so that the equations such as 4.22 are directly applicable. The coordinate origin is at its initial position where it is launched. At maximum height we observe $v_y = 0$ and denote $v_x = v$ which is also equal to v_{0x} . In this notation we have $v_0 = 5v$. We then observe $v_0 \cos \theta_0 = v_{0x} = v$ so that we arrive at an equation where $v \neq 0$ cancels which can be solved for θ_0

$$5v \cos \theta_0 = v \Rightarrow \theta_0 = \cos^{-1}\left(\frac{1}{5}\right) = 78.5^\circ.$$

30. Although we could use 4.26 to find where it lands we choose instead to work with 4.21 and 4.22 for the soccer ball since these will give information about where *and when* and these are also considered more fundamental than 4.26. With $\Delta y = 0$ we have

$$\Delta y = v_0 \sin \theta_0 t - \frac{1}{2}gt^2 \Rightarrow t = \frac{19.5 \text{ m/s} \sin 45.0^\circ}{9.80 \text{ m/s}^2} = 2.81 \text{ s}.$$

Then 4.21 yields $\Delta x = v_0 \cos \theta_0 t = 38.7 \text{ m}$. Thus using 4.8 the player must have an average velocity of

$$\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t} = \frac{38.7 \text{ m} \hat{i} - 55 \text{ m} \hat{j}}{2.81 \text{ s}} = -5.8 \text{ m/s} \hat{j}$$

which means his average speed assuming he ran in only one direction is 5.8 m/s.

31. We first find the time it takes for the volleyball to hit the ground. Using 4.22 we have

$$y - y_0 = v_0 \sin \theta_0 t - \frac{1}{2}gt^2 \Rightarrow 0 - 2.30 \text{ m} = -20.0 \text{ m/s} \sin 18.0^\circ t - \frac{1}{2} 9.80 \text{ m/s}^2 t^2$$

which gives $t = 0.30 \text{ s}$. Thus the range of the volleyball is

$$R = (v_0 \cos \theta_0)t = 20.0 \text{ m/s} \cos 18.0^\circ 0.30 \text{ s} = 5.71 \text{ m}$$

On the other hand when the angle is changed to $\theta'_0 = 8.00^\circ$ using the same procedure as shown above we find

$$y - y_0 = v_0 \sin \theta'_0 t' - \frac{1}{2}gt'^2 \Rightarrow 0 - 2.30 \text{ m} = -20.0 \text{ m/s} \sin 8.00^\circ t' - \frac{1}{2} 9.80 \text{ m/s}^2 t'^2$$

which yields $t' = 0.46 \text{ s}$ and the range is

$$R' = (v_0 \cos \theta'_0)t' = 20.0 \text{ m/s} \cos 8.00^\circ 0.46 \text{ s} = 9.06 \text{ m}$$

thus the ball travels an extra distance of

$$\Delta R = R' - R = 9.06 \text{ m} - 5.71 \text{ m} = 3.35 \text{ m}$$

32. We adopt the positive direction choices used in the textbook so that equations such as Eq. 4-22 are directly applicable. The coordinate origin is at the release point—the initial position for the ball as it begins projectile motion in the sense of Fig. 4-5—and we let θ_0 be the angle of throw shown in the figure. Since the horizontal component of the velocity of the ball is $v_x = v_0 \cos 40.0^\circ$, the time it takes for the ball to hit the wall is

$$t = \frac{\Delta x}{v_x} = \frac{22.0 \text{ m}}{25.0 \text{ m/s} \cos 40.0^\circ} = 1.15 \text{ s}.$$

a The vertical distance is

$$\Delta y = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 = (25.0 \text{ m/s} \sin 40.0^\circ)(1.15 \text{ s}) - \frac{1}{2} (9.80 \text{ m/s}^2)(1.15 \text{ s})^2 = 12.0 \text{ m}.$$

b The horizontal component of the velocity when it strikes the wall does not change from its initial value $v_x = v_0 \cos 40.0^\circ = 19.2 \text{ m/s}$.

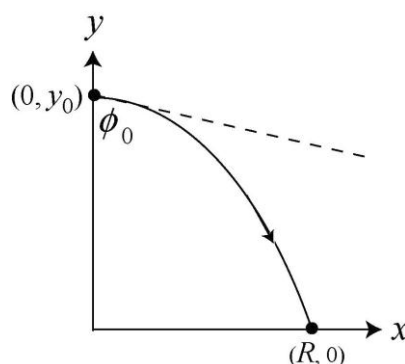
c The vertical component becomes using Eq. 4-23

$$v_y = v_0 \sin \theta_0 - g t = (25.0 \text{ m/s} \sin 40.0^\circ) - (9.80 \text{ m/s}^2)(1.15 \text{ s}) = 4.80 \text{ m/s}.$$

d Since $v_y > 0$ when the ball hits the wall, it has not reached the highest point yet.

33. **THINK** This problem deals with projectile motion. We're interested in the horizontal displacement and velocity of the projectile before it strikes the ground.

EXPRESS We adopt the positive direction choices used in the textbook so that equations such as Eq. 4-22 are directly applicable. The coordinate origin is at ground level directly below the release point. We write $\theta_0 = -37.0^\circ$ for the angle measured from the x axis since the angle $\phi_0 = 53.0^\circ$ given in the problem is measured from the $-y$ direction. The initial setup of the problem is shown in the figure to the right (not to scale).



ANALYZE (a) The initial speed of the projectile is the plane's speed at the moment of release. Given that $y_0 = 730 \text{ m}$ and $y = 0$ at $t = 5.00 \text{ s}$, we use Eq. 4-22 to find v_0

$$y - y_0 = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow 0 - 730 \text{ m} = v_0 \sin -37.0^\circ (5.00 \text{ s}) - \frac{1}{2} (9.80 \text{ m/s}^2) (5.00 \text{ s})^2$$

which yields $v_0 = 202 \text{ m/s}$.

b. The horizontal distance traveled is

$$R = v_x t = v_0 \cos \theta_0 t = (202 \text{ m/s}) \cos -37.0^\circ (5.00 \text{ s}) = 806 \text{ m}.$$

c. The x component of the velocity just before impact is

$$v_x = v_0 \cos \theta_0 = (202 \text{ m/s}) \cos -37.0^\circ = 161 \text{ m/s}.$$

d. The y component of the velocity just before impact is

$$v_y = v_0 \sin \theta_0 - g t = (202 \text{ m/s}) \sin -37.0^\circ - (9.80 \text{ m/s}^2) (5.00 \text{ s}) = -171 \text{ m/s}.$$

LEARN In this projectile problem we analyzed the kinematics in the vertical and horizontal directions separately since they do not affect each other. The x component of the velocity $v_x = v_0 \cos \theta_0$, remains unchanged throughout since there's no horizontal acceleration.

34. a. Since the y component of the velocity of the stone at the top of its path is zero its speed is

$$v = \sqrt{v_x^2 + v_y^2} = v_x = v_0 \cos \theta_0 = (28.0 \text{ m/s}) \cos 40.0^\circ = 21.4 \text{ m/s}.$$

b. Using the fact that $v_y = 0$ at the maximum height y_{ma} the amount of time it takes for the stone to reach y_{ma} is given by Eq. 4-23

$$0 = v_y = v_0 \sin \theta_0 - g t \Rightarrow t = \frac{v_0 \sin \theta_0}{g}.$$

Substituting the above expression into Eq. 4-22 we find the maximum height to be

$$y_{\text{ma}} = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 = v_0 \sin \theta_0 \left(\frac{v_0 \sin \theta_0}{g} \right) - \frac{1}{2} g \left(\frac{v_0 \sin \theta_0}{g} \right)^2 = \frac{v_0^2 \sin^2 \theta_0}{2g}.$$

To find the time the stone descends to $y = y_{\text{ma}}$ we solve the quadratic equation given in Eq. 4-22

$$y = \frac{1}{2} g t^2 = \frac{v_0^2 \sin^2 \theta_0}{2g} = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow t_{\pm} = \frac{2 \pm \sqrt{2} v_0 \sin \theta_0}{g}.$$

choosing $t = t_+$ for descending we have

$$v_x = v_0 \cos \theta_0 = 28.0 \text{ m/s} \cos 40.0^\circ = 21.4 \text{ m/s}$$

$$v_y = v_0 \sin \theta_0 - g \frac{2 + \sqrt{2} v_0 \sin \theta_0}{2g} = -\frac{\sqrt{2}}{2} v_0 \sin \theta_0 = -\frac{\sqrt{2}}{2} 28.0 \text{ m/s} \sin 40.0^\circ = -12.7 \text{ m/s}$$

thus the speed of the stone when $y = y_{\text{max}}$ is

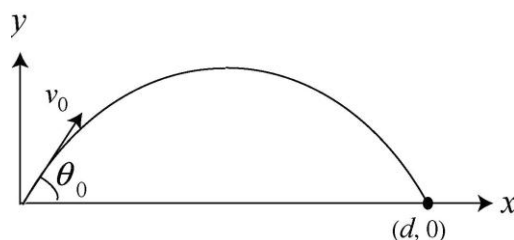
$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{(21.4 \text{ m/s})^2 + (-12.7 \text{ m/s})^2} = 24.9 \text{ m/s}.$$

c the percentage difference is

$$\frac{24.9 \text{ m/s} - 21.4 \text{ m/s}}{21.4 \text{ m/s}} = 0.163 = 16.3\%$$

35. **THINK** This problem deals with projectile motion of a bullet. We're interested in the firing angle that allows the bullet to strike a target at some distance away.

EXPRESS We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at the end of the rifle, the initial point for the bullet as it begins projectile motion in the sense of 4.5 and we let θ_0 be the firing angle. If the target is a distance d away then its coordinates are $x = d$, $y = 0$.



The projectile motion equations lead to

$$d = v_0 \cos \theta_0 t \quad 0 = v_0 t \sin \theta_0 - \frac{1}{2} g t^2$$

here θ_0 is the firing angle. The setup of the problem is shown in the figure above, scale exaggerated.

ANALYZE The time at which the bullet strikes the target is given by $t = d / v_0 \cos \theta_0$.

Eliminating t leads to $2v_0^2 \sin \theta_0 \cos \theta_0 - gd = 0$. Using $\sin \theta_0 \cos \theta_0 = \frac{1}{2} \sin(2\theta_0)$ we obtain

$$v_0^2 \sin 2\theta_0 = gd \Rightarrow \sin 2\theta_0 = \frac{gd}{v_0^2} = \frac{9.80 \text{ m/s}^2 \cdot 45.7 \text{ m}}{460 \text{ m/s}^2}$$

high yields $\sin 2\theta_0 = 2.11 \times 10^{-3}$ or $\theta_0 = 0.0606^\circ$. If the gun is aimed at a point a distance ℓ above the target then $\tan \theta_0 = \ell/d$ so that

$$\ell = d \tan \theta_0 = 45.7 \text{ m} \tan 0.0606^\circ = 0.0484 \text{ m} = 4.84 \text{ cm}.$$

LEARN Due to the downward gravitational acceleration in order for the bullet to strike the target the gun must be aimed at a point slightly above the target.

36. We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at ground level directly below the point where the ball was hit by the racket.

a. We want to know how high the ball is above the court when it is at $x = 12.0 \text{ m}$. First, 4.21 tells us the time it is over the fence

$$t = \frac{x}{v_0 \cos \theta_0} = \frac{12.0 \text{ m}}{(23.6 \text{ m/s}) \cos 0^\circ} = 0.508 \text{ s}.$$

At this moment the ball is at a height above the court of

$$y = y_0 + (v_0 \sin \theta_0)t - \frac{1}{2}gt^2 = 1.10 \text{ m}$$

which implies it does indeed clear the 0.90 m high fence.

b. At $t = 0.508 \text{ s}$ the center of the ball is $1.10 \text{ m} - 0.90 \text{ m} = 0.20 \text{ m}$ above the net.

c. Repeating the computation in part a with $\theta_0 = -5.0^\circ$ results in $t = 0.510 \text{ s}$ and $y = 0.040 \text{ m}$ which clearly indicates that it cannot clear the net.

d. In the situation discussed in part c the distance between the top of the net and the center of the ball at $t = 0.510 \text{ s}$ is $0.90 \text{ m} - 0.040 \text{ m} = 0.86 \text{ m}$.

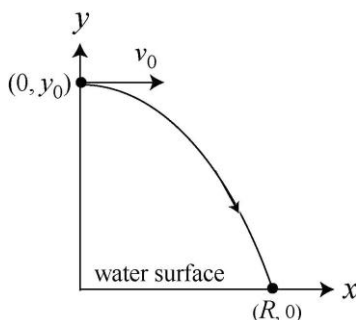
37. **THINK** The trajectory of the diver is a projectile motion. We are interested in the displacement of the diver at a later time.

EXPRESS The initial velocity has no vertical component $\theta_0 = 0^\circ$ but only an x component. Eqs. 4.21 and 4.22 can be simplified to

$$x - x_0 = v_{0x}t$$

$$y - y_0 = v_{0y}t - \frac{1}{2}gt^2 = -\frac{1}{2}gt^2.$$

here $x_0 = 0$, $v_{0x} = v_0 = +2.0 \text{ m/s}$ and $y_0 = 10.0 \text{ m}$ taking the water surface to be at $y = 0$. The setup of the problem is shown in the figure below.



ANALYZE a) At $t = 0.80 \text{ s}$ the horizontal distance of the diver from the edge is

$$x = x_0 + v_{0x}t = 0 + (2.0 \text{ m/s})(0.80 \text{ s}) = 1.60 \text{ m}.$$

b) Similarly using the second equation for the vertical motion we obtain

$$y = y_0 - \frac{1}{2}gt^2 = 10.0 \text{ m} - \frac{1}{2}(9.80 \text{ m/s}^2)(0.80 \text{ s})^2 = 6.86 \text{ m}.$$

c) At the instant the diver strikes the water surface $y = 0$. Solving for t using the equation $y = y_0 - \frac{1}{2}gt^2 = 0$ leads to

$$t = \sqrt{\frac{2y_0}{g}} = \sqrt{\frac{2(10.0 \text{ m})}{9.80 \text{ m/s}^2}} = 1.43 \text{ s}.$$

Using this time the x displacement of the diver is $R = x = (2.00 \text{ m/s})(1.43 \text{ s}) = 2.86 \text{ m}$.

LEARN Using Eq. 4.25 with $\theta_0 = 0$ the trajectory of the diver can also be written as

$$y = y_0 - \frac{gx^2}{2v_0^2}.$$

Part c can also be solved by using this equation

$$y = y_0 - \frac{gx^2}{2v_0^2} = 0 \Rightarrow x = R = \sqrt{\frac{2v_0^2 y_0}{g}} = \sqrt{\frac{2(2.0 \text{ m/s})^2(10.0 \text{ m})}{9.8 \text{ m/s}^2}} = 2.86 \text{ m}.$$

38. In this projectile motion problem we have $v_0 = v_x = \text{constant}$ and what is plotted is $v = \sqrt{v_x^2 + v_y^2}$. We infer from the plot that at $t = 2.5$ s the ball reaches its maximum height here $v_y = 0$. Therefore we infer from the graph that $v_x = 19$ m/s.

a During $t = 5$ s the horizontal motion is $x - x_0 = v_x t = 95$ m.

b Since $\sqrt{19^2 + v_{0y}^2} = 31$ m/s the first point on the graph we find $v_{0y} = 24.5$ m/s. Thus with $t = 2.5$ s we can use $y_{\text{ma}} - y_0 = v_{0y}t - \frac{1}{2}gt^2$ or $v_y^2 = 0 = v_{0y}^2 - 2g(y_{\text{ma}} - y_0)$ or $y_{\text{ma}} - y_0 = \frac{1}{2}(v_y + v_{0y})t$ to solve. Here we will use the latter

$$y_{\text{ma}} - y_0 = \frac{1}{2}(v_y + v_{0y})t \Rightarrow y_{\text{ma}} = \frac{1}{2}(0 + 24.5 \text{ m/s})(2.5 \text{ s}) = 31 \text{ m}$$

here we have taken $y_0 = 0$ as the ground level.

39. Following the hint we have the time reversed problem with the ball thrown from the ground to the right at 60° measured counterclockwise from a rightward axis. We see in this time reversed situation that it is convenient to use the familiar coordinate system with x as *rightward* and with positive angles measured counterclockwise.

a The x equation with $x_0 = 0$ and $x = 25.0$ m leads to

$$25.0 \text{ m} = v_0 \cos 60.0^\circ (1.50 \text{ s})$$

so that $v_0 = 33.3$ m/s. And with $y_0 = 0$ and $y = h = 0$ at $t = 1.50$ s we have $y - y_0 = v_{0y}t - \frac{1}{2}gt^2$ here $v_{0y} = v_0 \sin 60.0^\circ$. This leads to $h = 32.3$ m.

b We have

$$\begin{aligned} v_x &= v_{0x} = 33.3 \text{ m/s} \cos 60.0^\circ = 16.7 \text{ m/s} \\ v_y &= v_{0y} - gt = 33.3 \text{ m/s} \sin 60.0^\circ - 9.80 \text{ m/s}^2 (1.50 \text{ s}) = 14.2 \text{ m/s} \end{aligned}$$

The magnitude of \vec{v} is given by

$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{16.7^2 + 14.2^2} \text{ m/s} = 21.9 \text{ m/s}.$$

c The angle is

$$\theta = \tan^{-1}\left(\frac{v_y}{v_x}\right) = \tan^{-1}\left(\frac{14.2 \text{ m/s}}{16.7 \text{ m/s}}\right) = 40.4^\circ.$$

d We interpret this result (“undoing” the time reversal) as an initial velocity from the edge of the building of magnitude 21.9 m/s with angle θ down from leftward of 40.4° .

40. a Solving the quadratic equation . 4 22

$$y - y_0 = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow 0 - 2.160 \text{ m} = 15.00 \text{ m/s} \sin 45.00^\circ t - \frac{1}{2} 9.800 \text{ m/s}^2 t^2$$

the total travel time of the shot in the air is found to be $t = 2.352 \text{ s}$. Therefore the horizontal distance traveled is

$$R = (v_0 \cos \theta_0) t = 15.00 \text{ m/s} \cos 45.00^\circ 2.352 \text{ s} = 24.95 \text{ m}.$$

b Using the procedure outlined in a but for $\theta_0 = 42.00^\circ$ we have

$$y - y_0 = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow 0 - 2.160 \text{ m} = 15.00 \text{ m/s} \sin 42.00^\circ t - \frac{1}{2} 9.800 \text{ m/s}^2 t^2$$

and the total travel time is $t = 2.245 \text{ s}$. This gives

$$R = (v_0 \cos \theta_0) t = 15.00 \text{ m/s} \cos 42.00^\circ 2.245 \text{ s} = 25.02 \text{ m}.$$

41. With the archer fish set to be at the origin the position of the insect is given by x, y where $x = R/2 = v_0^2 \sin 2\theta_0 / 2g$ and y corresponds to the maximum height of the parabolic trajectory $y = y_{\text{ma}} = v_0^2 \sin^2 \theta_0 / 2g$. From the figure we have

$$\tan \phi = \frac{y}{x} = \frac{v_0^2 \sin^2 \theta_0 / 2g}{v_0^2 \sin 2\theta_0 / 2g} = \frac{1}{2} \tan \theta_0$$

Given that $\phi = 36.0^\circ$ we find the launch angle to be

$$\theta_0 = \tan^{-1}(2 \tan \phi) = \tan^{-1}(2 \tan 36.0^\circ) = \tan^{-1}(1.453) = 55.46^\circ \approx 55.5^\circ.$$

Note that θ_0 depends only on ϕ and is independent of d .

42. a Using the fact that the person as the projectile reaches the maximum height over the middle heel located at $x = 23 \text{ m} + 23/2 \text{ m} = 34.5 \text{ m}$ we can deduce the initial launch speed from . 4 26

$$x = \frac{R}{2} = \frac{v_0^2 \sin 2\theta_0}{2g} \Rightarrow v_0 = \sqrt{\frac{2gx}{\sin 2\theta_0}} = \sqrt{\frac{2 \cdot 9.8 \text{ m/s}^2 \cdot 34.5 \text{ m}}{\sin 2 \cdot 53^\circ}} = 26.5 \text{ m/s}.$$

Upon substituting the value to . 4 25 we obtain

$$y = y_0 + x \tan \theta_0 - \frac{gx^2}{2v_0^2 \cos^2 \theta_0} = 3.0 \text{ m} + 23 \text{ m} \tan 53^\circ - \frac{9.8 \text{ m/s}^2 (23 \text{ m})^2}{2 (26.5 \text{ m/s})^2 \cos^2 53^\circ} = 23.3 \text{ m}.$$

Since the height of the heel is $h_w = 18 \text{ m}$ the clearance over the first heel is $\Delta y = y - h_w = 23.3 \text{ m} - 18 \text{ m} = 5.3 \text{ m}$.

b The height of the person when he is directly above the second heel can be found by solving Eq. 4-24 with the second heel located at $x = 23 \text{ m} + 23.2 \text{ m} = 34.5 \text{ m}$. We have

$$y = y_0 + x \tan \theta_0 - \frac{gx^2}{2v_0^2 \cos^2 \theta_0} = 3.0 \text{ m} + 34.5 \text{ m} \tan 53^\circ - \frac{9.8 \text{ m/s}^2 (34.5 \text{ m})^2}{2 (26.52 \text{ m/s})^2 \cos^2 53^\circ} = 25.9 \text{ m}.$$

Therefore the clearance over the second heel is $\Delta y = y - h_w = 25.9 \text{ m} - 18 \text{ m} = 7.9 \text{ m}$.

c The location of the center of the net is given by

$$0 = y - y_0 = x \tan \theta_0 - \frac{gx^2}{2v_0^2 \cos^2 \theta_0} \Rightarrow x = \frac{v_0^2 \sin 2\theta_0}{g} = \frac{(26.52 \text{ m/s})^2 \sin 2 \cdot 53^\circ}{9.8 \text{ m/s}^2} = 69 \text{ m}.$$

43. We designate the given velocity $\vec{v} = 7.6 \text{ m/s} \hat{i} + 6.1 \text{ m/s} \hat{j}$ as \vec{v}_1 as opposed to the velocity when it reaches the maximum height \vec{v}_2 or the velocity when it returns to the ground \vec{v}_3 and take \vec{v}_0 as the launch velocity as usual. The origin is at its launch point on the ground.

a Different approaches are available but since it will be useful for the rest of the problem to first find the initial y velocity that is how we will proceed. Using Eq. 2-16 we have

$$v_{1y}^2 = v_{0y}^2 - 2g\Delta y \Rightarrow (6.1 \text{ m/s})^2 = v_{0y}^2 - 2(9.8 \text{ m/s}^2)(9.1 \text{ m})$$

which yields $v_{0y} = 14.7 \text{ m/s}$. Knowing that v_{2y} must be equal 0 we use Eq. 2-16 again but now with $\Delta y = h$ for the maximum height

$$v_{2y}^2 = v_{0y}^2 - 2gh \Rightarrow 0 = (14.7 \text{ m/s})^2 - 2(9.8 \text{ m/s}^2)h$$

which yields $h = 11 \text{ m}$.

b Recalling the derivation of Eq. 4-26 but using v_{0y} for $v_0 \sin \theta_0$ and v_{0x} for $v_0 \cos \theta_0$ we have

$$0 = v_{0y}t - \frac{1}{2}gt^2 \quad R = v_{0x}t$$

which leads to $R = 2v_{0x}v_{0y}$. Noting that $v_{0x} = v_{1x} = 7.6 \text{ m/s}$ we plug in values and obtain

$$R = 2(7.6 \text{ m/s})(14.7 \text{ m/s}) = 223 \text{ m}.$$

c Since $v_{3x} = v_{1x} = 7.6 \text{ m/s}$ and $v_{3y} = -v_{0y} = -14.7 \text{ m/s}$ we have

$$v_3 = \sqrt{v_{3x}^2 + v_{3y}^2} = \sqrt{(7.6 \text{ m/s})^2 + (-14.7 \text{ m/s})^2} = 17 \text{ m/s}.$$

d The angle measured from horizontal for \vec{v}_3 is one of these possibilities

$$\tan^{-1}\left(\frac{-14.7 \text{ m/s}}{7.6 \text{ m/s}}\right) = -63^\circ \text{ or } 117^\circ$$

Here we settle on the first choice -63° which is equivalent to 297° since the signs of its components imply that it is in the fourth quadrant.

44. We adopt the positive direction choices used in the textbook so that the equations such as 4.22 are directly applicable. The initial velocity is horizontal so that $v_{0y} = 0$ and $v_{0x} = v_0 = 161 \text{ km/h}$. Converting to SI units this is $v_0 = 44.7 \text{ m/s}$.

a With the origin at the initial point (where the ball leaves the pitcher's hand), the y coordinate of the ball is given by $y = -\frac{1}{2}gt^2$ and the x coordinate is given by $x = v_0t$. From the latter equation we have a simple proportionality between horizontal distance and time which means the time to travel half the total distance is half the total time. Specifically if $x = 18.3 \text{ m}$ then $t = 18.3 \text{ m} / 44.7 \text{ m/s} = 0.205 \text{ s}$.

b Find the time to travel the next 18.3 m must also be 0.205 s . It can be useful to write the horizontal equation as $\Delta x = v_0\Delta t$ in order that this result can be seen more clearly.

c Using the equation $y = -\frac{1}{2}gt^2$ we see that the ball has reached the height of $-\frac{1}{2}(9.80 \text{ m/s}^2)(0.205 \text{ s})^2 = -0.205 \text{ m}$ at the moment the ball is half way to the batter.

(d) The ball's height when it reaches the batter is $-\frac{1}{2}(9.80 \text{ m/s}^2)(0.409 \text{ s})^2 = -0.820 \text{ m}$

which when subtracted from the previous result implies it has fallen another 0.615 m . Since the value of y is not simply proportional to t we do not expect equal time intervals to correspond to equal height changes in a physical sense this is due to the fact that the initial y velocity for the first half of the motion is not the same as the "initial" y velocity for the second half of the motion.

45. a Let $m = \frac{d_2}{d_1} = 0.600$ be the slope of the ramp so $y = mx$ there. We choose our coordinate origin at the point of launch and use Eq. 4-25. Thus

$$y = \tan 50.0^\circ x - \frac{9.80 \text{ m/s}^2 x^2}{2 (10.0 \text{ m/s})^2 \cos^2 50.0^\circ} = 0.600x$$

which yields $x = 4.99 \text{ m}$. This is less than d_1 so the ball *does* land on the ramp.

b Using the value of x found in part (a) we obtain $y = mx = 2.99 \text{ m}$. Thus the Pythagorean theorem yields a displacement magnitude of $\sqrt{x^2 + y^2} = 5.82 \text{ m}$.

c The angle is of course the angle of the ramp $\tan^{-1} m = 31.0^\circ$.

46. Using the fact that $v_y = 0$ when the player is at the maximum height y_{ma} , the amount of time it takes to reach y_{ma} can be solved by using Eq. 4-23

$$0 = v_y = v_0 \sin \theta_0 - gt \Rightarrow t_{\text{ma}} = \frac{v_0 \sin \theta_0}{g}.$$

Substituting the above expression into Eq. 4-22 we find the maximum height to be

$$y_{\text{ma}} = v_0 \sin \theta_0 t_{\text{ma}} - \frac{1}{2} g t_{\text{ma}}^2 = v_0 \sin \theta_0 \left(\frac{v_0 \sin \theta_0}{g} \right) - \frac{1}{2} g \left(\frac{v_0 \sin \theta_0}{g} \right)^2 = \frac{v_0^2 \sin^2 \theta_0}{2g}.$$

To find the time when the player is at $y = y_{\text{ma}}/2$ we solve the quadratic equation given in Eq. 4-22

$$y = \frac{1}{2} y_{\text{ma}} = \frac{v_0^2 \sin^2 \theta_0}{4g} = v_0 \sin \theta_0 t - \frac{1}{2} g t^2 \Rightarrow t_{\pm} = \frac{2 \pm \sqrt{2} v_0 \sin \theta_0}{2g}.$$

With $t = t_-$ for ascending, the amount of time the player spends at a height $y \geq y_{\text{ma}}/2$ is

$$\Delta t = t_{\text{ma}} - t_- = \frac{v_0 \sin \theta_0}{g} - \frac{2 - \sqrt{2} v_0 \sin \theta_0}{2g} = \frac{v_0 \sin \theta_0}{\sqrt{2}g} = \frac{t_{\text{ma}}}{\sqrt{2}} \Rightarrow \frac{\Delta t}{t_{\text{ma}}} = \frac{1}{\sqrt{2}} = 0.707.$$

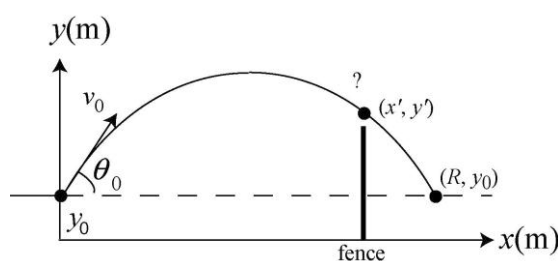
Therefore the player spends about 70.7% of the time in the upper half of the jump. Note that the ratio $\Delta t/t_{\text{ma}}$ is independent of v_0 and θ_0 even though Δt and t_{ma} depend on these quantities.

47. **THINK** The baseball undergoes projectile motion after being hit by the batter. We'd like to know if the ball clears a high fence at some distance away.

EXPRESS We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at ground level directly below impact point between bat and ball. In the absence of a fence with $\theta_0 = 45^\circ$ the horizontal range same launch level is $R = 107$ m. We want to know how high the ball is from the ground when it is at $x' = 97.5$ m which requires knowing the initial velocity. The trajectory of the baseball can be described by 4.25

$$y - y_0 = \tan \theta_0 x - \frac{gx^2}{2v_0^2 \cos^2 \theta_0}.$$

The setup of the problem is shown in the figure below (not to scale).



ANALYZE a We first solve for the initial speed v_0 . Using the range information $y = y_0$ when $x = R$ and $\theta_0 = 45^\circ$, 4.25 gives

$$v_0 = \sqrt{\frac{gR}{\sin 2\theta_0}} = \sqrt{\frac{(9.8 \text{ m/s}^2)(107 \text{ m})}{\sin 2 \cdot 45^\circ}} = 32.4 \text{ m/s}.$$

thus the time at which the ball flies over the fence is

$$x' = v_0 \cos \theta_0 t' \Rightarrow t' = \frac{x'}{v_0 \cos \theta_0} = \frac{97.5 \text{ m}}{(32.4 \text{ m/s}) \cos 45^\circ} = 4.26 \text{ s}.$$

At this moment the ball is at a height above the ground of

$$\begin{aligned} y' &= y_0 + (v_0 \sin \theta_0) t' - \frac{1}{2} g t'^2 \\ &= 1.22 \text{ m} + (32.4 \text{ m/s} \sin 45^\circ) (4.26 \text{ s}) - \frac{1}{2} (9.8 \text{ m/s}^2) (4.26 \text{ s})^2 \\ &= 9.88 \text{ m} \end{aligned}$$

which implies it does indeed clear the 7.32 m high fence.

b At $t' = 4.26$ s the center of the ball is $9.88 \text{ m} - 7.32 \text{ m} = 2.56 \text{ m}$ above the fence.

LEARN Using the trajectory equation above one can show that the minimum initial velocity required to clear the fence is given by

$$y' - y_0 = \tan \theta_0 x' - \frac{gx'^2}{2v_0^2 \cos^2 \theta_0}$$

or about 31.9 m/s.

48. Following the hint we have the time reversed problem with the ball thrown from the roof to the left at 60° measured clockwise from a leftward axis. We see in this time reversed situation that it is convenient to take x as *leftward* with positive angles measured clockwise. Lengths are in meters and time is in seconds.

a. With $y_0 = 20.0$ m and $y = 0$ at $t = 4.00$ s we have $y - y_0 = v_{0y}t - \frac{1}{2}gt^2$ here $v_{0y} = v_0 \sin 60^\circ$. This leads to $v_0 = 16.9$ m/s. This plugs into the x equation $x - x_0 = v_{0x}t$ with $x_0 = 0$ and $x = d$ to produce

$$d = 16.9 \text{ m/s} \cos 60^\circ (4.00 \text{ s}) = 33.7 \text{ m}.$$

b. We have

$$v_x = v_{0x} = 16.9 \text{ m/s} \cos 60.0^\circ = 8.43 \text{ m/s}$$

$$v_y = v_{0y} - gt = 16.9 \text{ m/s} \sin 60.0^\circ - 9.80 \text{ m/s}^2 (4.00 \text{ s}) = -24.6 \text{ m/s}.$$

The magnitude of \vec{v} is $\vec{v} = \sqrt{v_x^2 + v_y^2} = \sqrt{(8.43 \text{ m/s})^2 + (-24.6 \text{ m/s})^2} = 26.0 \text{ m/s}.$

c. The angle relative to horizontal is

$$\theta = \tan^{-1}\left(\frac{v_y}{v_x}\right) = \tan^{-1}\left(\frac{-24.6 \text{ m/s}}{8.43 \text{ m/s}}\right) = -71.1^\circ.$$

We may convert the result from rectangular components to magnitude-angle representation

$$\vec{v} = 8.43 \hat{i} - 24.6 \hat{j} \rightarrow 26.0 \angle -71.1^\circ$$

and we now interpret our result (“undoing” the time reversal) as an initial velocity of magnitude 26.0 m/s with angle up from rightward of 71.1°.

49. **THINK** In this problem a football is given an initial speed and it undergoes projectile motion. We’d like to know the smallest and greatest angles at which a field goal can be scored.

EXPRESS We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at the point where the ball is kicked. We use x and y to denote the coordinates of the ball at the goalpost and try to find the kicking angle θ_0 so that $y = 3.44$ m when $x = 50$ m. Writing the kinematic equations for projectile motion

$$x = v_0 \cos \theta_0 \quad y = v_0 t \sin \theta_0 - \frac{1}{2} g t^2$$

we see the first equation gives $t = x / v_0 \cos \theta_0$ and when this is substituted into the second the result is

$$y = x \tan \theta_0 - \frac{g x^2}{2 v_0^2 \cos^2 \theta_0}.$$

ANALYZE One may solve the above equation by trial and error systematically trying values of θ_0 until you find the two that satisfy the equation. A little manipulation however will give an algebraic solution using the trigonometric identity

$$1 - \cos^2 \theta_0 = \sin^2 \theta_0$$

we obtain

$$\frac{1}{2} \frac{g x^2}{v_0^2} \tan^2 \theta_0 - x \tan \theta_0 + y + \frac{1}{2} \frac{g x^2}{v_0^2} = 0$$

which is a second order equation for $\tan \theta_0$. To simplify writing the solution we denote

$$c = \frac{1}{2} g x^2 / v_0^2 = \frac{1}{2} (9.80 \text{ m/s}^2) (50 \text{ m})^2 / (25 \text{ m/s})^2 = 19.6 \text{ m}.$$

then the second order equation becomes $c \tan^2 \theta_0 - x \tan \theta_0 + y + c = 0$. Using the quadratic formula we obtain its solutions.

$$\tan \theta_0 = \frac{x \pm \sqrt{x^2 - 4(y+c)c}}{2c} = \frac{50 \text{ m} \pm \sqrt{50 \text{ m}^2 - 4(3.44 \text{ m} + 19.6 \text{ m})(19.6 \text{ m})}}{2(19.6 \text{ m})}.$$

The two solutions are given by $\tan \theta_0 = 1.95$ and $\tan \theta_0 = 0.605$. The corresponding first quadrant angles are $\theta_0 = 63^\circ$ and $\theta_0 = 31^\circ$. Thus

a The smallest elevation angle is $\theta_0 = 31^\circ$ and

b The greatest elevation angle is $\theta_0 = 63^\circ$.

LEARN If kicked at any angle between 31° and 63° the ball will travel above the cross bar on the goalposts.

50. We apply 4.21, 4.22 and 4.23.

a From $\Delta x = v_{0x} t$ we find $v_{0x} = 40 \text{ m/s} = 20 \text{ m/s}$.

b From $\Delta y = v_{0y} t - \frac{1}{2} g t^2$ we find $v_{0y} = \left(53 \text{ m} + \frac{1}{2} (9.8 \text{ m/s}^2) (2 \text{ s})^2 \right)^{1/2} = 36 \text{ m/s}$.

From $v_y = v_{0y} - gt'$ with $v_y = 0$ as the condition for maximum height we obtain $t' = 36 \text{ m/s} / 9.8 \text{ m/s}^2 = 3.7 \text{ s}$. During that time the x motion is constant so $x' - x_0 = 20 \text{ m/s} \cdot 3.7 \text{ s} = 74 \text{ m}$.

51. a. The skier jumps up at an angle of $\theta_0 = 11.3^\circ$ up from the horizontal and thus returns to the launch level with his velocity vector 11.3° below the horizontal. With the snow surface making an angle of $\alpha = 9.0^\circ$ down and with the horizontal the angle between the slope and the velocity vector is $\phi = \theta_0 - \alpha = 11.3^\circ - 9.0^\circ = 2.3^\circ$.

b. Suppose the skier lands at a distance d down the slope. Using Eq. 4-25 with $x = d \cos \alpha$ and $y = -d \sin \alpha$ (the edge of the track being the origin) we have

$$-d \sin \alpha = d \cos \alpha \tan \theta_0 - \frac{g d \cos^2 \alpha}{2v_0^2 \cos^2 \theta_0}.$$

Solving for d we obtain

$$\begin{aligned} d &= \frac{2v_0^2 \cos^2 \theta_0}{g \cos^2 \alpha} (\cos \alpha \tan \theta_0 + \sin \alpha) = \frac{2v_0^2 \cos \theta_0}{g \cos^2 \alpha} (\cos \alpha \sin \theta_0 + \cos \theta_0 \sin \alpha) \\ &= \frac{2v_0^2 \cos \theta_0}{g \cos^2 \alpha} \sin(\theta_0 + \alpha). \end{aligned}$$

Substituting the values given we find

$$d = \frac{2(10 \text{ m/s})^2 \cos 11.3^\circ}{9.8 \text{ m/s}^2 \cos^2 9.0^\circ} \sin 11.3^\circ + 9.0^\circ = 7.117 \text{ m}.$$

which gives

$$y = -d \sin \alpha = -7.117 \text{ m} \sin 9.0^\circ = -1.11 \text{ m}.$$

Therefore at landing the skier is approximately 1.1 m below the launch level.

c. The time it takes for the skier to land is

$$t = \frac{x}{v_x} = \frac{d \cos \alpha}{v_0 \cos \theta_0} = \frac{7.117 \text{ m} \cos 9.0^\circ}{10 \text{ m/s} \cos 11.3^\circ} = 0.72 \text{ s}.$$

Using Eq. 4-23 the x and y components of the velocity at landing are

$$\begin{aligned} v_x &= v_0 \cos \theta_0 = 10 \text{ m/s} \cos 11.3^\circ = 9.81 \text{ m/s} \\ v_y &= v_0 \sin \theta_0 - gt = 10 \text{ m/s} \sin 11.3^\circ - 9.8 \text{ m/s}^2 (0.72 \text{ s}) = -5.07 \text{ m/s} \end{aligned}$$

thus the direction of travel at landing is

$$\theta = \tan^{-1} \left(\frac{v_y}{v_x} \right) = \tan^{-1} \left(\frac{-5.07 \text{ m/s}}{9.81 \text{ m/s}} \right) = -27.3^\circ.$$

or 27.3° below the horizontal. The result implies that the angle between the skier's path and the slope is $\phi = 27.3^\circ - 9.0^\circ = 18.3^\circ$ or approximately 18° to two significant figures.

52. From Eq. 4-21 we find $t = x/v_{0x}$. Then Eq. 4-23 leads to

$$v_y = v_{0y} - gt = v_{0y} - \frac{gx}{v_{0x}}.$$

Since the slope of the graph is -0.500 we conclude

$$\frac{g}{v_{0x}} = \frac{1}{2} \Rightarrow v_{0x} = 19.6 \text{ m/s}.$$

And from the “y intercept” of the graph, we find $v_{0y} = 5.00 \text{ m/s}$. Consequently

$$\theta_0 = \tan^{-1} v_{0y}/v_{0x} = 14.3^\circ \approx 14^\circ.$$

53. Let $y_0 = h_0 = 1.00 \text{ m}$ at $x_0 = 0$ when the ball is hit. Let $y_1 = h$ the height of the ball and x_1 describe the point where it first rises above the ball one second after being hit similarly $y_2 = h$ and x_2 describe the point where it passes back down behind the ball four seconds later. And $y_f = 1.00 \text{ m}$ at $x_f = R$ is where it is caught. Lengths are in meters and time is in seconds.

a. Keeping in mind that v_x is constant we have $x_2 - x_1 = 50.0 \text{ m} = v_{1x} (4.00 \text{ s})$ which leads to $v_{1x} = 12.5 \text{ m/s}$. Thus applied to the full six seconds of motion

$$x_f - x_0 = R = v_x (6.00 \text{ s}) = 75.0 \text{ m}.$$

b. We apply $y - y_0 = v_{0y}t - \frac{1}{2}gt^2$ to the motion above the ball

$$y_2 - y_1 = 0 = v_{1y}(4.00 \text{ s}) - \frac{1}{2}g(4.00 \text{ s})^2$$

and obtain $v_{1y} = 19.6 \text{ m/s}$. One second earlier using $v_{1y} = v_{0y} - g(1.00 \text{ s})$ we find $v_{0y} = 29.4 \text{ m/s}$. Therefore the velocity of the ball just after being hit is

$$\vec{v} = v_{0x}\hat{i} + v_{0y}\hat{j} = 12.5 \text{ m/s} \hat{i} + 29.4 \text{ m/s} \hat{j}$$

ts magnitude is $\vec{v} = \sqrt{12.5 \text{ m s}^{-2} \quad 29.4 \text{ m s}^{-2}} = 31.9 \text{ m s}^{-1}$.

c The angle is

$$\theta = \tan^{-1}\left(\frac{v_y}{v_x}\right) = \tan^{-1}\left(\frac{29.4 \text{ m s}^{-1}}{12.5 \text{ m s}^{-1}}\right) = 67.0^\circ.$$

e interpret this result as a velocity of magnitude 31.9 m s^{-1} with angle 67.0° up from right and of 67.0° .

d During the first 1.00 s of motion $y = y_0 + v_{0y}t - \frac{1}{2}gt^2$ yields

$$h = 1.0 \text{ m} + (29.4 \text{ m s}^{-1})(1.00 \text{ s}) - \frac{1}{2}(9.8 \text{ m s}^{-2})(1.00 \text{ s})^2 = 25.5 \text{ m}.$$

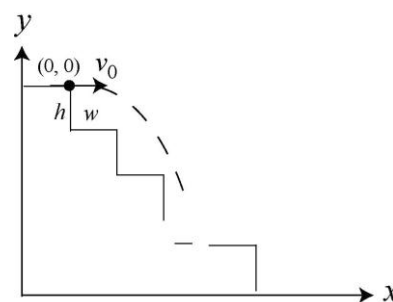
54. For $\Delta y = 0$, Eq. 4-22 leads to $t = 2v_0 \sin \theta_0 / g$ which immediately implies $t_{\text{ma}} = 2v_0 / g$ (which occurs for the “straight up” case: $\theta_0 = 90^\circ$). Thus

$$\frac{1}{2} t_{\text{ma}} = v_0 / g \Rightarrow \frac{1}{2} = \sin \theta_0.$$

Therefore the half maximum time flight is at angle $\theta_0 = 30.0^\circ$. Since the least speed occurs at the top of the trajectory which is here the velocity is simply the x component of the initial velocity $v_0 \cos \theta_0 = v_0 \cos 30^\circ$ for the half maximum time flight then we need to refer to the graph in order to find v_0 – in order that we may complete the solution. In the graph we note that the range is 240 m when $\theta_0 = 45.0^\circ$. Equation 4-26 then leads to $v_0 = 48.5 \text{ m s}^{-1}$. The answer is thus $48.5 \text{ m s}^{-1} \cos 30.0^\circ = 42.0 \text{ m s}^{-1}$.

55. **THINK** In this problem a ball rolls off the top of a stairway with an initial speed and we’d like to know on which step it lands first.

EXPRESS We denote h as the height of a step and w as the width. To hit step n the ball must fall a distance nh and travel horizontally a distance between $(n-1)w$ and nw . We take the origin of a coordinate system to be at the point where the ball leaves the top of the stairway and we choose the y axis to be positive in the upward direction as shown in the figure.



The coordinates of the ball at time t are given by $x = v_{0x}t$ and $y = -\frac{1}{2}gt^2$ since $v_{0y} = 0$.

ANALYZE We equate y to $-nh$ and solve for the time to reach the level of step n

$$t = \sqrt{\frac{2nh}{g}}.$$

the x coordinate then is

$$x = v_{0x} \sqrt{\frac{2nh}{g}} = 1.52 \text{ m s} \sqrt{\frac{2n \cdot 0.203 \text{ m}}{9.8 \text{ m s}^2}} = 0.309 \text{ m} \sqrt{n}.$$

The method is to try values of n until we find one for which x_w is less than n but greater than $n - 1$. For $n = 1$ $x = 0.309 \text{ m}$ and $x_w = 1.52$ which is greater than n . For $n = 2$ $x = 0.437 \text{ m}$ and $x_w = 2.15$ which is also greater than n . For $n = 3$ $x = 0.535 \text{ m}$ and $x_w = 2.64$. So this is less than n and greater than $n - 1$ so the ball hits the third step.

LEARN To check the consistency of our calculation we can substitute $n = 3$ into the above equations. The results are $t = 0.353 \text{ s}$, $y = 0.609 \text{ m}$ and $x = 0.535 \text{ m}$. This indeed corresponds to the third step.

56. We apply Eq. 4.35 to solve for speed v and Eq. 4.34 to find acceleration a .

a Since the radius of Earth is $6.37 \times 10^6 \text{ m}$ the radius of the satellite orbit is

$$r = 6.37 \times 10^6 + 640 \times 10^3 \text{ m} = 7.01 \times 10^6 \text{ m}.$$

Therefore the speed of the satellite is

$$v = \frac{2\pi r}{T} = \frac{2\pi(7.01 \times 10^6 \text{ m})}{(98.0 \text{ min})(60 \text{ s min})} = 7.49 \times 10^3 \text{ m s}^{-1}.$$

b The magnitude of the acceleration is

$$a = \frac{v^2}{r} = \frac{(7.49 \times 10^3 \text{ m s}^{-1})^2}{7.01 \times 10^6 \text{ m}} = 8.00 \text{ m s}^{-2}.$$

57. The magnitude of centripetal acceleration $a = v^2/r$ and its direction toward the center of the circle form the basis of this problem.

a If a passenger at this location experiences $\vec{a} = 1.83 \text{ m s}^{-2}$ east then the center of the circle is east of this location. The distance is $r = v^2/a = (3.66 \text{ m s}^{-1})^2 / 1.83 \text{ m s}^{-2} = 7.32 \text{ m}$.

b Thus relative to the center the passenger at that moment is located 7.32 m toward the east.

c If the direction of \vec{a} experienced by the passenger is not *south*—indicating that the center of the merry go round is south of him—then relative to the center the passenger at that moment is located 7.32 m toward the north.

58. a The circumference is $c = 2\pi r = 2\pi (0.15 \text{ m}) = 0.94 \text{ m}$.

b With $T = 60 \text{ s} / 1200 = 0.050 \text{ s}$ the speed is $v = c / T = 0.94 \text{ m} / 0.050 \text{ s} = 19 \text{ m/s}$. This is equivalent to using Eq. 4-35.

c The magnitude of the acceleration is $a = v^2 / r = (19 \text{ m/s})^2 / 0.15 \text{ m} = 2.4 \times 10^3 \text{ m/s}^2$.

d The period of revolution is $1200 \text{ rev/min}^{-1} = 8.3 \times 10^{-4} \text{ min}$ which becomes in units $T = 0.050 \text{ s} = 50 \text{ ms}$.

59. a Since the wheel completes 5 turns each minute its period is one fifth of a minute or 12 s.

b The magnitude of the centripetal acceleration is given by $a = v^2 / R$ where R is the radius of the wheel and v is the speed of the passenger. Since the passenger goes a distance $2\pi R$ for each revolution his speed is

$$v = \frac{2\pi(15 \text{ m})}{12 \text{ s}} = 7.85 \text{ m/s}$$

and his centripetal acceleration is $a = \frac{(7.85 \text{ m/s})^2}{15 \text{ m}} = 4.1 \text{ m/s}^2$.

c When the passenger is at the highest point his centripetal acceleration is downward toward the center of the orbit.

d At the lowest point the centripetal acceleration is $a = 4.1 \text{ m/s}^2$ same as part b.

e The direction is up toward the center of the orbit.

60. a During constant speed circular motion the velocity vector is perpendicular to the acceleration vector at every instant. Thus $\vec{v} \cdot \vec{a} = 0$.

b The acceleration in this vector at every instant points toward the center of the circle whereas the position vector points from the center of the circle to the object in motion. Thus the angle between \vec{r} and \vec{a} is 180° at every instant so $\vec{r} \times \vec{a} = 0$.

61. We apply Eq. 4-35 to solve for speed v and Eq. 4-34 to find centripetal acceleration a .

a $v = 2\pi r / T = 2\pi (20 \text{ km}) / 1.0 \text{ s} = 126 \text{ km/s} = 1.3 \times 10^5 \text{ m/s}$.

b The magnitude of the acceleration is

$$a = \frac{v^2}{r} = \frac{(126 \text{ km/s})^2}{20 \text{ km}} = 7.9 \times 10^5 \text{ m/s}^2.$$

c Clearly both v and a will increase if T is reduced.

62. The magnitude of the acceleration is

$$a = \frac{v^2}{r} = \frac{(10 \text{ m/s})^2}{25 \text{ m}} = 4.0 \text{ m/s}^2.$$

63. We first note that \vec{a}_1 the acceleration at $t_1 = 2.00 \text{ s}$ is perpendicular to \vec{a}_2 the acceleration at $t_2 = 5.00 \text{ s}$ by taking their scalar dot product

$$\vec{a}_1 \cdot \vec{a}_2 = 6.00 \text{ m/s}^2 \hat{i} \cdot 4.00 \text{ m/s}^2 \hat{j} = 0.$$

Since the acceleration vectors are in the negative radial directions then the two positions at t_1 and t_2 are a quarter circle apart or three quarters of a circle depending on whether one measures clockwise or counterclockwise. A quick sketch leads to the conclusion that if the particle is moving counterclockwise as the problem states then it travels three quarters of a circumference in moving from the position at time t_1 to the position at time t_2 . Letting T stand for the period then $t_2 - t_1 = 3.00 \text{ s} = 3T/4$. This gives $T = 4.00 \text{ s}$. The magnitude of the acceleration is

$$a = \sqrt{a_x^2 + a_y^2} = \sqrt{6.00^2 + 4.00^2} \text{ m/s}^2 = 7.21 \text{ m/s}^2.$$

Using Eqs. 4-34 and 4-35 we have $a = 4\pi^2 r / T^2$ which yields

$$r = \frac{aT^2}{4\pi^2} = \frac{7.21 \text{ m/s}^2 (4.00 \text{ s})^2}{4\pi^2} = 2.92 \text{ m}.$$

64. When traveling in circular motion with constant speed the instantaneous acceleration vector necessarily points toward the center. Thus, the center is “straight up” from the cited point.

a Since the center is “straight up” from $(4.00 \text{ m}, 4.00 \text{ m})$, the x coordinate of the center is 4.00 m .

b To find out “how far up” we need to know the radius. Using Eq. 4-34 we find

$$r = \frac{v^2}{a} = \frac{(5.00 \text{ m/s})^2}{12.5 \text{ m/s}^2} = 2.00 \text{ m}.$$

thus the y coordinate of the center is $2.00 \text{ m} + 4.00 \text{ m} = 6.00 \text{ m}$. thus the center may be written as $x, y = 4.00 \text{ m}, 6.00 \text{ m}$.

65. Since the period of a uniform circular motion is $T = 2\pi r/v$ here r is the radius and v is the speed the centripetal acceleration can be written as

$$a = \frac{v^2}{r} = \frac{1}{r} \left(\frac{2\pi r}{T} \right)^2 = \frac{4\pi^2 r}{T^2}.$$

Based on this expression we compare the magnitudes of theallet and purse accelerations and find their ratio is the ratio of r values. therefore $a_{\text{allet}} = 1.50 a_{\text{purse}}$. thus the allet acceleration vector is

$$a = 1.50 (2.00 \text{ m/s}^2) \hat{i} + 4.00 \text{ m/s}^2 \hat{j} = 3.00 \text{ m/s}^2 \hat{i} + 6.00 \text{ m/s}^2 \hat{j}.$$

66. The fact that the velocity is in the y direction and the acceleration is in the x direction at $t_1 = 4.00 \text{ s}$ implies that the motion is clockwise. The position corresponds to the “9 00 position.” On the other hand the position at $t_2 = 10.0 \text{ s}$ is in the “6 00 position” since the velocity points in the $-x$ direction and the acceleration is in the y direction. The time interval $\Delta t = 10.0 \text{ s} - 4.00 \text{ s} = 6.00 \text{ s}$ is equal to $3/4$ of a period

$$6.00 \text{ s} = \frac{3}{4}T \Rightarrow T = 8.00 \text{ s}.$$

Equation 4.35 then yields

$$r = \frac{vT}{2\pi} = \frac{3.00 \text{ m/s} \cdot 8.00 \text{ s}}{2\pi} = 3.82 \text{ m}.$$

a The x coordinate of the center of the circular path is $x = 5.00 \text{ m} + 3.82 \text{ m} = 8.82 \text{ m}$.

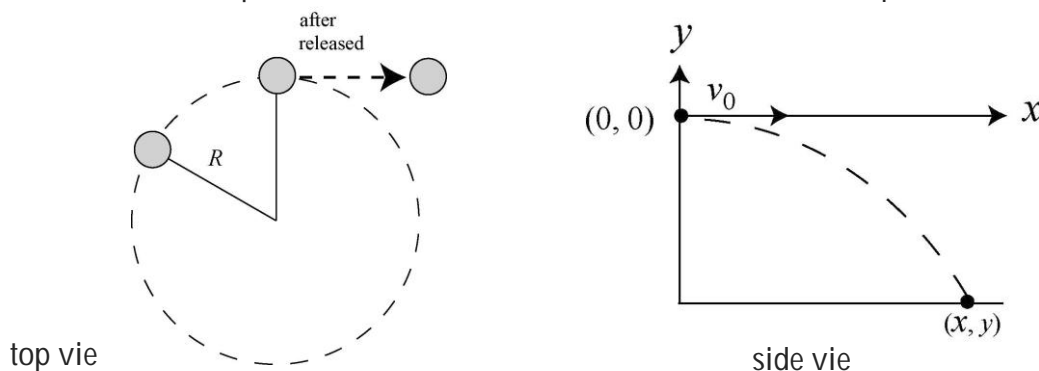
b The y coordinate of the center of the circular path is $y = 6.00 \text{ m}$.

In other words the center of the circle is at $x, y = 8.82 \text{ m}, 6.00 \text{ m}$.

67. **THINK** In this problem we have a stone whirled in a horizontal circle. After the string breaks the stone undergoes projectile motion.

EXPRESS The stone moves in a circular path. Top view shown below left initially but undergoes projectile motion after the string breaks. Side view shown below right. Since $a = v^2/R$ to calculate the centripetal acceleration of the stone we need to know its

speed during its circular motion this is also its initial speed when it flies off. We use the kinematic equations of projectile motion discussed in 4.6 to find that speed.



taking the y direction to be up and placing the origin at the point where the stone leaves its circular orbit then the coordinates of the stone during its motion as a projectile are given by $x = v_0 t$ and $y = -\frac{1}{2} g t^2$ since $v_{0y} = 0$. It hits the ground at $x = 10$ m and $y = -2.0$ m.

ANALYZE Formally solving the y component equation for the time we obtain $t = \sqrt{-2y/g}$ which we substitute into the first equation

$$v_0 = x \sqrt{-\frac{g}{2y}} = (10 \text{ m}) \sqrt{-\frac{9.8 \text{ m/s}^2}{2(-2.0 \text{ m})}} = 15.7 \text{ m/s}.$$

therefore the magnitude of the centripetal acceleration is

$$a = \frac{v_0^2}{R} = \frac{(15.7 \text{ m/s})^2}{1.5 \text{ m}} = 160 \text{ m/s}^2.$$

LEARN The above equations can be combined to give $a = \frac{gx^2}{-2yR}$. The equation implies

that the greater the centripetal acceleration the greater the initial speed of the projectile and the greater the distance traveled by the stone. This is precisely what we expect.

68. We note that after three seconds have elapsed $t_2 - t_1 = 3.00$ s the velocity for this object in circular motion of period T is reversed. We infer that it takes three seconds to reach the opposite side of the circle. Thus $T = 2(3.00 \text{ s}) = 6.00$ s.

According to 4.35 $r = vT/2\pi$ here $v = \sqrt{3.00 \text{ m/s}^2 + 4.00 \text{ m/s}^2} = 5.00 \text{ m/s}$ we obtain $r = 4.77$ m. The magnitude of the object's centripetal acceleration is therefore $a = v^2/r = 5.24 \text{ m/s}^2$.

b The average acceleration is given by . 4 15

$$\vec{a}_{\text{avg}} = \frac{\vec{v}_2 - \vec{v}_1}{t_2 - t_1} = \frac{-3.00\hat{i} - 4.00\hat{j} \text{ m/s} - (-3.00\hat{i} + 4.00\hat{j} \text{ m/s})}{5.00 \text{ s} - 2.00 \text{ s}} = -2.00 \text{ m/s}^2 \hat{i} - 2.67 \text{ m/s}^2 \hat{j}$$

which implies $a_{\text{avg}} = \sqrt{(-2.00 \text{ m/s}^2)^2 + (-2.67 \text{ m/s}^2)^2} = 3.33 \text{ m/s}^2$.

69. We use . 4 15 first using velocities relative to the truck (subscript t) and then using velocities relative to the ground (subscript g). We work with units so $20 \text{ km/h} \rightarrow 5.6 \text{ m/s}$, $30 \text{ km/h} \rightarrow 8.3 \text{ m/s}$ and $45 \text{ km/h} \rightarrow 12.5 \text{ m/s}$. We choose east as the $+\hat{i}$ direction.

a The velocity of the cheetah (subscript c) at the end of the 2.0 s interval is from . 4 44

$$\vec{v}_{ct} = \vec{v}_{cg} - \vec{v}_{tg} = 12.5 \text{ m/s} \hat{i} - 5.6 \text{ m/s} \hat{i} = 6.9 \text{ m/s} \hat{i}$$

relative to the truck. Since the velocity of the cheetah relative to the truck at the beginning of the 2.0 s interval is $-8.3 \text{ m/s} \hat{i}$ the average acceleration vector relative to the cameraman in the truck is

$$\vec{a}_{\text{avg}} = \frac{6.9 \text{ m/s} \hat{i} - (-8.3 \text{ m/s} \hat{i})}{2.0 \text{ s}} = 7.6 \text{ m/s}^2 \hat{i}$$

or $a_{\text{avg}} = 7.6 \text{ m/s}^2$.

b The direction of \vec{a}_{avg} is \hat{i} or eastward.

c The velocity of the cheetah at the start of the 2.0 s interval is from . 4 44

$$\vec{v}_{cg} = \vec{v}_{ct} + \vec{v}_{tg} = -8.3 \text{ m/s} \hat{i} + -5.6 \text{ m/s} \hat{i} = -13.9 \text{ m/s} \hat{i}$$

relative to the ground. The average acceleration vector relative to the cameraman on the ground is

$$\vec{a}_{\text{avg}} = \frac{6.9 \text{ m/s} \hat{i} - (-13.9 \text{ m/s} \hat{i})}{2.0 \text{ s}} = 10.4 \text{ m/s}^2 \hat{i} \quad a_{\text{avg}} = 10.4 \text{ m/s}^2$$

identical to the result of part a.

d The direction of \vec{a}_{avg} is \hat{i} or eastward.

70. We use . 4 44 noting that the upstream corresponds to the $+\hat{i}$ direction.

a The subscript b is for the boat, s is for the stream, and g is for the ground.

$$\vec{v}_{bg} = \vec{v}_b + \vec{v}_g = 14 \text{ km/h } \hat{i} + -9 \text{ km/h } \hat{i} = 5 \text{ km/h } \hat{i}.$$

thus the magnitude is $|\vec{v}_{bg}| = 5 \text{ km/h}$.

b the direction of \vec{v}_{bg} is $+x$ or upstream.

c we use the subscript c for the child and obtain

$$\vec{v}_{cg} = \vec{v}_{cb} + \vec{v}_{bg} = -6 \text{ km/h } \hat{i} + 5 \text{ km/h } \hat{i} = -1 \text{ km/h } \hat{i}.$$

the magnitude is $|\vec{v}_{cg}| = 1 \text{ km/h}$.

d the direction of \vec{v}_{cg} is $-x$ or downstream.

71. While moving in the same direction as the sidewalk's motion (covering a distance d relative to the ground in time $t_1 = 2.50 \text{ s}$), the man leads to

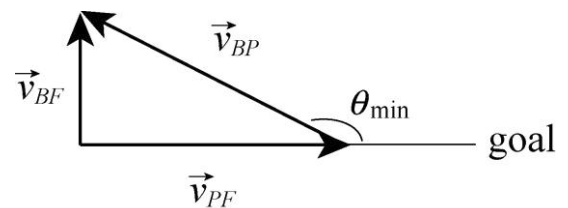
$$v_{\text{sidewalk}} + v_{\text{man running}} = \frac{d}{t_1}.$$

While he runs back taking time $t_2 = 10.0 \text{ s}$, we have

$$v_{\text{sidewalk}} - v_{\text{man running}} = -\frac{d}{t_2}.$$

Dividing these equations and solving for the desired ratio, we get $\frac{12.5}{7.5} = \frac{5}{3} = 1.67$.

72. We denote the velocity of the player with \vec{v}_{PF} and the relative velocity between the player and the ball be \vec{v}_{BP} . Then the velocity \vec{v}_{BF} of the ball relative to the field is given by $\vec{v}_{BF} = \vec{v}_{PF} + \vec{v}_{BP}$. The smallest angle θ_{\min} corresponds to the case when $\vec{v}_{BF} \perp \vec{v}_{PF}$. Hence



$$\theta_{\min} = 180^\circ - \cos^{-1} \left(\frac{|\vec{v}_{PF}|}{|\vec{v}_{BP}|} \right) = 180^\circ - \cos^{-1} \left(\frac{4.0 \text{ m/s}}{6.0 \text{ m/s}} \right) = 130^\circ.$$

73. We denote the police and the motorist with subscripts p and m respectively. The coordinate system is indicated in Fig. 4.46.

a the velocity of the motorist with respect to the police car is

$$\vec{v}_{m/p} = \vec{v}_m - \vec{v}_p = -60 \text{ km/h } \hat{i} - (-80 \text{ km/h } \hat{i}) = 80 \text{ km/h } \hat{i} - 60 \text{ km/h } \hat{i}.$$

b \vec{v}_{mp} does happen to be along the line of sight. Referring to fig. 4.46 we find the vector pointing from one car to another is $\vec{r} = 800 \text{ m } \hat{i} - 600 \text{ m } \hat{j}$ from M to P . Since the ratio of components in \vec{r} is the same as in \vec{v}_{mp} they must point the same direction.

c so they remain unchanged.

74. Velocities are taken to be constant thus the velocity of the plane relative to the ground is $\vec{v}_{PG} = 55 \text{ km/h } \hat{i} = 220 \text{ km/h } \hat{i}$. In addition

$$\vec{v}_{AG} = 42 \text{ km/h } \cos 20^\circ \hat{i} - \sin 20^\circ \hat{j} = 39 \text{ km/h } \hat{i} - 14 \text{ km/h } \hat{j}.$$

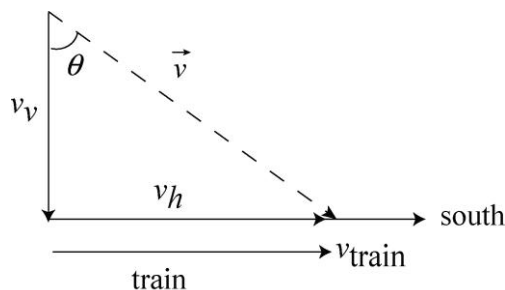
Since $\vec{v}_{PG} = \vec{v}_{PA} + \vec{v}_{AG}$ we have

$$\vec{v}_{PA} = \vec{v}_{PG} - \vec{v}_{AG} = -39 \text{ km/h } \hat{i} + 234 \text{ km/h } \hat{j}.$$

which implies $v_{PA} = 237 \text{ km/h}$ or 240 km/h to two significant figures.

75. **THINK** This problem deals with relative motion in two dimensions. Raindrops appear to fall vertically by an observer on a moving train.

EXPRESS Since the raindrops fall vertically relative to the train the horizontal component of the velocity of a raindrop $v_h = 30 \text{ m/s}$ must be the same as the speed of the train i.e. $v_h = v_{\text{train}}$ see figure.



On the other hand if v_v is the vertical component of the velocity and θ is the angle between the direction of motion and the vertical then $\tan \theta = v_h / v_v$. Knowing v_v and v_h allows us to determine the speed of the raindrops.

ANALYZE With $\theta = 70^\circ$ we find the vertical component of the velocity to be

$$v_v = v_h \tan \theta = 30 \text{ m/s } \tan 70^\circ = 10.9 \text{ m/s}.$$

Therefore the speed of a raindrop is

$$v = \sqrt{v_h^2 + v_v^2} = \sqrt{(30 \text{ m/s})^2 + (10.9 \text{ m/s})^2} = 32 \text{ m/s}.$$

LEARN As long as the horizontal component of the velocity of the raindrops coincides with the speed of the train the passenger on board will see the rain falling perfectly vertically.

76. The destination is $\vec{D} = 800 \text{ km}$. Here we orient axes so that y points north and x points east. This takes two hours so the constant velocity of the plane relative to the ground is $\vec{v}_{pg} = 400 \text{ km/h}$. This must be the vector sum of the plane's velocity with respect to the air which has x, y components $500\cos 70^\circ$ $500\sin 70^\circ$ and the velocity of the air (wind) relative to the ground \vec{v}_{ag} . Thus

$$400 \text{ km/h} = 500 \text{ km/h} \cos 70^\circ \hat{i} + 500 \text{ km/h} \sin 70^\circ \hat{j} + \vec{v}_{ag}$$

which yields

$$\vec{v}_{ag} = -171 \text{ km/h} \hat{i} - 70.0 \text{ km/h} \hat{j}.$$

a The magnitude of \vec{v}_{ag} is $|\vec{v}_{ag}| = \sqrt{(-171 \text{ km/h})^2 + (-70.0 \text{ km/h})^2} = 185 \text{ km/h}$.

b The direction of \vec{v}_{ag} is

$$\theta = \tan^{-1} \left(\frac{-70.0 \text{ km/h}}{-171 \text{ km/h}} \right) = 22.3^\circ \text{ south of west}.$$

77. **THINK** This problem deals with relative motion in two dimensions. Snow flakes falling vertically do not and are seen to fall at an angle by a moving observer.

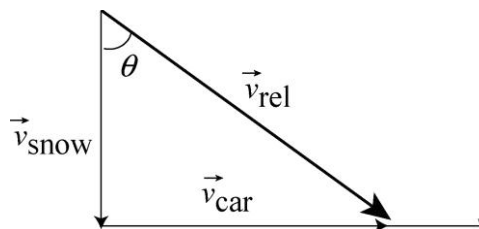
EXPRESS Relative to the car the velocity of the snow flakes has a vertical component of $v_v = 8.0 \text{ m/s}$ and a horizontal component of $v_h = 50 \text{ km/h} = 13.9 \text{ m/s}$.

ANALYZE The angle θ from the vertical is found from

$$\tan \theta = \frac{v_h}{v_v} = \frac{13.9 \text{ m/s}}{8.0 \text{ m/s}} = 1.74$$

which yields $\theta = 60^\circ$.

LEARN The problem can also be solved by expressing the velocity relation in vector notation $\vec{v}_{\text{rel}} = \vec{v}_{\text{car}} + \vec{v}_{\text{snow}}$ as shown in the figure.



78. We make use of 4.44 and 4.45.

The velocity of deep P relative to A at the instant is

$$\vec{v}_{PA} = 40.0 \text{ m/s} \cos 60^\circ \hat{i} + \sin 60^\circ \hat{j} = 20.0 \text{ m/s} \hat{i} + 34.6 \text{ m/s} \hat{j}.$$

imilarly the velocity of ship B relative to A at the instant is

$$\vec{v}_{BA} = 20.0 \text{ m/s} \cos 30^\circ \hat{i} + \sin 30^\circ \hat{j} = 17.3 \text{ m/s} \hat{i} + 10.0 \text{ m/s} \hat{j}.$$

thus the velocity of P relative to B is

$$\vec{v}_{PB} = \vec{v}_{PA} - \vec{v}_{BA} = 20.0\hat{i} + 34.6\hat{j} \text{ m/s} - 17.3\hat{i} + 10.0\hat{j} \text{ m/s} = 2.68 \text{ m/s} \hat{i} + 24.6 \text{ m/s} \hat{j}.$$

a the magnitude of \vec{v}_{PB} is $v_{PB} = \sqrt{2.68^2 + 24.6^2} \text{ m/s} = 24.8 \text{ m/s}.$

b the direction of \vec{v}_{PB} is $\theta = \tan^{-1} \frac{24.6 \text{ m/s}}{2.68 \text{ m/s}} = 83.8^\circ$ north of east or 6.2° east of north.

c the acceleration of P is

$$\vec{a}_{PA} = 0.400 \text{ m/s}^2 \cos 60.0^\circ \hat{i} + \sin 60.0^\circ \hat{j} = 0.200 \text{ m/s}^2 \hat{i} + 0.346 \text{ m/s}^2 \hat{j}$$

and $\vec{a}_{PA} = \vec{a}_{PB}$. thus we have $\vec{a}_{PB} = 0.400 \text{ m/s}^2.$

d the direction is 60.0° north of east or 30.0° east of north.

79. THINK This problem involves analyzing the relative motion of two ships sailing in different directions.

EXPRESS Given that $\theta_A = 45^\circ$ and $\theta_B = 40^\circ$ as defined in the figure the velocity vectors relative to the shore for ships A and B are given by

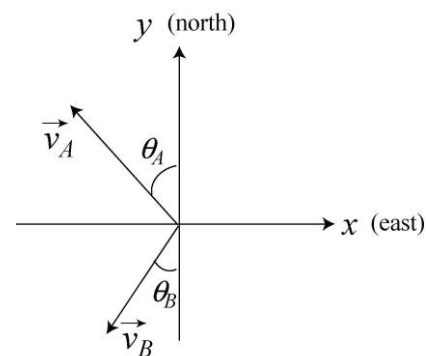
$$\vec{v}_A = -v_A \cos 45^\circ \hat{i} + v_A \sin 45^\circ \hat{j}$$

$$\vec{v}_B = -v_B \sin 40^\circ \hat{i} - v_B \cos 40^\circ \hat{j}$$

With $v_A = 24$ knots and $v_B = 28$ knots. We take east as $+\hat{i}$ and north as $+\hat{j}$.

The velocity of ship A relative to ship B is simply given by $\vec{v}_{AB} = \vec{v}_A - \vec{v}_B$.

ANALYZE a the relative velocity is



$$\begin{aligned}\vec{v}_{AB} &= \vec{v}_A - \vec{v}_B = v_B \sin 40^\circ - v_A \cos 45^\circ \hat{i} + v_B \cos 40^\circ + v_A \sin 45^\circ \hat{j} \\ &= 1.03 \text{ knots } \hat{i} + 38.4 \text{ knots } \hat{j}\end{aligned}$$

the magnitude of which is $v_{AB} = \sqrt{1.03 \text{ knots}^2 + 38.4 \text{ knots}^2} \approx 38.4 \text{ knots}$.

b The angle θ_{AB} which \vec{v}_{AB} makes with north is given by

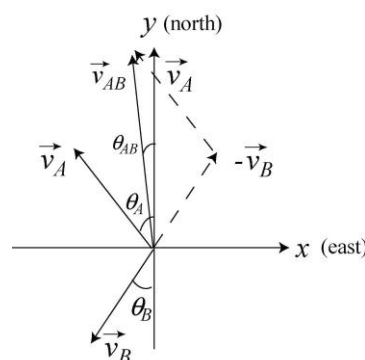
$$\theta_{AB} = \tan^{-1} \left(\frac{v_{ABx}}{v_{ABy}} \right) = \tan^{-1} \left(\frac{1.03 \text{ knots}}{38.4 \text{ knots}} \right) = 1.5^\circ$$

which is to say that \vec{v}_{AB} points 1.5° east of north.

c Since the two ships started at the same time their relative velocity describes at that rate the distance between them is increasing. Because the rate is steady we have

$$t = \frac{\Delta r_{AB}}{v_{AB}} = \frac{160 \text{ nautical miles}}{38.4 \text{ knots}} = 4.2 \text{ h.}$$

d The velocity \vec{v}_{AB} does not change with time in this problem and \vec{r}_{AB} is in the same direction as \vec{v}_{AB} since they started at the same time. Reversing the points of view we have $\vec{v}_{AB} = -\vec{v}_{BA}$ so that $\vec{r}_{AB} = -\vec{r}_{BA}$ i.e. they are 180° opposite to each other. Hence we conclude that B stays at a bearing of 1.5° east of south relative to A during the journey neglecting the curvature of earth.



LEARN The relative velocity is depicted in the figure on the right. When analyzing relative motion in two dimensions a vector diagram such as the one shown can be very helpful.

80. This is a classic problem involving two dimensional relative motion. We align our coordinates so that *east* corresponds to x and *north* corresponds to y . We write the vector addition equation as $\vec{v}_{BG} = \vec{v}_{BW} + \vec{v}_{WG}$. We have $\vec{v}_{WG} = 2.0 \angle 0^\circ$ in the magnitude angle notation with the unit m/s understood or $\vec{v}_{WG} = 2.0\hat{i}$ in unit vector notation. We also have $\vec{v}_{BW} = 8.0 \angle 120^\circ$ here we have been careful to phrase the angle in the 'standard' way (measured counterclockwise from the $+x$ axis) or $\vec{v}_{BW} = -4.0\hat{i} + 6.9\hat{j} \text{ m/s}$.

a We can solve the vector addition equation for \vec{v}_{BG}

$$\vec{v}_{BG} = \vec{v}_{BW} + \vec{v}_{WG} = 2.0 \text{ m/s } \hat{i} + (-4.0\hat{i} - 6.9\hat{j}) \text{ m/s} = -2.0 \text{ m/s } \hat{i} + 6.9 \text{ m/s } \hat{j}.$$

thus we find $\vec{v}_{BG} = 7.2 \text{ m/s}$.

b The direction of \vec{v}_{BG} is $\theta = \tan^{-1} \frac{6.9 \text{ m/s}}{-2.0 \text{ m/s}} = 106^\circ$ measured counterclockwise from the x axis or 16° east of north.

c The velocity is constant and we apply $y - y_0 = v_y t$ in a reference frame. Thus in the *ground* reference frame we have $200 \text{ m} = 7.2 \text{ m/s} \sin 106^\circ t \rightarrow t = 29 \text{ s}$. Note if a student obtains “28 s,” then the student has probably neglected to take the y component properly a common mistake.

81. Here the subscript W refers to the water. Our coordinates are chosen with x being *east* and y being *north*. In these terms the angle specifying *east* could be 0° and the angle specifying *south* could be -90° or 270° . Here the length unit is not displayed km is to be understood.

a We have $\vec{v}_{AW} = \vec{v}_{AB} + \vec{v}_{BW}$ so that

$$\vec{v}_{AB} = 22 \angle -90^\circ - 40 \angle 37^\circ = 56 \angle -125^\circ$$

in the magnitude angle notation conveniently done with a vector capable calculator in polar mode. Converting to rectangular components we obtain

$$\vec{v}_{AB} = -32 \text{ km/h } \hat{i} - 46 \text{ km/h } \hat{j}.$$

Of course this could have been done in unit vector notation from the outset.

b Since the velocity components are constant integrating them to obtain the position is straightforward and $\vec{r} - \vec{r}_0 = \int \vec{v} dt$

$$\vec{r} = 2.5 - 32t \hat{i} + 4.0 - 46t \hat{j}$$

with lengths in kilometers and time in hours.

c The magnitude of this \vec{r} is $r = \sqrt{(2.5 - 32t)^2 + (4.0 - 46t)^2}$. We minimize this by taking a derivative and requiring it to be equal zero — which leaves us with an equation for t

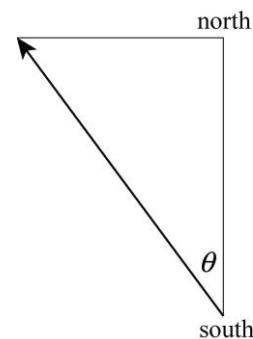
$$\frac{dr}{dt} = \frac{1}{2} \frac{6286t - 528}{\sqrt{(2.5 - 32t)^2 + (4.0 - 46t)^2}} = 0$$

which yields $t = 0.084 \text{ h}$.

plugging this value of t back into the expression for the distance between the ships r we obtain $r = 0.2$ km. Of course the calculator offers more digits ($r = 0.225\dots$), but they are not significant in fact the uncertainties implicit in the given data here should make the ship captains sorry.

82. We construct a right triangle starting from the clearing on the south bank drawing a line 200 m long due north *upward* in our sketch across the river and then a line due east upstream leftward in our sketch along the north bank for a distance $82 \text{ m} + 1.1 \text{ m/s } t$. Here the t dependent contribution is the distance that the river will carry the boat downstream during time t .

The hypotenuse of this right triangle the arrow in our sketch also depends on t and on the boat's speed (relative to the water), and we set it equal to the Pythagorean "sum" of the triangle's sides:



$$(4.0)t = \sqrt{200^2 + (82 + 1.1t)^2}$$

which leads to a quadratic equation for t

$$46724 + 180.4t - 14.8t^2 = 0.$$

we solve for t first and find a positive value $t = 62.6$ s.

the angle between the northward 200 m leg of the triangle and the hypotenuse (which is measured "west of north") is then given by

$$\theta = \tan^{-1} \left(\frac{82 + 1.1t}{200} \right) = \tan^{-1} \left(\frac{151}{200} \right) = 37^\circ.$$

83. We establish coordinates with \hat{i} pointing to the far side of the river perpendicular to the current and \hat{j} pointing in the direction of the current. We are told that the magnitude presumed constant of the velocity of the boat relative to the water is $\vec{v}_{bw} = 6.4 \text{ km/h}$. Its angle relative to the x axis is θ . With km and h as the understood units the velocity of the water relative to the ground is $\vec{v}_{wg} = 3.2 \text{ km/h}$.

(a) To reach a point "directly opposite" means that the velocity of her boat relative to ground must be $\vec{v}_{bg} = v_{bg} \hat{i}$ here $v_{bg} > 0$ is unknown. Thus all \hat{j} components must cancel in the vector sum $\vec{v}_{bw} + \vec{v}_{wg} = \vec{v}_{bg}$ which means the $\vec{v}_{bw} \sin \theta = -3.2 \text{ km/h}$ so

$$\theta = \sin^{-1} \left(\frac{-3.2 \text{ km/h}}{6.4 \text{ km/h}} \right) = -30^\circ.$$

b Using the result from part a we find $v_{bg} = v_{bw} \cos \theta = 5.5 \text{ km/h}$. Thus traveling a distance of $\ell = 6.4 \text{ km}$ requires a time of $6.4 \text{ km} / 5.5 \text{ km/h} = 1.15 \text{ h}$ or 69 min.

c If her motion is completely along the y axis as the problem implies then with $v_{wg} = 3.2 \text{ km/h}$ the faster speed we have

$$t_{\text{total}} = \frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}} = 1.33 \text{ h}$$

here $D = 3.2 \text{ km}$. This is equivalent to 80 min.

d Since

$$\frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}} = \frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}}$$

the answer is the same as in the previous part that is $t_{\text{total}} = 80 \text{ min}$.

e The shortest time path should have $\theta = 0^\circ$. This can also be shown by noting that the case of general θ leads to

$$\vec{v}_{bg} = \vec{v}_{bw} + \vec{v}_{wg} = v_{bw} \cos \theta \hat{i} + v_{bw} \sin \theta \hat{j} + v_{wg} \hat{j}$$

here the x component of \vec{v}_{bg} must equal ℓ/t . Thus

$$t = \frac{\ell}{v_{bw} \cos \theta}$$

which can be minimized using $dt/d\theta = 0$.

f The above expression leads to $t = 6.4 \text{ km} / 6.4 \text{ km/h} = 1.0 \text{ h}$ or 60 min.

84. Relative to the sled the launch velocity is $\vec{v}_{\text{rel}} = v_{\text{ox}} \hat{i} + v_{\text{oy}} \hat{j}$. Since the sled's motion is in the negative direction with speed v_s note that we are treating v_s as a positive number, so the sled's velocity is actually $-v_s \hat{i}$ then the launch velocity relative to the ground is $\vec{v}_0 = (v_{\text{ox}} - v_s) \hat{i} + v_{\text{oy}} \hat{j}$. The horizontal and vertical displacement relative to the ground are therefore

$$x_{\text{land}} - x_{\text{launch}} = \Delta x_{\text{bg}} = (v_{\text{ox}} - v_s) t_{\text{flight}}$$

$$y_{\text{land}} - y_{\text{launch}} = 0 = v_{\text{oy}} t_{\text{flight}} - \frac{1}{2} g t_{\text{flight}}^2.$$

Combining these equations leads to

$$\Delta x_{bg} = \frac{2v_{0x}v_{0y}}{g} - \left(\frac{2v_{0y}}{g} \right) v_s.$$

he first term corresponds to the “y intercept” on the graph and the second term (in parentheses) corresponds to the magnitude of the “slope.” From the figure we have

$$\Delta x_{bg} = 40 - 4v_s.$$

this implies $v_{0y} = 4.0 \text{ s} \cdot 9.8 \text{ m/s}^2 = 39.2 \text{ m/s}$ and that furnishes enough information to determine v_{0x} .

a $v_{0x} = 40 \text{ m} / 4.0 \text{ s} = 10 \text{ m/s}$

b As noted above $v_{0y} = 39.2 \text{ m/s}$

c Relative to the sled the displacement Δx_{bs} does not depend on the sled's speed, so $\Delta x_{bs} = v_{0x} t_{\text{flight}} = 40 \text{ m}$.

d As in c relative to the sled the displacement Δx_{bs} does not depend on the sled's speed and $\Delta x_{bs} = v_{0x} t_{\text{flight}} = 40 \text{ m}$.

85. Using displacement = velocity \times time for each constant velocity part of the trip along with the fact that 1 hour = 60 minutes we have the following vector addition exercise using notation appropriate to many vector capable calculators

$$1667 \text{ m} \angle 0^\circ + 1333 \text{ m} \angle -90^\circ + 333 \text{ m} \angle 180^\circ + 833 \text{ m} \angle -90^\circ + 667 \text{ m} \angle 180^\circ + 417 \text{ m} \angle -90^\circ = 2668 \text{ m} \angle -76^\circ$$

a Thus the magnitude of the net displacement is 2.7 km.

b Its direction is 76° clockwise relative to the initial direction of motion.

86. We use a coordinate system with x eastward and y upward.

a We note that 123° is the angle between the initial position and later position vectors so that the angle from x to the later position vector is $40^\circ + 123^\circ = 163^\circ$. In unit vector notation the position vectors are

$$\vec{r}_1 = 360 \text{ m} \cos 40^\circ \hat{i} + 360 \text{ m} \sin 40^\circ \hat{j} = 276 \text{ m} \hat{i} + 231 \text{ m} \hat{j}$$

$$\vec{r}_2 = 790 \text{ m} \cos 163^\circ \hat{i} + 790 \text{ m} \sin 163^\circ \hat{j} = -755 \text{ m} \hat{i} + 231 \text{ m} \hat{j}$$

respectively. Consequently we plug into Eq. 4-3

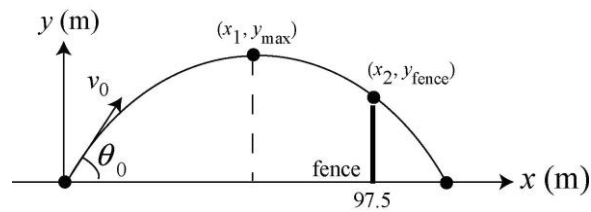
$$\Delta \vec{r} = -755 \text{ m} \hat{i} - 276 \text{ m} \hat{j} - 231 \text{ m} \hat{i} - 231 \text{ m} \hat{j} = -1031 \text{ m} \hat{i}.$$

the magnitude of the displacement $\Delta \vec{r}$ is $|\Delta \vec{r}| = 1031 \text{ m}$.

b the direction of $\Delta \vec{r}$ is $-\hat{i}$ or westward.

87. **THINK** This problem deals with the projectile motion of a baseball. Given the information on the position of the ball at two instants we are asked to analyze its trajectory.

EXPRESS The trajectory of the baseball is shown in the figure on the right. According to the problem statement at $t_1 = 3.0 \text{ s}$ the ball reaches its maximum height y_{ma} and at $t_2 = t_1 + 2.5 \text{ s} = 5.5 \text{ s}$ it barely clears a fence at $x_2 = 97.5 \text{ m}$.



Equation 2.15 can be applied to the vertical y axis motion related to reaching the maximum height when $t_1 = 3.0 \text{ s}$ and $v_y = 0$

$$y_{\text{ma}} - y_0 = v_{y0}t - \frac{1}{2}gt^2.$$

ANALYZE a With ground level chosen so $y_0 = 0$ this equation gives the result

$$y_{\text{ma}} = \frac{1}{2}gt_1^2 = \frac{1}{2}(9.8 \text{ m/s}^2)(3.0 \text{ s})^2 = 44.1 \text{ m}$$

b After the moment it reached maximum height it is falling at $t_2 = t_1 + 2.5 \text{ s} = 5.5 \text{ s}$ it will have fallen an amount given by Equation 2.18

$$y_{\text{fence}} - y_{\text{ma}} = 0 - \frac{1}{2}g(t_2 - t_1)^2.$$

thus the height of the fence is

$$y_{\text{fence}} = y_{\text{ma}} - \frac{1}{2}g(t_2 - t_1)^2 = 44.1 \text{ m} - \frac{1}{2}(9.8 \text{ m/s}^2)(2.5 \text{ s})^2 = 13.48 \text{ m}.$$

c Since the horizontal component of velocity in a projectile motion problem is constant neglecting air friction we find from $97.5 \text{ m} = v_{0x}(5.5 \text{ s})$ that $v_{0x} = 17.7 \text{ m/s}$. The total flight time of the ball is $T = 2t_1 = 2(3.0 \text{ s}) = 6.0 \text{ s}$. Thus the range of the baseball is

$$R = v_{0x}T = (17.7 \text{ m/s})(6.0 \text{ s}) = 106.4 \text{ m}$$

which means that the ball travels an additional distance

$$\Delta x = R - x_2 = 106.4 \text{ m} - 97.5 \text{ m} = 8.86 \text{ m}$$

beyond the fence before striking the ground.

LEARN Part c can also be solved by noting that after passing the fence the ball will strike the ground in 0.5 s so that the total fall time equals the rise time. With $v_{0x} = 17.7 \text{ m/s}$ we have $\Delta x = 17.7 \text{ m/s} \cdot 0.5 \text{ s} = 8.86 \text{ m}$.

88. When moving in the same direction as the jet stream of speed v_s the time is

$$t_1 = \frac{d}{v_{ja} + v_s}$$

here $d = 4000 \text{ km}$ is the distance and v_a is the speed of the jet relative to the air 1000 km/h . When moving against the jet stream the time is

$$t_2 = \frac{d}{v_{ja} - v_s}$$

here $t_2 - t_1 = \frac{70}{60} \text{ h}$. Combining these equations and using the quadratic formula to solve gives $v_s = 143 \text{ km/h}$.

89. **THINK** We have a particle moving in a two dimensional plane with a constant acceleration. Since the x and y components of the acceleration are constants we can use Table 2.1 for the motion along both axes.

EXPRESS Using vector notation with $\vec{r}_0 = 0$ the position and velocity of the particle as a function of time are given by $\vec{r}(t) = \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$ and $\vec{v}(t) = \vec{v}_0 + \vec{a} t$ respectively. Here units are not shown units are to be understood.

ANALYZE Given the initial velocity $\vec{v}_0 = 8.0 \text{ m/s} \hat{i}$ and the acceleration $\vec{a} = 4.0 \text{ m/s}^2 \hat{i} + 2.0 \text{ m/s}^2 \hat{j}$ the position vector of the particle is

$$\vec{r} = \vec{v}_0 t + \frac{1}{2} \vec{a} t^2 = (8.0 \hat{i}) t + \frac{1}{2} (4.0 \hat{i} + 2.0 \hat{j}) t^2 = (2.0 t^2) \hat{i} + (8.0 t + 1.0 t^2) \hat{j}.$$

Therefore the time that corresponds to $x = 29 \text{ m}$ can be found by solving the equation $2.0 t^2 = 29$ which leads to $t = 3.8 \text{ s}$. The y coordinate at that time is

$$y = 8.0 \text{ m/s} \cdot 3.8 \text{ s} + 1.0 \text{ m/s}^2 \cdot (3.8 \text{ s})^2 = 45 \text{ m}.$$

b The velocity of the particle is given by $\vec{v} = \vec{v}_0 + \vec{a}t$. Thus at $t = 3.8$ s the velocity is

$$\vec{v} = 8.0 \text{ m/s } \hat{i} + (4.0 \text{ m/s}^2 \hat{i} + 2.0 \text{ m/s}^2 \hat{j})(3.8 \text{ s}) = 15.2 \text{ m/s } \hat{i} + 15.6 \text{ m/s } \hat{j}$$

which has a magnitude of $v = \sqrt{v_x^2 + v_y^2} = \sqrt{15.2^2 + 15.6^2} = 22 \text{ m/s}$.

LEARN Instead of using the vector notation we can also deal with the x and the y components individually.

90. Using the same coordinate system assumed in Ex. 4.25 we rearrange that equation to solve for the initial speed

$$v_0 = \frac{x}{\cos \theta_0} \sqrt{\frac{g}{2x \tan \theta_0 - y}}$$

which yields $v_0 = 23 \text{ ft/s}$ for $g = 32 \text{ ft/s}^2$, $x = 13 \text{ ft}$, $y = 3 \text{ ft}$ and $\theta_0 = 55^\circ$.

91. We make use of Ex. 4.25.

a By rearranging Ex. 4.25 we obtain the initial speed

$$v_0 = \frac{x}{\cos \theta_0} \sqrt{\frac{g}{2x \tan \theta_0 - y}}$$

which yields $v_0 = 255.5 \approx 2.6 \times 10^2 \text{ m/s}$ for $x = 9400 \text{ m}$, $y = -3300 \text{ m}$ and $\theta_0 = 35^\circ$.

b From Ex. 4.21 we obtain the time of flight

$$t = \frac{x}{v_0 \cos \theta_0} = \frac{9400 \text{ m}}{255.5 \text{ m/s } \cos 35^\circ} = 45 \text{ s}.$$

c We expect the air to provide resistance but no appreciable lift to the rock so we would need a greater launching speed to reach the same target.

92. We apply Ex. 4.34 to solve for speed v and Ex. 4.35 to find the period T .

a We obtain

$$v = \sqrt{ra} = \sqrt{(5.0 \text{ m})(7.0)(9.8 \text{ m/s}^2)} = 19 \text{ m/s}.$$

b The time to go around once the period is $T = 2\pi r/v = 1.7 \text{ s}$. Therefore in one minute $t = 60 \text{ s}$ the astronaut executes

$$\frac{t}{T} = \frac{60 \text{ s}}{1.7 \text{ s}} = 35$$

revolutions. Thus 35 rev/min is needed to produce a centripetal acceleration of $7g$ when the radius is 5.0 m.

c As noted above $T = 1.7 \text{ s}$.

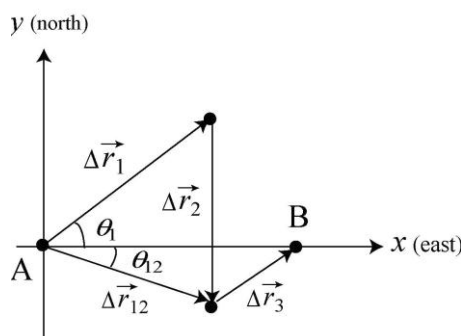
93. **THINK** This problem deals with the two-dimensional kinematics of a desert camel moving from oasis to oasis.

EXPRESS The journey of the camel is illustrated in the figure on the right. We use a 'standard' coordinate system with $+x$ east and $+y$ north. Lengths are in kilometers and times are in hours. Using vector notation we write the displacements for the first two segments of the trip as

$$\Delta \vec{r}_1 = 75 \text{ km} \cos 37^\circ \hat{i} + 75 \text{ km} \sin 37^\circ \hat{j}$$

$$\Delta \vec{r}_2 = -65 \text{ km} \hat{j}$$

The net displacement is $\Delta \vec{r}_{12} = \Delta \vec{r}_1 + \Delta \vec{r}_2$. As can be seen from the figure to reach oasis B requires an additional displacement $\Delta \vec{r}_3$.



ANALYZE a We perform the vector addition of individual displacements to find the net displacement of the camel $\Delta \vec{r}_{12} = \Delta \vec{r}_1 + \Delta \vec{r}_2 = 60 \text{ km} \hat{i} - 20 \text{ km} \hat{j}$. Its corresponding magnitude is

$$\Delta r_{12} = \sqrt{(60 \text{ km})^2 + (-20 \text{ km})^2} = 63 \text{ km}.$$

b The direction of $\Delta \vec{r}_{12}$ is $\theta_{12} = \tan^{-1} \frac{-20 \text{ km}}{60 \text{ km}} = -18^\circ$ or 18° south of east.

c To calculate the average velocity for the first two segments of the journey including rest we use the result from part a in 4.8 along with the fact that

$$\Delta t_{12} = \Delta t_1 + \Delta t_2 + \Delta t_{\text{rest}} = 50 \text{ h} + 35 \text{ h} + 5.0 \text{ h} = 90 \text{ h}.$$

In unit vector notation we have $\vec{v}_{12 \text{ avg}} = \frac{60 \hat{i} - 20 \hat{j} \text{ km}}{90 \text{ h}} = 0.67 \hat{i} - 0.22 \hat{j} \text{ km/h}.$

This leads to $\vec{v}_{12 \text{ avg}} = 0.70 \text{ km/h}.$

d The direction of $\vec{v}_{12 \text{ avg}}$ is $\theta_{12} = \tan^{-1} \frac{-0.22 \text{ km/h}}{0.67 \text{ km/h}} = -18^\circ$ or 18° south of east.

e the average speed is distinguished from the magnitude of average velocity in that it depends on the total distance as opposed to the net displacement. Since the camel travels 140 km we obtain $140 \text{ km} / 90 \text{ h} = 1.56 \text{ km/h} \approx 1.6 \text{ km/h}$.

f the net displacement is required to be the 90 km east from A to B . The displacement from the resting place to B is denoted $\Delta \vec{r}_3$. Thus we must have

$$\Delta \vec{r}_1 + \Delta \vec{r}_2 + \Delta \vec{r}_3 = 90 \text{ km } \hat{i}$$

which produces $\Delta \vec{r}_3 = 30 \text{ km } \hat{i} + 20 \text{ km } \hat{j}$ in unit vector notation or $36 \angle 33^\circ$ in magnitude-angle notation. Therefore using 4.8 we obtain

$$\vec{v}_{3 \text{ avg}} = \frac{36 \text{ km}}{120 - 90 \text{ h}} = 1.2 \text{ km/h}.$$

g the direction of $\vec{v}_{3 \text{ avg}}$ is the same as $\Delta \vec{r}_3$ that is 33° north of east.

LEARN With a vector-capable calculator in polar mode we could perform the vector addition of the displacements as $75 \angle 37^\circ + 65 \angle -90^\circ = 63 \angle -18^\circ$. Note the distinction between average velocity and average speed.

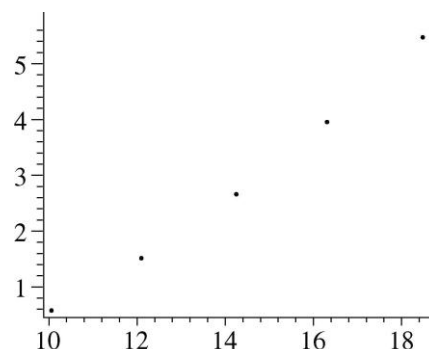
94. We compute the coordinate pairs x, y from $x = v_0 \cos \theta t$ and $y = v_0 \sin \theta t - \frac{1}{2} g t^2$ for $t = 20 \text{ s}$ and the speeds and angles given in the problem.

a we obtain

$$\begin{aligned} (x_A, y_A) &= (10.1 \text{ km}, 0.556 \text{ km}) & (x_B, y_B) &= (12.1 \text{ km}, 1.51 \text{ km}) \\ (x_C, y_C) &= (14.3 \text{ km}, 2.68 \text{ km}) & (x_D, y_D) &= (16.4 \text{ km}, 3.99 \text{ km}) \end{aligned}$$

and $x_E, y_E = 18.5 \text{ km}, 5.53 \text{ km}$ which we plot in the next part.

b The vertical y and horizontal x axes are in kilometers. The graph does not start at the origin. The curve to “fit” the data is not shown but is easily imagined forming the “curtain of death”.



95. a With $\Delta x = 8.0 \text{ m}$, $t = \Delta t_1$, $a = a_x$ and $v_{0x} = 0$, 2.15 gives

$$8.0 \text{ m} = \frac{1}{2} a_x \Delta t_1^2$$

and the corresponding expression for motion along the y axis leads to

$$\Delta y = 12 \text{ m} = \frac{1}{2} a_y \Delta t_1^2.$$

Dividing the second expression by the first leads to $a_y/a_x = 3/2 = 1.5$.

b. Letting $t = 2\Delta t_1$ then $3/2 = 1.5$ leads to $\Delta x = 8.0 \text{ m} \cdot 2^2 = 32 \text{ m}$ which implies that its x coordinate is now $4.0 + 32 \text{ m} = 36 \text{ m}$. Similarly $\Delta y = 12 \text{ m} \cdot 2^2 = 48 \text{ m}$ which means its y coordinate has become $6.0 + 48 \text{ m} = 54 \text{ m}$.

96. We assume the ball's initial velocity is perpendicular to the plane of the net. We choose coordinates so that $x_0 = y_0 = 0$, 3.0 m and $v_x = 0$; note that $v_{0y} = 0$.

a. So barely clear the net we have

$$y - y_0 = v_{0y}t - \frac{1}{2}gt^2 \Rightarrow 2.24 \text{ m} - 3.0 \text{ m} = 0 - \frac{1}{2}(9.8 \text{ m/s}^2)t^2$$

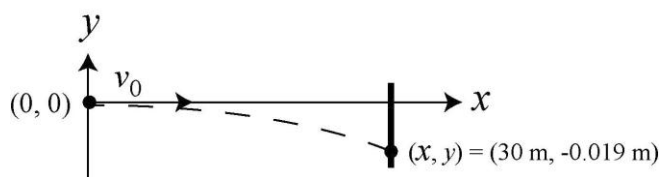
which gives $t = 0.39 \text{ s}$ for the time it is passing over the net. This is plugged into the x equation to yield the minimum initial velocity $v_x = 8.0 \text{ m/s} \cdot 0.39 \text{ s} = 20.3 \text{ m/s}$.

b. We require $y = 0$ and find time t from the equation $y - y_0 = v_{0y}t - \frac{1}{2}gt^2$. This value $t = \sqrt{2(3.0 \text{ m})/9.8 \text{ m/s}^2} = 0.78 \text{ s}$ is plugged into the x equation to yield the maximum initial velocity $v_x = 17.0 \text{ m/s} \cdot 0.78 \text{ s} = 21.7 \text{ m/s}$.

97. **THINK** A bullet fired horizontally from a rifle strikes the target at some distance below its aiming point. We're asked to find its total flight time and speed.

EXPRESS The trajectory of the bullet is shown in the figure on the right (not to scale). Note that the origin is chosen to be at the firing point. With this convention the y coordinate of the bullet is given by $y = -\frac{1}{2}gt^2$. Knowing the coordinates

x and y at the target allows us to calculate the total flight time and speed of the bullet.



ANALYZE If t is the time of flight and $y = -0.019 \text{ m}$ indicates where the bullet hits the target then

$$t = \sqrt{\frac{-2y}{g}} = \sqrt{\frac{-2(-0.019 \text{ m})}{9.8 \text{ m/s}^2}} = 6.2 \times 10^{-2} \text{ s}.$$

b The muzzle velocity is the initial horizontal velocity of the bullet. Since $x = 30 \text{ m}$ is the horizontal position of the target we have $x = v_0 t$. Thus

$$v_0 = \frac{x}{t} = \frac{30 \text{ m}}{6.3 \times 10^{-2} \text{ s}} = 4.8 \times 10^2 \text{ m/s}.$$

LEARN Alternatively we may use Eq. 4.25 to solve for the initial velocity. With $\theta_0 = 0$

and $y_0 = 0$ the equation simplifies to $y = -\frac{gx^2}{2v_0^2}$ from which we find

$$v_0 = \sqrt{-\frac{gx^2}{2y}} = \sqrt{-\frac{9.8 \text{ m/s}^2 (30 \text{ m})^2}{2(-0.019 \text{ m})}} = 4.8 \times 10^2 \text{ m/s}$$

in agreement with that we calculated in part b.

98. For circular motion we must have \vec{v} with direction perpendicular to \vec{r} and since the speed is constant magnitude $v = 2\pi r/T$ here $r = \sqrt{(2.00 \text{ m})^2 + (-3.00 \text{ m})^2}$ and $T = 7.00 \text{ s}$. The \vec{r} given in the problem statement specifies a point in the fourth quadrant and since the motion is clockwise then the velocity must have both components negative. Our result satisfying these three conditions using unit vector notation which makes it easy to double check that $\vec{r} \cdot \vec{v} = 0$ for $\vec{v} = -2.69 \text{ m/s} \hat{i} - 1.80 \text{ m/s} \hat{j}$.

99. Let $v_0 = 2\pi (0.200 \text{ m}) / (0.00500 \text{ s}) \approx 251 \text{ m/s}$ using Eq. 4.35 be the speed it had in circular motion and $\theta_0 = (1 \text{ hr} / 3600 \text{ s}) (12 \text{ hr})$ for full rotation $= 30.0^\circ$. Then Eq. 4.25 leads to

$$y = 2.50 \text{ m} \tan 30.0^\circ - \frac{9.8 \text{ m/s}^2 (2.50 \text{ m})^2}{2 (251 \text{ m/s})^2 \cos^2 30.0^\circ} \approx 1.44 \text{ m}$$

which means its height above the floor is $1.44 \text{ m} + 1.20 \text{ m} = 2.64 \text{ m}$.

100. Noting that $\vec{v}_2 = 0$ then using Eq. 4.15 the average acceleration is

$$\vec{a}_{\text{avg}} = \frac{\Delta \vec{v}}{\Delta t} = \frac{0 - (6.30 \hat{i} - 8.42 \hat{j}) \text{ m/s}}{3 \text{ s}} = (-2.1 \hat{i} + 2.8 \hat{j}) \text{ m/s}^2$$

101. Using Eq. 2.16 we obtain $v^2 = v_0^2 - 2gh$ or $h = (v_0^2 - v^2) / 2g$.

a Since $v = 0$ at the maximum height of an upward motion with $v_0 = 7.00 \text{ m/s}$ we have

$$h = \frac{7.00 \text{ m/s}^2}{2 \times 9.80 \text{ m/s}^2} = 2.50 \text{ m}.$$

b The relative speed is $v_r = v_0 - v_c = 7.00 \text{ m/s} - 3.00 \text{ m/s} = 4.00 \text{ m/s}$ with respect to the floor. Using the above equation we obtain $h = \frac{4.00 \text{ m/s}^2}{2 \times 9.80 \text{ m/s}^2} = 0.82 \text{ m}.$

c The acceleration or the rate of change of speed of the ball with respect to the ground is 9.80 m/s^2 downward.

d Since the elevator cab moves at constant velocity the rate of change of speed of the ball with respect to the cab floor is also 9.80 m/s^2 downward.

102. a With $r = 0.15 \text{ m}$ and $a = 3.0 \times 10^{14} \text{ m/s}^2$. 4.34 gives

$$v = \sqrt{ra} = 6.7 \times 10^6 \text{ m/s}.$$

b The period is given by . 4.35

$$T = \frac{2\pi r}{v} = 1.4 \times 10^{-7} \text{ s}.$$

103. a The magnitude of the displacement vector $\Delta \vec{r}$ is given by

$$\Delta \vec{r} = \sqrt{21.5 \text{ km}^2 + 9.7 \text{ km}^2 + 2.88 \text{ km}^2} = 23.8 \text{ km}.$$

thus

$$\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t} = \frac{23.8 \text{ km}}{3.50 \text{ h}} = 6.79 \text{ km/h}.$$

b The angle θ in question is given by

$$\theta = \tan^{-1} \left(\frac{2.88 \text{ km}}{\sqrt{21.5 \text{ km}^2 + 9.7 \text{ km}^2}} \right) = 6.96^\circ.$$

104. The initial velocity has magnitude v_0 and because it is horizontal it is equal to v_x the horizontal component of velocity at impact. Thus the speed at impact is

$$\sqrt{v_0^2 + v_y^2} = 3v_0$$

here $v_y = \sqrt{2gh}$ and we have used . 2.16 with Δx replaced with $h = 20 \text{ m}$. Squaring both sides of the first equality and substituting from the second we find

$$v_0^2 + 2gh = (3v_0)^2$$

which leads to $gh = 4v_0^2$ and therefore to $v_0 = \sqrt{9.8 \text{ m/s}^2 \cdot 20 \text{ m}}/2 = 7.0 \text{ m/s}$.

105. We choose horizontal x and vertical y axes such that both components of \vec{v}_0 are positive. Positive angles are counterclockwise from x and negative angles are clockwise from it. In unit vector notation the velocity at each instant during the projectile motion is

$$\vec{v} = v_0 \cos \theta_0 \hat{i} + (v_0 \sin \theta_0 - gt) \hat{j}.$$

a. With $v_0 = 30 \text{ m/s}$ and $\theta_0 = 60^\circ$ we obtain $\vec{v} = 15\hat{i} - 6.4\hat{j} \text{ m/s}$ for $t = 2.0 \text{ s}$. The magnitude of \vec{v} is $|\vec{v}| = \sqrt{15^2 + 6.4^2} = 16 \text{ m/s}$.

b. The direction of \vec{v} is

$$\theta = \tan^{-1} \frac{6.4 \text{ m/s}}{15 \text{ m/s}} = 23^\circ$$

measured counterclockwise from x .

c. Since the angle is positive it is above the horizontal.

d. With $t = 5.0 \text{ s}$ we find $\vec{v} = 15\hat{i} - 23\hat{j} \text{ m/s}$ which yields

$$|\vec{v}| = \sqrt{15^2 + 23^2} = 27 \text{ m/s}.$$

e. The direction of \vec{v} is $\theta = \tan^{-1} \frac{-23 \text{ m/s}}{15 \text{ m/s}} = -57^\circ$ or 57° measured clockwise from x .

f. Since the angle is negative it is below the horizontal.

106. We use 4.2 and 4.3.

a. With the initial position vector as \vec{r}_1 and the later vector as \vec{r}_2 , 4.3 yields

$$\Delta \vec{r} = -2.0 \text{ m} - 5.0 \text{ m} \hat{i} + 6.0 \text{ m} - (-6.0 \text{ m}) \hat{j} + 2.0 \text{ m} - 2.0 \text{ m} \hat{k} = -7.0 \text{ m} \hat{i} + 12 \text{ m} \hat{j}$$

for the displacement vector in unit vector notation.

b. Since there is no z component that is the coefficient of \hat{k} is zero the displacement vector is in the xy plane.

107. We write our magnitude angle results in the form $(R \angle \theta)$ with units for the magnitude understood m for distances m/s for speeds m/s^2 for accelerations. All angles θ are measured counterclockwise from x but we will occasionally refer to angles ϕ which are measured counterclockwise from the vertical line between the circle center and the coordinate origin and the line drawn from the circle center to the particle location see r in the figure. We note that the speed of the particle is $v = 2\pi r/T$ here $r = 3.00$ m and $T = 20.0$ s thus $v = 0.942$ m/s. The particle is moving counterclockwise in fig. 4-56.

a. At $t = 5.0$ s the particle has traveled a fraction of

$$\frac{t}{T} = \frac{5.00 \text{ s}}{20.0 \text{ s}} = \frac{1}{4}$$

of a full revolution around the circle starting at the origin. Thus relative to the circle center the particle is at

$$\phi = \frac{1}{4} 360^\circ = 90^\circ$$

measured from vertical as explained above. Referring to fig. 4-56 we see that this position (which is the “3 o’clock” position on the circle) corresponds to $x = 3.0$ m and $y = 3.0$ m relative to the coordinate origin. In our magnitude angle notation this is expressed as $(R \angle \theta) = (4.2 \angle 45^\circ)$. Although this position is easy to analyze without resorting to trigonometric relations it is useful for the computations below to note that these values of x and y relative to coordinate origin can be gotten from the angle ϕ from the relations

$$x = r \sin \phi \quad y = r - r \cos \phi.$$

Of course $R = \sqrt{x^2 + y^2}$ and θ comes from choosing the appropriate possibility from $\tan^{-1} y/x$ or by using particular functions of vector capable calculators.

b. At $t = 7.5$ s the particle has traveled a fraction of $7.5/20 = 3/8$ of a revolution around the circle starting at the origin. Relative to the circle center the particle is therefore at $\phi = 3/8 \cdot 360^\circ = 135^\circ$ measured from vertical in the manner discussed above. Referring to fig. 4-56 we compute that this position corresponds to

$$\begin{aligned} x &= 3.00 \text{ m} \sin 135^\circ = 2.1 \text{ m} \\ y &= 3.0 \text{ m} - 3.0 \text{ m} \cos 135^\circ = 5.1 \text{ m} \end{aligned}$$

relative to the coordinate origin. In our magnitude angle notation this is expressed as $R \angle \theta = 5.5 \angle 68^\circ$.

c. At $t = 10.0$ s the particle has traveled a fraction of $10/20 = 1/2$ of a revolution around the circle. Relative to the circle center the particle is at $\phi = 180^\circ$ measured from vertical see explanation above. Referring to fig. 4-56 we see that this position corresponds to x

$x = 0$ and $y = 6.0$ m relative to the coordinate origin. In our magnitude-angle notation, this is expressed as $(R \angle \theta) = (6.0 \angle 90^\circ)$.

Now we subtract the position vector in part (a) from the position vector in part (c)

$$(6.0 \angle 90^\circ) - (4.2 \angle 45^\circ) = (4.2 \angle 135^\circ)$$

using magnitude-angle notation convenient when using vector-capable calculators. If we wish instead to use unit vector notation, we write

$$\Delta \vec{R} = 0 - 3.0 \text{ m } \hat{i} + 6.0 \text{ m} - 3.0 \text{ m } \hat{i} = -3.0 \text{ m } \hat{i} + 3.0 \text{ m } \hat{j}$$

which leads to $|\Delta \vec{R}| = 4.2$ m and $\theta = 135^\circ$.

From Eq. 4-8 we have $\vec{v}_{\text{avg}} = \Delta \vec{R} / \Delta t$. With $\Delta t = 5.0$ s we have

$$\vec{v}_{\text{avg}} = -0.60 \text{ m/s } \hat{i} + 0.60 \text{ m/s } \hat{j}$$

in unit vector notation or $0.85 \angle 135^\circ$ in magnitude-angle notation.

For the speed, we have already noted $v = 0.94$ m/s, but its direction is best seen by referring again to Fig. 4-56. The velocity vector is tangent to the circle at its “3 o’clock position” (see part (a)), which means \vec{v} is vertical. Thus our result is $(0.94 \angle 90^\circ)$.

Again, the speed has been noted above $v = 0.94$ m/s, but its direction is best seen by referring to Fig. 4-56. The velocity vector is tangent to the circle at its “12 o’clock position” (see part (c)), which means \vec{v} is horizontal. Thus our result is $(0.94 \angle 180^\circ)$.

For the acceleration, we have noted $a = v^2 / r = 0.30$ m/s² and at this instant (see part (a)) it is horizontal toward the center of the circle. Thus our result is $(0.30 \angle 180^\circ)$.

Again, $a = v^2 / r = 0.30$ m/s², but at this instant (see part (c)) it is vertical toward the center of the circle. Thus our result is $(0.30 \angle 270^\circ)$.

108. Equation 4-34 describes an inverse proportionality between r and a , so that a large acceleration results from a small radius. Thus an upper limit for a corresponds to a lower limit for r .

(a) The minimum turning radius of the train is given by

$$r_{\min} = \frac{v^2}{a_{\max}} = \frac{(216 \text{ km h}^{-1})^2}{(0.050)(9.8 \text{ m s}^{-2})} = 7.3 \times 10^3 \text{ m}.$$

b The speed of the train must be reduced to no more than

$$v = \sqrt{a_{\max} r} = \sqrt{0.050(9.8 \text{ m s}^{-2})(1.00 \times 10^3 \text{ m})} = 22 \text{ m s}^{-1}$$

which is roughly 80 km h⁻¹.

109. a Using the same coordinate system assumed in Problem 4.25, we find

$$y = x \tan \theta_0 - \frac{gx^2}{2(v_0 \cos \theta_0)^2} = -\frac{gx^2}{2v_0^2} \quad \text{if } \theta_0 = 0.$$

Thus, with $v_0 = 3.0 \times 10^6 \text{ m s}^{-1}$ and $x = 1.0 \text{ m}$, we obtain $y = -5.4 \times 10^{-13} \text{ m}$, which is not practical to measure and suggests that gravitational processes play such a small role in the fields of atomic and subatomic physics.

b It is clear from the above expression that y decreases as v_0 is increased.

110. When the escalator is stalled the speed of the person is $v_p = \ell/t$, where ℓ is the length of the escalator and t is the time the person takes to walk up it. This is $v_p = 15 \text{ m} / 90 \text{ s} = 0.167 \text{ m s}^{-1}$. The escalator moves at $v_e = 15 \text{ m} / 60 \text{ s} = 0.250 \text{ m s}^{-1}$. The speed of the person walking up the moving escalator is

$$v = v_p + v_e = 0.167 \text{ m s}^{-1} + 0.250 \text{ m s}^{-1} = 0.417 \text{ m s}^{-1}$$

and the time taken to move the length of the escalator is

$$t = \ell / v = 15 \text{ m} / 0.417 \text{ m s}^{-1} = 36 \text{ s}.$$

If the various times given are independent of the escalator length, then the answer does not depend on that length either. In terms of ℓ in meters, the speed in meters per second of the person walking on the stalled escalator is $\ell/90$, the speed of the moving escalator is $\ell/60$, and the speed of the person walking on the moving escalator is $v = (\ell/90) + (\ell/60) = 0.0278\ell$. The time taken is $t = \ell/v = \ell/0.0278\ell = 36 \text{ s}$ and is independent of ℓ .

111. The radius of Earth may be found in Appendix D.

(a) The speed of an object at Earth's equator is $v = 2\pi R / T$, where R is the radius of Earth, $6.37 \times 10^6 \text{ m}$, and T is the length of a day, $8.64 \times 10^4 \text{ s}$.

$$v = 2\pi \frac{6.37 \times 10^6 \text{ m}}{8.64 \times 10^4 \text{ s}} = 463 \text{ m/s}.$$

the magnitude of the acceleration is given by

$$a = \frac{v^2}{R} = \frac{(463 \text{ m/s})^2}{6.37 \times 10^6 \text{ m}} = 0.034 \text{ m/s}^2.$$

if T is the period then $v = 2\pi R/T$ is the speed and the magnitude of the acceleration is

$$a = \frac{v^2}{R} = \frac{(2\pi R/T)^2}{R} = \frac{4\pi^2 R}{T^2}.$$

thus

$$T = 2\pi \sqrt{\frac{R}{a}} = 2\pi \sqrt{\frac{6.37 \times 10^6 \text{ m}}{9.8 \text{ m/s}^2}} = 5.1 \times 10^3 \text{ s} = 84 \text{ min}.$$

112. With $g_B = 9.8128 \text{ m/s}^2$ and $g_M = 9.7999 \text{ m/s}^2$ we apply Eq. 4-26

$$R_M - R_B = \frac{v_0^2 \sin 2\theta_0}{g_M} - \frac{v_0^2 \sin 2\theta_0}{g_B} = \frac{v_0^2 \sin 2\theta_0}{g_B} \left(\frac{g_B}{g_M} - 1 \right)$$

which becomes

$$R_M - R_B = R_B \left(\frac{9.8128 \text{ m/s}^2}{9.7999 \text{ m/s}^2} - 1 \right)$$

and yields upon substituting $R_B = 8.09 \text{ m}$ $R_M - R_B = 0.01 \text{ m} = 1 \text{ cm}$.

113. From the figure the three displacements can be written as

$$\vec{d}_1 = d_1 \cos \theta_1 \hat{i} + \sin \theta_1 \hat{j} = 5.00 \text{ m} \cos 30^\circ \hat{i} + \sin 30^\circ \hat{j} = 4.33 \text{ m} \hat{i} + 2.50 \text{ m} \hat{j}$$

$$\begin{aligned} \vec{d}_2 &= d_2 \cos 180^\circ + \theta_1 - \theta_2 \hat{i} + \sin 180^\circ + \theta_1 - \theta_2 \hat{j} = 8.00 \text{ m} \cos 160^\circ \hat{i} + \sin 160^\circ \hat{j} \\ &= -7.52 \text{ m} \hat{i} + 2.74 \text{ m} \hat{j} \end{aligned}$$

$$\begin{aligned} \vec{d}_3 &= d_3 \cos 360^\circ - \theta_3 - \theta_2 + \theta_1 \hat{i} + \sin 360^\circ - \theta_3 - \theta_2 + \theta_1 \hat{j} = 12.0 \text{ m} \cos 260^\circ \hat{i} + \sin 260^\circ \hat{j} \\ &= -2.08 \text{ m} \hat{i} - 11.8 \text{ m} \hat{j} \end{aligned}$$

here the angles are measured from the x axis. The net displacement is

$$\vec{d} = \vec{d}_1 + \vec{d}_2 + \vec{d}_3 = -5.27 \text{ m} \hat{i} - 6.58 \text{ m} \hat{j}.$$

a The magnitude of the net displacement is

$$\vec{d} = \sqrt{-5.27 \text{ m}^2 + -6.58 \text{ m}^2} = 8.43 \text{ m}.$$

b The direction of \vec{d} is $\theta = \tan^{-1}\left(\frac{d_y}{d_x}\right) = \tan^{-1}\left(\frac{-6.58 \text{ m}}{-5.27 \text{ m}}\right) = 51.3^\circ$ or 231° .

We choose 231° measured counterclockwise from x since the desired angle is in the third quadrant. The equivalent answer is -129° measured clockwise from x .

114. Taking derivatives of $\vec{r} = 2t\hat{i} + 2\sin \pi t \hat{j}$ with lengths in meters, time in seconds, and angles in radians provides the expressions for velocity and acceleration

$$\vec{v} = \frac{d\vec{r}}{dt} = 2\hat{i} + \frac{\pi}{2} \cos\left(\frac{\pi t}{4}\right)\hat{j}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = -\frac{\pi^2}{8} \sin\left(\frac{\pi t}{4}\right)\hat{j}.$$

thus we obtain

time t s			0.0	1.0	2.0	3.0	4.0
a	\vec{r} position	x m	0.0	2.0	4.0	6.0	8.0
		y m	0.0	1.4	2.0	1.4	0.0
b	\vec{v} velocity	v_x m/s		2.0	2.0	2.0	
		v_y m/s		1.1	0.0	-1.1	
c	\vec{a} acceleration	a_x m/s ²		0.0	0.0	0.0	
		a_y m/s ²		-0.87	-1.2	-0.87	

115. Since this problem involves constant downward acceleration of magnitude a similar to the projectile motion situation, we use the equations of 4.6 as long as we substitute a for g . We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The initial velocity is horizontal so that $v_{0,y} = 0$ and

$$v_{0,x} = v_0 = 1.00 \times 10^9 \text{ cm/s}.$$

a If ℓ is the length of a plate and t is the time an electron is between the plates, then $\ell = v_0 t$ where v_0 is the initial speed. Thus

$$t = \frac{\ell}{v_0} = \frac{2.00 \text{ cm}}{1.00 \times 10^9 \text{ cm/s}} = 2.00 \times 10^{-9} \text{ s}.$$

b the vertical displacement of the electron is

$$y = -\frac{1}{2}at^2 = -\frac{1}{2}(1.00 \times 10^{17} \text{ cm s}^{-2})(2.00 \times 10^{-9} \text{ s})^2 = -0.20 \text{ cm} = -2.00 \text{ mm}$$

or $y = 2.00 \text{ mm}$.

c the x component of velocity does not change

$$v_x = v_0 = 1.00 \times 10^9 \text{ cm s} = 1.00 \times 10^7 \text{ m s}.$$

d the y component of the velocity is

$$\begin{aligned} v_y &= a_y t = (1.00 \times 10^{17} \text{ cm s}^{-2})(2.00 \times 10^{-9} \text{ s}) = 2.00 \times 10^8 \text{ cm s} \\ &= 2.00 \times 10^6 \text{ m s}. \end{aligned}$$

116. We neglect air resistance which justifies setting $a = -g = -9.8 \text{ m s}^{-2}$ taking *down* as the $-y$ direction for the duration of the motion of the shot ball. We are allowed to use Table 2.1 with Δy replacing Δx because the ball has constant acceleration motion. We use primed variables for the constant velocity elevator so $v = 10 \text{ m s}^{-1}$ and unprimed variables for the ball with initial velocity $v_0 = v' + 20 = 30 \text{ m s}^{-1}$ relative to the ground. Units are used throughout.

a Taking the time to be zero at the instant the ball is shot we compute its maximum height y relative to the ground with $v^2 = v_0^2 - 2g(y - y_0)$ where the highest point is characterized by $v = 0$. Thus

$$y = y_0 + \frac{v_0^2}{2g} = 76 \text{ m}$$

here $y_0 = y'_0 + 2 = 30 \text{ m}$ where $y'_0 = 28 \text{ m}$ is given in the problem and $v_0 = 30 \text{ m s}^{-1}$ relative to the ground as noted above.

b There are a variety of approaches to this question. One is to continue working in the frame of reference adopted in part (a) (which treats the ground as motionless and “fixes” the coordinate origin to it) in this case one describes the elevator motion with $y' = y'_0 + v't$ and the ball motion with . 2.15 and solves them for the case where they reach the same point at the same time. Another is to work in the frame of reference of the elevator the boy in the elevator might be oblivious to the fact the elevator is moving since it isn’t accelerating), which is what we show here in detail

$$\Delta y_e = v_{0_e} t - \frac{1}{2} g t^2 \Rightarrow t = \frac{v_{0_e} + \sqrt{v_{0_e}^2 - 2g\Delta y_e}}{g}$$

here $v_{0e} = 20 \text{ m/s}$ is the initial velocity of the ball relative to the elevator and $\Delta y_e = -2.0 \text{ m}$ is the ball's displacement relative to the floor of the elevator. The positive root is chosen to yield a positive value for t the result is $t = 4.2 \text{ s}$.

117. We adopt the positive direction choices used in the textbook so that equations such as 4.22 are directly applicable. The coordinate origin is at the initial position for the football as it begins projectile motion in the sense of 4.5 and we let θ_0 be the angle of its initial velocity measured from the x axis.

a $x = 46 \text{ m}$ and $y = -1.5 \text{ m}$ are the coordinates for the landing point it lands at time $t = 4.5 \text{ s}$. Since $x = v_{0x}t$

$$v_{0x} = \frac{x}{t} = \frac{46 \text{ m}}{4.5 \text{ s}} = 10.2 \text{ m/s}.$$

Since $y = v_{0y}t - \frac{1}{2}gt^2$

$$v_{0y} = \frac{y + \frac{1}{2}gt^2}{t} = \frac{-1.5 \text{ m} + \frac{1}{2}(9.8 \text{ m/s}^2)(4.5 \text{ s})^2}{4.5 \text{ s}} = 21.7 \text{ m/s}.$$

The magnitude of the initial velocity is

$$v_0 = \sqrt{v_{0x}^2 + v_{0y}^2} = \sqrt{(10.2 \text{ m/s})^2 + (21.7 \text{ m/s})^2} = 24 \text{ m/s}.$$

b The initial angle satisfies $\tan \theta_0 = v_{0y}/v_{0x}$. Thus

$$\theta_0 = \tan^{-1} \frac{21.7 \text{ m/s}}{10.2 \text{ m/s}} = 65^\circ.$$

118. The velocity of Larry is v_1 and that of Curly is v_2 . Also we denote the length of the corridor by L . Now, Larry's time of passage is $t_1 = 150 \text{ s}$ which must equal L/v_1 and Curly's time of passage is $t_2 = 70 \text{ s}$ which must equal L/v_2 . The time Joe takes is therefore

$$t = \frac{L}{v_1 + v_2} = \frac{1}{\frac{1}{v_1} + \frac{1}{v_2}} = \frac{1}{\frac{1}{150 \text{ s}} + \frac{1}{70 \text{ s}}} = 48 \text{ s}.$$

119. The boat has velocity $\vec{v}_{cg} = v_1 \hat{i}$ relative to the ground and the bullet has velocity

$$\vec{v}_{0bg} = v_2 \cos \theta \hat{i} + v_2 \sin \theta \hat{j}$$

relative to the ground before entering the car. We are neglecting the effects of gravity on the bullet. While in the car its velocity relative to the outside ground is

$$\vec{v}_{bg} = 0.8v_2 \cos \theta \hat{i} + 0.8v_2 \sin \theta \hat{j}$$

due to the 20° reduction mentioned in the problem. The problem indicates that the velocity of the bullet in the car *relative to the car* is \vec{v}_{bc} with v_3 unspecified. Eq. 4-44 provides the condition

$$\vec{v}_{bg} = \vec{v}_{bc} + \vec{v}_{cg}$$

$$0.8v_2 \cos \theta \hat{i} + 0.8v_2 \sin \theta \hat{j} = v_3 \hat{i} + v_1 \hat{j}$$

so that equating x components allows us to find θ . If one wished to find v_3 one could also equate the y components and from this if the car's width were given one could find the time spent by the bullet in the car but this information is not asked for which is why the width is irrelevant. Therefore equating the x components in SI units leads to

$$\theta = \cos^{-1} \left(\frac{v_1}{0.8v_2} \right) = \cos^{-1} \left(\frac{85 \text{ km/h} \left(\frac{1000 \text{ m}}{3600 \text{ s}} \right)}{0.8 \cdot 650 \text{ m/s}} \right)$$

which yields 87° for the direction of \vec{v}_{bg} measured from \hat{i} (which is the direction of motion of the car). The problem asks, “from what direction was it fired?” — which means the answer is not 87° but rather its supplement 93° measured from the direction of motion. Noting this more carefully in the coordinate system we have adopted in our solution the bullet velocity vector is in the first quadrant at 87° measured counterclockwise from the x direction the direction of train motion which means that the direction from which the bullet came (here the sniper is) is in the third quadrant at -93° that is 93° measured clockwise from x .

120. a. Since $a = v^2/R$ the radius of the track is

$$R = \frac{v^2}{a} = \frac{9.20 \text{ m/s}^2}{3.80 \text{ m/s}^2} = 22.3 \text{ m}.$$

b. Since $T = 2\pi R/v$ the period of the circular motion is

$$T = \frac{2\pi R}{v} = \frac{2\pi \cdot 22.3 \text{ m}}{9.20 \text{ m/s}} = 15.2 \text{ s}$$

121. a. With $v = c/10 = 3 \times 10^7 \text{ m/s}$ and $a = 20g = 196 \text{ m/s}^2$ Eq. 4-34 gives

$$r = v^2/a = 4.6 \times 10^{12} \text{ m}.$$

b. The period is given by Eq. 4-35 $T = 2\pi r/v = 9.6 \times 10^5 \text{ s}$. Thus the time to make a quarter turn is $T/4 = 2.4 \times 10^5 \text{ s}$ or about 2.8 days.

122. Since $v_y^2 = v_{0y}^2 - 2g\Delta y$ and $v_y = 0$ at the target we obtain

$$v_{0y} = \sqrt{2(9.80 \text{ m/s}^2)(5.00 \text{ m})} = 9.90 \text{ m/s}$$

a Since $v_0 \sin \theta_0 = v_{0y}$ with $v_0 = 12.0 \text{ m/s}$ we find $\theta_0 = 55.6^\circ$.

b So $v_y = v_{0y} - gt$ gives $t = \frac{9.90 \text{ m/s}}{9.80 \text{ m/s}^2} = 1.01 \text{ s}$. Thus

$$\Delta x = v_0 \cos \theta_0 t = 6.85 \text{ m}.$$

c The velocity at the target has only the v_x component which is equal to $v_{0x} = v_0 \cos \theta_0 = 6.78 \text{ m/s}$.

123. With $v_0 = 30.0 \text{ m/s}$ and $R = 20.0 \text{ m}$, Eq. 4.26 gives

$$\sin 2\theta_0 = \frac{gR}{v_0^2} = 0.218.$$

Because $\sin \phi = \sin (180^\circ - \phi)$ there are two roots of the above equation

$$2\theta_0 = \sin^{-1} 0.218 = 12.58^\circ \text{ and } 167.4^\circ.$$

which correspond to the two possible launch angles that will hit the target in the absence of air friction and related effects.

a The smallest angle is $\theta_0 = 6.29^\circ$.

b The greatest angle is and $\theta_0 = 83.7^\circ$.

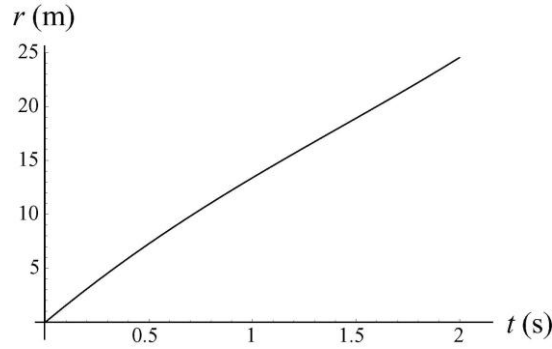
An alternative approach to this problem in terms of Eq. 4.25 with $y = 0$ and $1 \cos^2 = 1 \tan^2$ is possible — and leads to a quadratic equation for $\tan \theta_0$ with the roots providing these two possible θ_0 values.

124. We make use of Eq. 4.21 and Eq. 4.22.

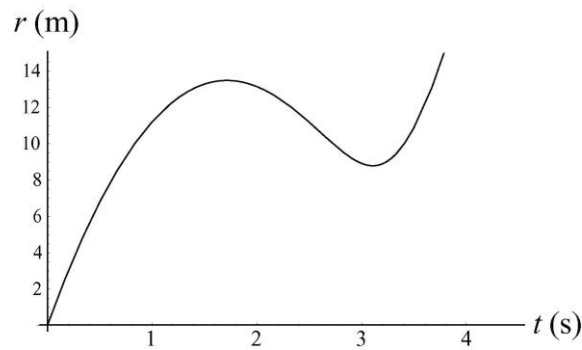
a With $v_0 = 16 \text{ m/s}$ we square Eq. 4.21 and Eq. 4.22 and add them then using Pythagoras' theorem) take the square root to obtain r

$$\begin{aligned} r &= \sqrt{(x - x_0)^2 + (y - y_0)^2} = \sqrt{v_0^2 \cos^2 \theta_0 t^2 + (v_0 \sin \theta_0 t - gt)^2} \\ &= t \sqrt{v_0^2 - v_0 g \sin \theta_0 + g^2 t} \end{aligned}$$

So we plot r as a function of time for $\theta_0 = 40.0^\circ$



b For this next graph for r versus t we set $\theta_0 = 80.0^\circ$.



c Differentiating r with respect to t we obtain

$$\frac{dr}{dt} = \frac{v_0^2 - 3v_0 g t \sin \theta_0}{\sqrt{v_0^2 - v_0 g \sin \theta_0 t + g^2 t^2}} - \frac{2}{4}$$

Setting $\frac{dr}{dt} = 0$ with $v_0 = 16.0 \text{ m/s}$ and $\theta_0 = 40.0^\circ$ we have $256 - 151t + 48t^2 = 0$. The equation has no real solution. This means that the maximum is reached at the end of the flight with

$$t_{\text{total}} = 2v_0 \sin \theta_0 / g = 2(16.0 \text{ m/s}) \sin 40.0^\circ / 9.80 \text{ m/s}^2 = 2.10 \text{ s}.$$

d The value of r is given by

$$r = 2.10 \sqrt{16.0^2 - 16.0(9.80 \sin 40.0^\circ)(2.10) + 9.80^2 (2.10)^2 / 4} = 25.7 \text{ m}.$$

e The horizontal distance is $r_x = v_0 \cos \theta_0 t = 16.0 \text{ m/s} \cos 40.0^\circ (2.10 \text{ s}) = 25.7 \text{ m}$.

f The vertical distance is $r_y = 0$.

g For the $\theta_0 = 80^\circ$ launch the condition for maximum r is $256 - 232t + 48t^2 = 0$ or $t = 1.71 \text{ s}$ the other solution $t = 3.13 \text{ s}$ corresponds to a minimum.

h the distance traveled is

$$r = 1.71 \sqrt{16.0^2 - 16.0 \cdot 9.80 \sin 80.0^\circ \cdot 1.71 + 9.80^2 \cdot 1.71^2} / 4 = 13.5 \text{ m.}$$

i the horizontal distance is

$$r_x = v_0 \cos \theta_0 t = 16.0 \text{ m/s} \cos 80.0^\circ \cdot 1.71 \text{ s} = 4.75 \text{ m.}$$

the vertical distance is

$$r_y = v_0 \sin \theta_0 t - \frac{gt^2}{2} = 16.0 \text{ m/s} \sin 80^\circ \cdot 1.71 \text{ s} - \frac{9.80 \text{ m/s}^2 \cdot 1.71 \text{ s}^2}{2} = 12.6 \text{ m.}$$

125. Using the same coordinate system assumed in . 4 25 we find x for the elevated cannon from

$$y = x \tan \theta_0 - \frac{gx^2}{2(v_0 \cos \theta_0)^2} \quad \text{here } y = -30 \text{ m.}$$

Using the quadratic formula choosing the positive root we find

$$x = v_0 \cos \theta_0 \left(\frac{v_0 \sin \theta_0 + \sqrt{(v_0 \sin \theta_0)^2 - 2gy}}{g} \right)$$

which yields $x = 715 \text{ m}$ for $v_0 = 82 \text{ m/s}$ and $\theta_0 = 45^\circ$. This is 29 m longer than the distance of 686 m.

126. At maximum height the y component of a projectile's velocity vanishes, so the given 10 m/s is the constant x component of velocity.

a Using v_{0y} to denote the y velocity 1.0 s before reaching the maximum height then with $v_y = 0$ the equation $v_y = v_{0y} - gt$ leads to $v_{0y} = 9.8 \text{ m/s}$. The magnitude of the velocity vector or *speed* at that moment is therefore

$$\sqrt{v_x^2 + v_{0y}^2} = \sqrt{10 \text{ m/s}^2 + 9.8 \text{ m/s}^2} = 14 \text{ m/s.}$$

b It is clear from the symmetry of the problem that the speed is the same 1.0 s after reaching the top as it was 1.0 s before 14 m/s again. This may be verified by using $v_y = v_{0y} - gt$ again but now "starting the clock" at the highest point so that $v_{0y} = 0$ and $t = 1.0 \text{ s}$. This leads to $v_y = -9.8 \text{ m/s}$ and $\sqrt{10 \text{ m/s}^2 + (-9.8 \text{ m/s})^2} = 14 \text{ m/s}.$

c The x_0 value may be obtained from $x = 0 = x_0 + 10 \text{ m/s} \cdot 1.0 \text{ s}$ which yields $x_0 = -10 \text{ m}$.

d With $v_{0y} = 9.8 \text{ m/s}$ denoting the y component of velocity one second before the top of the trajectory then we have $y = 0 = y_0 + v_{0y}t - \frac{1}{2}gt^2$ here $t = 1.0 \text{ s}$. This yields $y_0 = -4.9 \text{ m}$.

e By using $x - x_0 = 10 \text{ m/s} \cdot 1.0 \text{ s}$ here $x_0 = 0$ we obtain $x = 10 \text{ m}$.

f Let $t = 0$ at the top with $y_0 = v_{0y} = 0$. From $y - y_0 = v_{0y}t - \frac{1}{2}gt^2$ we have for $t = 1.0 \text{ s}$

$$y = -9.8 \text{ m/s}^2 \cdot 1.0 \text{ s}^2 / 2 = -4.9 \text{ m}.$$

127. With no acceleration in the x direction yet a constant acceleration of 1.40 m/s^2 in the y direction the position in meters as a function of time in seconds must be

$$\vec{r} = 6.00t \hat{i} + \left(\frac{1}{2} 1.40 t^2 \right) \hat{j}$$

and \vec{v} is its derivative with respect to t .

a At $t = 3.00 \text{ s}$ therefore $\vec{v} = 6.00\hat{i} + 4.20\hat{j} \text{ m/s}$.

b At $t = 3.00 \text{ s}$ the position is $\vec{r} = 18.0\hat{i} + 6.30\hat{j} \text{ m}$.

128. We note that

$$\vec{v}_{PG} = \vec{v}_{PA} + \vec{v}_{AG}$$

describes a right triangle with one leg being \vec{v}_{PG} east another leg being \vec{v}_{AG} magnitude = 20 direction = south and the hypotenuse being \vec{v}_{PA} magnitude = 70. Lengths are in kilometers and time is in hours. Using the Pythagorean theorem we have

$$|\vec{v}_{PA}| = \sqrt{\vec{v}_{PG}^2 + \vec{v}_{AG}^2} \Rightarrow 70 \text{ km/h} = \sqrt{\vec{v}_{PG}^2 + 20 \text{ km/h}^2}$$

which can be solved to give the ground speed $\vec{v}_{PG} = 67 \text{ km/h}$.

129. The figure offers many interesting points to analyze and others are easily inferred such as the point of maximum height. The focus here to begin with will be the final point shown 1.25 s after the ball is released which is when the ball returns to its original height. In English units $g = 32 \text{ ft/s}^2$.

a Since $x - x_0 = v_x t$ we obtain $v_x = 40 \text{ ft} / 1.25 \text{ s} = 32 \text{ ft/s}$. And $y - y_0 = 0 = v_{0y} t - \frac{1}{2} g t^2$ yields $v_{0y} = \frac{1}{2} (32 \text{ ft/s}^2)(1.25 \text{ s}) = 20 \text{ ft/s}$. Thus the initial speed is

$$v_0 = \vec{v}_0 = \sqrt{32 \text{ ft/s}^2 + 20 \text{ ft/s}^2} = 38 \text{ ft/s}.$$

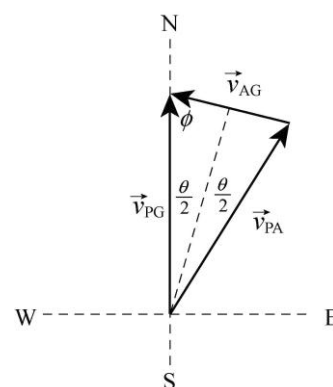
b Since $v_y = 0$ at the maximum height and the horizontal velocity stays constant then the speed at the top is the same as $v_x = 32 \text{ ft/s}$.

c We can infer from the figure or compute from $v_y = 0 = v_{0y} - g t$ that the time to reach the top is 0.625 s . With this we can use $y - y_0 = v_{0y} t - \frac{1}{2} g t^2$ to obtain 9.3 ft here $y_0 = 3 \text{ ft}$ has been used. An alternative approach is to use $v_y^2 = v_{0y}^2 - 2g(y - y_0)$.

130. We denote \vec{v} as the velocity of the plane relative to the ground, \vec{v}_A as the velocity of the air relative to the ground and \vec{v}_{PA} as the velocity of the plane relative to the air.

a The vector diagram is shown on the right. $\vec{v} = \vec{v}_A + \vec{v}_{PA}$. Since the magnitudes v and v_{PA} are equal the triangle is isosceles with two sides of equal length.

Consider either of the right triangles formed when the bisector of θ is drawn (the dashed line). It bisects \vec{v} so



$$\sin(\theta/2) = \frac{v}{2v} = \frac{70.0 \text{ mi/h}}{2(135 \text{ mi/h})}$$

which leads to $\theta = 30.1^\circ$. So \vec{v} makes the same angle with the dashed line as the dashed line does with the \vec{v}_A line. The wind is blowing in the direction 15.0° north of east. Thus it is blowing from 75.0° east of south.

b The plane is headed along \vec{v} in the direction 30.0° east of north. Here is another solution with the plane headed 30.0° west of north and the wind blowing 15° north of east that is from 75° west of south.

131. We make use of 4.24 and 4.25.

a With $x = 180 \text{ m}$, $\theta_0 = 30^\circ$ and $v_0 = 43 \text{ m/s}$ we obtain

$$y = \tan 30^\circ (180 \text{ m}) - \frac{9.8 \text{ m/s}^2 (180 \text{ m})^2}{2 (43 \text{ m/s})^2 \cos^2 30^\circ} = -11 \text{ m}$$

or $y = 11$ m. This implies the rise is roughly eleven meters above the fair way.

b The horizontal component in the absence of air friction is unchanged but the vertical component increases see 4.24. The Pythagorean theorem then gives the magnitude of final velocity right before striking the ground 45 m/s.

132. We let g_p denote the magnitude of the gravitational acceleration on the planet. The number of the points on the graph (including some “inferred” points — such as the maximum height point at $x = 12.5$ m and $t = 1.25$ s) can be analyzed profitably for future reference. We label with subscripts the first $(x_0, y_0 = 0, 2 \text{ at } t_0 = 0)$ and last (“final”) points $((x_f, y_f = 25, 2 \text{ at } t_f = 2.5)$ with lengths in meters and time in seconds.

a The x component of the initial velocity is found from $x_f - x_0 = v_{0x} t_f$. Therefore $v_{0x} = 25/2.5 = 10$ m/s. We try to obtain the y component from

$$y_f - y_0 = 0 = v_{0y} t_f - \frac{1}{2} g_p t_f^2.$$

This gives us $v_{0y} = 1.25 g_p$ and we see we need another equation by analyzing another point say the next to last one $y - y_0 = v_{0y} t - \frac{1}{2} g_p t^2$ with $y = 6$ and $t = 2$ this produces our second equation $v_{0y} = 2 g_p$. Simultaneous solution of these two equations produces results for v_{0y} and g_p relevant to part b. Thus our complete answer for the initial velocity is $\vec{v} = 10 \text{ m/s } \hat{i} + 10 \text{ m/s } \hat{j}$.

b As a by product of the part a computations we have $g_p = 8.0 \text{ m/s}^2$.

c Solving for t_g the time to reach the ground in $y_g = 0 = y_0 + v_{0y} t_g - \frac{1}{2} g_p t_g^2$ leads to a positive answer $t_g = 2.7$ s.

d With $g = 9.8 \text{ m/s}^2$ the method employed in part c could produce the quadratic equation $-4.9 t_g^2 + 10 t_g + 2 = 0$ and then the positive result $t_g = 2.2$ s.

133. (a) The helicopter's speed is $v' = 6.2$ m/s which implies that the speed of the package is $v_0 = 12 - v' = 5.8$ m/s relative to the ground.

b Letting x be in the direction of \vec{v}_0 for the package and y be downward we have for the motion of the package

$$\Delta x = v_0 t \quad \text{and} \quad \Delta y = \frac{1}{2} g t^2$$

Here $\Delta y = 9.5$ m. From these we find $t = 1.39$ s and $\Delta x = 8.08$ m for the package while $\Delta x'$ for the helicopter which is moving in the opposite direction is $-v' t = -8.63$ m. Thus the horizontal separation between them is $8.08 - (-8.63) = 16.7 \text{ m} \approx 17 \text{ m}$.

c The components of \vec{v} at the moment of impact are $v_x, v_y = 5.8, 13.6$ in units. The vertical component has been computed using $\tan^{-1} \frac{13.6}{5.8} = 67^\circ$. The angle which is below horizontal for this vector is $\tan^{-1} \frac{13.6}{5.8} = 67^\circ$.

134. The type of acceleration involved in steady speed circular motion is the centripetal acceleration $a = \frac{v^2}{r}$ which is at each moment directed towards the center of the circle. The radius of the circle is $r = 12^2 \cdot 3 = 48$ m.

a Thus if at the instant the car is traveling *clockwise* around the circle it is 48 m east of the center of its circular path.

b The same result holds here if at the instant the car is traveling *counterclockwise*. That is it is 48 m east of the center of its circular path.

135. a Using the same coordinate system assumed in 4.21 and 4.22 so that $\theta_0 = -20.0^\circ$ we use $v_0 = 15.0$ m/s and find the horizontal displacement of the ball at $t = 2.30$ s

$$\Delta x = (v_0 \cos \theta_0)t = 32.4 \text{ m.}$$

b The vertical displacement is $\Delta y = (v_0 \sin \theta_0)t - \frac{1}{2}gt^2 = -37.7$ m.

136. We take the initial x, y specification to be $0.000, 0.762$ m and the positive x direction to be towards the “green monster.” The components of the initial velocity are $33.53 \angle 55^\circ \rightarrow 19.23, 27.47$ m/s.

a With $t = 5.00$ s we have $x = x_0 + v_x t = 96.2$ m.

b At that time $y = y_0 + v_{0y}t - \frac{1}{2}gt^2 = 15.59$ m which is 4.31 m above the ball.

c The moment in question is specified by $t = 4.50$ s. At that time $x - x_0 = 19.23 \cdot 4.50 = 86.5$ m.

d The vertical displacement is $y = y_0 + v_{0y}t - \frac{1}{2}gt^2 = 25.1$ m.

137. When moving in the same direction as the jet stream of speed v_s the time is $t = d / (v_{ja} + v_s)$ where $d = 4350$ km is the distance and $v_{ja} = 966$ km/h is the speed of the jet relative to the air. When moving against the jet stream the time is $t' = d / (v_{ja} - v_s)$ with $t' - t = 50$ min = $\frac{5}{6}$ h. Combining the expressions gives

$$t' - t = \frac{d}{v_{ja} - v_s} - \frac{d}{v_{ja} + v_s} = \frac{2dv_s}{v_{ja}^2 - v_s^2} = \frac{5}{6} \text{ h}$$

upon rearranging and using the quadratic formula to solve for v_s we get $v_s = 88.63 \text{ km/h}$.

138. We establish coordinates with \hat{i} pointing to the far side of the river perpendicular to the current and \hat{j} pointing in the direction of the current. We are told that the magnitude presumed constant of the velocity of the boat relative to the water is $\vec{v}_{bw} = 6.4 \text{ km/h}$. Its angle relative to the x axis is θ . With km and h as the understood units the velocity of the water relative to the ground is $\vec{v}_{wg} = 3.2\hat{j}$.

(a) To reach a point “directly opposite” means that the velocity of her boat relative to ground must be $\vec{v}_{bg} = v_{bg}\hat{i}$ where $v_{bg} > 0$ is unknown. Thus all \hat{j} components must cancel in the vector sum

$$\vec{v}_{bw} + \vec{v}_{wg} = \vec{v}_{bg}$$

which means the $v_{bw} \sin \theta = -3.2$ so $\theta = \sin^{-1}(-3.2/6.4) = -30^\circ$.

(b) Using the result from part (a) we find $v_{bg} = v_{bw} \cos \theta = 5.5 \text{ km/h}$. Thus traveling a distance of $\ell = 6.4 \text{ km}$ requires a time of $6.4/5.5 = 1.15 \text{ h}$ or 69 min.

(c) If her motion is completely along the y axis as the problem implies then with $v_{wg} = 3.2 \text{ km/h}$ the water speed we have

$$t_{\text{total}} = \frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}} = 1.33 \text{ h}$$

here $D = 3.2 \text{ km}$. This is equivalent to 80 min.

(d) Since

$$\frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}} = \frac{D}{v_{bw} - v_{wg}} + \frac{D}{v_{bw} + v_{wg}}$$

the answer is the same as in the previous part i.e. $t_{\text{total}} = 80 \text{ min}$.

(e) The shortest time path should have $\theta = 0$. This can also be shown by noting that the case of general θ leads to

$$\vec{v}_{bg} = \vec{v}_{bw} + \vec{v}_{wg} = v_{bw} \cos \theta \hat{i} + v_{bw} \sin \theta \hat{j} + v_{wg} \hat{j}$$

here the x component of \vec{v}_{bg} must be equal ℓ/t . Thus $t = \frac{\ell}{v_{bw} \cos \theta}$ which can be

minimized using the condition $dt/d\theta = 0$. The above expression leads to $t = 6.4/6.4 = 1.0 \text{ h}$ or 60 min.

Chapter

1. We are only concerned with horizontal forces in this problem; gravity plays no direct role. We take east as the x direction and north as y . This calculation is efficiently implemented on a vector-capable calculator using magnitude-angle notation with units understood.

$$\vec{a} = \frac{\vec{F}}{m} = \frac{(9.0 \angle 0^\circ) + (8.0 \angle 118^\circ)}{3.0} = (2.9 \angle 53^\circ)$$

Therefore, the acceleration has a magnitude of 2.9 m/s^2 .

2. We apply Newton's second law (Eq. 5-1 or equivalently 5-2). The net force applied on the chopping block is $\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2$; here the vector addition is done using unit vector notation. The acceleration of the block is given by $\vec{a} = (\vec{F}_1 + \vec{F}_2)/m$.

a. In the first case

$$\vec{F}_1 + \vec{F}_2 = [(3.0 \text{ N})\hat{i} + (4.0 \text{ N})\hat{j}] + [(-3.0 \text{ N})\hat{i} + (-4.0 \text{ N})\hat{j}] = 0$$

so $\vec{a} = 0$.

b. In the second case, the acceleration \vec{a} equals

$$\frac{\vec{F}_1 + \vec{F}_2}{m} = \frac{[(3.0 \text{ N})\hat{i} + (4.0 \text{ N})\hat{j}] + [(-3.0 \text{ N})\hat{i} + (4.0 \text{ N})\hat{j}]}{2.0 \text{ kg}} = 4.0 \text{ m/s}^2 \hat{j}.$$

c. In this final situation, \vec{a} is

$$\frac{\vec{F}_1 + \vec{F}_2}{m} = \frac{[(3.0 \text{ N})\hat{i} + (4.0 \text{ N})\hat{j}] + [(3.0 \text{ N})\hat{i} + (-4.0 \text{ N})\hat{j}]}{2.0 \text{ kg}} = 3.0 \text{ m/s}^2 \hat{i}.$$

3. We apply Newton's second law (specifically, Eq. 5-2).

a. We find the x component of the force is

$$F_x = ma_x = ma \cos 20.0^\circ = (1.00 \text{ kg})(2.00 \text{ m/s}^2) \cos 20.0^\circ = 1.88 \text{ N}.$$

b. The y component of the force is

$$F_y = ma_y = ma \sin 20.0^\circ = (1.0 \text{ kg}) (2.00 \text{ m s}^{-2}) \sin 20.0^\circ = 0.684 \text{ N}.$$

c In unit vector notation the force vector is

$$\vec{F} = F_x \hat{i} + F_y \hat{j} = 1.88 \hat{i} + 0.684 \hat{j} \text{ N}.$$

4. Since $\vec{v} = \text{constant}$ we have $\vec{a} = 0$ which implies

$$\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 = m\vec{a} = 0.$$

Thus the other force must be

$$\vec{F}_2 = -\vec{F}_1 = -2 \hat{i} + 6 \hat{j} \text{ N}.$$

5. The net force applied on the chopping block is $\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3$ here the vector addition is done using unit vector notation. The acceleration of the block is given by $\vec{a} = (\vec{F}_1 + \vec{F}_2 + \vec{F}_3) / m$.

a The forces exerted by the three astronauts can be expressed in unit vector notation as follows

$$\begin{aligned}\vec{F}_1 &= 32 \text{ N} (\cos 30^\circ \hat{i} + \sin 30^\circ \hat{j}) = 27.7 \hat{i} + 16 \hat{j} \text{ N} \\ \vec{F}_2 &= 55 \text{ N} (\cos 0^\circ \hat{i} + \sin 0^\circ \hat{j}) = 55 \hat{i} \text{ N} \\ \vec{F}_3 &= 41 \text{ N} (\cos(-60^\circ) \hat{i} + \sin(-60^\circ) \hat{j}) = 20.5 \hat{i} - 35.5 \hat{j} \text{ N}.\end{aligned}$$

The resultant acceleration of the asteroid of mass $m = 120 \text{ kg}$ is therefore

$$\vec{a} = \frac{(27.7 \hat{i} + 16 \hat{j}) + (55 \hat{i}) + (20.5 \hat{i} - 35.5 \hat{j})}{120 \text{ kg}} = 0.86 \text{ m s}^{-2} \hat{i} - 0.16 \text{ m s}^{-2} \hat{j}.$$

b The magnitude of the acceleration vector is

$$|\vec{a}| = \sqrt{a_x^2 + a_y^2} = \sqrt{(0.86 \text{ m s}^{-2})^2 + (-0.16 \text{ m s}^{-2})^2} = 0.88 \text{ m s}^{-2}.$$

c The vector \vec{a} makes an angle θ with the x axis here

$$\theta = \tan^{-1} \left(\frac{a_y}{a_x} \right) = \tan^{-1} \left(\frac{-0.16 \text{ m s}^{-2}}{0.86 \text{ m s}^{-2}} \right) = -11^\circ.$$

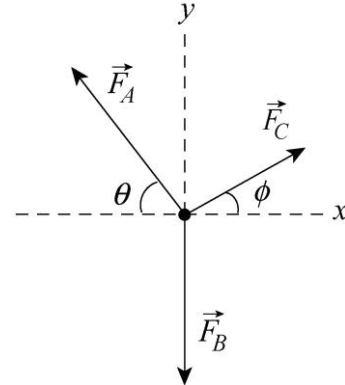
6. Since the tire remains stationary, by Newton's second law, the net force must be zero:

$$\vec{F}_{\text{net}} = \vec{F}_A + \vec{F}_B + \vec{F}_C = m\vec{a} = 0.$$

From the free body diagram shown on the right we have

$$0 = \sum F_{\text{net } x} = F_C \cos \phi - F_A \cos \theta$$

$$0 = \sum F_{\text{net } y} = F_A \sin \theta + F_C \sin \phi - F_B$$



To solve for F_B we first compute ϕ . With $F_A = 220$ N, $F_C = 170$ N, and $\theta = 47^\circ$ we get

$$\cos \phi = \frac{F_A \cos \theta}{F_C} = \frac{220 \cos 47.0^\circ}{170} = 0.883 \Rightarrow \phi = 28.0^\circ$$

Substituting the value into the second force equation we find

$$F_B = F_A \sin \theta + F_C \sin \phi = 220 \sin 47.0^\circ + 170 \sin 28.0^\circ = 241 \text{ N}.$$

7. **THINK** A box is under acceleration by two applied forces. We use Newton's second law to solve for the unknown second force.

EXPRESS We denote the two forces as \vec{F}_1 and \vec{F}_2 . According to Newton's second law, $\vec{F}_1 + \vec{F}_2 = m\vec{a}$ so the second force is $\vec{F}_2 = m\vec{a} - \vec{F}_1$. Note that since the acceleration is in the third quadrant we expect \vec{F}_2 to be in the third quadrant as well.

ANALYZE In unit vector notation $\vec{F}_1 = (20.0 \text{ N})\hat{i}$ and

$$\vec{a} = -(12.0 \sin 30.0^\circ \text{ m/s}^2)\hat{i} - (12.0 \cos 30.0^\circ \text{ m/s}^2)\hat{j} = -(6.00 \text{ m/s}^2)\hat{i} - (10.4 \text{ m/s}^2)\hat{j}.$$

Therefore we find the second force to be

$$\begin{aligned} \vec{F}_2 &= m\vec{a} - \vec{F}_1 \\ &= (2.00 \text{ kg})(-6.00 \text{ m/s}^2)\hat{i} + (2.00 \text{ kg})(-10.4 \text{ m/s}^2)\hat{j} - (20.0 \text{ N})\hat{i} \\ &= (-32.0 \text{ N})\hat{i} - (20.8 \text{ N})\hat{j}. \end{aligned}$$

b The magnitude of \vec{F}_2 is $F_2 = \sqrt{F_{2x}^2 + F_{2y}^2} = \sqrt{(-32.0)^2 + (-20.8)^2} = 38.2 \text{ N}.$

c The angle that \vec{F}_2 makes with the positive x axis is found from

$$\tan \phi = \left(\frac{F_{2y}}{F_{2x}} \right) = \frac{-20.8}{-32.0} = 0.656.$$

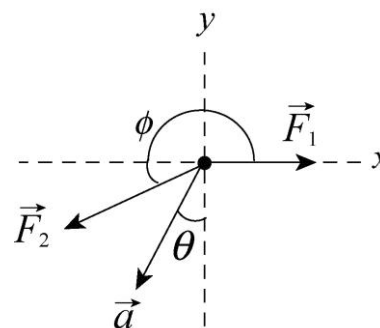
Consequently the angle is either 33.0° or $33.0^\circ + 180^\circ = 213^\circ$. Since both the x and y components are negative the correct result is $\phi = 213^\circ$ from the x axis. An alternative answer is $213^\circ - 360^\circ = -147^\circ$.

LEARN The result is shown in the figure on the right.

The calculation confirms our expectation that \vec{F}_2 lies in the third quadrant same as \vec{a} . The net force is

$$\begin{aligned}\vec{F}_{\text{net}} &= \vec{F}_1 + \vec{F}_2 = (20.0 \text{ N})\hat{i} + [(-32.0 \text{ N})\hat{i} + (-20.8 \text{ N})\hat{j}] \\ &= (-12.0 \text{ N})\hat{i} + (-20.8 \text{ N})\hat{j}\end{aligned}$$

which points in the same direction as \vec{a} .



8. We note that $m\vec{a} = -16 \text{ N}\hat{i} + 12 \text{ N}\hat{j}$. With the other forces as specified in the problem, then Newton's second law gives the third force as

$$\vec{F}_3 = m\vec{a} - \vec{F}_1 - \vec{F}_2 = -34 \text{ N}\hat{i} - 12 \text{ N}\hat{j}.$$

9. To solve the problem we note that acceleration is the second time derivative of the position function. It is a vector and can be determined from its components. The net force is related to the acceleration via Newton's second law. Thus, differentiating $x(t) = -15.0 + 2.00t + 4.00t^3$ twice with respect to t we get

$$\frac{dx}{dt} = 2.00 - 12.0t^2 \quad \frac{d^2x}{dt^2} = -24.0t$$

Similarly differentiating $y(t) = 25.0 + 7.00t - 9.00t^2$ twice with respect to t yields

$$\frac{dy}{dt} = 7.00 - 18.0t \quad \frac{d^2y}{dt^2} = -18.0$$

a. The acceleration is

$$\vec{a} = a_x\hat{i} + a_y\hat{j} = \frac{d^2x}{dt^2}\hat{i} + \frac{d^2y}{dt^2}\hat{j} = -24.0t\hat{i} + -18.0\hat{j}.$$

At $t = 0.700 \text{ s}$ we have $\vec{a} = -16.8 \text{ m/s}^2\hat{i} + -18.0 \text{ m/s}^2\hat{j}$ with a magnitude of

$$a = |\vec{a}| = \sqrt{(-16.8)^2 + (-18.0)^2} = 24.6 \text{ m/s}^2.$$

thus the magnitude of the force is $F = ma = 0.34 \text{ kg} \cdot 24.6 \text{ m s}^{-2} = 8.37 \text{ N}$.

b. The angle \vec{F} or $\vec{a} = \vec{F}/m$ makes with $+x$ is

$$\theta = \tan^{-1} \left(\frac{a_y}{a_x} \right) = \tan^{-1} \left(\frac{-18.0 \text{ m s}^{-2}}{-16.8 \text{ m s}^{-2}} \right) = 47.0^\circ \text{ or } -133^\circ.$$

We choose the latter -133° since \vec{F} is in the third quadrant.

c. The direction of travel is the direction of a tangent to the path which is the direction of the velocity vector

$$\vec{v}(t) = v_x \hat{i} + v_y \hat{j} = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} = (2.00 - 12.0t^2) \hat{i} + (7.00 - 18.0t) \hat{j}.$$

At $t = 0.700 \text{ s}$ we have $\vec{v}(t = 0.700 \text{ s}) = -3.88 \text{ m s}^{-1} \hat{i} - 5.60 \text{ m s}^{-1} \hat{j}$. Therefore the angle \vec{v} makes with $+x$ is

$$\theta_v = \tan^{-1} \left(\frac{v_y}{v_x} \right) = \tan^{-1} \left(\frac{-5.60 \text{ m s}^{-1}}{-3.88 \text{ m s}^{-1}} \right) = 55.3^\circ \text{ or } -125^\circ.$$

We choose the latter -125° since \vec{v} is in the third quadrant.

10. To solve the problem we note that acceleration is the second time derivative of the position function, and the net force is related to the acceleration via Newton's second law. Thus differentiating

$$x(t) = -13.00 + 2.00t + 4.00t^2 - 3.00t^3$$

twice with respect to t we get

$$\frac{dx}{dt} = 2.00 + 8.00t - 9.00t^2 \quad \frac{d^2x}{dt^2} = 8.00 - 18.0t$$

The net force acting on the particle at $t = 3.40 \text{ s}$ is

$$\vec{F} = m \frac{d^2x}{dt^2} \hat{i} = 0.150 [8.00 - 18.0(3.40)] \hat{i} = -7.98 \text{ N} \hat{i}$$

11. The velocity is the derivative with respect to time of given function x and the acceleration is the derivative of the velocity. Thus $a = 2c - 3(2.0)(2.0)t$ which we use in Newton's second law: $F = (2.0 \text{ kg})a = 4.0c - 24t$ with units understood. At $t = 3.0 \text{ s}$ we are told that $F = -36 \text{ N}$. Thus $-36 = 4.0c - 24(3.0)$ can be used to solve for c . The result is $c = 9.0 \text{ m s}^{-2}$.

12. From the slope of the graph we find $a_x = 3.0 \text{ m/s}^2$. Applying Newton's second law to the x axis and taking θ to be the angle between F_1 and F_2 we have

$$F_1 - F_2 \cos \theta = ma_x \Rightarrow \theta = 56^\circ.$$

13. a From the fact that $T_3 = 9.8$ we conclude the mass of disk D is 1.0 kg . Both this and that of disk C cause the tension $T_2 = 49$ which allows us to conclude that disk C has a mass of 4.0 kg . The weights of these two disks plus that of disk B determine the tension $T_1 = 58.8$ which leads to the conclusion that $m_B = 1.0 \text{ kg}$. The weights of all the disks must add to the 98 force described in the problem therefore disk A has mass 4.0 kg .

b $m_B = 1.0 \text{ kg}$ as found in part a.

c $m_C = 4.0 \text{ kg}$ as found in part a.

d $m_D = 1.0 \text{ kg}$ as found in part a.

14. Three vertical forces are acting on the block: the earth pulls down on the block with gravitational force 3.0 ; a spring pulls up on the block with elastic force 1.0 ; and the surface pushes up on the block with normal force F_N . There is no acceleration so

$$\sum F_y = 0 = F_N + (1.0) + (-3.0)$$

yields $F_N = 2.0$.

a By Newton's third law, the force exerted by the block on the surface has that same magnitude but opposite direction -2.0 .

b The direction is down.

15. **THINK** We have a piece of salami hung to a spring scale in various ways. The problem is to explore the concept of weight.

EXPRESS We first note that the reading on the spring scale is proportional to the weight of the salami. In all three cases a – c depicted in Fig. 5.34 the scale is not accelerating which means that the two cords exert forces of equal magnitude on it. The scale reads the magnitude of either of these forces. In each case the tension force of the cord attached to the salami must be the same in magnitude as the weight of the salami because the salami is not accelerating. Thus the scale reading is mg where m is the mass of the salami.

ANALYZE In all three cases a – c the reading on the scale is

$$w = mg = (11.0 \text{ kg})(9.8 \text{ m/s}^2) = 108 \text{ N}.$$

LEARN The weight of an object is measured when the object is not accelerating vertically relative to the ground. If it is, then the weight measured is called the apparent weight.

16. a. There are six legs and the vertical component of the tension force in each leg is $T \sin \theta$ where $\theta = 40^\circ$. For vertical equilibrium (zero acceleration in the y direction) then Newton's second law leads to

$$6T \sin \theta = mg \Rightarrow T = \frac{mg}{6 \sin \theta}$$

which (expressed as a multiple of the bug's weight mg) gives roughly $T/mg \approx 0.260$.

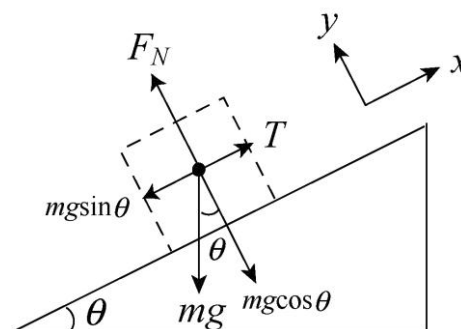
b. The angle θ is measured from horizontal, so as the insect "straightens out the legs" θ will increase (getting closer to 90°) which causes $\sin \theta$ to increase (getting closer to 1) and consequently since $\sin \theta$ is in the denominator causes T to decrease.

17. **THINK** A block attached to a cord is resting on an incline plane. We apply Newton's second law to solve for the tension in the cord and the normal force on the block.

EXPRESS The free body diagram of the problem is shown to the right. Since the acceleration of the block is zero, the components of Newton's second law equation yield

$$\begin{aligned} T - mg \sin \theta &= 0 \\ F_N - mg \cos \theta &= 0 \end{aligned}$$

where T is the tension in the cord and F_N is the normal force on the block.



ANALYZE a. Solving the first equation for the tension in the string we find

$$T = mg \sin \theta = (8.5 \text{ kg})(9.8 \text{ m/s}^2) \sin 30^\circ = 42 \text{ N}.$$

b. We solve the second equation above for the normal force F_N

$$F_N = mg \cos \theta = (8.5 \text{ kg})(9.8 \text{ m/s}^2) \cos 30^\circ = 72 \text{ N}.$$

c. When the cord is cut it no longer exerts a force on the block and the block accelerates. The x component of the second law becomes $-mg \sin \theta = ma$ so the acceleration becomes

$$a = -g \sin \theta = -(9.8 \text{ m/s}^2) \sin 30^\circ = -4.9 \text{ m/s}^2.$$

he negative sign indicates the acceleration is down the plane. The magnitude of the acceleration is 4.9 m/s^2 .

LEARN The normal force F_N on the block must be equal to $mg \cos \theta$ so that the block is in contact with the surface of the incline at all time. When the cord is cut the block has an acceleration $a = -g \sin \theta$ which in the limit $\theta \rightarrow 90^\circ$ becomes $-g$ as in the case of a free fall.

18. The free body diagram of the cars is shown on the right. The force exerted by Johnassis is

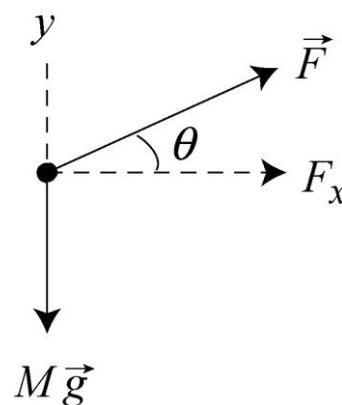
$$F = 2.5mg = 2.5(80 \text{ kg})(9.8 \text{ m/s}^2) = 1960 \text{ N}.$$

Since the motion is along the horizontal x axis, using Newton's second law we have $F_x = F \cos \theta = Ma_x$ where M is the total mass of the railroad cars. Thus the acceleration of the cars is

$$a_x = \frac{F \cos \theta}{M} = \frac{1960 \text{ N} \cos 30^\circ}{7.0 \times 10^5 \text{ kg}} = 0.024 \text{ m/s}^2.$$

Using Eq. 2-16 the speed of the car at the end of the pull is

$$v_x = \sqrt{2a_x \Delta x} = \sqrt{2(0.024 \text{ m/s}^2)(1.0 \text{ m})} = 0.22 \text{ m/s}.$$



19. **THINK** In this problem we're interested in the force applied to a rocket sled to accelerate it from rest to a given speed in a given time interval.

EXPRESS In terms of magnitudes, Newton's second law is $F = ma$ where $F = |\vec{F}_{\text{net}}|$, $a = |\vec{a}|$ and m is the always positive mass. The magnitude of the acceleration can be found using constant acceleration kinematics (Table 2-1). Solving $v = v_0 + at$ for the case where it starts from rest we have $a = v/t$ which we interpret in terms of magnitudes making specification of coordinate directions unnecessary. Thus the required force is $F = ma = mv/t$.

ANALYZE Expressing the velocity in SI units as

$$v = 1600 \text{ km/h} \left(\frac{1000 \text{ m}}{1 \text{ km}} \right) \left(\frac{1 \text{ h}}{3600 \text{ s}} \right) = 444 \text{ m/s}$$

we find the force to be

$$F = m \frac{v}{t} = (500 \text{ kg}) \frac{444 \text{ m/s}}{1.8 \text{ s}} = 1.2 \times 10^5 \text{ N}.$$

LEARN From the expression $F = mv/t$ we see that the shorter the time to attain a given speed the greater the force required.

20. The stopping force \vec{F} and the path of the passenger are horizontal. Our x axis is in the direction of the passenger's motion, so that the passenger's acceleration ("deceleration") is negative valued and the stopping force is in the $-x$ direction $\vec{F} = -F\hat{i}$. Using $\Delta x = 0.65 \text{ m}$ with

$$v_0 = 53 \text{ km/h} = 1000 \text{ m/km} \cdot 3600 \text{ s/h} = 14.7 \text{ m/s}$$

and $v = 0$ the acceleration is found to be

$$v^2 = v_0^2 + 2a\Delta x \Rightarrow a = -\frac{v_0^2}{2\Delta x} = -\frac{(14.7 \text{ m/s})^2}{2(0.65 \text{ m})} = -167 \text{ m/s}^2.$$

Assuming there are no significant horizontal forces other than the stopping force, Eq. 5-1 leads to

$$\vec{F} = m\vec{a} \Rightarrow -F = (41 \text{ kg})(-167 \text{ m/s}^2)$$

which results in $F = 6.8 \times 10^3 \text{ N}$.

21. a. The slope of each graph gives the corresponding component of acceleration. Thus we find $a_x = 3.00 \text{ m/s}^2$ and $a_y = -5.00 \text{ m/s}^2$. The magnitude of the acceleration vector is therefore

$$a = \sqrt{(3.00 \text{ m/s}^2)^2 + (-5.00 \text{ m/s}^2)^2} = 5.83 \text{ m/s}^2$$

and the force is obtained from this by multiplying with the mass $m = 2.00 \text{ kg}$. The result is $F = ma = 11.7 \text{ N}$.

b. The direction of the force is the same as that of the acceleration

$$\theta = \tan^{-1} \frac{-5.00 \text{ m/s}^2}{3.00 \text{ m/s}^2} = -59.0^\circ.$$

22. a. The coin undergoes free fall. Therefore with respect to ground its acceleration is

$$\vec{a}_{\text{coin}} = \vec{g} = -9.8 \text{ m/s}^2 \hat{j}.$$

b. Since the customer is being pulled down with an acceleration of $\vec{a}'_{\text{customer}} = 1.24\vec{g} = -12.15 \text{ m/s}^2 \hat{j}$ the acceleration of the coin with respect to the customer is

$$\vec{a}_{\text{rel}} = \vec{a}_{\text{coin}} - \vec{a}'_{\text{customer}} = -9.8 \text{ m/s}^2 \hat{j} - (-12.15 \text{ m/s}^2 \hat{j}) = +2.35 \text{ m/s}^2 \hat{j}.$$

c The time it takes for the coin to reach the ceiling is

$$t = \sqrt{\frac{2h}{a_{\text{rel}}}} = \sqrt{\frac{2(2.20 \text{ m})}{2.35 \text{ m/s}^2}} = 1.37 \text{ s}.$$

d Since gravity is the only force acting on the coin the actual force on the coin is

$$\vec{F}_{\text{coin}} = m\vec{a}_{\text{coin}} = m\vec{g} = (0.567 \times 10^{-3} \text{ kg})(-9.8 \text{ m/s}^2 \hat{j}) = -5.56 \times 10^{-3} \hat{j}.$$

(e) In the customer's frame, the coin travels upward at a constant acceleration. Therefore the apparent force on the coin is

$$\vec{F}_{\text{app}} = m\vec{a}_{\text{rel}} = (0.567 \times 10^{-3} \text{ kg})(+2.35 \text{ m/s}^2 \hat{j}) = +1.33 \times 10^{-3} \hat{j}.$$

23. Note that the rope is 22.0° from vertical and therefore 68.0° from horizontal.

a With $T = 760 \text{ N}$ then its components are

$$\vec{T} = T \cos 68.0^\circ \hat{i} + T \sin 68.0^\circ \hat{j} = (285 \text{ N}) \hat{i} + (705 \text{ N}) \hat{j}.$$

(b) No longer in contact with the cliff, the only other force on Tarzan is due to earth's gravity. Thus

$$\vec{F}_{\text{net}} = \vec{T} + \vec{W} = (285 \text{ N}) \hat{i} + (705 \text{ N}) \hat{j} - (820 \text{ N}) \hat{j} = (285 \text{ N}) \hat{i} - (115 \text{ N}) \hat{j}.$$

c In a manner that is efficiently implemented on a vector capable calculator we convert from rectangular x - y components to magnitude-angle notation

$$\vec{F}_{\text{net}} = (285 \hat{i} - 115 \hat{j}) \rightarrow (307 \angle -22.0^\circ)$$

so that the net force has a magnitude of 307 N .

d The angle (see part c) has been found to be -22.0° or 22.0° below horizontal away from the cliff.

e Since $\vec{a} = \vec{F}_{\text{net}}/m$ here $m = W/g = 83.7 \text{ kg}$ we obtain $\vec{a} = 3.67 \text{ m/s}^2$.

f 5.1 requires that $\vec{a} \parallel \vec{F}_{\text{net}}$ so that the angle is also -22.0° or 22.0° below horizontal away from the cliff.

24. We take rightward as the x direction. Thus $\vec{F}_1 = (20 \text{ N}) \hat{i}$. In each case we use Newton's second law $\vec{F}_1 + \vec{F}_2 = m\vec{a}$ here $m = 2.0 \text{ kg}$.

- a f $\vec{a} = +10 \text{ m s}^{-2} \hat{i}$ then the equation above gives $\vec{F}_2 = 0$.
- b f $\vec{a} = +20 \text{ m s}^{-2} \hat{i}$ then that equation gives $\vec{F}_2 = 20 \hat{i}$.
- c f $\vec{a} = 0$ then the equation gives $\vec{F}_2 = -20 \hat{i}$.
- d f $\vec{a} = -10 \text{ m s}^{-2} \hat{i}$ the equation gives $\vec{F}_2 = -40 \hat{i}$.
- e f $\vec{a} = -20 \text{ m s}^{-2} \hat{i}$ the equation gives $\vec{F}_2 = -60 \hat{i}$.

25. a the acceleration is

$$a = \frac{F}{m} = \frac{20}{900 \text{ kg}} = 0.022 \text{ m/s}^2.$$

b the distance traveled in 1 day = 86400 s is

$$s = \frac{1}{2}at^2 = \frac{1}{2}(0.0222 \text{ m/s}^2)(86400 \text{ s})^2 = 8.3 \times 10^7 \text{ m}.$$

c the speed it will be traveling is given by

$$v = at = (0.0222 \text{ m/s}^2)(86400 \text{ s}) = 1.9 \times 10^3 \text{ m/s}.$$

26. Some assumptions not so much for realism but rather in the interest of using the given information efficiently are needed in this calculation. We assume the fishing line and the path of the salmon are horizontal. Thus the weight of the fish contributes only via $\sin 52^\circ$ to information about its mass $m = W \sin 52^\circ = 8.7 \text{ kg}$. Our x axis is in the direction of the salmon's velocity (away from the fisherman), so that its acceleration ("deceleration") is negative valued and the force of tension is in the $-x$ direction $\vec{T} = -T \hat{i}$. We use $\sin 52^\circ$ and $\cos 52^\circ$ units noting that $v = 0$.

$$v^2 = v_0^2 + 2a\Delta x \Rightarrow a = -\frac{v_0^2}{2\Delta x} = -\frac{2.8 \text{ m s}^{-2}}{2(0.11 \text{ m})} = -36 \text{ m s}^{-2}.$$

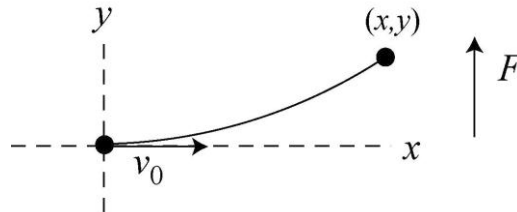
Assuming there are no significant horizontal forces other than the tension $\sin 51^\circ$ leads to

$$\vec{T} = m\vec{a} \Rightarrow -T = (8.7 \text{ kg})(-36 \text{ m/s}^2)$$

which results in $T = 3.1 \times 10^2 \text{ N}$.

27. **THINK** An electron moving horizontally is under the influence of a vertical force. Its path will be deflected toward the direction of the applied force.

EXPRESS The setup is shown in the figure below. The acceleration of the electron is vertical and for all practical purposes the only force acting on it is the electric force. The force of gravity is negligible. We take the x axis to be in the direction of the initial velocity v_0 and the y axis to be in the direction of the electrical force and place the origin at the initial position of the electron.



Since the force and acceleration are constant we use the equations from Table 2.1 $x = v_0 t$ and

$$y = \frac{1}{2} a t^2 = \frac{1}{2} \left(\frac{F}{m} \right) t^2.$$

ANALYZE The time taken by the electron to travel a distance $x = 30$ mm horizontally is $t = x/v_0$ and its deflection in the direction of the force is

$$y = \frac{1}{2} \frac{F}{m} \left(\frac{x}{v_0} \right)^2 = \frac{1}{2} \left(\frac{4.5 \times 10^{-16}}{9.11 \times 10^{-31} \text{ kg}} \right) \left(\frac{30 \times 10^{-3} \text{ m}}{1.2 \times 10^7 \text{ m/s}} \right)^2 = 1.5 \times 10^{-3} \text{ m}.$$

LEARN Since the applied force is constant the acceleration in the y direction is also constant and the path is parabolic with $y \propto x^2$.

28. The stopping force \vec{F} and the path of the car are horizontal. Thus the weight of the car contributes only via W_g to information about its mass $m = W_g/g = 1327 \text{ kg}$. Our x axis is in the direction of the car's velocity, so that its acceleration ("deceleration") is negative valued and the stopping force is in the $-x$ direction $\vec{F} = -F\hat{i}$.

a We use 2.16 and SI units noting that $v = 0$ and $v_0 = 40\,1000\,3600 = 11.1 \text{ m/s}$.

$$v^2 = v_0^2 + 2a\Delta x \Rightarrow a = -\frac{v_0^2}{2\Delta x} = -\frac{11.1 \text{ m/s}^2}{2(15 \text{ m})}$$

which yields $a = -4.12 \text{ m/s}^2$. Assuming there are no significant horizontal forces other than the stopping force 2.51 leads to

$$\vec{F} = m\vec{a} \Rightarrow -F = (1327 \text{ kg}) (-4.12 \text{ m/s}^2)$$

which results in $F = 5.5 \times 10^3$.

b Equation 2.11 readily yields $t = -v_0/a = 2.7$ s.

c Keeping F the same means keeping a the same in which case since $v = 0$. 2.16 we observe a direct proportionality between Δx and v_0^2 . Therefore doubling v_0 means quadrupling Δx . That is the new over the old stopping distances is a factor of 4.0.

d Equation 2.11 illustrates a direct proportionality between t and v_0 so that doubling one means doubling the other. That is the new time of stopping is a factor of 2.0 greater than the one found in part b .

29. We choose up as the y direction so $\vec{a} = -3.00 \text{ m/s}^2 \hat{y}$ which without the unit vector we denote as a since this is a 1 dimensional problem in which Table 2.1 applies . From Eq. 2.12, we obtain the firefighter's mass: $m = W/g = 72.7$ kg.

a We denote the force exerted by the pole on the firefighter $\vec{F}_{fp} = F_{fp} \hat{y}$ and apply Eq. 2.11. Since $\vec{F}_{net} = m\vec{a}$ we have

$$F_{fp} - F_g = ma \Rightarrow F_{fp} - 712 \text{ N} = 72.7 \text{ kg} (-3.00 \text{ m/s}^2)$$

which yields $F_{fp} = 494$ N .

b The fact that the result is positive means \vec{F}_{fp} points up.

(c) Newton's third law indicates $\vec{F}_{fp} = -\vec{F}_{pf}$ which leads to the conclusion that $\vec{F}_{pf} = 494$ N .

d The direction of \vec{F}_{pf} is down.

30. The stopping force \vec{F} and the path of the toothpick are horizontal. Our x axis is in the direction of the toothpick's motion, so that the toothpick's acceleration ("deceleration") is negative valued and the stopping force is in the $-x$ direction $\vec{F} = -F\hat{i}$. Using Eq. 2.16 with $v_0 = 220 \text{ m/s}$ and $v = 0$ the acceleration is found to be

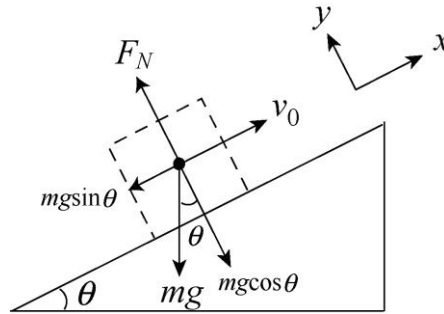
$$v^2 = v_0^2 + 2a\Delta x \Rightarrow a = -\frac{v_0^2}{2\Delta x} = -\frac{220 \text{ m/s}^2}{2(0.015 \text{ m})} = -1.61 \times 10^6 \text{ m/s}^2.$$

thus the magnitude of the force exerted by the branch on the toothpick is

$$F = m a = 1.3 \times 10^{-4} \text{ kg } 1.61 \times 10^6 \text{ m s}^{-2} = 2.1 \times 10^2 \text{ N}.$$

31. THINK In this problem we analyze the motion of a block sliding up an inclined plane and back down.

EXPRESS The free body diagram is shown below. \vec{F}_N is the normal force of the plane on the block and $m\vec{g}$ is the force of gravity on the block. We take the x direction to be up the incline and the y direction to be in the direction of the normal force exerted by the incline on the block.



The x component of Newton's second law is then $mg \sin \theta = -ma$ thus the acceleration is $a = -g \sin \theta$. Placing the origin at the bottom of the plane the kinematic equations table 2.1 for motion along the x axis which we will use are $v^2 = v_0^2 + 2ax$ and $v = v_0 + at$. The block momentarily stops at its highest point where $v = 0$ according to the second equation this occurs at time $t = -v_0/a$.

ANALYZE a The position where the block stops is

$$x = v_0 t + \frac{1}{2} a t^2 = v_0 \left(\frac{-v_0}{a} \right) + \frac{1}{2} a \left(\frac{-v_0}{a} \right)^2 = -\frac{1}{2} \frac{v_0^2}{a} = -\frac{1}{2} \left(\frac{3.50 \text{ m s}^{-1}}{-(9.8 \text{ m s}^{-2}) \sin 32.0^\circ} \right) = 1.18 \text{ m}.$$

b The time it takes for the block to get there is

$$t = \frac{v_0}{a} = -\frac{v_0}{-g \sin \theta} = -\frac{3.50 \text{ m s}}{-9.8 \text{ m s}^{-2} \sin 32.0^\circ} = 0.674 \text{ s}.$$

c That the return speed is identical to the initial speed is to be expected since there are no dissipative forces in this problem. In order to prove this one approach is to set $x = 0$ and solve $x = v_0 t + \frac{1}{2} a t^2$ for the total time up and back down t . The result is

$$t = -\frac{2v_0}{a} = -\frac{2v_0}{-g \sin \theta} = -\frac{2(3.50 \text{ m/s})}{-9.8 \text{ m/s}^2 \sin 32.0^\circ} = 1.35 \text{ s}.$$

the velocity when it returns is therefore

$$v = v_0 + at = v_0 - gt \sin \theta = 3.50 \text{ m/s} - 9.8 \text{ m/s}^2 (1.35 \text{ s}) \sin 32^\circ = -3.50 \text{ m/s}.$$

The negative sign indicates the direction is down the plane.

LEARN The expected speed of the block when it gets back to the bottom of the incline is the same as its initial speed. We shall see in Chapter 8 this is a consequence of energy conservation. If friction is present then the return speed will be smaller than the initial speed.

32. Using notation suitable to a vector capable calculator the $\vec{F}_{\text{net}} = 0$ condition becomes

$$\vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 6.00 \angle 150^\circ + 7.00 \angle -60.0^\circ + \vec{F}_3 = 0.$$

$$\text{thus } \vec{F}_3 = 1.70 \hat{i} + 3.06 \hat{j}.$$

b. Constant velocity condition requires zero acceleration so the answer is the same.

c. The acceleration is

$$\vec{a} = 13.0 \text{ m/s}^2 \hat{i} - 14.0 \text{ m/s}^2 \hat{j}.$$

Using $\vec{F}_{\text{net}} = m \vec{a}$ with $m = 0.025 \text{ kg}$ we now obtain

$$\vec{F}_3 = 2.02 \hat{i} + 2.71 \hat{j}.$$

33. The free body diagram is shown below. Let \vec{T} be the tension of the cable and $m\vec{g}$ be the force of gravity. If the upward direction is positive then Newton's second law is $T - mg = ma$ where a is the acceleration.

Thus the tension is $T = m(g + a)$. We use constant acceleration kinematics (Table 2-1) to find the acceleration where $v = 0$ is the final velocity, $v_0 = -12 \text{ m/s}$ is the initial velocity and $y = -42 \text{ m}$ is the coordinate at the stopping point. Consequently $v^2 = v_0^2 + 2ay$ leads to

$$a = -\frac{v_0^2}{2y} = -\frac{(-12 \text{ m/s})^2}{2(-42 \text{ m})} = 1.71 \text{ m/s}^2.$$

We now return to calculate the tension

$$\begin{aligned}
 T &= m(g + a) \\
 &= (1600 \text{ kg}) (9.8 \text{ m/s}^2 + 1.71 \text{ m/s}^2) \\
 &= 1.8 \times 10^4 \text{ N}
 \end{aligned}$$

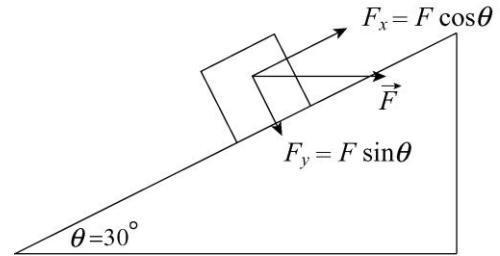


34. We resolve this horizontal force into appropriate components.

(a) Newton's second law applied to the x axis produces

$$F \cos \theta - mg \sin \theta = ma.$$

or $a = 0$ this yields $F = 566 \text{ N}$.



(b) Applying Newton's second law to the y axis, where there is no acceleration, we have

$$F_N - F \sin \theta - mg \cos \theta = 0$$

which yields the normal force $F_N = 1.13 \times 10^3 \text{ N}$.

35. The acceleration vector as a function of time is

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d}{dt} (8.00t \hat{i} + 3.00t^2 \hat{j}) \text{ m/s}^2 = 8.00 \hat{i} + 6.00t \hat{j} \text{ m/s}^2.$$

(a) The magnitude of the force acting on the particle is

$$F = ma = m |\vec{a}| = 3.00 \sqrt{8.00^2 + 6.00t^2} = 3.00 \sqrt{64.0 + 36.0t^2} \text{ N}.$$

Thus $F = 35.0 \text{ N}$ corresponds to $t = 1.415 \text{ s}$ and the acceleration vector at this instant is

$$\vec{a} = 8.00 \hat{i} + 6.00(1.415) \hat{j} \text{ m/s}^2 = 8.00 \text{ m/s}^2 \hat{i} + 8.49 \text{ m/s}^2 \hat{j}.$$

The angle \vec{a} makes with the x axis is

$$\theta_a = \tan^{-1} \left(\frac{a_y}{a_x} \right) = \tan^{-1} \left(\frac{8.49 \text{ m/s}^2}{8.00 \text{ m/s}^2} \right) = 46.7^\circ.$$

(b) The velocity vector at $t = 1.415 \text{ s}$ is

$$\vec{v} = [8.00 \hat{i} + 3.00 \hat{j}] \text{ m/s} = 11.3 \text{ m/s} \hat{i} + 6.01 \text{ m/s} \hat{j}.$$

herefore the angle \vec{v} makes with x is

$$\theta_v = \tan^{-1} \left(\frac{v_y}{v_x} \right) = \tan^{-1} \left(\frac{6.01 \text{ m/s}}{11.3 \text{ m/s}} \right) = 28.0^\circ.$$

36. (a) Constant velocity implies zero acceleration, so the “uphill” force must equal (in magnitude) the “downhill” force: $T = mg \sin \theta$. Thus with $m = 50 \text{ kg}$ and $\theta = 8.0^\circ$ the tension in the rope equals 68 N.

(b) With an uphill acceleration of 0.10 m/s^2 , Newton’s second law (applied to the sled) yields

$$T - mg \sin \theta = ma \Rightarrow T - (50 \text{ kg})(9.8 \text{ m/s}^2) \sin 8.0^\circ = (50 \text{ kg})(0.10 \text{ m/s}^2)$$

which leads to $T = 73 \text{ N}$.

37. (a) Since friction is negligible the force of the girl is the only horizontal force on the sled. The vertical forces—the force of gravity and the normal force of the ice—sum to zero. The acceleration of the sled is

$$a_s = \frac{F}{m_s} = \frac{5.2}{8.4 \text{ kg}} = 0.62 \text{ m/s}^2.$$

(b) According to Newton’s third law the force of the sled on the girl is also 5.2 N. Her acceleration is

$$a_g = \frac{F}{m_g} = \frac{5.2}{40 \text{ kg}} = 0.13 \text{ m/s}^2.$$

(c) The accelerations of the sled and girl are in opposite directions. Assuming the girl starts at the origin and moves in the x direction her coordinate is given by $x_g = \frac{1}{2} a_g t^2$.

The sled starts at $x_0 = 15 \text{ m}$ and moves in the $-x$ direction. Its coordinate is given by $x_s = x_0 - \frac{1}{2} a_s t^2$. They meet when $x_g = x_s$ or

$$\frac{1}{2} a_g t^2 = x_0 - \frac{1}{2} a_s t^2.$$

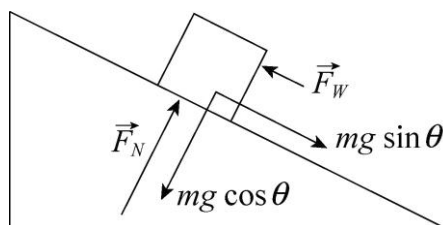
This occurs at time

$$t = \sqrt{\frac{2x_0}{a_g + a_s}}.$$

By then the girl has gone the distance

$$x_g = \frac{1}{2} a_g t^2 = \frac{x_0 a_g}{a_g + a_s} = \frac{(15 \text{ m})(0.13 \text{ m/s}^2)}{0.13 \text{ m/s}^2 + 0.62 \text{ m/s}^2} = 2.6 \text{ m}.$$

38. We label the 40 kg skier “ m ” which is represented as a block in the figure shown. The force of the wind is denoted \vec{F}_w and might be either “uphill” or “downhill” (it is shown uphill in our sketch). The incline angle θ is 10° . The $-x$ direction is downhill.



(a) Constant velocity implies zero acceleration; thus, application of Newton’s second law along the x axis leads to $mg \sin \theta - F_w = 0$. This yields $F_w = 68$ uphill.

(b) Given our coordinate choice we have $a = a = 1.0 \text{ m/s}^2$. Newton’s second law

$$mg \sin \theta - F_w = ma$$

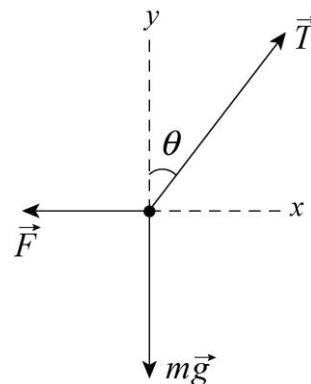
now leads to $F_w = 28$ uphill.

(c) Continuing with the forces as shown in our figure the equation

$$mg \sin \theta - F_w = ma$$

will lead to $F_w = -12$ when $a = 2.0 \text{ m/s}^2$. This simply tells us that the wind is opposite to the direction shown in our sketch in other words $\vec{F}_w = 12$ downhill.

39. The solutions to parts (a) and (b) have been combined here. The free-body diagram is shown to the right with the tension of the string \vec{T} , the force of gravity $m\vec{g}$, and the force of the air \vec{F} . Our coordinate system is shown. Since the sphere is motionless the net force on it is zero and the x and the y components of the equations are



$$\begin{aligned} T \sin \theta - F &= 0 \\ T \cos \theta - mg &= 0 \end{aligned}$$

Here $\theta = 37^\circ$. We answer the questions in the reverse order. Solving $T \cos \theta - mg = 0$ for the tension we obtain

$$T = mg \cos \theta = 3.0 \times 10^{-4} \text{ kg} \cdot 9.8 \text{ m/s}^2 \cos 37^\circ = 3.7 \times 10^{-3} \text{ N}.$$

solving $T \sin \theta - F = 0$ for the force of the air

$$F = T \sin \theta = 3.7 \times 10^{-3} \text{ N} \sin 37^\circ = 2.2 \times 10^{-3} \text{ N}.$$

40. The acceleration of an object neither pushed nor pulled by any force other than gravity on a smooth inclined plane of angle θ is $a = -g \sin \theta$. The slope of the graph shown with the problem statement indicates $a = -2.50 \text{ m/s}^2$. Therefore we find $\theta = 14.8^\circ$. Examining the forces perpendicular to the incline which must sum to zero since there is no component of acceleration in this direction we find $F_N = mg \cos \theta$ where $m = 5.00 \text{ kg}$. Thus the normal perpendicular force exerted at the board ramp interface is 47.4 N.

41. The mass of the bundle is $m = 449 \text{ kg}$ and $9.80 \text{ m/s}^2 = 45.8 \text{ kg}$ and we choose y upward.

(a) Newton's second law, applied to the bundle, leads to

$$T - mg = ma \Rightarrow a = \frac{387 \text{ N} - 449 \text{ kg} \cdot 9.80 \text{ m/s}^2}{45.8 \text{ kg}}$$

which yields $a = -1.4 \text{ m/s}^2$ or $a = 1.4 \text{ m/s}^2$ for the acceleration. The minus sign in the result indicates the acceleration vector points downward. Any downward acceleration of magnitude greater than this is also acceptable since that could lead to even smaller values of tension.

b. We use Eq. 2.16 with Δx replaced by $\Delta y = -6.1 \text{ m}$. We assume $v_0 = 0$.

$$|v| = \sqrt{2a\Delta y} = \sqrt{2(-1.35 \text{ m/s}^2)(-6.1 \text{ m})} = 4.1 \text{ m/s}.$$

For downward accelerations greater than 1.4 m/s^2 the speeds at impact will be larger than 4.1 m/s .

42. The direction of motion (the direction of the barge's acceleration) is $+\hat{i}$ and $+\hat{j}$ is chosen so that the pull \vec{F}_h from the horse is in the first quadrant. The components of the unknown force of the water are denoted simply F_x and F_y .

(a) Newton's second law applied to the barge, in the x and y directions leads to

$$\begin{aligned} (7900 \text{ N}) \cos 18^\circ + F_x &= ma \\ (7900 \text{ N}) \sin 18^\circ + F_y &= 0 \end{aligned}$$

respectively. Plugging in $a = 0.12 \text{ m/s}^2$ and $m = 9500 \text{ kg}$ we obtain $F_x = -6.4 \times 10^3$ and $F_y = -2.4 \times 10^3$. The magnitude of the force of the water is therefore

$$F_{\text{water}} = \sqrt{F_x^2 + F_y^2} = 6.8 \times 10^3.$$

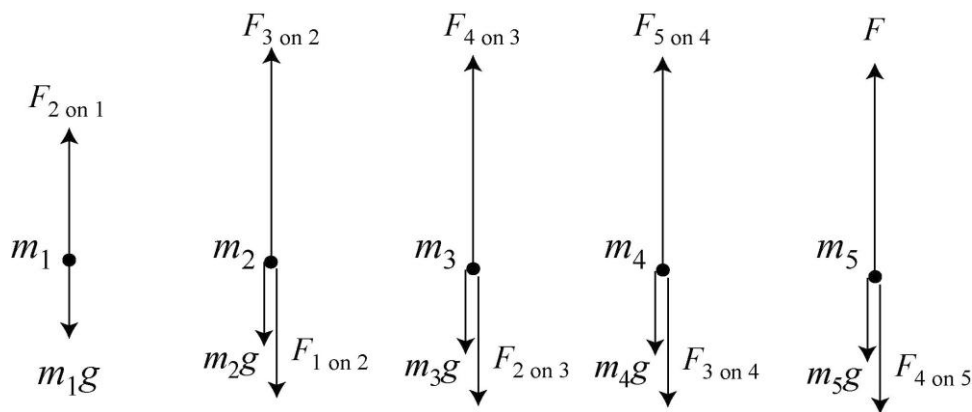
but its angle measured from $+\hat{i}$ is either

$$\tan^{-1} \left(\frac{F_y}{F_x} \right) = +21^\circ \text{ or } 201^\circ.$$

The signs of the components indicate the latter is correct so \vec{F}_{water} is at 201° measured counterclockwise from the line of motion $+\hat{x}$ is.

43. **THINK** A chain of five links is accelerated vertically upward by an external force. We are interested in the forces exerted by one link on its adjacent one.

EXPRESS The links are numbered from bottom to top. The forces on the first link are the force of gravity $m_1\vec{g}$ downward and the force $\vec{F}_{2\text{on}1}$ of link 2 upward as shown in the free body diagram below (not drawn to scale). Take the positive direction to be upward. Then Newton's second law for the first link is $F_{2\text{on}1} - m_1g = m_1a$. The equations for the other links can be written in a similar manner (see below).



ANALYZE a Given that $a = 2.50 \text{ m/s}^2$ from $F_{2\text{on}1} - m_1g = m_1a$ the force exerted by link 2 on link 1 is

$$F_{2\text{on}1} = m_1(a + g) = 0.100 \text{ kg}(2.5 \text{ m/s}^2 + 9.80 \text{ m/s}^2) = 1.23.$$

b From the free body diagram above we see that the forces on the second link are the force of gravity $m_2\vec{g}$ downward and the force $\vec{F}_{1\text{on}2}$ of link 1 downward and the force $\vec{F}_{3\text{on}2}$

of link 3, upward. According to Newton's third law \vec{F}_{1on2} has the same magnitude as \vec{F}_{2on1} . Newton's second law for the second link is

$$F_{3on2} - F_{1on2} - m_2 g = m_2 a$$

so

$$F_{3on2} = m_2 (a + g) \quad F_{1on2} = 0.100 \text{ kg} (2.50 \text{ m/s}^2 + 9.80 \text{ m/s}^2 + 1.23) = 2.46 \text{ N}$$

(c) Newton's second law equation for link 3 is $F_{4on3} - F_{2on3} - m_3 g = m_3 a$ so

$$F_{4on3} = m_3 (a + g) \quad F_{2on3} = 0.100 \text{ kg} (2.50 \text{ m/s}^2 + 9.80 \text{ m/s}^2 + 2.46) = 3.69 \text{ N}$$

where Newton's third law implies $F_{2on3} = F_{3on2}$ since these are magnitudes of the force vectors.

(d) Newton's second law for link 4 is

$$F_{5on4} - F_{3on4} - m_4 g = m_4 a$$

so

$$F_{5on4} = m_4 (a + g) \quad F_{3on4} = 0.100 \text{ kg} (2.50 \text{ m/s}^2 + 9.80 \text{ m/s}^2 + 3.69) = 4.92 \text{ N}$$

where Newton's third law implies $F_{3on4} = F_{4on3}$.

(e) Newton's second law for the top link is $F - F_{4on5} - m_5 g = m_5 a$ so

$$F = m_5 (a + g) \quad F_{4on5} = 0.100 \text{ kg} (2.50 \text{ m/s}^2 + 9.80 \text{ m/s}^2 + 4.92) = 6.15 \text{ N}$$

here $F_{4on5} = F_{5on4}$ by Newton's third law.

Each link has the same mass $m_1 = m_2 = m_3 = m_4 = m_5 = m$ and the same acceleration so the same net force acts on each of them

$$F_{\text{net}} = ma = 0.100 \text{ kg} (2.50 \text{ m/s}^2) = 0.250 \text{ N}$$

LEARN In solving this problem we have used both Newton's second and third laws. Each pair of links constitutes a third law force pair with $\vec{F}_{i \text{ on } j} = -\vec{F}_{j \text{ on } i}$.

44. (a) The term "deceleration" means the acceleration vector is in the direction opposite to the velocity vector which the problem tells us is downward. Thus with y up and the acceleration is $a = -2.4 \text{ m/s}^2$. Newton's second law leads to

$$T - mg = ma \Rightarrow m = \frac{T}{g + a}$$

which yields $m = 7.3 \text{ kg}$ for the mass.

b Repeating the above computation now to solve for the tension with $a = -2.4 \text{ m/s}^2$ will of course lead us right back to $T = 89 \text{ N}$. Since the direction of the velocity did not enter our computation this is to be expected.

45. a The mass of the elevator is $m = 27800/9.80 = 2837 \text{ kg}$ and with y up and the acceleration is $a = -1.22 \text{ m/s}^2$. Newton's second law leads to

$$T - mg = ma \Rightarrow T = m(g + a)$$

which yields $T = 3.13 \times 10^4 \text{ N}$ for the tension.

(b) The term “deceleration” means the acceleration vector is in the direction opposite to the velocity vector which the problem tells us is up and . Thus with y up and the acceleration is now $a = -1.22 \text{ m/s}^2$ so that the tension is

$$T = m(g - a) = 2.43 \times 10^4 \text{ N}.$$

46. With a_{ce} meaning “the acceleration of the coin relative to the elevator” and a_{eg} meaning “the acceleration of the elevator relative to the ground,” we have

$$a_{ce} - a_{eg} = a_{cg} \Rightarrow -8.00 \text{ m/s}^2 - a_{eg} = -9.80 \text{ m/s}^2$$

which leads to $a_{eg} = -1.80 \text{ m/s}^2$. We have chosen up and as the positive y direction. Then Newton's second law (in the “ground” reference frame) yields $T - mg = ma_{eg}$ or

$$T = m(g - a_{eg}) = m(g + 1.80 \text{ m/s}^2) = 2000 \text{ kg} (9.80 \text{ m/s}^2 + 1.80 \text{ m/s}^2) = 23.6 \text{ kN}.$$

47. Using Eq. 4-26 the launch speed of the projectile is

$$v_0 = \sqrt{\frac{gR}{\sin 2\theta}} = \sqrt{\frac{9.8 \text{ m/s}^2 (69 \text{ m})}{\sin 2(53^\circ)}} = 26.52 \text{ m/s}.$$

The horizontal and vertical components of the speed are

$$v_x = v_0 \cos \theta = 26.52 \text{ m/s} \cos 53^\circ = 15.96 \text{ m/s}$$

$$v_y = v_0 \sin \theta = 26.52 \text{ m/s} \sin 53^\circ = 21.18 \text{ m/s}.$$

Since the acceleration is constant we can use Eq. 2-16 to analyze the motion. The horizontal component of the acceleration in the horizontal direction is

$$a_x = \frac{v_x^2}{2x} = \frac{(15.96 \text{ m/s})^2}{2(5.2 \text{ m} \cos 53^\circ)} = 40.7 \text{ m/s}^2$$

and the force component is

$$F_x = ma_x = 85 \text{ kg } 40.7 \text{ m s}^{-2} = 3460 \text{ N}.$$

Similarly in the vertical direction we have

$$a_y = \frac{v_y^2}{2y} = \frac{21.18 \text{ m s}^{-1}}{2 \times 5.2 \text{ m} \sin 53^\circ} = 54.0 \text{ m s}^{-2}.$$

and the force component is

$$F_y = ma_y + mg = 85 \text{ kg } 54.0 \text{ m s}^{-2} + 9.80 \text{ m s}^{-2} = 5424 \text{ N}.$$

thus the magnitude of the force is

$$F = \sqrt{F_x^2 + F_y^2} = \sqrt{3460^2 + 5424^2} = 6434 \text{ N} \approx 6.4 \times 10^3 \text{ N}$$

to two significant figures.

48. Applying Newton's second law to cab B of mass m we have

$$a = \frac{T}{m} - g = 4.89 \text{ m s}^{-2}.$$

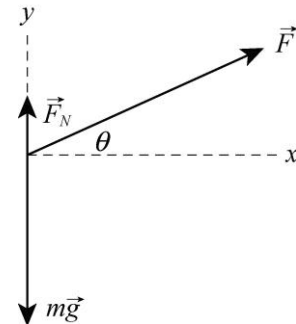
we then apply it to the bob of mass m_b to find the normal force

$$F_N = m_b (g + a) = 176 \text{ N}.$$

49. The free body diagram (not to scale) for the block is shown to the right. \vec{F}_N is the normal force exerted by the floor and $m\vec{g}$ is the force of gravity.

and the x component of Newton's second law is $F \cos \theta = ma$ where m is the mass of the block and a is the x component of its acceleration. we obtain

$$a = \frac{F \cos \theta}{m} = \frac{(12.0 \text{ N}) \cos 25.0^\circ}{5.00 \text{ kg}} = 2.18 \text{ m s}^{-2}.$$



this is its acceleration provided it remains in contact with the floor. assuming it does we find the value of F_N and if F_N is positive then the assumption is true but if F_N is negative then the block leaves the floor. the y component of Newton's second law becomes

$$F_N - F \sin \theta - mg = 0$$

so

$$F_N = mg + F \sin \theta = 5.00 \text{ kg } 9.80 \text{ m s}^{-2} + 12.0 \text{ N } \sin 25.0^\circ = 43.9 \text{ N}.$$

ence the block remains on the floor and its acceleration is $a = 2.18 \text{ m s}^{-2}$.

b If F is the minimum force for which the block leaves the floor then $F_N = 0$ and the y component of the acceleration vanishes. The y component of the second law becomes

$$F \sin \theta - mg = 0 \Rightarrow F = \frac{mg}{\sin \theta} = \frac{(5.00 \text{ kg})(9.80 \text{ m s}^{-2})}{\sin 25.0^\circ} = 116 \text{ N}.$$

c The acceleration is still in the x direction and is still given by the equation developed in part a

$$a = \frac{F \cos \theta}{m} = \frac{116 \text{ N} \cos 25.0^\circ}{5.00 \text{ kg}} = 21.0 \text{ m s}^{-2}.$$

50. a The net force on the *system* of total mass $M = 80.0 \text{ kg}$ is the force of gravity acting on the total overhanging mass $m_{BC} = 50.0 \text{ kg}$. The magnitude of the acceleration is therefore $a = m_{BC} g / M = 6.125 \text{ m s}^{-2}$. Next we apply Newton's second law to block C itself choosing *down* as the y direction and obtain

$$m_C g - T_{BC} = m_C a.$$

this leads to $T_{BC} = 36.8 \text{ N}$.

b We use Eq. 2-15 choosing *rightward* as the x direction $\Delta x = 0 - \frac{1}{2} a t^2 = 0.191 \text{ m}$.

51. The free body diagrams for m_1 and m_2 are shown in the figures below. The only forces on the blocks are the upward tension \vec{T} and the downward gravitational forces $\vec{F}_1 = m_1 g$ and $\vec{F}_2 = m_2 g$. Applying Newton's second law we obtain

$$T - m_1 g = m_1 a$$

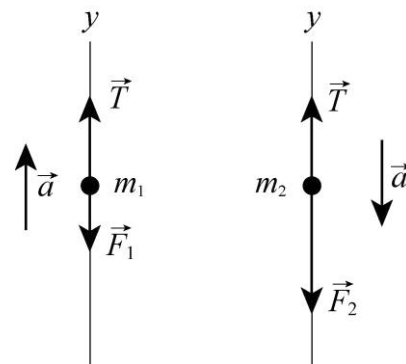
$$m_2 g - T = m_2 a$$

which can be solved to yield

$$a = \left(\frac{m_2 - m_1}{m_2 + m_1} \right) g$$

substituting the result back we have

$$T = \left(\frac{2m_1 m_2}{m_1 + m_2} \right) g$$



a With $m_1 = 1.3 \text{ kg}$ and $m_2 = 2.8 \text{ kg}$ the acceleration becomes

$$a = \left(\frac{2.80 \text{ kg} - 1.30 \text{ kg}}{2.80 \text{ kg} + 1.30 \text{ kg}} \right) 9.80 \text{ m/s}^2 = 3.59 \text{ m/s}^2 \approx 3.6 \text{ m/s}^2.$$

b Similarly the tension in the cord is

$$T = \frac{2(1.30 \text{ kg} + 2.80 \text{ kg})}{1.30 \text{ kg} + 2.80 \text{ kg}} 9.80 \text{ m/s}^2 = 17.4 \approx 17 \text{ N}.$$

52. Treating the man-rope-sandbag as a system means that we should be careful to choose a consistent positive direction of motion (though there are other ways to proceed, say, starting with individual application of Newton's law to each mass). We take *down* as positive for the man's motion and *up* as positive for the sandbag's motion and, without ambiguity, denote their acceleration as a . The net force on the system is the difference between the weight of the man and that of the sandbag. The system mass is $m_{\text{sys}} = 85 \text{ kg} + 65 \text{ kg} = 150 \text{ kg}$. Thus, Eq. 5.1 leads to

$$(85 \text{ kg} - 65 \text{ kg}) 9.8 \text{ m/s}^2 = m_{\text{sys}} a$$

which yields $a = 1.3 \text{ m/s}^2$. Since the system starts from rest, Eq. 2.16 determines the speed after traveling $\Delta y = 10 \text{ m}$ as follows

$$v = \sqrt{2a\Delta y} = \sqrt{2(1.3 \text{ m/s}^2)(10 \text{ m})} = 5.1 \text{ m/s}.$$

53. We apply Newton's second law first to the three blocks as a single system and then to the individual blocks. The x direction is to the right in Fig. 5.48.

a With $m_{\text{sys}} = m_1 + m_2 + m_3 = 67.0 \text{ kg}$, we apply Eq. 5.2 to the x motion of the system in which case there is only one force $\vec{T}_3 = +T_3 \hat{i}$. Therefore

$$T_3 = m_{\text{sys}} a \Rightarrow 65.0 \text{ N} = 67.0 \text{ kg } a$$

which yields $a = 0.970 \text{ m/s}^2$ for the system and for each of the blocks individually.

b Applying Eq. 5.2 to block 1 we find

$$T_1 = m_1 a = (12.0 \text{ kg})(0.970 \text{ m/s}^2) = 11.6 \text{ N}.$$

c In order to find T_2 we can either analyze the forces on block 3 or we can treat blocks 1 and 2 as a system and examine its forces. We choose the latter.

$$T_2 = (m_1 + m_2) a = (12.0 \text{ kg} + 24.0 \text{ kg})(0.970 \text{ m/s}^2) = 34.9 \text{ N}.$$

54. first we consider all the penguins 1 through 4 counting left to right as one system to which we apply Newton's second law:

$$T_4 = (m_1 + m_2 + m_3 + m_4)a \Rightarrow 222 = (12\text{ kg} + m_2 + 15\text{ kg} + 20\text{ kg})a.$$

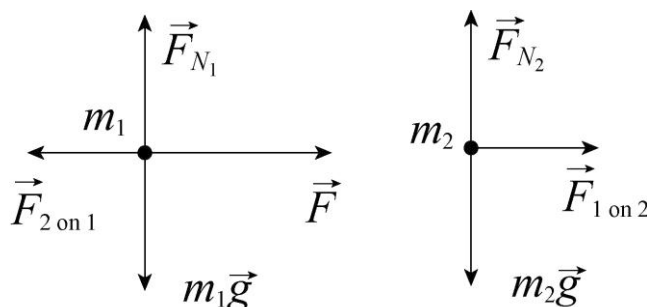
second we consider penguins 3 and 4 as one system for which we have

$$\begin{aligned} T_4 - T_2 &= (m_3 + m_4)a \\ 111 &= (15\text{ kg} + 20\text{ kg})a \Rightarrow a = 3.2\text{ m s}^{-2}. \end{aligned}$$

substituting the value we obtain $m_2 = 23\text{ kg}$.

55. **THINK** In this problem a horizontal force is applied to block 1 which then pushes against block 2. Both blocks move together as a rigid connected system.

EXPRESS The free body diagrams for the two blocks in a are shown below. \vec{F} is the applied force and $\vec{F}_{1\text{on}2}$ is the force exerted by block 1 on block 2. We note that \vec{F} is applied directly to block 1 and that block 2 exerts a force $\vec{F}_{2\text{on}1} = -\vec{F}_{1\text{on}2}$ on block 1 (taking Newton's third law into account).

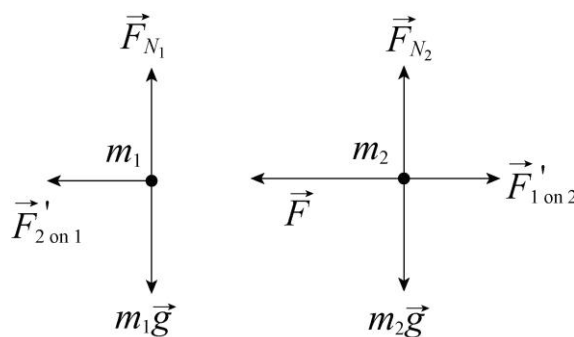


Newton's second law for block 1 is $F - F_{2\text{on}1} = m_1a$ where a is the acceleration. The second law for block 2 is $F_{1\text{on}2} = m_2a$. Since the blocks move together they have the same acceleration and the same symbol is used in both equations.

ANALYZE From the second equation we obtain the expression $a = F_{1\text{on}2} / m_2$ which we substitute into the first equation to get $F - F_{2\text{on}1} = m_1 F_{1\text{on}2} / m_2$. Since $F_{2\text{on}1} = F_{1\text{on}2}$ same magnitude for third law force pair we obtain

$$F_{2\text{on}1} = F_{1\text{on}2} = \frac{m_2}{m_1 + m_2} F = \frac{1.2\text{ kg}}{2.3\text{ kg} + 1.2\text{ kg}} (3.2) = 1.1.$$

but if \vec{F} is applied to block 2 instead of block 1 and in the opposite direction the free body diagrams could look like the following



the corresponding force of contact between the blocks could be

$$F'_{2on1} = F'_{1on2} = \frac{m_1}{m_1 + m_2} F = \frac{2.3 \text{ kg}}{2.3 \text{ kg} + 1.2 \text{ kg}} (3.2) = 2.1 \text{ N}.$$

One can note that the acceleration of the blocks is the same in the two cases. In part (a) the force F_{1on2} is the only horizontal force on the block of mass m_2 and in part (b) F'_{2on1} is the only horizontal force on the block with $m_1 + m_2$. Since $F_{1on2} = m_2 a$ in part (a) and $F'_{2on1} = m_1 a$ in part (b) then for the accelerations to be the same $F'_{2on1} > F_{1on2}$ i.e. force between blocks must be larger in part (b).

LEARN This problem demonstrates that when two blocks are being accelerated together under an external force the contact force between the two blocks is greater if the smaller mass is pushing against the bigger one as in part (b). In the special case where the two masses are equal $m_1 = m_2 = m$ $F'_{2on1} = F_{2on1} = F/2$.

56. Both situations involve the same applied force and the same total mass so the accelerations must be the same in both figures.

(a) The direct force causing B to have this acceleration in the first figure is twice as big as the direct force causing A to have that acceleration. Therefore B has the twice the mass of A . Since their total is given as 12.0 kg then B has a mass of $m_B = 8.00 \text{ kg}$ and A has mass $m_A = 4.00 \text{ kg}$. Considering the first figure $20.0 \text{ N} - 8.00 \text{ kg} = 2.50 \text{ m/s}^2$. Of course the same result comes from considering the second figure $10.0 \text{ N} - 4.00 \text{ kg} = 2.50 \text{ m/s}^2$.

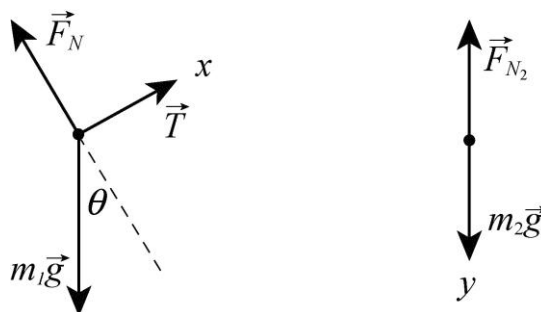
(b) $F_a = 12.0 \text{ kg} \cdot 2.50 \text{ m/s}^2 = 30.0 \text{ N}$

57. The free body diagram for each block is shown below. T is the tension in the cord and $\theta = 30^\circ$ is the angle of the incline. For block 1 we take the x direction to be up the incline and the y direction to be in the direction of the normal force \vec{F}_N that the plane exerts on the block. For block 2 we take the y direction to be down. In this way the accelerations of the two blocks can be represented by the same symbol a without

ambiguity. Applying Newton's second law to the x and y axes for block 1 and to the y axis of block 2 we obtain

$$\begin{aligned}T - m_1 g \sin \theta &= m_1 a \\F_N - m_1 g \cos \theta &= 0 \\m_2 g - T &= m_2 a\end{aligned}$$

respectively. The first and third of these equations provide a simultaneous set for obtaining values of a and T . The second equation is not needed in this problem since the normal force is neither asked for nor is it needed as part of some further computation such as can occur in formulas for friction.



a We add the first and third equations above

$$m_2 g - m_1 g \sin \theta = m_1 a + m_2 a.$$

Consequently we find

$$a = \frac{(m_2 - m_1 \sin \theta)g}{m_1 + m_2} = \frac{2.30 \text{ kg} - 3.70 \text{ kg} \sin 30.0^\circ (9.80 \text{ m/s}^2)}{3.70 \text{ kg} + 2.30 \text{ kg}} = 0.735 \text{ m/s}^2.$$

b The result for a is positive indicating that the acceleration of block 1 is indeed up the incline and that the acceleration of block 2 is vertically down.

c The tension in the cord is

$$T = m_1 a + m_1 g \sin \theta = (3.70 \text{ kg})(0.735 \text{ m/s}^2) + (3.70 \text{ kg})(9.80 \text{ m/s}^2) \sin 30.0^\circ = 20.8 \text{ N}.$$

58. The motion of the man and chair is positive if upward.

a When the man is grasping the rope pulling with a force equal to the tension T in the rope the total upward force on the man and chair due to its two contact points with the rope is $2T$. Thus, Newton's second law leads to

$$2T - mg = ma$$

so that when $a = 0$ the tension is $T = 466$ N.

b When $a = 1.30 \text{ m/s}^2$ the equation in part a predicts that the tension will be $T = 527$ N.

c When the man is not holding the rope instead the coworker attached to the ground is pulling on the rope with a force equal to the tension T in it there is only one contact point between the rope and the man and chair, and Newton's second law now leads to

$$T - mg = ma$$

so that when $a = 0$ the tension is $T = 931$ N.

d When $a = 1.30 \text{ m/s}^2$ the equation in c yields $T = 1.05 \times 10^3$ N.

e The rope comes into contact pulling down in each case at the left edge and the right edge of the pulley producing a total downward force of magnitude $2T$ on the ceiling. Thus in part a this gives $2T = 931$ N.

f In part b the downward force on the ceiling has magnitude $2T = 1.05 \times 10^3$ N.

g In part c the downward force on the ceiling has magnitude $2T = 1.86 \times 10^3$ N.

h In part d the downward force on the ceiling has magnitude $2T = 2.11 \times 10^3$ N.

59. THINK This problem involves the application of Newton's third law. As the monkey climbs up a tree it pulls downward on the rope but the rope pulls upward on the monkey.

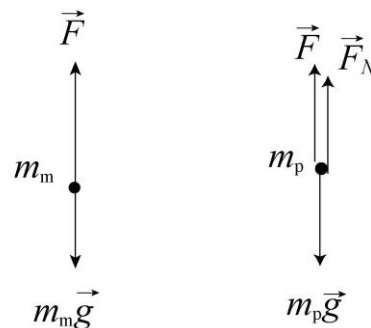
EXPRESS We take y to be up for both the monkey and the package. The force the monkey pulls downward on the rope has magnitude F .

The free body diagrams for the monkey and the package are shown to the right (not to scale). According to Newton's third law, the rope pulls upward on the monkey with a force of the same magnitude, so Newton's second law for forces acting on the monkey leads to

$$F - m_m g = m_m a_m$$

here m_m is the mass of the monkey and a_m is its acceleration.

Since the rope is massless $F = T$ is the tension in the rope. The rope pulls upward on the package with a force of magnitude F , so Newton's second law for the package is



$$F - F_N - m_p g = m_p a_p$$

here m_p is the mass of the package a_p is its acceleration and F_N is the normal force exerted by the ground on it. So if F is the minimum force required to lift the package then $F_N = 0$ and $a_p = 0$. According to the second law equation for the package this means $F = m_p g$.

ANALYZE a substituting $m_p g$ for F in the equation for the monkey we solve for a_m

$$a_m = \frac{F - m_m g}{m_m} = \frac{(m_p - m_m)g}{m_m} = \frac{(15 \text{ kg} - 10 \text{ kg})(9.8 \text{ m/s}^2)}{10 \text{ kg}} = 4.9 \text{ m/s}^2.$$

(b) As discussed, Newton's second law leads to $F - m_p g = m_p a'_p$ for the package and $F - m_m g = m_m a'_m$ for the monkey. If the acceleration of the package is down and then the acceleration of the monkey is up and so $a'_m = -a'_p$. Solving the first equation for F

$$F = m_p (g + a'_p) = m_p (g - a'_m)$$

and substituting this result into the second equation

$$m_p (g - a'_m) - m_m g = m_m a'_m$$

we solve for a'_m

$$a'_m = \frac{(m_p - m_m)g}{m_p + m_m} = \frac{(15 \text{ kg} - 10 \text{ kg})(9.8 \text{ m/s}^2)}{15 \text{ kg} + 10 \text{ kg}} = 2.0 \text{ m/s}^2.$$

c The result is positive indicating that the acceleration of the monkey is upward.

d Solving the second law equation for the package the tension in the rope is

$$F = m_p (g - a'_m) = (15 \text{ kg})(9.8 \text{ m/s}^2 - 2.0 \text{ m/s}^2) = 120 \text{ N}.$$

LEARN The situations described in b and d are similar to that of an Atwood machine. With $m_p > m_m$ the package accelerates downward while the monkey accelerates upward.

60. The horizontal component of the acceleration is determined by the net horizontal force.

a If the rate of change of the angle is

$$\frac{d\theta}{dt} = 2.00 \times 10^{-2} \text{ }^\circ/\text{s} = 2.00 \times 10^{-2} \text{ }^\circ/\text{s} \cdot \left(\frac{\pi \text{ rad}}{180^\circ} \right) = 3.49 \times 10^{-4} \text{ rad/s}$$

then using $F_x = F \cos \theta$ we find the rate of change of acceleration to be

$$\begin{aligned}\frac{da_x}{dt} &= \frac{d}{dt} \left(\frac{F \cos \theta}{m} \right) = -\frac{F \sin \theta}{m} \frac{d\theta}{dt} = -\frac{20.0}{5.00 \text{ kg}} \sin 25.0^\circ (3.49 \times 10^{-4} \text{ rad/s}) \\ &= -5.90 \times 10^{-4} \text{ m/s}^3.\end{aligned}$$

b If the rate of change of the angle is

$$\frac{d\theta}{dt} = -2.00 \times 10^{-2} \text{ }^\circ/\text{s} = -2.00 \times 10^{-2} \text{ }^\circ/\text{s} \cdot \left(\frac{\pi \text{ rad}}{180^\circ} \right) = -3.49 \times 10^{-4} \text{ rad/s}$$

then the rate of change of acceleration would be

$$\begin{aligned}\frac{da_x}{dt} &= \frac{d}{dt} \left(\frac{F \cos \theta}{m} \right) = -\frac{F \sin \theta}{m} \frac{d\theta}{dt} = -\frac{20.0}{5.00 \text{ kg}} \sin 25.0^\circ (-3.49 \times 10^{-4} \text{ rad/s}) \\ &= +5.90 \times 10^{-4} \text{ m/s}^3.\end{aligned}$$

61. **THINK** As more mass is thrown out of the hot air balloon, its upward acceleration increases.

EXPRESS The forces on the balloon are the force of gravity $m\vec{g}$ downward and the force of the air \vec{F}_a upward. We take the y to be up and use a to mean the *magnitude* of the acceleration. When the mass is M before the ballast is thrown out, the acceleration is downward and Newton's second law is

$$Mg - F_a = Ma$$

After the ballast is thrown out, the mass is $M - m$, where m is the mass of the ballast, and the acceleration is now upward. Newton's second law leads to

$$F_a - (M - m)g = (M - m)a.$$

Combining the two equations allows us to solve for m .

ANALYZE The first equation gives $F_a = Mg - a$ and this plugs into the new equation to give

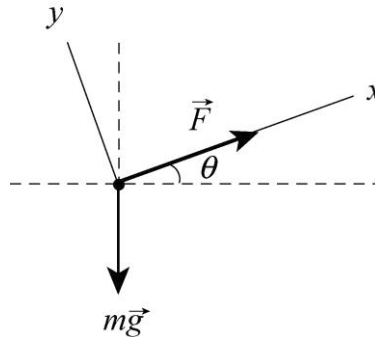
$$M(g - a) - (M - m)g = (M - m)a \Rightarrow m = \frac{2Ma}{g + a}.$$

LEARN More generally, if a ballast mass m' is tossed, the resulting acceleration is a' , which is related to m' via

$$m' = M \frac{a' + a}{g + a}$$

showing that the more mass thrown out the greater is the upward acceleration. For $a' = a$ we get $m' = 2Ma / (g + a)$ which agrees with that as found above.

62. To solve the problem we note that the acceleration along the slanted path depends on only the force components along the path not the components perpendicular to the path.



From the free body diagram shown we see that the net force on the putting shot along the x axis is

$$F_{\text{net } x} = F - mg \sin \theta = 380.0 \text{ N} - 7.260 \text{ kg} \cdot 9.80 \text{ m/s}^2 \sin 30^\circ = 344.4 \text{ N}$$

which in turn gives

$$a_x = F_{\text{net } x} / m = 344.4 \text{ N} / 7.260 \text{ kg} = 47.44 \text{ m/s}^2.$$

Using 2.16 for constant acceleration motion the speed of the shot at the end of the acceleration phase is

$$v = \sqrt{v_0^2 + 2a_x \Delta x} = \sqrt{2.500 \text{ m/s}^2 + 2 \cdot 47.44 \text{ m/s}^2 \cdot 1.650 \text{ m}} = 12.76 \text{ m/s}.$$

For $\theta = 42^\circ$ then

$$a_x = \frac{F_{\text{net } x}}{m} = \frac{F - mg \sin \theta}{m} = \frac{380.0 \text{ N} - 7.260 \text{ kg} \cdot 9.80 \text{ m/s}^2 \sin 42.00^\circ}{7.260 \text{ kg}} = 45.78 \text{ m/s}^2$$

and the final launch speed is

$$v = \sqrt{v_0^2 + 2a_x \Delta x} = \sqrt{2.500 \text{ m/s}^2 + 2 \cdot 45.78 \text{ m/s}^2 \cdot 1.650 \text{ m}} = 12.54 \text{ m/s}.$$

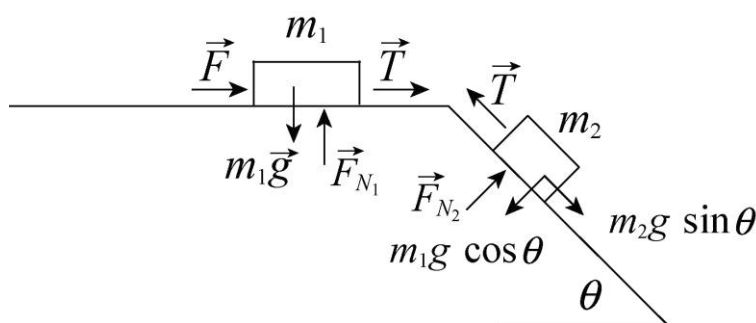
The decrease in launch speed when changing the angle from 30.00° to 42.00° is

$$\frac{12.76 \text{ m/s} - 12.54 \text{ m/s}}{12.76 \text{ m/s}} = 0.0169 = 1.69 \%$$

63. a. The acceleration which equals F/m in this problem is the derivative of the velocity. Thus the velocity is the integral of F/m , so we find the “area” in the graph (15 units) and divide by the mass 3 to obtain $v - v_0 = 15/3 = 5$. Since $v_0 = 3.0 \text{ m/s}$ then $v = 8.0 \text{ m/s}$.

b. Our positive answer in part a implies \vec{v} points in the x direction.

64. The x direction for $m_2 = 1.0 \text{ kg}$ is “downhill” and the $+x$ direction for $m_1 = 3.0 \text{ kg}$ is rightward and thus they accelerate with the same sign.



(a) We apply Newton’s second law to the x axis of each block

$$\begin{aligned} m_2 g \sin \theta - T &= m_2 a \\ F + T &= m_1 a \end{aligned}$$

Adding the two equations allows us to solve for the acceleration

$$a = \frac{m_2 g \sin \theta + F}{m_1 + m_2}$$

With $F = 2.3$ and $\theta = 30^\circ$ we have $a = 1.8 \text{ m/s}^2$. We plug back in and find $T = 3.1$.

b. We consider the “critical” case where the F has reached the max value causing the tension to vanish. The first of the equations in part a shows that $a = g \sin 30^\circ$ in this case thus $a = 4.9 \text{ m/s}^2$. This implies along with $T = 0$ in the second equation in part a that

$$F = 3.0 \text{ kg} \cdot 4.9 \text{ m/s}^2 = 14.7 \approx 15$$

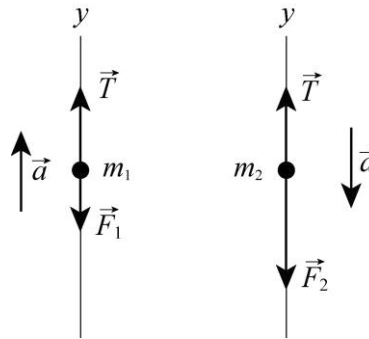
in the critical case.

65. The free body diagrams for m_1 and m_2 are shown in the figures below. The only forces on the blocks are the upward tension \vec{T} and the downward gravitational forces $\vec{F}_1 = m_1 g$ and $\vec{F}_2 = m_2 g$. Applying Newton’s second law we obtain

$$\begin{aligned}T - m_1 g &= m_1 a \\ m_2 g - T &= m_2 a\end{aligned}$$

which can be solved to give

$$a = \left(\frac{m_2 - m_1}{m_2 + m_1} \right) g$$



a At $t = 0$, $m_1 = 1.30 \text{ kg}$. With $\frac{dm_1}{dt} = -0.200 \text{ kg/s}$, find the rate of change of acceleration to be

$$\frac{da}{dt} = \frac{da}{dm_1} \frac{dm_1}{dt} = -\frac{2m_2 g}{(m_2 + m_1)^2} \frac{dm_1}{dt} = -\frac{2(2.80 \text{ kg})(9.80 \text{ m/s}^2)}{(2.80 \text{ kg} + 1.30 \text{ kg})^2} (-0.200 \text{ kg/s}) = 0.653 \text{ m/s}^3.$$

b At $t = 3.00 \text{ s}$, $m_1 = m_1 + \frac{dm_1}{dt} t = 1.30 \text{ kg} + (-0.200 \text{ kg/s})(3.00 \text{ s}) = 0.700 \text{ kg}$ and the rate of change of acceleration is

$$\frac{da}{dt} = \frac{da}{dm_1} \frac{dm_1}{dt} = -\frac{2m_2 g}{(m_2 + m_1)^2} \frac{dm_1}{dt} = -\frac{2(2.80 \text{ kg})(9.80 \text{ m/s}^2)}{(2.80 \text{ kg} + 0.700 \text{ kg})^2} (-0.200 \text{ kg/s}) = 0.896 \text{ m/s}^3.$$

c The acceleration reaches its maximum value when

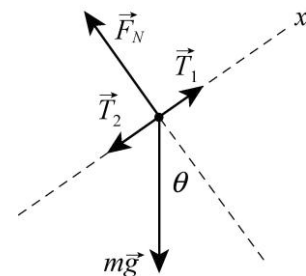
$$0 = m_1 = m_{10} + \frac{dm_1}{dt} t = 1.30 \text{ kg} + (-0.200 \text{ kg/s}) t$$

or $t = 6.50 \text{ s}$.

66. The free body diagram is shown to the right. Newton's second law for the mass m for the x direction leads to

$$T_1 - T_2 - mg \sin \theta = ma$$

which gives the difference in the tension in the pull cable



$$T_1 - T_2 = m(g \sin \theta + a) = (2800 \text{ kg})[9.8 \text{ m/s}^2 \sin 35^\circ + 0.81 \text{ m/s}^2] = 1.8 \times 10^4 \text{ N}.$$

67. First we analyze the entire system with “clockwise” motion considered positive (that is, down is positive for block C , right is positive for block B , and up is positive for block A). $m_C g - m_A g = Ma$ where $M = \text{mass of the system} = 24.0 \text{ kg}$. This yields an acceleration of

$$a = g \frac{m_C - m_A}{M} = 1.63 \text{ m/s}^2.$$

Let's analyze the forces just on block C : $m_C g - T = m_C a$. Thus the tension is

$$T = m_C g - 2m_A m_B = 81.7 \text{ N}.$$

68. We first use Eq. 2-26 to solve for the launch speed of the shot

$$y - y_0 = \tan \theta x - \frac{g x^2}{2 v'^2 \cos^2 \theta}.$$

With $\theta = 34.10^\circ$, $y_0 = 2.11 \text{ m}$ and $x = y = 15.90 \text{ m}$ we find the launch speed to be $v' = 11.85 \text{ m/s}$. During this phase the acceleration is

$$a = \frac{v'^2 - v_0^2}{2L} = \frac{11.85^2 \text{ m}^2/\text{s}^2 - 2.50^2 \text{ m}^2/\text{s}^2}{2(1.65 \text{ m})} = 40.63 \text{ m/s}^2.$$

Since the acceleration along the slanted path depends on only the force components along the path, not the components perpendicular to the path, the average force on the shot during the acceleration phase is

$$F = m(a + g \sin \theta) = 7.260 \text{ kg} [40.63 \text{ m/s}^2 + 9.80 \text{ m/s}^2 \sin 34.10^\circ] = 334.8 \text{ N}.$$

69. We begin by examining a slightly different problem, similar to this figure but without the string. The motivation is that if without the string, block A is found to accelerate faster or exactly as fast as block B , then returning to the original problem, the tension in the string is trivially zero. In the absence of the string

$$a_A = F_A / m_A = 3.0 \text{ m/s}^2$$

$$a_B = F_B / m_B = 4.0 \text{ m/s}^2$$

so the trivial case does not occur. Even without the string, consider the net force on the system: $Ma = F_A + F_B = 36 \text{ N}$. Since $M = 10 \text{ kg}$, the total mass of the system, we obtain $a = 3.6 \text{ m/s}^2$. The two forces on block A are F_A and T in the same direction, so we have

$$m_A a = F_A + T \Rightarrow T = 2.4 \text{ N}.$$

70. a. For the 0.50 meter drop in “free fall,” Eq. 2-16 yields a speed of 3.13 m/s . Using this as the “initial speed” for the final motion over 0.02 meter, during which his motion slows at rate “ a ” we find the magnitude of his average acceleration from when his feet first touch the patio until the moment his body stops moving is $a = 245 \text{ m/s}^2$.

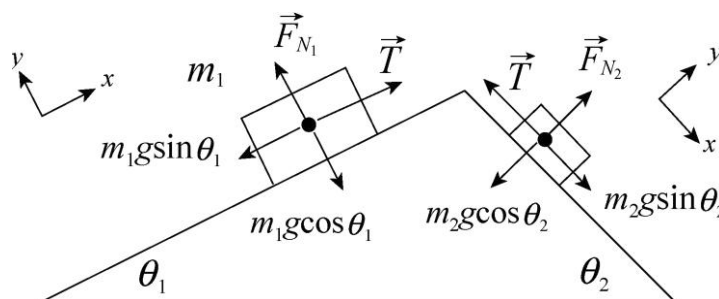
b. We apply Newton's second law: $F_{\text{stop}} - mg = ma \Rightarrow F_{\text{stop}} = 20.4 \text{ kN}$.

71. **THINK** We have two blocks connected together by a cord and placed on a wedge. The system accelerates together and we'd like to know the tension in the cord.

EXPRESS The x axis is “uphill” for $m_1 = 3.0$ kg and “downhill” for $m_2 = 2.0$ kg so they both accelerate with the same sign. The x components of the two masses along the x axis are given by $m_1 g \sin \theta_1$ and $m_2 g \sin \theta_2$ respectively. The free body diagram is shown below. Applying Newton's second law we obtain

$$T - m_1 g \sin \theta_1 = m_1 a$$

$$m_2 g \sin \theta_2 - T = m_2 a$$



Adding the two equations allows us to solve for the acceleration

$$a = \left(\frac{m_2 \sin \theta_2 - m_1 \sin \theta_1}{m_2 + m_1} \right) g$$

ANALYZE With $\theta_1 = 30^\circ$ and $\theta_2 = 60^\circ$ we have $a = 0.45 \text{ m/s}^2$. This value is plugged back into either of the two equations to yield the tension

$$T = \frac{m_1 m_2 g}{m_2 + m_1} (\sin \theta_2 + \sin \theta_1) = 16.1$$

LEARN In this problem we find $m_2 \sin \theta_2 > m_1 \sin \theta_1$ so that $a > 0$ indicating that m_2 slides down and m_1 slides up. The situation could reverse if $m_2 \sin \theta_2 < m_1 \sin \theta_1$. When $m_2 \sin \theta_2 = m_1 \sin \theta_1$ the acceleration is $a = 0$ and the two masses hang in balance. Notice also the symmetry between the two masses in the expression for T .

72. Since the velocity of the particle does not change it undergoes no acceleration and must therefore be subject to zero net force. Therefore

$$\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 0.$$

Thus the third force \vec{F}_3 is given by

$$\vec{F}_3 = -\vec{F}_1 - \vec{F}_2 = -(2\hat{i} + 3\hat{j} - 2\hat{k}) - (-5\hat{i} + 8\hat{j} - 2\hat{k}) = (3\hat{i} - 11\hat{j} + 4\hat{k}).$$

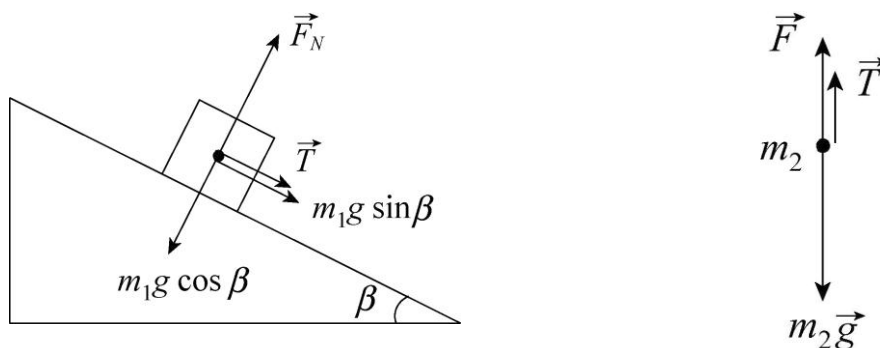
the specific value of the velocity is not used in the computation.

73. THINK We have two masses connected together by a cord. A force is applied to the second mass and the system accelerates together. We apply Newton's second law to solve the problem.

EXPRESS The free body diagrams for the two masses are shown below (not to scale). We first analyze the forces on $m_1 = 1.0 \text{ kg}$. The x direction is "downhill" (parallel to \vec{T}). With an acceleration $a = 5.5 \text{ m/s}^2$ in the positive x direction for m_1 , Newton's second law applied to the x axis gives

$$T + m_1 g \sin \beta = m_1 a.$$

On the other hand, for the second mass $m_2 = 2.0 \text{ kg}$ we have $m_2 g - F - T = m_2 a$ (here the tension comes in as an upward force; the cord can pull, not push). The two equations can be combined to solve for T and β .



ANALYZE We solve both first. By combining the two equations above we obtain

$$\sin \beta = \frac{m_1 + m_2}{m_1 g} \frac{a + F - m_2 g}{m_1} = \frac{1.0 \text{ kg} + 2.0 \text{ kg}}{1.0 \text{ kg}} \frac{5.5 \text{ m/s}^2 + 6.0 - 2.0 \text{ kg} \cdot 9.8 \text{ m/s}^2}{9.8 \text{ m/s}^2} = 0.296$$

which gives $\beta = 17.2^\circ$.

and substituting the value for β found in (a) into the first equation we have

$$T = m_1 (a - g \sin \beta) = 1.0 \text{ kg} [5.5 \text{ m/s}^2 - 9.8 \text{ m/s}^2 \sin 17.2^\circ] = 2.60 \text{ N}.$$

LEARN For $\beta = 0$ the problem becomes the same as that discussed in Sample Problem "Block on table, block hanging." In this case, our results reduce to the familiar expressions $a = m_2 g / (m_1 + m_2)$ and $T = m_1 m_2 g / (m_1 + m_2)$.

74. We are only concerned with horizontal forces in this problem; gravity plays no direct role. Without loss of generality, we take one of the forces along the x direction and the other at 80° measured counterclockwise from the x axis. This calculation is efficiently implemented on a vector-capable calculator in polar mode as follows using magnitude-angle notation with angles understood to be in degrees:

$$\vec{F}_{\text{net}} = 20 \angle 0^\circ + 35 \angle 80^\circ = 43 \angle 53^\circ \Rightarrow F_{\text{net}} = 43 \text{ N}.$$

Therefore, the mass is $m = 43 \text{ N} / 20 \text{ m/s}^2 = 2.2 \text{ kg}$.

75. The goal is to arrive at the least magnitude of \vec{F}_{net} and as long as the magnitudes of \vec{F}_2 and \vec{F}_3 are in total less than or equal to $|\vec{F}_1|$, then we should orient them opposite to the direction of \vec{F}_1 , which is the x direction.

a. We orient both \vec{F}_2 and \vec{F}_3 in the $-x$ direction. Then the magnitude of the net force is $50 - 30 - 20 = 0$, resulting in zero acceleration for the tire.

b. We again orient \vec{F}_2 and \vec{F}_3 in the negative x direction. We obtain an acceleration along the x axis with magnitude

$$a = \frac{F_1 - F_2 - F_3}{m} = \frac{50 - 30 - 10}{12 \text{ kg}} = 0.83 \text{ m/s}^2.$$

c. The least value is $a = 0$. In this case, the forces \vec{F}_2 and \vec{F}_3 are collectively strong enough to have y components, one positive and one negative, that cancel each other and still have enough x contributions in the $-x$ direction to cancel \vec{F}_1 . Since $|\vec{F}_2| = |\vec{F}_3|$, we see that the angle above the $-x$ axis to one of them should be equal to the angle below the $-x$ axis to the other one. We denote this angle θ . We require

$$-50 \text{ N} = F_{2x} + F_{3x} = -(30 \text{ N})\cos\theta - (30 \text{ N})\cos\theta$$

which leads to

$$\theta = \cos^{-1}\left(\frac{50}{60}\right) = 34^\circ.$$

76. A small segment of the rope has mass and is pulled down by the gravitational force of the earth. Equilibrium is reached because neighboring portions of the rope pull up sufficiently on it. Since tension is a force *along* the rope, at least one of the neighboring portions must slope up away from the segment we are considering. Then the tension has an upward component, which means the rope sags.

b The only force acting with a horizontal component is the applied force \vec{F} . Treating the block and rope as a single object, we write Newton's second law for it: $F = (M + m)a$ where a is the acceleration and the positive direction is taken to be to the right. The acceleration is given by $a = F / (M + m)$.

c The force of the rope F_r is the only force with a horizontal component acting on the block. Then Newton's second law for the block gives

$$F_r = Ma = \frac{MF}{M + m}$$

here the expression found above for a has been used.

d Treating the block and half the rope as a single object with mass $M + \frac{1}{2}m$ where the horizontal force on it is the tension T_m at the midpoint of the rope, we use Newton's second law

$$T_m = \left(M + \frac{1}{2}m\right)a = \frac{(M + \frac{1}{2}m)F}{(M + m)} = \frac{(2M + m)F}{2(M + m)}.$$

77. **THINK** We have a crate that is being pulled at an angle. We apply Newton's second law to analyze the motion.

EXPRESS Although the full specification of $\vec{F}_{\text{net}} = m\vec{a}$ in this situation involves both x and y axes, only the x application is needed to find what this particular problem asks for. We note that $a_y = 0$ so that there is no ambiguity denoting a_x simply as a . We choose x to the right and y up. The free body diagram (not to scale) is shown to the right. The x component of the rope's tension acting on the crate is

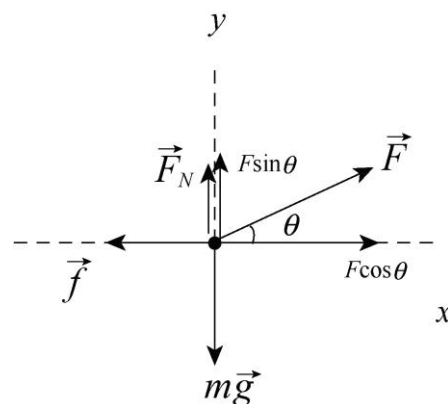
$$F_x = F \cos \theta = 450 \cos 38^\circ = 355$$

and the resistive force pointing in the $-x$ direction has magnitude $f = 125$.

ANALYZE (a) Newton's second law leads to

$$F_x - f = ma \Rightarrow a = \frac{F \cos \theta - f}{m} = \frac{355 - 125}{310 \text{ kg}} = 0.74 \text{ m/s}^2.$$

b In this case we use 5.12 to find the mass $m' = W/g = 31.6 \text{ kg}$. Newton's second law then leads to



$$F_x - f = m'a' \Rightarrow a' = \frac{F_x - f}{m'} = \frac{355 - 125}{31.6 \text{ kg}} = 7.3 \text{ m s}^{-2}.$$

LEARN The resistive force opposing the motion is due to the friction between the crate and the floor. This topic is discussed in greater detail in Chapter 6.

78. We take x uphill for the $m_2 = 1.0 \text{ kg}$ box and x rightward for the $m_1 = 3.0 \text{ kg}$ box so the accelerations of the two boxes have the same magnitude and the same sign. The uphill force on m_2 is F and the downhill forces on it are T and $m_2 g \sin \theta$ where $\theta = 37^\circ$. The only horizontal force on m_1 is the rightward pointed tension. Applying Newton's second law to each box we find

$$\begin{aligned} F - T - m_2 g \sin \theta &= m_2 a \\ T &= m_1 a \end{aligned}$$

which can be added to obtain

$$F - m_2 g \sin \theta = (m_1 + m_2) a.$$

This yields the acceleration

$$a = \frac{12 - 1.0 \text{ kg} \cdot 9.8 \text{ m s}^{-2} \sin 37^\circ}{1.0 \text{ kg} + 3.0 \text{ kg}} = 1.53 \text{ m s}^{-2}.$$

Thus the tension is $T = m_1 a = 3.0 \text{ kg} \cdot 1.53 \text{ m s}^{-2} = 4.6 \text{ N}$.

79. We apply Eq. 5.12.

a. The mass is

$$m = W/g = 22 \text{ N} / 9.8 \text{ m s}^{-2} = 2.2 \text{ kg}.$$

At a place where $g = 4.9 \text{ m s}^{-2}$ the mass is still 2.2 kg but the gravitational force is

$$F_g = mg = 2.2 \text{ kg} \cdot 4.0 \text{ m s}^{-2} = 11 \text{ N}.$$

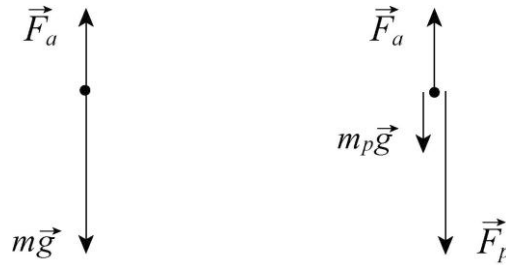
b. As noted $m = 2.2 \text{ kg}$.

c. At a place where $g = 0$ the gravitational force is zero.

d. The mass is still 2.2 kg.

80. We take down to be the y direction.

a. The first diagram shown below left is the free body diagram for the person and parachute considered as a single object with a mass of $80 \text{ kg} + 5.0 \text{ kg} = 85 \text{ kg}$.



\vec{F}_a is the force of the air on the parachute and $m\vec{g}$ is the force of gravity. Application of Newton's second law produces $mg - F_a = ma$ here a is the acceleration. Solving for F_a we find

$$F_a = m(g - a) = (85 \text{ kg})(9.8 \text{ m/s}^2 - 2.5 \text{ m/s}^2) = 620 \text{ N}.$$

b The second diagram above right is the free body diagram for the parachute alone. \vec{F}_a is the force of the air, $m_p\vec{g}$ is the force of gravity and \vec{F}_p is the force of the person. Now, Newton's second law leads to

$$m_pg - F_p - F_a = m_pa.$$

Solving for F_p we obtain

$$F_p = m_p(a - g) + F_a = (5.0 \text{ kg})(2.5 \text{ m/s}^2 - 9.8 \text{ m/s}^2) + 620 \text{ N} = 580 \text{ N}.$$

81. The mass of the pilot is $m = 735/9.8 = 75 \text{ kg}$. Denoting the upward force exerted by the spaceship's seat presumably on the pilot as \vec{F} and choosing upward as the y direction, then Newton's second law leads to

$$F - mg_{\text{moon}} = ma \Rightarrow F = (75 \text{ kg})(1.6 \text{ m/s}^2 + 1.0 \text{ m/s}^2) = 195 \text{ N}.$$

82. With units understood the net force on the boat is

$$\vec{F}_{\text{net}} = (3.0 + 14 \cos 30^\circ - 11) \hat{i} + (14 \sin 30^\circ + 5.0 - 17) \hat{j}$$

$$\text{which yields } \vec{F}_{\text{net}} = 4.1 \hat{i} - 5.0 \hat{j}.$$

(a) Newton's second law applied to the $m = 4.0 \text{ kg}$ boat leads to

$$\vec{a} = \frac{\vec{F}_{\text{net}}}{m} = 1.0 \text{ m/s}^2 \hat{i} - 1.3 \text{ m/s}^2 \hat{j}.$$

b The magnitude of \vec{a} is $a = \sqrt{1.0^2 + (-1.3)^2} = 1.6 \text{ m/s}^2$.

clockwise angle is $\tan^{-1} \frac{-1.3 \text{ m s}^{-2}}{1.0 \text{ m s}^{-2}} = -50^\circ$ that is 50° measured clockwise from the right and a is 1.3 m s^{-2} .

83. THINK This problem deals with the relationship between the three quantities force, mass, and acceleration in Newton's second law $F = ma$.

EXPRESS The "certain force," denoted as F is assumed to be the net force on the object when it gives m_1 an acceleration $a_1 = 12 \text{ m s}^{-2}$ and when it gives m_2 an acceleration $a_2 = 3.3 \text{ m s}^{-2}$ i.e. $F = m_1 a_1 = m_2 a_2$. The accelerations for $m_2 + m_1$ and $m_2 - m_1$ can be solved by substituting $m_1 = F/a_1$ and $m_2 = F/a_2$.

ANALYZE a) To seek the acceleration a of an object of mass $m_2 - m_1$ when F is the net force on it. The result is

$$a = \frac{F}{m_2 - m_1} = \frac{F}{F/a_2 - F/a_1} = \frac{a_1 a_2}{a_1 - a_2} = \frac{12.0 \text{ m s}^{-2} \cdot 3.30 \text{ m s}^{-2}}{12.0 \text{ m s}^{-2} - 3.30 \text{ m s}^{-2}} = 4.55 \text{ m s}^{-2}.$$

b) Similarly for an object of mass $m_2 + m_1$ we have

$$a' = \frac{F}{m_2 + m_1} = \frac{F}{F/a_2 + F/a_1} = \frac{a_1 a_2}{a_1 + a_2} = \frac{12.0 \text{ m s}^{-2} \cdot 3.30 \text{ m s}^{-2}}{12.0 \text{ m s}^{-2} + 3.30 \text{ m s}^{-2}} = 2.59 \text{ m s}^{-2}.$$

LEARN With the same applied force, the greater the mass, the smaller the acceleration. In this problem, we have $a_1 > a > a_2 > a'$. This implies $m_1 < m_2 - m_1 < m_2 < m_2 + m_1$.

84. We assume the direction of motion is x and assume the refrigerator starts from rest so that the speed being discussed is the velocity \vec{v} that results from the process. The only force along the x axis is the x component of the applied force \vec{F} .

a) Since $v_0 = 0$, the combination of Eqs. 2-11 and 2-5 leads simply to

$$F_x = m \left(\frac{v}{t} \right) \Rightarrow v_i = \left(\frac{F \cos \theta_i}{m} \right) t$$

for $i = 1$ or 2 . Here we denote $\theta_1 = 0$ and $\theta_2 = \theta$ for the two cases. Hence we see that the ratio v_2 over v_1 is equal to $\cos \theta$.

b) Since $v_0 = 0$, the combination of Eqs. 2-16 and 2-5 leads to

$$F_x = m \left(\frac{v^2}{2\Delta x} \right) \Rightarrow v_i = \sqrt{2 \left(\frac{F \cos \theta_i}{m} \right) \Delta x}$$

for $i = 1$ or 2 again $\theta_1 = 0$ and $\theta_2 = \theta$ is used for the two cases. In this scenario we see that the ratio v_2 over v_1 is equal to $\sqrt{\cos\theta}$.

85. a Since the performer's weight is $(52 \text{ kg})(9.8 \text{ m/s}^2) = 510$ the rope breaks.

b Setting $T = 425 \text{ N}$ in Newton's second law (with $+y$ upward) leads to

$$T - mg = ma \Rightarrow a = \frac{T}{m} - g$$

which yields $a = 1.6 \text{ m/s}^2$.

86. We use $W_p = mg_p$ where W_p is the weight of an object of mass m on the surface of a certain planet p and g_p is the acceleration of gravity on that planet.

a The weight of the space ranger on Earth is

$$W_e = mg_e = 75 \text{ kg} \cdot 9.8 \text{ m/s}^2 = 7.4 \times 10^2 \text{ N}.$$

b The weight of the space ranger on Mars is

$$W_m = mg_m = 75 \text{ kg} \cdot 3.7 \text{ m/s}^2 = 2.8 \times 10^2 \text{ N}.$$

c The weight of the space ranger in interplanetary space is zero where the effects of gravity are negligible.

d The mass of the space ranger remains the same $m = 75 \text{ kg}$ at all the locations.

87. From the reading when the elevator is at rest we know the mass of the object is $m = 65 \text{ kg}$. $9.8 \text{ m/s}^2 = 6.6 \text{ kg}$. We choose y upward and note there are two forces on the object mg downward and T upward in the cord that connects it to the balance T is the reading on the scale by Newton's third law).

(a) "Upward at constant speed" means constant velocity, which means no acceleration. Thus the situation is just as it is at rest $T = 65 \text{ N}$.

b The term "deceleration" is used when the acceleration vector points in the direction opposite to the velocity vector. We're told the velocity is upward, so the acceleration vector points downward ($a = -2.4 \text{ m/s}^2$). Newton's second law gives

$$T - mg = ma \Rightarrow T = 6.6 \text{ kg} \cdot 9.8 \text{ m/s}^2 - 2.4 \text{ m/s}^2 = 49 \text{ N}.$$

88. We use the notation g as the acceleration due to gravity near the surface of Earth, m as the mass of the landing craft, a as the acceleration of the landing craft, and F as the rocket thrust. We take down to be the positive direction. Thus, Newton's second law takes the form $mg - F = ma$. If the thrust is $F_1 = 3260 \text{ N}$ then the acceleration is zero.

so $mg - F_1 = 0$. If the thrust is $F_2 = 2200$ then the acceleration is $a_2 = 0.39 \text{ m s}^{-2}$ so $mg - F_2 = ma_2$.

a The first equation gives the weight of the landing craft $mg = F_1 = 3260$.

b The second equation gives the mass

$$m = \frac{mg - F_2}{a_2} = \frac{3260 - 2200}{0.39 \text{ m s}^{-2}} = 2.7 \times 10^3 \text{ kg}.$$

c The weight divided by the mass gives the acceleration due to gravity

$$g = \frac{3260}{2.7 \times 10^3 \text{ kg}} = 1.2 \text{ m s}^{-2}.$$

89. a When $\vec{F}_{\text{net}} = 3F - mg = 0$ we have

$$F = \frac{1}{3}mg = \frac{1}{3}(1400 \text{ kg})(9.8 \text{ m s}^{-2}) = 4.6 \times 10^3$$

for the force exerted by each bolt on the engine.

b The force on each bolt now satisfies $3F - mg = ma$ which yields

$$F = \frac{1}{3}m(g + a) = \frac{1}{3}(1400 \text{ kg})(9.8 \text{ m s}^{-2} + 2.6 \text{ m s}^{-2}) = 5.8 \times 10^3.$$

90. We write the length unit light month the distance traveled by light in one month as c month in this solution.

a The magnitude of the required acceleration is given by

$$a = \frac{\Delta v}{\Delta t} = \frac{(0.10)(3.0 \times 10^8 \text{ m s}^{-1})}{(3.0 \text{ days})(86400 \text{ s day}^{-1})} = 1.2 \times 10^2 \text{ m s}^{-2}.$$

b The acceleration in terms of g is $a = \left(\frac{a}{g}\right)g = \left(\frac{1.2 \times 10^2 \text{ m s}^{-2}}{9.8 \text{ m s}^{-2}}\right)g = 12g$.

c The force needed is

$$F = ma = (1.20 \times 10^6 \text{ kg})(1.2 \times 10^2 \text{ m s}^{-2}) = 1.4 \times 10^8.$$

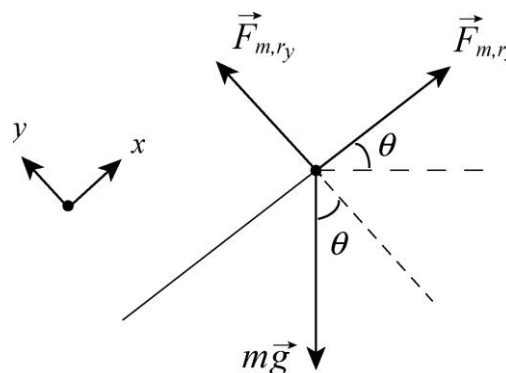
d The spaceship will travel a distance $d = 0.1 c$ month during one month. The time it takes for the spaceship to travel at constant speed for 5.0 light months is

$$t = \frac{d}{v} = \frac{5.0 \text{ c} \cdot \text{months}}{0.1c} = 50 \text{ months} \approx 4.2 \text{ years}.$$

91. **THINK** We have a motorcycle going up a ramp at a constant acceleration. We apply Newton's second law to calculate the net force on the rider and the force on the rider from the motorcycle.

EXPRESS The free body diagram is shown to the right (not to scale). Note that F_{m,r_y} and F_{m,r_x} respectively denote the y and x components of the force $\vec{F}_{m,r}$ exerted by the motorcycle on the rider. The net force on the rider is

$$\vec{F}_{\text{net}} = m\vec{a}.$$



ANALYZE a) Since the net force equals $m\vec{a}$ then the magnitude of the net force on the rider is

$$F_{\text{net}} = ma = 60.0 \text{ kg} \cdot 3.0 \text{ m/s}^2 = 1.8 \times 10^2 \text{ N}.$$

(b) To calculate the force by the motorcycle on the rider, we apply Newton's second law to the x - and the y axes separately. For the x axis we have

$$F_{m,r_x} - mg \sin \theta = ma$$

here $m = 60.0 \text{ kg}$, $a = 3.0 \text{ m/s}^2$ and $\theta = 10^\circ$. Thus $F_{m,r_x} = 282 \text{ N}$. Applying it to the y -axis where there is no acceleration we have

$$F_{m,r_y} - mg \cos \theta = 0$$

which gives $F_{m,r_y} = 579 \text{ N}$. Using the Pythagorean theorem we find

$$F_{m,r} = \sqrt{F_{m,r_x}^2 + F_{m,r_y}^2} = \sqrt{282^2 + 579^2} = 644 \text{ N}.$$

So the magnitude of the force exerted on the rider by the motorcycle is the same magnitude of force exerted by the rider on the motorcycle so the answer is 644 N.

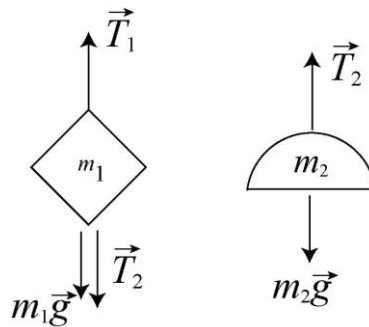
LEARN The force exerted by the motorcycle on the rider keeps the rider accelerating in the x direction while maintaining contact with the incline's surface $a_y = 0$.

92. We denote the thrust as T and choose y up the incline. Newton's second law leads to

$$T - Mg = Ma \Rightarrow a = \frac{2.6 \times 10^5}{1.3 \times 10^4 \text{ kg}} - 9.8 \text{ m s}^{-2} = 10 \text{ m s}^{-2}.$$

93. **THINK** In this problem we have mobiles consisting of masses connected by cords. We apply Newton's second law to calculate the tensions in the cords.

EXPRESS The free body diagrams for m_1 and m_2 for part a are shown to the right.



The bottom cord is only supporting $m_2 = 4.5 \text{ kg}$ against gravity so its tension is $T_2 = m_2 g$. On the other hand the top cord is supporting a total mass of $m_1 + m_2 = 3.5 \text{ kg} + 4.5 \text{ kg} = 8.0 \text{ kg}$ against gravity. Applying Newton's second law gives

$$T_1 - T_2 - m_1 g = 0$$

so the tension is

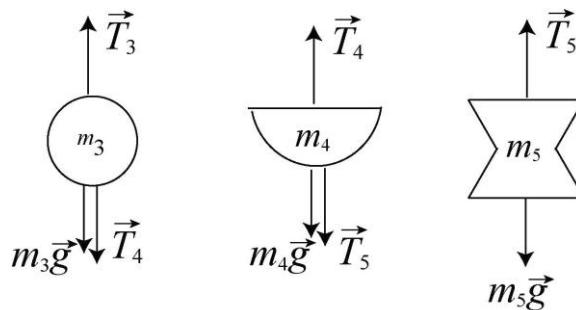
$$T_1 = m_1 g + T_2 = (m_1 + m_2) g.$$

ANALYZE a From the equations above we find the tension in the bottom cord to be

$$T_2 = m_2 g = 4.5 \text{ kg} \cdot 9.8 \text{ m s}^{-2} = 44 \text{ N}.$$

b Similarly the tension in the top cord is $T_1 = (m_1 + m_2) g = 8.0 \text{ kg} \cdot 9.8 \text{ m s}^{-2} = 78 \text{ N}.$

c The free body diagrams for m_3 , m_4 and m_5 for part b are shown below (not to scale).



From the diagram we see that the lowest cord supports a mass of $m_5 = 5.5 \text{ kg}$ against gravity and consequently has a tension of

$$T_5 = m_5 g = 5.5 \text{ kg} \cdot 9.8 \text{ m/s}^2 = 54 \text{ N}.$$

and the top cord as we are told has a tension $T_3 = 199 \text{ N}$ which supports a total of $199 \text{ N} / 9.80 \text{ m/s}^2 = 20.3 \text{ kg}$ of which is already accounted for in the figure. Thus the unknown mass in the middle must be $m_4 = 20.3 \text{ kg} - 10.3 \text{ kg} = 10.0 \text{ kg}$ and the tension in the cord above it must be enough to support

$$m_4 + m_5 = 10.0 \text{ kg} + 5.50 \text{ kg} = 15.5 \text{ kg}$$

$$\text{so } T_4 = 15.5 \text{ kg} \cdot 9.80 \text{ m/s}^2 = 152 \text{ N}.$$

LEARN Another way to calculate T_4 is to examine the forces on m_3 – one of the downward forces on it is T_4 . From Newton's second law, we have $T_3 - m_3 g - T_4 = 0$ which can be solved to give

$$T_4 = T_3 - m_3 g = 199 \text{ N} - 4.8 \text{ kg} \cdot 9.8 \text{ m/s}^2 = 152 \text{ N}.$$

94. The coordinate choices are made in the problem statement.

a. We write the velocity of the armadillo as $\vec{v} = v_x \hat{i} + v_y \hat{j}$. Since there is no net force exerted on it in the x direction the x component of the velocity of the armadillo is a constant $v_x = 5.0 \text{ m/s}$ in the y direction at $t = 3.0 \text{ s}$ we have using 2.11 with $v_{0y} = 0$

$$v_y = v_{0y} + a_y t = v_{0y} + \left(\frac{F_y}{m} \right) t = \left(\frac{17}{12 \text{ kg}} \right) (3.0 \text{ s}) = 4.3 \text{ m/s}.$$

$$\text{thus } \vec{v} = 5.0 \text{ m/s } \hat{i} + 4.3 \text{ m/s } \hat{j}.$$

b. We write the position vector of the armadillo as $\vec{r} = r_x \hat{i} + r_y \hat{j}$. At $t = 3.0 \text{ s}$ we have $r_x = 5.0 \text{ m/s} \cdot 3.0 \text{ s} = 15 \text{ m}$ and using 2.15 with $v_{0y} = 0$

$$r_y = v_{0y} t + \frac{1}{2} a_y t^2 = \frac{1}{2} \left(\frac{F_y}{m} \right) t^2 = \frac{1}{2} \left(\frac{17}{12 \text{ kg}} \right) (3.0 \text{ s})^2 = 6.4 \text{ m}.$$

$$\text{The position vector at } t = 3.0 \text{ s is therefore } \vec{r} = 15 \text{ m } \hat{i} + 6.4 \text{ m } \hat{j}.$$

95. A intuition readily leads to the conclusion that the heavier block should be the hanging one, for largest acceleration. The force that “drives” the system into motion is the weight of the hanging block. Gravity acting on the block on the table has no effect on the dynamics so long as we ignore friction. Thus $m = 4.0 \text{ kg}$.

The acceleration of the system and the tension in the cord can be readily obtained by solving

$$mg - T = ma \quad T = Ma.$$

b the acceleration is given by $a = \left(\frac{m}{m + M} \right) g = 6.5 \text{ m s}^{-2}$.

c the tension is

$$T = Ma = \left(\frac{Mm}{m + M} \right) g = 13 \text{ N}.$$

96. According to Newton's second law, the magnitude of the force is given by $F = ma$ where a is the magnitude of the acceleration of the neutron. We use kinematics table 2.1 to find the acceleration that brings the neutron to rest in a distance d . Assuming the acceleration is constant then $v^2 = v_0^2 + 2ad$ produces the value of a

$$a = \frac{(v^2 - v_0^2)}{2d} = \frac{-(1.4 \times 10^7 \text{ m s}^{-1})^2}{2(1.0 \times 10^{-14} \text{ m})} = -9.8 \times 10^{27} \text{ m s}^{-2}.$$

The magnitude of the force is consequently

$$F = ma = (1.67 \times 10^{-27} \text{ kg})(9.8 \times 10^{27} \text{ m s}^{-2}) = 16 \text{ N}.$$

97. a With units understood the net force is

$$\vec{F}_{\text{net}} = \vec{F}_1 + \vec{F}_2 = (3.0 \hat{i} + (-2.0 \hat{j})) + (4.0 \hat{i} + (-6.0 \hat{j}))$$

which yields $\vec{F}_{\text{net}} = 1.0 \hat{i} - 2.0 \hat{j}$.

b The magnitude of \vec{F}_{net} is $F_{\text{net}} = \sqrt{1.0^2 + (-2.0)^2} = 2.2 \text{ N}$.

c The angle of \vec{F}_{net} is $\theta = \tan^{-1} \left(\frac{-2.0}{1.0} \right) = -63^\circ$.

d The magnitude of \vec{a} is $a = F_{\text{net}} / m = 2.2 \text{ N} / 1.0 \text{ kg} = 2.2 \text{ m s}^{-2}$.

e Since \vec{F}_{net} is equal to \vec{a} multiplied by mass m which is a positive scalar that cannot affect the direction of the vector it multiplies \vec{a} has the same angle as the net force i.e. $\theta = -63^\circ$. In magnitude-angle notation we may write $\vec{a} = (2.2 \text{ m s}^{-2} \angle -63^\circ)$.

Chapter

1. The greatest deceleration of magnitude a is provided by the maximum friction force (Eq. 6.1 with $F_N = mg$ in this case). Using Newton's second law, we find

$$a = f_{s, \max} / m = \mu_s g.$$

Eq. 2.16 then gives the shortest distance to stop $\Delta x = v^2 / 2a = 36 \text{ m}$. In this calculation it is important to first convert v to 13 m/s .

2. Applying Newton's second law to the horizontal motion, we have $F - \mu_k mg = ma$ (here we have used Eq. 6.2 assuming that $F_N = mg$ which is equivalent to assuming that the vertical force from the broom is negligible). Eq. 2.16 relates the distance traveled and the final speed to the acceleration $v^2 = 2a\Delta x$. This gives $a = 1.4 \text{ m/s}^2$. Returning to the force equation we find with $F = 25 \text{ N}$ and $m = 3.5 \text{ kg}$ that $\mu_k = 0.58$.

3. **THINK** In the presence of friction between the floor and the bureau a minimum horizontal force must be applied before the bureau could begin to move.

EXPRESS The free body diagram for the bureau is shown to the right. We denote \vec{F} as the horizontal force of the person. \vec{f}_s is the force of static friction in the $-x$ direction. F_N is the vertical normal force exerted by the floor in the $+y$ direction and $m\vec{g}$ is the force of gravity. We do not consider the possibility that the bureau might tip (and treat this as a purely horizontal motion problem with the person's push \vec{F} in the $+x$ direction). Applying Newton's second law to the x and y axes we obtain

$$F - f_{s, \max} = ma$$

$$F_N - mg = 0$$

respectively.

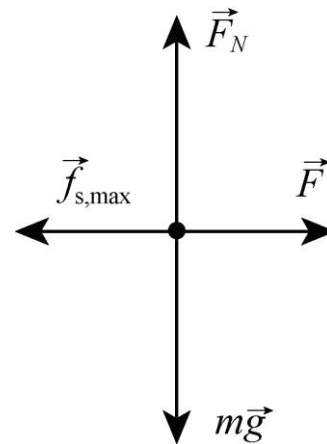
The second equation yields the normal force $F_N = mg$. Hereupon the maximum static friction is found to be from Eq. 6.1 $f_{s, \max} = \mu_s mg$. Thus the first equation becomes

$$F - \mu_s mg = ma = 0$$

here we have set $a = 0$ to be consistent with the fact that the static friction is still just barely able to prevent the bureau from moving.

ANALYZE With $\mu_s = 0.45$ and $m = 45 \text{ kg}$ the equation above leads to

$$F = \mu_s mg = 0.45 (45 \text{ kg})(9.8 \text{ m/s}^2) = 198 \text{ N}.$$

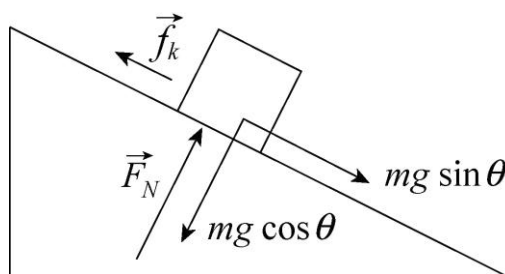


o bring the bureau into a state of motion the person should push with any force greater than this value. Rounding to two significant figures we can therefore say the minimum required push is $F = 2.0 \times 10^2$ N.

By replacing $m = 45$ kg with $m = 28$ kg the reasoning above leads to roughly $F = 1.2 \times 10^2$ N.

LEARN The values found above represent the minimum force required to overcome the friction. Applying a force greater than $\mu_s mg$ results in a net force in the x direction and hence non-zero acceleration.

4. We first analyze the forces on the pig of mass m . The incline angle is θ .



The x direction is “downhill.” Application of Newton’s second law to the x and y axes leads to

$$\begin{aligned} mg \sin \theta - f_k &= ma \\ F_N - mg \cos \theta &= 0. \end{aligned}$$

Solving these along with $f_k = \mu_k F_N$ produces the following result for the pig’s downhill acceleration

$$a = g(\sin \theta - \mu_k \cos \theta).$$

To compute the time to slide from rest through a downhill distance ℓ we use Eq. 2-15

$$\ell = v_0 t + \frac{1}{2} a t^2 \Rightarrow t = \sqrt{\frac{2\ell}{a}}.$$

We denote the frictionless $\mu_k = 0$ case with a prime and set up a ratio

$$\frac{t}{t'} = \frac{\sqrt{2\ell/a}}{\sqrt{2\ell/a'}} = \sqrt{\frac{a'}{a}}$$

which leads us to conclude that if $t/t' = 2$ then $a' = 4a$. Putting in what we found out above about the accelerations we have

$$g \sin \theta = 4g (\sin \theta - \mu_k \cos \theta).$$

sing $\theta = 35^\circ$ we obtain $\mu_k = 0.53$.

5. In addition to the forces already shown in Fig. 6.17 a free body diagram could include an upward normal force \vec{F}_N exerted by the floor on the block and $m\vec{g}$ representing the gravitational pull exerted by Earth and an assumed leftward \vec{f} for the kinetic or static friction. We choose x rightwards and y upwards. We apply Newton's second law to these axes

$$\begin{aligned} F - f &= ma \\ P + F_N - mg &= 0 \end{aligned}$$

here $F = 6.0$ and $m = 2.5$ kg is the mass of the block.

a. In this case $P = 8.0$ leads to

$$F_N = 2.5 \text{ kg} \cdot 9.8 \text{ m/s}^2 - 8.0 = 16.5 \text{ N}.$$

sing . 6.1 this implies $f_{s \text{ max}} = \mu_s F_N = 6.6$ which is larger than the 6.0 rightward force – so the block which was initially at rest does not move. Putting $a = 0$ into the first of our equations above yields a static friction force of $f = P = 6.0$ N.

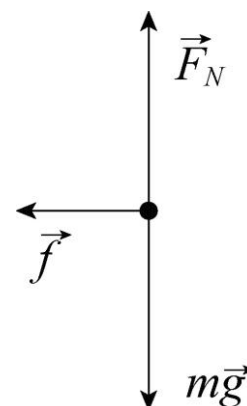
b. In this case $P = 10$ the normal force is

$$F_N = 2.5 \text{ kg} \cdot 9.8 \text{ m/s}^2 - 10 = 14.5 \text{ N}.$$

sing . 6.1 this implies $f_{s \text{ max}} = \mu_s F_N = 5.8$ which is less than the 6.0 rightward force – so the block does move. Hence we are dealing not with static but with kinetic friction which . 6.2 reveals to be $f_k = \mu_k F_N = 3.6$ N.

c. In this last case $P = 12$ leads to $F_N = 12.5$ and thus to $f_{s \text{ max}} = \mu_s F_N = 5.0$ which as expected is less than the 6.0 rightward force – so the block moves. The kinetic friction force then is $f_k = \mu_k F_N = 3.1$ N.

6. The free body diagram for the player is shown to the right. \vec{F}_N is the normal force of the ground on the player $m\vec{g}$ is the force of gravity and \vec{f} is the force of friction. The force of friction is related to the normal force by $f = \mu_k F_N$. We use Newton's second law applied to the vertical axis to find the normal force. The vertical component of the acceleration is zero so we obtain $F_N - mg = 0$ thus $F_N = mg$. Consequently

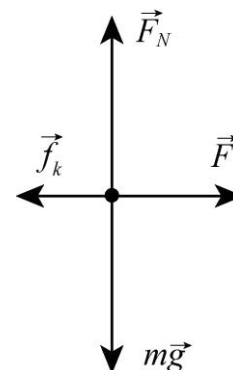


$$\mu_k = \frac{f}{F_N} = \frac{470}{(79 \text{ kg})(9.8 \text{ m/s}^2)} = 0.61.$$

7. THINK force is being applied to accelerate a crate in the presence of friction. We apply Newton's second law to solve for the acceleration.

EXPRESS The free body diagram for the crate is shown to the right.

We denote \vec{F} as the horizontal force of the person exerted on the crate in the $+x$ direction. \vec{f}_k is the force of kinetic friction in the $-x$ direction. F_N is the vertical normal force exerted by the floor in the $+y$ direction and $m\vec{g}$ is the force of gravity. The magnitude of the force of friction is given by Eq. 6.2 $f_k = \mu_k F_N$. Applying Newton's second law to the x and y axes we obtain



$$\begin{aligned} F - f_k &= ma \\ F_N - mg &= 0 \end{aligned}$$

respectively.

ANALYZE a The second equation above yields the normal force $F_N = mg$ so that the friction is

$$f_k = \mu_k F_N = \mu_k mg = (0.35)(55 \text{ kg})(9.8 \text{ m/s}^2) = 1.9 \times 10^2 \text{ N}.$$

b The first equation becomes

$$F - \mu_k mg = ma$$

which with $F = 220 \text{ N}$ we solve to find

$$a = \frac{F}{m} - \mu_k g = \frac{220}{55 \text{ kg}} - 0.35(9.8 \text{ m/s}^2) = 0.56 \text{ m/s}^2.$$

LEARN For the crate to accelerate the condition $F > f_k = \mu_k mg$ must be met. As can be seen from the equation above the greater the value of μ_k the smaller the acceleration under the same applied force.

8. To maintain the stone's motion, a horizontal force (in the $+x$ direction) is needed that cancels the retarding effect due to kinetic friction. Applying Newton's second to the x and y axes we obtain

$$\begin{aligned} F - f_k &= ma \\ F_N - mg &= 0 \end{aligned}$$

respectively. The second equation yields the normal force $F_N = mg$ so that using Eq. 6.2 the kinetic friction becomes $f_k = \mu_k mg$. Thus the first equation becomes

$$F - \mu_k mg = ma = 0$$

here we have set $a = 0$ to be consistent with the idea that the horizontal velocity of the stone should remain constant. With $m = 20 \text{ kg}$ and $\mu_k = 0.80$ we find $F = 1.6 \times 10^2 \text{ N}$.

9. We choose x horizontally rightwards and y upwards and observe that the 15 N force has components $F_x = F \cos \theta$ and $F_y = -F \sin \theta$.

(a) We apply Newton's second law to the y axis

$$F_N - F \sin \theta - mg = 0 \Rightarrow F_N = 15 \sin 40^\circ + 3.5 \text{ kg} \cdot 9.8 \text{ m/s}^2 = 44 \text{ N}.$$

With $\mu_k = 0.25$, $f_k = 11 \text{ N}$.

(b) We apply Newton's second law to the x axis

$$F \cos \theta - f_k = ma \Rightarrow a = \frac{(15 \text{ N}) \cos 40^\circ - 11 \text{ N}}{3.5 \text{ kg}} = 0.14 \text{ m/s}^2.$$

Since the result is positive valued then the block is accelerating in the x rightward direction.

10. a. The free body diagram for the block is shown below with \vec{F} being the force applied to the block, \vec{F}_N the normal force of the floor on the block, $m\vec{g}$ the force of gravity and \vec{f} the force of friction.

We take the x direction to be horizontal to the right and the y direction to be up. The equations for the x and the y components of the force according to Newton's second law are

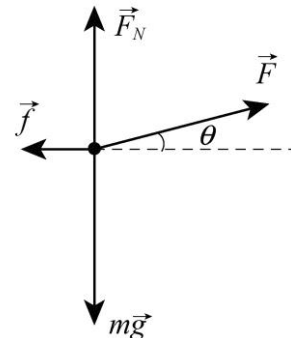
$$\begin{aligned} F_x &= F \cos \theta - f = ma \\ F_y &= F \sin \theta + F_N - mg = 0 \end{aligned}$$

so $f = \mu_k F_N$ and the second equation gives $F_N = mg - F \sin \theta$ which yields $f = \mu_k mg - F \sin \theta$. This expression is substituted for f in the first equation to obtain

$$F \cos \theta - \mu_k mg - F \sin \theta = ma$$

so the acceleration is

$$a = \frac{F}{m} (\cos \theta + \mu_k \sin \theta) - \mu_k g.$$



a If $\mu_s = 0.600$ and $\mu_k = 0.500$ then the magnitude of \vec{f} has a maximum value of

$$f_{s \text{ max}} = \mu_s F_N = 0.600 \, mg - 0.500 \, mg \sin 20^\circ = 0.497 \, mg.$$

On the other hand $F \cos \theta = 0.500 \, mg \cos 20^\circ = 0.470 \, mg$. Therefore $F \cos \theta < f_{s \text{ max}}$ and the block remains stationary with $a = 0$.

b If $\mu_s = 0.400$ and $\mu_k = 0.300$ then the magnitude of \vec{f} has a maximum value of

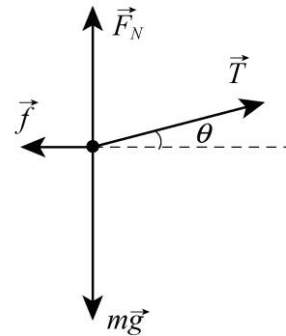
$$f_{s \text{ max}} = \mu_s F_N = 0.400 \, mg - 0.500 \, mg \sin 20^\circ = 0.332 \, mg.$$

In this case $F \cos \theta = 0.500 \, mg \cos 20^\circ = 0.470 \, mg > f_{s \text{ max}}$. Therefore the acceleration of the block is

$$\begin{aligned} a &= \frac{F}{m} (\cos \theta + \mu_k \sin \theta) - \mu_k g \\ &= 0.500 \, 9.80 \, \text{m/s}^2 [\cos 20^\circ + 0.300 \sin 20^\circ] - 0.300 \, 9.80 \, \text{m/s}^2 \\ &= 2.17 \, \text{m/s}^2. \end{aligned}$$

11. **THINK** Since the crate is being pulled by a rope at an angle with the horizontal, we need to analyze the force components in both the x and y directions.

EXPRESS The free body diagram for the crate is shown to the right. Here \vec{T} is the tension force of the rope on the crate, \vec{F}_N is the normal force of the floor on the crate, $m\vec{g}$ is the force of gravity, and \vec{f} is the force of friction. We take the x direction to be horizontal to the right and the y direction to be up. We assume the crate is motionless.



The equations for the x and the y components of the force according to Newton's second law are

$$T \cos \theta - f = 0 \quad T \sin \theta + F_N - mg = 0$$

Here $\theta = 15^\circ$ is the angle between the rope and the horizontal. The first equation gives $f = T \cos \theta$ and the second gives $F_N = mg - T \sin \theta$. If the crate is to remain at rest f must be less than $\mu_s F_N$ or $T \cos \theta < \mu_s (mg - T \sin \theta)$. When the tension force is sufficient to just start the crate moving we must have $T \cos \theta = \mu_s (mg - T \sin \theta)$.

ANALYZE a We solve for the tension

$$T = \frac{\mu_s mg}{\cos \theta + \mu_s \sin \theta} = \frac{(0.50)(68 \text{ kg})(9.8 \text{ m s}^{-2})}{\cos 15^\circ + 0.50 \sin 15^\circ} = 304 \approx 3.0 \times 10^2 \text{ N}.$$

b The second law equations for the moving crate are

$$T \cos \theta - f = ma \quad T \sin \theta + F_N - mg = 0.$$

so $f = \mu_k F_N$ and the second equation above gives $F_N = mg - T \sin \theta$ which then yields $f = \mu_k (mg - T \sin \theta)$. This expression is substituted for f in the first equation to obtain

$$T \cos \theta - \mu_k (mg - T \sin \theta) = ma$$

so the acceleration is

$$\begin{aligned} a &= \frac{T(\cos \theta + \mu_k \sin \theta)}{m} - \mu_k g \\ &= \frac{304 \text{ N}}{68 \text{ kg}} - 0.35(9.8 \text{ m s}^{-2}) = 1.3 \text{ m s}^{-2}. \end{aligned}$$

LEARN Let's check the limit where $\theta = 0$. In this case we recover the familiar expressions $T = \mu_s mg$ and $a = T - \mu_k mg / m$.

12. There is no acceleration so the up and static friction forces there are four of them one for each thumb and one for each set of opposing fingers equals the magnitude of the down and pull of gravity. Since 61 kg we have

$$4\mu_s F_N = mg = 79 \text{ kg} \cdot 9.8 \text{ m s}^{-2}$$

which with $\mu_s = 0.70$ yields $F_N = 2.8 \times 10^2 \text{ N}$.

13. We denote the magnitude of 110 N force exerted by the worker on the crate as F . The magnitude of the static frictional force can vary between zero and $f_{s \text{ max}} = \mu_s F_N$.

(a) In this case, application of Newton's second law in the vertical direction yields $F_N = mg$. Thus

$$f_{s \text{ max}} = \mu_s F_N = \mu_s mg = (0.37)(35 \text{ kg})(9.8 \text{ m s}^{-2}) = 1.3 \times 10^2 \text{ N}$$

which is greater than F .

b The block which is initially at rest stays at rest since $F < f_{s \text{ max}}$. Thus it does not move.

c By applying Newton's second law to the horizontal direction that the magnitude of the frictional force exerted on the crate is $f_s = 1.1 \times 10^2 \text{ N}$.

denoting the upward force exerted by the second order as F_2 then application of Newton's second law in the vertical direction yields $F_N = mg - F_2$ which leads to

$$f_{s, \max} = \mu_s F_N = \mu_s (mg - F_2) .$$

In order to move the crate F must satisfy the condition $F - f_{s, \max} = \mu_s (mg - F_2)$, or

$$110 > (0.37)[35 \text{ kg} \cdot 9.8 \text{ m/s}^2 - F_2] .$$

The minimum value of F_2 that satisfies this inequality is a value slightly bigger than 45.7 so we express our answer as $F_{2, \min} = 46$.

In this final case moving the crate requires a greater horizontal push from the order than static friction (as computed in part (a)) can resist. Thus, Newton's law in the horizontal direction leads to

$$F + F_2 > f_{s, \max} \Rightarrow 110 + F_2 > 126.9$$

which leads after appropriate rounding to $F_{2, \min} = 17$.

14. Using the result obtained in Sample Problem – “Friction, applied force at an angle,” the maximum angle for which static friction applies is

$$\theta_{\max} = \tan^{-1} \mu_s = \tan^{-1} 0.63 \approx 32^\circ .$$

This is greater than the dip angle in the problem so the block does not slide.

(b) Applying Newton's second law, we have

$$\begin{aligned} F + mg \sin \theta - f_{s, \max} &= ma = 0 \\ F_N - mg \cos \theta &= 0. \end{aligned}$$

Along with $\mu_s = 0.61$ $f_{s, \max} = \mu_s F_N$ we have enough information to solve for F . With $\theta = 24^\circ$ and $m = 1.8 \times 10^7 \text{ kg}$ we find

$$F = mg(\mu_s \cos \theta - \sin \theta) = 3.0 \times 10^7 \text{ N} .$$

15. An excellent discussion and equation development related to this problem is given in Sample Problem – “Friction, applied force at an angle.” We merely quote (and apply) their main result

$$\theta = \tan^{-1} \mu_s = \tan^{-1} 0.04 \approx 2^\circ .$$

16. a In this situation we take \vec{f}_s to point uphill and to be equal to its maximum value in which case $f_{s \text{ max}} = \mu_s F_N$ applies here $\mu_s = 0.25$. Applying Newton's second law to the block of mass $m = W/g = 8.2 \text{ kg}$ in the x and y directions produces

$$\begin{aligned} F_{\min 1} - mg \sin \theta + f_{s \text{ max}} &= ma = 0 \\ F_N - mg \cos \theta &= 0 \end{aligned}$$

which with $\theta = 20^\circ$ leads to

$$F_{\min 1} - mg(\sin \theta + \mu_s \cos \theta) = 8.6 \text{ N}.$$

b So we take \vec{f}_s to point downhill and to be equal to its maximum value in which case $f_{s \text{ max}} = \mu_s F_N$ applies here $\mu_s = 0.25$. Applying Newton's second law to the block of mass $m = W/g = 8.2 \text{ kg}$ in the x and y directions produces

$$\begin{aligned} F_{\min 2} = mg \sin \theta - f_{s \text{ max}} &= ma = 0 \\ F_N - mg \cos \theta &= 0 \end{aligned}$$

which with $\theta = 20^\circ$ leads to

$$F_{\min 2} = mg(\sin \theta + \mu_s \cos \theta) = 46 \text{ N}.$$

A value slightly larger than the “exact” result of this calculation is required to make it accelerate uphill but since we quote our results here to two significant figures 46 N is a “good enough” answer.

c Finally we are dealing with kinetic friction pointing downhill so that

$$\begin{aligned} 0 &= F - mg \sin \theta - f_k = ma \\ 0 &= F_N - mg \cos \theta \end{aligned}$$

along with $f_k = \mu_k F_N$ here $\mu_k = 0.15$ brings us to

$$F = mg(\sin \theta + \mu_k \cos \theta) = 39 \text{ N}.$$

17. If the block is sliding then we compute the kinetic friction from Eq. 6.2 if it is not sliding, then we determine the extent of static friction from applying Newton's law, with zero acceleration to the x axis which is parallel to the incline surface. The question of whether or not it is sliding is therefore crucial and depends on the maximum static friction force as calculated from Eq. 6.1. The forces are resolved in the incline plane coordinate system in Figure 6.5 in the textbook. The acceleration if there is any is along the x axis and we are taking uphill as $+x$. The net force along the y axis then is certainly zero which provides the following relationship

$$\sum \vec{F}_y = 0 \Rightarrow F_N = W \cos \theta$$

here $W = mg = 45$ is the weight of the block and $\theta = 15^\circ$ is the incline angle. Thus $F_N = 43.5$ which implies that the maximum static friction force should be

$$f_{s \max} = 0.50 \cdot 43.5 = 21.7 \text{ N}.$$

a) or $\vec{P} = -5.0 \hat{i}$, Newton's second law, applied to the x axis becomes

$$f - P - mg \sin \theta = ma.$$

Here we are assuming \vec{f} is pointing uphill as shown in Figure 6.5 and if it turns out that it points downhill which is a possibility then the result for f_s will be negative. If $f = f_s$ then $a = 0$ we obtain

$$f_s = P + mg \sin \theta = 5.0 + 43.5 \sin 15^\circ = 17 \text{ N}$$

or $\vec{f}_s = 17 \hat{i}$. This is clearly allowed since f_s is less than $f_{s \max}$.

b) or $\vec{P} = -8.0 \hat{i}$ we obtain from the same equation $\vec{f}_s = 20 \hat{i}$ which is still allowed since it is less than $f_{s \max}$.

c) but for $\vec{P} = -15 \hat{i}$ we obtain from the same equation $f_s = 27$ which is not allowed since it is larger than $f_{s \max}$. Thus we conclude that it is the kinetic friction instead of the static friction that is relevant in this case. The result is

$$\vec{f}_k = \mu_k F_N \hat{i} = 0.34 \cdot 43.5 \hat{i} = 15 \hat{i}.$$

18. a) We apply Newton's second law to the "downhill" direction:

$$mg \sin \theta - f = ma$$

here using 6.11

$$f = f_k = \mu_k F_N = \mu_k mg \cos \theta.$$

thus with $\mu_k = 0.600$ we have

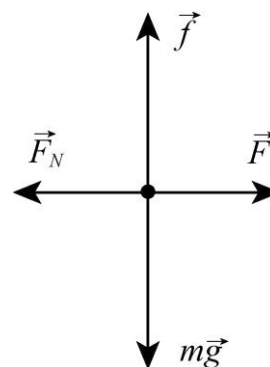
$$a = g \sin \theta - \mu_k \cos \theta = -3.72 \text{ m/s}^2$$

which means since we have chosen the positive direction in the direction of motion down the slope then the acceleration vector points "uphill"; it is decelerating. With $v_0 = 18.0 \text{ m/s}$ and $\Delta x = d = 24.0 \text{ m}$, 2.16 leads to

$$v = \sqrt{v_0^2 + 2ad} = 12.1 \text{ m/s}.$$

b In this case we find $a = 1.1 \text{ m/s}^2$ and the speed when impact occurs is 19.4 m/s .

19. a The free body diagram for the block is shown below. \vec{F} is the applied force \vec{F}_N is the normal force of the wall on the block \vec{f} is the force of friction and $m\vec{g}$ is the force of gravity. To determine if the block falls we find the magnitude f of the force of friction required to hold it without accelerating and also find the normal force of the wall on the block. We compare f and $\mu_s F_N$. If $f > \mu_s F_N$ the block does not slide on the wall but if $f < \mu_s F_N$ the block does slide. The horizontal component of Newton's second law is $F - F_N = 0$ so $F_N = F = 12$ and



$$\mu_s F_N = 0.60(12) = 7.2.$$

The vertical component is $f - mg = 0$ so $f = mg = 5.0$. Since $f < \mu_s F_N$ the block does not slide.

b Since the block does not move $f = 5.0$ and $F_N = 12$. The force of the wall on the block is

$$\vec{F}_w = -F_N \hat{i} + f \hat{j} = -(12) \hat{i} + (5.0) \hat{j}$$

here the axes are as shown on Fig. 6-26 of the text.

20. Treating the two boxes as a single system of total mass $m = m_1 + m_2 = 1.0 + 3.0 = 4.0 \text{ kg}$ subject to a total leftward friction of magnitude $2.0 + 4.0 = 6.0$ we apply Newton's second law (with $+x$ rightward)

$$F - f_{\text{total}} = m_{\text{total}} a \Rightarrow 12.0 - 6.0 = 4.0 \text{ kg } a$$

which yields the acceleration $a = 1.5 \text{ m/s}^2$. We have treated F as if it were known to the nearest tenth of a Newton so that our acceleration is "good" to two significant figures.

Turning our attention to the larger box the heavier box of mass $m = 3.0 \text{ kg}$ we apply Newton's second law to find the contact force F' exerted by the heavier box on it.

$$F' - f = m a \Rightarrow F' - 4.0 = 3.0 \text{ kg } (1.5 \text{ m/s}^2).$$

From the above equation we find the contact force to be $F' = 8.5$.

21. Fig. 6-4 in the textbook shows a similar situation using ϕ for the unknown angle along with a free body diagram. We use the same coordinate system as in that figure.

(a) Thus, Newton's second law leads to

$$\begin{array}{l} x \quad T \cos \phi - f = ma \\ y \quad T \sin \phi + F_N - mg = 0 \end{array}$$

Setting $a = 0$ and $f = f_{s \max} = \mu_s F_N$ we solve for the mass of the block and sand as a function of angle

$$m = \frac{T}{g} \left(\sin \phi + \frac{\cos \phi}{\mu_s} \right)$$

which we will solve with calculus techniques to find the angle ϕ_m corresponding to the maximum mass that can be pulled.

$$\frac{dm}{d\phi} = \frac{T}{g} \left(\cos \phi_m - \frac{\sin \phi_m}{\mu_s} \right) = 0$$

this leads to $\tan \phi_m = \mu_s$ which for $\mu_s = 0.35$ yields $\phi_m = 19^\circ$.

Plugging our value for ϕ_m into the equation we found for the mass of the block and sand yields $m = 340 \text{ kg}$. This corresponds to a weight of $mg = 3.3 \times 10^3 \text{ N}$.

22. The free body diagram for the sled is shown below with \vec{F} being the force applied to the sled, \vec{F}_N the normal force of the inclined plane on the sled, $m\vec{g}$ the force of gravity and \vec{f} the force of friction.

We take the x direction to be along the inclined plane and the y direction to be in its normal direction. The equations for the x and the y components of the force according to Newton's second law are

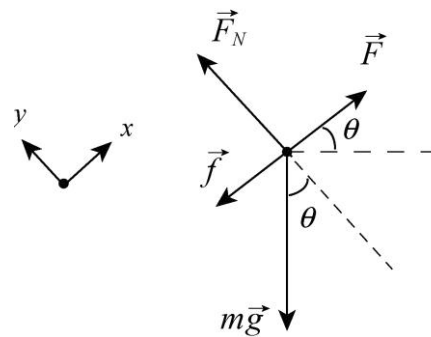
$$\begin{array}{l} F_x = F - f - mg \sin \theta = ma = 0 \\ F_y = F_N - mg \cos \theta = 0 \end{array}$$

so $f = \mu F_N$ and the second equation gives $F_N = mg \cos \theta$ which yields $f = \mu mg \cos \theta$. This expression is substituted for f in the first equation to obtain

$$F = mg \sin \theta + \mu mg \cos \theta$$

From the figure we see that $F = 2.0 \text{ N}$ when $\mu = 0$. This implies $mg \sin \theta = 2.0 \text{ N}$. Similarly we also find $F = 5.0 \text{ N}$ when $\mu = 0.5$

$$5.0 \text{ N} = mg \sin \theta + 0.50 mg \cos \theta = 2.0 \text{ N} + 0.50 mg \cos \theta$$



high yields $mg \cos \theta = 6.0$. Combining the two results we get

$$\tan \theta = \frac{2}{6} = \frac{1}{3} \Rightarrow \theta = 18^\circ.$$

23. Let the tensions on the strings connecting m_2 and m_3 be T_{23} and that connecting m_2 and m_1 be T_{12} respectively. Applying Newton's second law (and Eq. 6.2 with $F_N = m_2 g$ in this case) to the *system* we have

$$\begin{aligned} m_3 g - T_{23} &= m_3 a \\ T_{23} - \mu_k m_2 g - T_{12} &= m_2 a \\ T_{12} - m_1 g &= m_1 a \end{aligned}$$

Adding up the three equations and using $m_1 = M$, $m_2 = m_3 = 2M$ we obtain

$$2Mg - 2\mu_k Mg - Mg = 5Ma.$$

With $a = 0.500 \text{ m/s}^2$ this yields $\mu_k = 0.372$. Thus the coefficient of kinetic friction is roughly $\mu_k = 0.37$.

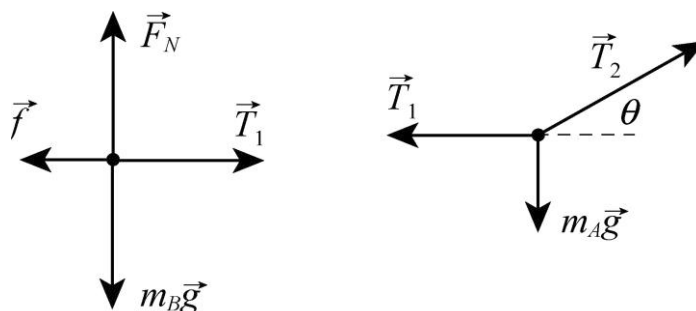
24. We find the acceleration from the slope of the graph recall $\Delta y / \Delta x = a = 4.5 \text{ m/s}^2$. Thus, Newton's second law leads to

$$F - \mu_k mg = ma$$

here $F = 40.0$ is the constant horizontal force applied. With $m = 4.1 \text{ kg}$ we arrive at $\mu_k = 0.54$.

25. **THINK** In order that the two blocks remain in equilibrium friction must be present between block B and the surface.

EXPRESS The free body diagrams for block B and for the knot just above block A are shown below. \vec{T}_1 is the tension force of the rope pulling on block B or pulling on the knot as the case may be. \vec{T}_2 is the tension force exerted by the second rope at angle $\theta = 30^\circ$ on the knot. \vec{f} is the force of static friction exerted by the horizontal surface on block B . \vec{F}_N is normal force exerted by the surface on block B . W_A is the weight of block A . W_A is the magnitude of $m_A \vec{g}$ and W_B is the weight of block B . $W_B = 711$ is the magnitude of $m_B \vec{g}$.



For each object we take x horizontally rightward and y upward. Applying Newton's second law in the x and y directions for block B and then doing the same for the knot results in four equations

$$\begin{aligned} T_1 - f_s &= 0 \\ F_N - W_B &= 0 \\ T_2 \cos \theta - T_1 &= 0 \\ T_2 \sin \theta - W_A &= 0 \end{aligned}$$

Here we assume the static friction to be at its maximum value permitting us to use Eq. 6.1. The above equations yield $T_1 = \mu_s F_N$, $F_N = W_B$ and $T_1 = T_2 \cos \theta$.

ANALYZE Solving these equations with $\mu_s = 0.25$ we obtain

$$\begin{aligned} W_A &= T_2 \sin \theta = T_1 \tan \theta = \mu_s F_N \tan \theta = \mu_s W_B \tan \theta \\ &= 0.25 (711 \text{ N}) \tan 30^\circ = 1.0 \times 10^2 \text{ N} \end{aligned}$$

LEARN As expected the maximum weight of A is proportional to the weight of B as well as the coefficient of static friction. In addition we see that W_A is proportional to $\tan \theta$; the larger the angle the greater the vertical component of T_2 that supports its weight.

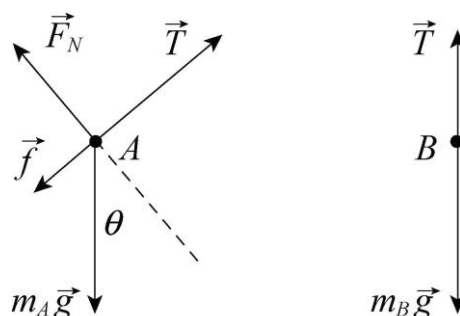
26. a Applying Newton's second law to the *system* of total mass $M = 60.0 \text{ kg}$ and using Eq. 6.2 with $F_N = Mg$ in this case we obtain

$$F - \mu_k Mg = Ma \Rightarrow a = 0.473 \text{ m/s}^2.$$

We then examine the forces just on m_3 and find $F_{32} = m_3 a + \mu_k g = 147 \text{ N}$. If the algebra steps are done more systematically one ends up with the interesting relationship $F_{32} = m_3 (M + F)$ which is independent of the friction.

b As remarked at the end of our solution to part a the result does not depend on the frictional parameters. The answer here is the same as in part a.

27. First we check to see if the bodies start to move. We assume they remain at rest and compute the force of static friction which holds them there and compare its magnitude with the maximum value $\mu_s F_N$. The free body diagrams are shown below.



T is the magnitude of the tension force of the string f is the magnitude of the force of friction on body A F_N is the magnitude of the normal force of the plane on body A $m_A \vec{g}$ is the force of gravity on body A with magnitude $W_A = 102$ and $m_B \vec{g}$ is the force of gravity on body B with magnitude $W_B = 32$. $\theta = 40^\circ$ is the angle of incline. We are told the direction of \vec{f} but we assume it is downhill. If we obtain a negative result for f then we know the force is actually up the plane.

For A we take the x to be uphill and y to be in the direction of the normal force. The x and y components of Newton's second law become

$$\begin{aligned} T - f - W_A \sin \theta &= 0 \\ F_N - W_A \cos \theta &= 0. \end{aligned}$$

Taking the positive direction to be *downward* for body B , Newton's second law leads to $W_B - T = 0$. Solving these three equations leads to

$$f = W_B - W_A \sin \theta = 32 - 102 \sin 40^\circ = -34$$

indicating that the force of friction is *uphill* and to

$$F_N = W_A \cos \theta = 102 \cos 40^\circ = 78$$

which means that

$$f_{s \max} = \mu_s F_N = 0.56 \cdot 78 = 44.$$

Since the magnitude f of the force of friction that holds the bodies motionless is less than $f_{s \max}$ the bodies remain at rest. The acceleration is zero.

(b) Since A is moving up the incline the force of friction is downhill with magnitude $f_k = \mu_k F_N$. Newton's second law, using the same coordinates as in part (a), leads to

$$\begin{aligned}T - f_k - W_A \sin \theta &= m_A a \\F_N - W_A \cos \theta &= 0 \\W_B - T &= m_B a\end{aligned}$$

for the two bodies. We solve for the acceleration

$$\begin{aligned}a &= \frac{W_B - W_A \sin \theta - \mu_k W_A \cos \theta}{m_B + m_A} = \frac{32 - (102) \sin 40^\circ - (0.25)(102) \cos 40^\circ}{(32 + 102) / (9.8 \text{ m/s}^2)} \\&= -3.9 \text{ m/s}^2.\end{aligned}$$

The acceleration is down the plane i.e. $\vec{a} = -3.9 \text{ m/s}^2 \hat{i}$ which is to say since the initial velocity was uphill that the objects are slowing down. We note that $m = W/g$ has been used to calculate the masses in the calculation above.

Consider body A is initially moving down the plane so the force of friction is uphill with magnitude $f_k = \mu_k F_N$. The force equations become

$$\begin{aligned}T + f_k - W_A \sin \theta &= m_A a \\F_N - W_A \cos \theta &= 0 \\W_B - T &= m_B a\end{aligned}$$

which we solve to obtain

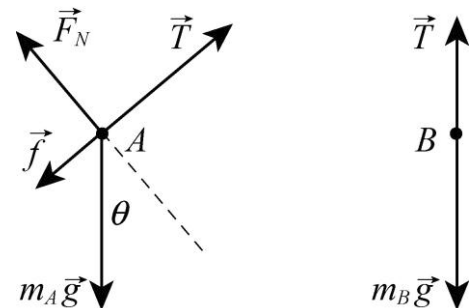
$$\begin{aligned}a &= \frac{W_B - W_A \sin \theta + \mu_k W_A \cos \theta}{m_B + m_A} = \frac{32 - (102) \sin 40^\circ + (0.25)(102) \cos 40^\circ}{(32 + 102) / (9.8 \text{ m/s}^2)} \\&= -1.0 \text{ m/s}^2.\end{aligned}$$

The acceleration is again downhill the plane i.e. $\vec{a} = -1.0 \text{ m/s}^2 \hat{i}$. In this case the objects are speeding up.

28. The free body diagrams are shown to the right

where T is the magnitude of the tension force of the string f is the magnitude of the force of friction on block A F_N is the magnitude of the normal force of the plane on block A $m_A \vec{g}$ is the force of gravity on body A

where $m_A = 10 \text{ kg}$ and $m_B \vec{g}$ is the force of gravity on block B . $\theta = 30^\circ$ is the angle of incline. For A we take the x to be uphill and y to be in the direction of the normal force the positive direction is chosen *downward* for block B .



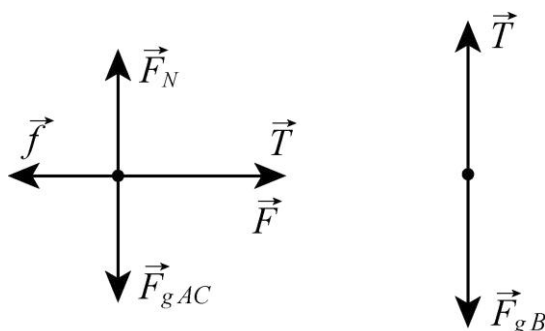
Since A is moving down the incline the force of friction is uphill with magnitude $f_k = \mu_k F_N$ (here $\mu_k = 0.20$). Newton's second law leads to

$$\begin{aligned}
 T - f_k + m_A g \sin \theta &= m_A a = 0 \\
 F_N - m_A g \cos \theta &= 0 \\
 m_B g - T &= m_B a = 0
 \end{aligned}$$

for the two bodies here $a = 0$ is a consequence of the velocity being constant. Solve these for the mass of block B .

$$m_B = m_A (\sin \theta - \mu_k \cos \theta) = 3.3 \text{ kg.}$$

29. a free body diagrams for the blocks A and C considered as a single object and for the block B are shown below.



T is the magnitude of the tension force of the rope F_N is the magnitude of the normal force of the table on block A f is the magnitude of the force of friction W_{AC} is the combined weight of blocks A and C the magnitude of force \vec{F}_{gAC} shown in the figure and W_B is the weight of block B the magnitude of force \vec{F}_{gB} shown. Assume the blocks are not moving. For the blocks on the table let the x axis be to the right and the y axis be upward. From Newton's second law, we have

$$x \text{ component} \quad T - f = 0$$

$$y \text{ component} \quad F_N - W_{AC} = 0.$$

For block B take the downward direction to be positive. Then Newton's second law for that block is $W_B - T = 0$. The third equation gives $T = W_B$ and the first gives $f = T = W_B$.

The second equation gives $F_N = W_{AC}$. If sliding is not to occur f must be less than $\mu_s F_N$ or $W_B < \mu_s W_{AC}$. The smallest that W_{AC} can be with the blocks still at rest is

$$W_{AC} = W_B / \mu_s = 22 / 0.20 = 110 \text{ N.}$$

Since the weight of block A is 44 N the least weight for C is $110 - 44 = 66 \text{ N}$.

b. The second law equations become

$$T - f = W_A g a$$

$$\begin{aligned} F_N - W_A &= 0 \\ W_B - T &= W_B g a. \end{aligned}$$

In addition $f = \mu_k F_N$. The second equation gives $F_N = W_A$ so $f = \mu_k W_A$. The third gives $T = W_B - W_B g a$. Substituting these two expressions into the first equation we obtain

$$W_B - W_B g a - \mu_k W_A = W_A g a.$$

hence

$$a = \frac{g(W_B - \mu_k W_A)}{W_A + W_B} = \frac{9.8 \text{ m s}^{-2} (22 - (0.15)(44))}{44 + 22} = 2.3 \text{ m s}^{-2}.$$

30. We use the familiar horizontal and vertical axes for x and y directions with right and up and positive respectively. The rope is assumed massless so that the force exerted by the child \vec{F} is identical to the tension uniformly through the rope. The x and y components of \vec{F} are $F \cos \theta$ and $F \sin \theta$ respectively. The static friction force points leftward.

(a) Newton's Law applied to the y axis where there is presumed to be no acceleration leads to

$$F_N + F \sin \theta - mg = 0$$

which implies that the maximum static friction is $\mu_s mg - F \sin \theta$. If $f_s = f_{s, \text{max}}$ is assumed then Newton's second law applied to the x axis which also has $a = 0$ even though it is "verging" on moving) yields

$$F \cos \theta - f_s = ma \Rightarrow F \cos \theta - \mu_s mg - F \sin \theta = 0$$

which we solve for $\theta = 42^\circ$ and $\mu_s = 0.42$ to obtain $F = 74 \text{ N}$.

(b) Solving the above equation algebraically for F with W denoting the weight we obtain

$$F = \frac{\mu_s W}{\cos \theta + \mu_s \sin \theta} = \frac{0.42 \cdot 180}{\cos \theta + 0.42 \sin \theta} = \frac{76}{\cos \theta + 0.42 \sin \theta}.$$

(c) We minimize the above expression for F by working through the condition

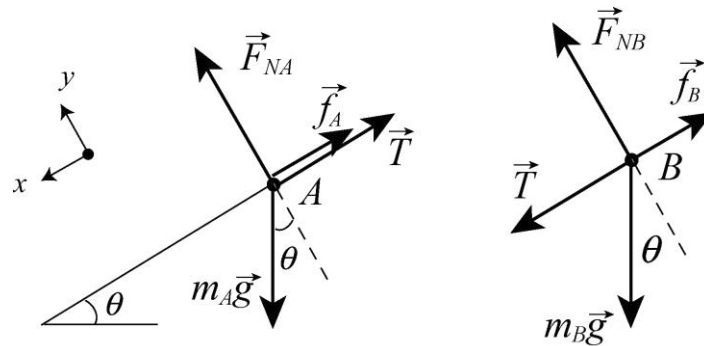
$$\frac{dF}{d\theta} = \frac{\mu_s W \sin \theta - \mu_s \cos \theta}{(\cos \theta + \mu_s \sin \theta)^2} = 0$$

which leads to the result $\theta = \tan^{-1} \mu_s = 23^\circ$.

(d) Plugging $\theta = 23^\circ$ into the above result for F with $\mu_s = 0.42$ and $W = 180 \text{ N}$ yields $F = 70 \text{ N}$.

31. **THINK** In this problem we have two blocks connected by a string sliding down an inclined plane. The blocks have different coefficients of kinetic friction.

EXPRESS The free body diagrams for the two blocks are shown below. T is the magnitude of the tension force of the string. \vec{F}_{NA} is the normal force on block A the leading block. \vec{F}_{NB} is the normal force on block B. \vec{f}_A is kinetic friction force on block A. \vec{f}_B is kinetic friction force on block B. Also m_A is the mass of block A here $m_A = W_A/g$ and $W_A = 3.6$ and m_B is the mass of block B here $m_B = W_B/g$ and $W_B = 7.2$. The angle of the incline is $\theta = 30^\circ$.



For each block we take x down the hill which is to the right in these diagrams and y in the direction of the normal force. Applying Newton's second law to the x and y directions of both blocks A and B we arrive at four equations

$$W_A \sin \theta - f_A - T = m_A a$$

$$F_{NA} - W_A \cos \theta = 0$$

$$W_B \sin \theta - f_B + T = m_B a$$

$$F_{NB} - W_B \cos \theta = 0$$

which when combined with 6.2 $f_A = \mu_{kA} F_{NA}$ here $\mu_{kA} = 0.10$ and $f_B = \mu_{kB} F_{NB}$ here $\mu_{kB} = 0.20$ fully describe the dynamics of the system so long as the blocks have the same acceleration and $T \geq 0$.

ANALYZE a From these equations we find the acceleration to be

$$a = g \left(\sin \theta - \left(\frac{\mu_{kA} W_A + \mu_{kB} W_B}{W_A + W_B} \right) \cos \theta \right) = 3.5 \text{ m/s}^2.$$

b We solve the above equations for the tension and obtain

$$T = \left(\frac{W_A W_B}{W_A + W_B} \right) (\mu_{kB} - \mu_{kA}) \cos \theta = \frac{3.6 \cdot 7.2}{3.6 + 7.2} (0.20 - 0.10) \cos 30^\circ = 0.21 \text{ N}.$$

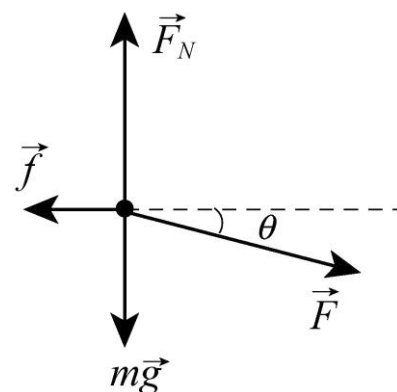
LEARN The tension in the string is proportional to $\mu_{kB} - \mu_{kA}$ the difference in coefficients of kinetic friction for the two blocks. When the coefficients are equal $\mu_{kB} = \mu_{kA}$, the two blocks can be viewed as moving independent of one another and the tension is zero. Similarly when $\mu_{kB} < \mu_{kA}$ the leading block A has larger coefficient than the B the string is slack so the tension is also zero.

32. The free body diagram for the block is shown below with \vec{F} being the force applied to the block \vec{F}_N the normal force of the floor on the block $m\vec{g}$ the force of gravity and \vec{f} the force of friction. We take the x direction to be horizontal to the right and the y direction to be up. The equations for the x and the y components of the force according to Newton's second law are

$$\begin{aligned} F_x &= F \cos \theta - f = ma \\ F_y &= F_N - F \sin \theta - mg = 0 \end{aligned}$$

so $f = \mu_k F_N$ and the second equation gives $F_N = mg + F \sin \theta$ which yields

$$f = \mu_k (mg + F \sin \theta).$$



This expression is substituted for f in the first equation to obtain

$$F \cos \theta - \mu_k (mg + F \sin \theta) = ma$$

so the acceleration is

$$a = \frac{F}{m} (\cos \theta - \mu_k \sin \theta) - \mu_k g.$$

From the figure we see that $a = 3.0 \text{ m/s}^2$ when $\mu_k = 0$. This implies

$$3.0 \text{ m/s}^2 = \frac{F}{m} \cos \theta.$$

We also find $a = 0$ when $\mu_k = 0.20$

$$\begin{aligned} 0 &= \frac{F}{m} (\cos \theta - 0.20 \sin \theta) - 0.20 (9.8 \text{ m/s}^2) = 3.00 \text{ m/s}^2 - 0.20 \frac{F}{m} \sin \theta - 1.96 \text{ m/s}^2 \\ &= 1.04 \text{ m/s}^2 - 0.20 \frac{F}{m} \sin \theta \end{aligned}$$

which yields $5.2 \text{ m/s}^2 = \frac{F}{m} \sin \theta$. Combining the two results we get

$$\tan \theta = \left(\frac{5.2 \text{ m s}^2}{3.0 \text{ m s}^2} \right) = 1.73 \Rightarrow \theta = 60^\circ.$$

33. **THINK** In this problem the frictional force is not a constant but instead proportional to the speed of the boat. Integration is required to solve for the speed.

EXPRESS We denote the magnitude of the frictional force as αv here $\alpha = 70 \text{ N} \cdot \text{s/m}$. We take the direction of the boat's motion to be positive. Newton's second law gives

$$-\alpha v = m \frac{dv}{dt} \Rightarrow \frac{dv}{v} = -\frac{\alpha}{m} dt.$$

Integrating the equation gives

$$\int_{v_0}^v \frac{dv}{v} = -\frac{\alpha}{m} \int_0^t dt$$

here v_0 is the velocity at time zero and v is the velocity at time t . Solving the integral allows us to calculate the time it takes for the boat to slow down to 45 km/h or $v = v_0/2$ here $v_0 = 90 \text{ km/h}$.

ANALYZE The integrals are evaluated with the result

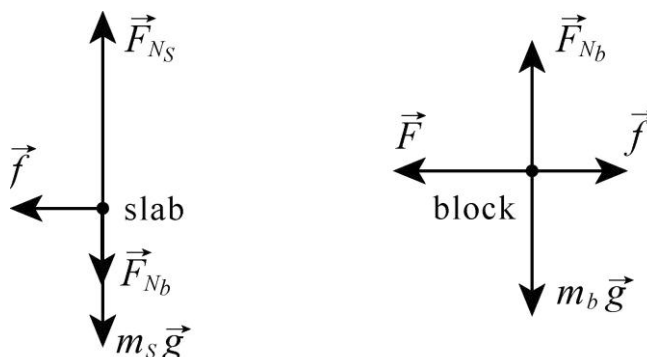
$$\ln \left(\frac{v}{v_0} \right) = -\frac{\alpha t}{m}$$

With $v = v_0/2$ and $m = 1000 \text{ kg}$ we find the time to be

$$t = -\frac{m}{\alpha} \ln \left(\frac{v}{v_0} \right) = -\frac{m}{\alpha} \ln \left(\frac{1}{2} \right) = -\frac{1000 \text{ kg}}{70 \text{ N} \cdot \text{s/m}} \ln \left(\frac{1}{2} \right) = 9.9 \text{ s}.$$

LEARN The speed of the boat is given by $v(t) = v_0 e^{-\alpha t/m}$ showing exponential decay with time. The greater the value of α the more rapidly the boat slows down.

34. The free body diagrams for the slab and block are shown below.



\vec{F} is the 100 N force applied to the block \vec{F}_{Ns} is the normal force of the floor on the slab F_{Nb} is the magnitude of the normal force between the slab and the block \vec{f} is the force of friction between the slab and the block m_s is the mass of the slab and m_b is the mass of the block. For both objects we take the x direction to be to the right and the y direction to be up.

Applying Newton's second law for the x and y axes for first the slab and second the block results in four equations

$$\begin{aligned} -f &= m_s a_s \\ F_{Ns} - F_{Nb} - m_s g &= 0 \\ f - F &= m_b a_b \\ F_{Nb} - m_b g &= 0 \end{aligned}$$

from which we note that the maximum possible static friction magnitude could be

$$\mu_s F_{Nb} = \mu_s m_b g = 0.60 (10 \text{ kg}) (9.8 \text{ m/s}^2) = 59 \text{ N}.$$

We check to see if the block slides on the slab. Assuming it does not then $a_s = a_b$ which we denote simply as a and we solve for f

$$f = \frac{m_s F}{m_s + m_b} = \frac{40 \text{ kg} (100 \text{ N})}{40 \text{ kg} + 10 \text{ kg}} = 80 \text{ N}$$

which is greater than $f_{s \text{ max}}$ so that we conclude the block is sliding across the slab their accelerations are different.

a Using $f = \mu_k F_{Nb}$ the above equations yield

$$a_b = \frac{\mu_k m_b g - F}{m_b} = \frac{0.40 (10 \text{ kg}) (9.8 \text{ m/s}^2) - 100 \text{ N}}{10 \text{ kg}} = -6.1 \text{ m/s}^2.$$

The negative sign means that the acceleration is leftward. That is $\vec{a}_b = -6.1 \text{ m/s}^2 \hat{i}$

b We also obtain

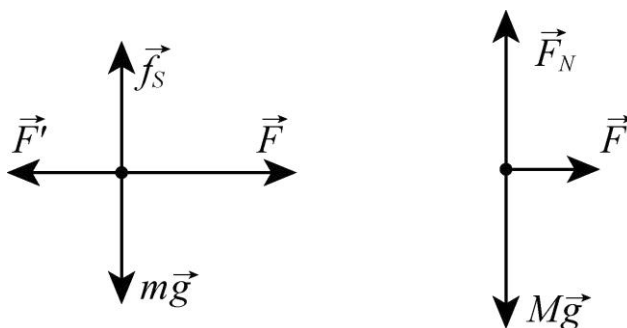
$$a_s = -\frac{\mu_k m_b g}{m_s} = -\frac{0.40 (10 \text{ kg}) (9.8 \text{ m/s}^2)}{40 \text{ kg}} = -0.98 \text{ m/s}^2.$$

As mentioned above this means it accelerates to the left. That is $\vec{a}_s = -0.98 \text{ m/s}^2 \hat{i}$

35. The free body diagrams for the two blocks treated individually are shown below first m and then M . F' is the contact force between the two blocks and the static friction force \vec{f}_s is at its maximum value so $\mu_s F' = f_s$ leads to $f_s = f_{s \max} = \mu_s F'$ here $\mu_s = 0.38$.

Treating the two blocks together as a single system sliding across a frictionless floor we apply Newton's second law (with $+x$ rightward) to find an expression for the acceleration

$$F = m_{\text{total}} a \Rightarrow a = \frac{F}{m + M}$$



This is equivalent to having analyzed the two blocks individually and then combined their equations. Now, when we analyze the small block individually, we apply Newton's second law to the x and y axes substitute in the above expression for a and use $\mu_s F' = f_s$.

$$F - F' = ma \Rightarrow F' = F - m \left(\frac{F}{m + M} \right)$$

$$f_s - mg = 0 \Rightarrow \mu_s F' - mg = 0$$

These expressions are combined to eliminate F' and we arrive at

$$F = \frac{mg}{\mu_s \left(1 - \frac{m}{m + M} \right)} = 4.9 \times 10^2 \text{ N}$$

36. Using $\mu_s = 0.616$ we solve for the area $A \frac{2m g}{C \rho v_t^2}$ which illustrates the inverse proportionality between the area and the speed squared. Thus when we set up a ratio of areas – of the slower case to the faster case – we obtain

$$\frac{A_{\text{slow}}}{A_{\text{fast}}} = \left(\frac{310 \text{ km/h}}{160 \text{ km/h}} \right)^2 = 3.75.$$

37. In the solution to exercise 4 we found that the force provided by the wind needed to be equal $F = 157$ (here that last figure is not “significant”).

a. Setting $F = D$ for drag force we use Eq. 6.14 to find the wind speed v along the ground (which actually is relative to the moving stone) but we assume the stone is moving slowly enough that this does not invalidate the result

$$v = \sqrt{\frac{2F}{C\rho A}} = \sqrt{\frac{2(157)}{(0.80)(1.21 \text{ kg m}^3)(0.040 \text{ m}^2)}} = 90 \text{ m/s} = 3.2 \times 10^2 \text{ km/h}.$$

b. Doubling our previous result we find the reported speed to be $6.5 \times 10^2 \text{ km/h}$.

c. The result is not reasonable for a terrestrial storm. Category 5 hurricane has speeds on the order of $2.6 \times 10^2 \text{ m/s}$.

38. a. From Table 6.1 and Eq. 6.16 we have

$$v_t = \sqrt{\frac{2F_g}{C\rho A}} \Rightarrow C\rho A = 2\frac{mg}{v_t^2}$$

here $v_t = 60 \text{ m/s}$. We estimate the pilot's mass at about $m = 70 \text{ kg}$. So we convert $v = 1300/1000 = 1.3 \text{ km/s} \approx 360 \text{ m/s}$ and plug into Eq. 6.14

$$D = \frac{1}{2}C\rho A v^2 = \frac{1}{2} \left(2\frac{mg}{v_t^2} \right) v^2 = mg \left(\frac{v}{v_t} \right)^2$$

which yields $D = (70 \text{ kg})(9.8 \text{ m/s}^2) \left(\frac{360}{60} \right)^2 \approx 2 \times 10^4 \text{ N}$.

b. We assume the mass of the ejection seat is roughly equal to the mass of the pilot. Thus, Newton's second law (in the horizontal direction) applied to this system of mass $2m$ gives the magnitude of acceleration

$$|a| = \frac{D}{2m} = \frac{g}{2} \left(\frac{v}{v_t} \right)^2 = 18g.$$

39. For the passenger jet $D_j = \frac{1}{2}C\rho_1 A v_j^2$ and for the prop-driven transport $D_t = \frac{1}{2}C\rho_2 A v_t^2$ where ρ_1 and ρ_2 represent the air density at 10 km and 5.0 km respectively. Thus the ratio in question is

$$\frac{D_j}{D_t} = \frac{\rho_1 v_j^2}{\rho_2 v_t^2} = \frac{(0.38 \text{ kg m}^3)(1000 \text{ km/h})^2}{(0.67 \text{ kg m}^3)(500 \text{ km/h})^2} = 2.3.$$

40. This problem involves Newton's second law for motion along the slope.

a The force along the slope is given by

$$\begin{aligned} F_g &= mg \sin \theta - \mu F_N = mg \sin \theta - \mu mg \cos \theta = mg \sin \theta - \mu \cos \theta \\ &= 85.0 \text{ kg } 9.80 \text{ m s}^{-2} [\sin 40.0^\circ - 0.04000 \cos 40.0^\circ] \\ &= 510 \text{ N} \end{aligned}$$

thus the terminal speed of the skier is

$$v_t = \sqrt{\frac{2F_g}{C\rho A}} = \sqrt{\frac{2 \cdot 510}{0.150 \cdot 1.20 \text{ kg m}^{-3} \cdot 1.30 \text{ m}^2}} = 66.0 \text{ m s}^{-1}$$

b Differentiating v_t with respect to C we obtain

$$\begin{aligned} dv_t &= -\frac{1}{2} \sqrt{\frac{2F_g}{\rho A}} C^{-3/2} dC = -\frac{1}{2} \sqrt{\frac{2 \cdot 510}{1.20 \text{ kg m}^{-3} \cdot 1.30 \text{ m}^2}} \cdot 0.150^{-3/2} dC \\ &= -2.20 \times 10^2 \text{ m s}^{-1} dC. \end{aligned}$$

41. Perhaps surprisingly the equations pertaining to this situation are exactly those in Sample Problem – “Car in flat circular turn,” although the logic is a little different. In the Sample Problem the car moves along a stationary road whereas in this problem the cat is stationary relative to the merry-go-round platform. But the static friction plays the same role in both cases since the bottom-most point of the car tire is instantaneously at rest with respect to the race track just as static friction applies to the contact surface between cat and platform. Using Eqs. 6-23 with $\omega = 4.35 \text{ rad s}^{-1}$ we find

$$\mu_s = 2\pi R/T^2 \cdot gR = 4\pi^2 R/gT^2.$$

With $T = 6.0 \text{ s}$ and $R = 5.4 \text{ m}$ we obtain $\mu_s = 0.60$.

42. The magnitude of the acceleration of the car as it rounds the curve is given by v^2/R where v is the speed of the car and R is the radius of the curve. Since the road is horizontal only the frictional force of the road on the tires makes this acceleration possible. The horizontal component of Newton's second law is $f = mv^2/R$. If F_N is the normal force of the road on the car and m is the mass of the car the vertical component of Newton's second law leads to $F_N = mg$. Thus using Eq. 6-1 the maximum value of static friction is

$$f_{\text{max}} = \mu_s F_N = \mu_s mg.$$

If the car does not slip $f \leq \mu_s mg$. This means

$$\frac{v^2}{R} \leq \mu_s g \Rightarrow v \leq \sqrt{\mu_s R g}.$$

Consequently the maximum speed with which the car can round the curve without slipping is

$$v_{\max} = \sqrt{\mu_s R g} = \sqrt{0.60 \cdot 30.5 \text{ m} \cdot 9.8 \text{ m/s}^2} = 13 \text{ m/s} \approx 48 \text{ km/h}.$$

43. The magnitude of the acceleration of the cyclist as it rounds the curve is given by v^2/R where v is the speed of the cyclist and R is the radius of the curve. Since the road is horizontal only the frictional force of the road on the tires makes this acceleration possible. The horizontal component of Newton's second law is $f = mv^2/R$. If F_N is the normal force of the road on the bicycle and m is the mass of the bicycle and rider the vertical component of Newton's second law leads to $F_N = mg$. Thus using 0.61 the maximum value of static friction is

$$f_{\max} = \mu_s F_N = \mu_s mg.$$

If the bicycle does not slip $f \leq \mu_s mg$. This means

$$\frac{v^2}{R} \leq \mu_s g \Rightarrow R \geq \frac{v^2}{\mu_s g}.$$

Consequently the minimum radius with which a cyclist moving at $29 \text{ km/h} = 8.1 \text{ m/s}$ can round the curve without slipping is

$$R_{\min} = \frac{v^2}{\mu_s g} = \frac{8.1 \text{ m/s}^2}{0.32 \cdot 9.8 \text{ m/s}^2} = 21 \text{ m}.$$

44. With $v = 96.6 \text{ km/h} = 26.8 \text{ m/s}$, 6.17 readily yields

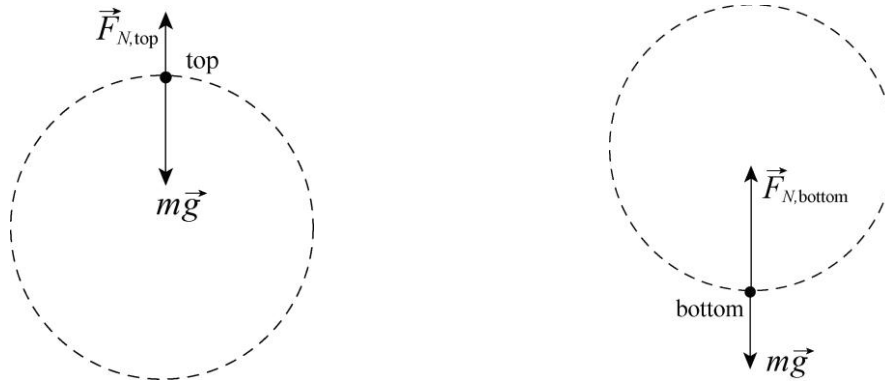
$$a = \frac{v^2}{R} = \frac{26.8 \text{ m/s}^2}{7.6 \text{ m}} = 94.7 \text{ m/s}^2$$

which we express as a multiple of g

$$a = \left(\frac{a}{g} \right) g = \left(\frac{94.7 \text{ m/s}^2}{9.80 \text{ m/s}^2} \right) g = 9.7g.$$

45. **THINK** Ferris wheel ride is a vertical circular motion. The apparent weight of the rider varies with his position.

EXPRESS The free body diagrams of the student at the top and bottom of the Ferris wheel are shown next.



At the top, the highest point in the circular motion, the seat pushes up on the student with a force of magnitude $F_{N\text{ top}}$ while the earth pulls down with a force of magnitude mg . Newton's second law for the radial direction gives

$$mg - F_{N\text{ top}} = \frac{mv^2}{R}.$$

At the bottom of the ride, $F_{N\text{ bottom}}$ is the magnitude of the upward force exerted by the seat. The net force toward the center of the circle is choosing upward as the positive direction

$$F_{N\text{ bottom}} - mg = \frac{mv^2}{R}.$$

The Ferris wheel is “steadily rotating” so the value $F_c = \frac{mv^2}{R}$ is the same everywhere. The apparent weight of the student is given by F_N .

ANALYZE At the top, we are told that $F_{N\text{ top}} = 556 \text{ N}$ and $mg = 667 \text{ N}$. This means that the seat is pushing up with a force that is smaller than the student's weight, and we say the student experiences a decrease in his “apparent weight” at the highest point. Thus he feels “light.”

b. From a, we find the centripetal force to be

$$F_c = \frac{mv^2}{R} = mg - F_{N\text{ top}} = 667 \text{ N} - 556 \text{ N} = 111 \text{ N}.$$

Thus the normal force at the bottom is

$$F_{N\text{ bottom}} = \frac{mv^2}{R} + mg = F_c + mg = 111 \text{ N} + 667 \text{ N} = 778 \text{ N}.$$

c. If the speed is doubled

$$F'_c = \frac{m(2v)^2}{R} = 4(111 \text{ N}) = 444 \text{ N}.$$

Therefore at the highest point, we have

$$F'_{N \text{ top}} = mg - F'_c = 667 - 444 = 223 \text{ N}.$$

d Similarly the normal force at the lowest point is now found to be

$$F'_{N \text{ bottom}} = F'_c + mg = 444 + 667 = 1111 \text{ N}.$$

LEARN The apparent weight of the student is the greatest at the bottom and smallest at the top of the ride. The speed $v = \sqrt{gR}$ would result in $F'_{N \text{ top}} = 0$ giving the student a sudden sensation of “weightlessness” at the top of the ride.

46. a We note that the speed 80.0 km/h in units is roughly 22.2 m/s. The horizontal force that keeps her from sliding must equal the centripetal force Eq. 6.18 and the upward force on her must equal mg . Thus

$$F_{\text{net}} = \sqrt{(mg)^2 + (mv^2/R)^2} = 547 \text{ N}.$$

b The angle is

$$\tan^{-1}[(mv^2/R) / mg] = \tan^{-1}(v^2/gR) = 9.53^\circ$$

as measured from a vertical axis.

47. a Eq. 6.35 gives $T = 2\pi R/v = 2\pi(10 \text{ m})/(6.1 \text{ m/s}) = 10 \text{ s}$.

b The situation is similar to that of Sample Problem – “Vertical circular loop, Diavolo,” but with the normal force direction reversed. Adapting Eq. 6.19 we find

$$F_N = mg - v^2/R = 486 \text{ N} \approx 4.9 \times 10^2 \text{ N}.$$

c To reverse both the normal force direction and the acceleration direction from what is shown in Sample Problem – “Vertical circular loop, Diavolo”) and adapt Eq. 6.19 accordingly. Thus we obtain

$$F_N = mg + v^2/R = 1081 \text{ N} \approx 1.1 \text{ kN}.$$

48. We will start by assuming that the normal force on the car from the rail points up. Note that gravity points down and the y axis is chosen positive upwards. Also the direction to the center of the circle – the direction of centripetal acceleration – is down. Thus, Newton’s second law leads to

$$F_N - mg = m\left(-\frac{v^2}{r}\right).$$

a When $v = 11 \text{ m/s}$ we obtain $F_N = 3.7 \times 10^3 \text{ N}$.

b \vec{F}_N points upward.

c When $v = 14 \text{ m/s}$ we obtain $F_N = -1.3 \times 10^3$ or $F_N = 1.3 \times 10^3$.

d The fact that this answer is negative means that \vec{F}_N points opposite to what we had assumed. Thus the magnitude of \vec{F}_N is $F_N = 1.3 \text{ k}$ and its direction is *down*.

49. At the top of the hill the situation is similar to that of a simple problem – “Vertical circular loop, Diavolo,” but with the normal force direction reversed. Adapting Eq. 6-19 we find

$$F_N = m g - v^2/R.$$

Since $F_N = 0$ there as stated in the problem then $v^2 = gR$. Later at the bottom of the valley we reverse both the normal force direction and the acceleration direction from what is shown in the simple problem and adapt Eq. 6-19 accordingly. Thus we obtain

$$F_N = m g + v^2/R = 2mg = 1372 \approx 1.37 \times 10^3.$$

50. The centripetal force on the passenger is $F = mv^2/r$.

a The slope of the plot at $v = 8.30 \text{ m/s}$ is

$$\left. \frac{dF}{dv} \right|_{v=8.30 \text{ m/s}} = \left. \frac{2mv}{r} \right|_{v=8.30 \text{ m/s}} = \frac{2(85.0 \text{ kg})(8.30 \text{ m/s})}{3.50 \text{ m}} = 403 \text{ N/s}.$$

b The period of the circular ride is $T = 2\pi r/v$. Thus

$$F = \frac{mv^2}{r} = \frac{m}{r} \left(\frac{2\pi r}{T} \right)^2 = \frac{4\pi^2 mr}{T^2}$$

and the variation of F with respect to T while holding r constant is

$$dF = -\frac{8\pi^2 mr}{T^3} dT.$$

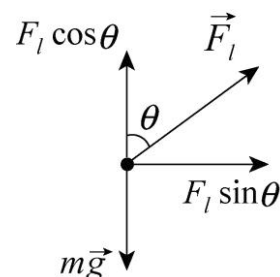
The slope of the plot at $T = 2.50 \text{ s}$ is

$$\left. \frac{dF}{dT} \right|_{T=2.50 \text{ s}} = -\frac{8\pi^2 mr}{T^3} \bigg|_{T=2.50 \text{ s}} = \frac{8\pi^2 (85.0 \text{ kg})(3.50 \text{ m})}{(2.50 \text{ s})^3} = -1.50 \times 10^3 \text{ N/s}.$$

51. **THINK** An airplane with its wings tilted at an angle is in a circular motion. Centripetal force is involved in this problem.

EXPRESS The free body diagram for the airplane of mass m is shown to the right. Note that \vec{F}_l is the force of aerodynamic lift and \vec{a} points rightwards in the figure. We also note that $\vec{a} = v^2/R$. Applying Newton's law to the axes of the problem (x rightward and y upward) we obtain

$$\begin{aligned} F_l \sin \theta &= m \frac{v^2}{R} \\ F_l \cos \theta &= mg \end{aligned}$$



Eliminating mass from these equations leads to $\tan \theta = \frac{v^2}{gR}$. The equation allows us to solve for the radius R .

ANALYZE With $v = 480 \text{ km/h} = 133 \text{ m/s}$ and $\theta = 40^\circ$ we find

$$R = \frac{v^2}{g \tan \theta} = \frac{133 \text{ m/s}^2}{9.8 \text{ m/s}^2 \tan 40^\circ} = 2151 \text{ m} \approx 2.2 \times 10^3 \text{ m}.$$

LEARN Our approach to solving this problem is identical to that discussed in the sample problem – “Car in banked circular turn.” Do you see the similarities?

52. The situation is somewhat similar to that shown in the “loop the loop” example done in the textbook (see Figure 6.10) except that instead of a downward normal force we are dealing with the force of the boom \vec{F}_B on the car – which is capable of pointing any direction. We will assume it to be upward as we apply Newton's second law to the car (of total weight 5000 N). $F_B - W = ma$ here $m = W/g$ and $a = -v^2/r$. Note that the centripetal acceleration is downward our choice for negative direction for a body at the top of its circular trajectory.

a. If $r = 10 \text{ m}$ and $v = 5.0 \text{ m/s}$ we obtain $F_B = 3.7 \times 10^3 \text{ N} = 3.7 \text{ kN}$.

b. The direction of \vec{F}_B is up.

c. If $r = 10 \text{ m}$ and $v = 12 \text{ m/s}$ we obtain $F_B = -2.3 \times 10^3 \text{ N} = -2.3 \text{ kN}$ or $F_B = 2.3 \text{ kN}$.

d. The minus sign indicates that \vec{F}_B points downward.

53. The free body diagram for the hand straps of mass m is the view that a passenger might see if she was looking forward and the streetcar was curving to the right so \vec{a} points rightwards in the figure. We note that $\vec{a} = v^2/R$ here $v = 16 \text{ km/h} = 4.4 \text{ m/s}$.

Applying Newton's law to the axes of the problem ($+x$ is rightward and y is upward) we obtain

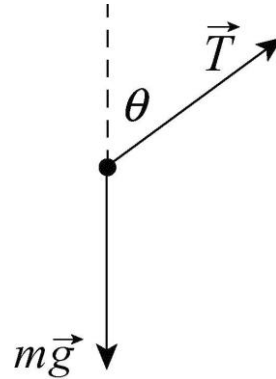
$$T \sin \theta = m \frac{v^2}{R}$$

$$T \cos \theta = mg.$$

we solve these equations for the angle

$$\theta = \tan^{-1} \left(\frac{v^2}{Rg} \right)$$

which yields $\theta = 12^\circ$.



54. The centripetal force on the passenger is $F = mv^2/r$.

a The variation of F with respect to r while holding v constant is $dF = -\frac{mv^2}{r^2} dr$.

b The variation of F with respect to v while holding r constant is $dF = \frac{2mv}{r} dv$.

c The period of the circular ride is $T = 2\pi r/v$. Thus

$$F = \frac{mv^2}{r} = \frac{m}{r} \left(\frac{2\pi r}{T} \right)^2 = \frac{4\pi^2 mr}{T^2}$$

and the variation of F with respect to T while holding r constant is

$$dF = -\frac{8\pi^2 mr}{T^3} dT = -8\pi^2 mr \left(\frac{v}{2\pi r} \right)^3 dT = -\left(\frac{mv^3}{\pi r^2} \right) dT.$$

55. We note that the period T is eight times the time between flashes $\frac{1}{2000}$ s so $T = 0.0040$ s. Combining 6.18 with 6.435 leads to

$$F = \frac{4m\pi^2 R}{T^2} = \frac{4(0.030 \text{ kg})\pi^2(0.035 \text{ m})}{(0.0040 \text{ s})^2} = 2.6 \times 10^3 \text{ N}.$$

56. We refer the reader to Sample Problem – “Car in banked circular turn,” and use the result 6.26

$$\theta = \tan^{-1} \left(\frac{v^2}{gR} \right)$$

With $v = 60 \text{ km/h} = 17 \text{ m/s}$ and $R = 200 \text{ m}$, the banking angle is therefore $\theta = 8.1^\circ$.
 So we consider a vehicle taking this banked curve at $v' = 40 \text{ km/h} = 11 \text{ m/s}$. Its

horizontal acceleration is $a' = v'^2/R$ which has components parallel the incline and perpendicular to it

$$a_{\parallel} = a' \cos \theta = \frac{v'^2 \cos \theta}{R}$$

$$a_{\perp} = a' \sin \theta = \frac{v'^2 \sin \theta}{R}.$$

These enter Newton's second law as follows (choosing downhill as the x direction and away from incline as y)

$$mg \sin \theta - f_s = ma$$

$$F_N - mg \cos \theta = ma_{\perp}$$

and we are led to

$$\frac{f_s}{F_N} = \frac{mg \sin \theta - mv'^2 \cos \theta / R}{mg \cos \theta + mv'^2 \sin \theta / R}.$$

We cancel the mass and plug in obtaining $f_s/F_N = 0.078$. The problem implies we should set $f_s = f_{s \text{ max}}$ so that by 6.1 we have $\mu_s = 0.078$.

57. For the puck to remain at rest the magnitude of the tension force T of the cord must be equal the gravitational force Mg on the cylinder. The tension force supplies the centripetal force that keeps the puck in its circular orbit so $T = mv^2/r$. Thus $Mg = mv^2/r$. We solve for the speed

$$v = \sqrt{\frac{Mg r}{m}} = \sqrt{\frac{2.50 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 0.200 \text{ m}}{1.50 \text{ kg}}} = 1.81 \text{ m/s}.$$

58. a Using the kinematic equation given in Table 2.1 the deceleration of the car is

$$v^2 = v_0^2 + 2ad \Rightarrow 0 = (35 \text{ m/s})^2 + 2a(107 \text{ m})$$

which gives $a = -5.72 \text{ m/s}^2$. Thus the force of friction required to stop by car is

$$f = m|a| = 1400 \text{ kg} \cdot 5.72 \text{ m/s}^2 \approx 8.0 \times 10^3 \text{ N}.$$

b The maximum possible static friction is

$$f_{s \text{ max}} = \mu_s mg = 0.50 \cdot 1400 \text{ kg} \cdot 9.80 \text{ m/s}^2 \approx 6.9 \times 10^3 \text{ N}.$$

c If $\mu_k = 0.40$ then $f_k = \mu_k mg$ and the deceleration is $a = -\mu_k g$. Therefore the speed of the car when it hits the wall is

$$v = \sqrt{v_0^2 + 2ad} = \sqrt{35 \text{ m s}^{-2} - 2(0.40)(9.8 \text{ m s}^{-2})(107 \text{ m})} \approx 20 \text{ m s}^{-1}$$

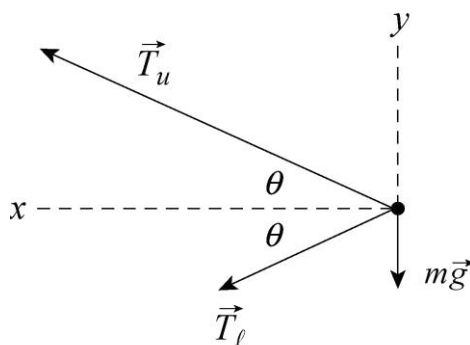
d The force required to keep the motion circular is

$$F_r = \frac{mv_0^2}{r} = \frac{1400 \text{ kg} (35.0 \text{ m s}^{-1})^2}{107 \text{ m}} = 1.6 \times 10^4 \text{ N}$$

e Since $F_r > f_{s \text{ max}}$ no circular path is possible.

59. **THINK** As illustrated in Fig. 6-45, our system consists of a ball connected by two strings to a rotating rod. The tensions in the strings provide the source of centripetal force.

EXPRESS The free body diagram for the ball is shown below. \vec{T}_u is the tension exerted by the upper string on the ball, \vec{T}_ℓ is the tension in the lower string, and m is the mass of the ball. Note that the tension in the upper string is greater than the tension in the lower string. It must balance the downward pull of gravity and the force of the lower string.



We take the x direction to be leftward toward the center of the circular orbit and y upward. Since the magnitude of the acceleration is $a = v^2/R$, the x component of Newton's second law is

$$T_u \cos \theta + T_\ell \cos \theta = \frac{mv^2}{R}$$

where v is the speed of the ball and R is the radius of its orbit. The y component is

$$T_u \sin \theta - T_\ell \sin \theta - mg = 0.$$

The second equation gives the tension in the lower string $T_\ell = T_u - mg / \sin \theta$.

ANALYZE a Since the triangle is equilateral, the angle is $\theta = 30.0^\circ$. Thus

$$T_\ell = T_u - \frac{mg}{\sin \theta} = 35.0 \text{ N} - \frac{1.34 \text{ kg} (9.80 \text{ m s}^{-2})}{\sin 30.0^\circ} = 8.74 \text{ N}$$

b The net force in the y direction is zero. In the x direction the net force has magnitude

$$F_{\text{net str}} = (T_u + T_\ell) \cos \theta = 35.0 + 8.74 \cos 30.0^\circ = 37.9 \text{ N}.$$

c The radius of the path is

$$R = L \cos \theta = 1.70 \text{ m} \cos 30^\circ = 1.47 \text{ m}.$$

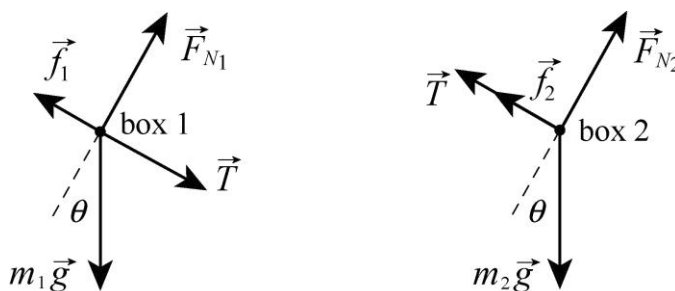
Using $F_{\text{net str}} = mv^2/R$ we find the speed of the ball to be

$$v = \sqrt{\frac{RF_{\text{net str}}}{m}} = \sqrt{\frac{1.47 \text{ m} \cdot 37.9 \text{ N}}{1.34 \text{ kg}}} = 6.45 \text{ m/s}.$$

d The direction of $\vec{F}_{\text{net str}}$ is leftward (“radially inward”).

LEARN The upper string has a tension about 4 times that in the lower string $T_u \approx 4T_\ell$. The upper string will break more easily than the lower one.

60. The free body diagrams for the two boxes are shown below. T is the magnitude of the force in the rod. When $T > 0$ the rod is said to be in tension and when $T < 0$ the rod is under compression. \vec{F}_{N2} is the normal force on box 2, the uncle box. \vec{F}_{N1} is the normal force on the aunt box, box 1. \vec{f}_1 is kinetic friction force on the aunt box and \vec{f}_2 is kinetic friction force on the uncle box. Also $m_1 = 1.65 \text{ kg}$ is the mass of the aunt box and $m_2 = 3.30 \text{ kg}$ is the mass of the uncle box. (The uncle box is a lot of ants.)



For each block we take x downhill (which is to the left in these diagrams) and y in the direction of the normal force. Applying Newton's second law to the x and y directions of first box 2 and then box 1 we arrive at four equations

$$m_2 g \sin \theta - f_2 - T = m_2 a$$

$$F_{N2} - m_2 g \cos \theta = 0$$

$$m_1 g \sin \theta - f_1 + T = m_1 a$$

$$F_{N1} - m_1 g \cos \theta = 0$$

which when combined with $f_1 = \mu_1 F_{N1}$ here $\mu_1 = 0.226$ and $f_2 = \mu_2 F_{N2}$ here $\mu_2 = 0.113$ fully describe the dynamics of the system.

a We solve the above equations for the tension and obtain

$$T = \left(\frac{m_2 m_1 g}{m_2 + m_1} \right) (\mu_1 - \mu_2 \cos \theta) = 1.05 \text{ N}.$$

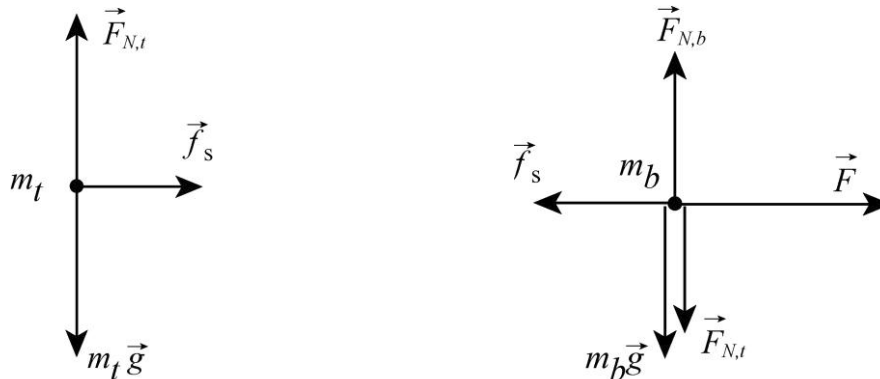
b These equations lead to an acceleration equal to

$$a = g \left(\sin \theta - \left(\frac{\mu_2 m_2 + \mu_1 m_1}{m_2 + m_1} \right) \cos \theta \right) = 3.62 \text{ m/s}^2.$$

c Reversing the blocks is equivalent to switching the labels. We see from our algebraic result in part a that this gives a negative value for T equal in magnitude to the result we got before. Thus the situation is as it was before except that the rod is now in a state of compression.

61. **THINK** Our system consists of two blocks one on top of the other. If we pull the bottom block too hard, the top block will slip on the bottom one. We're interested in the maximum force that can be applied such that the two will move together.

EXPRESS The free body diagrams for the two blocks are shown below.



We first calculate the coefficient of static friction for the surface between the two blocks. When the force applied is at a maximum the frictional force between the two blocks must also be a maximum. Since $F_t = 12 \text{ N}$ of force has to be applied to the top block for slipping to take place using $F_t = f_{s \text{ max}} = \mu_s F_{N,t} = \mu_s m_t g$ we have

$$\mu_s = \frac{F_t}{m_t g} = \frac{12}{4.0 \text{ kg} \cdot 9.8 \text{ m/s}^2} = 0.31.$$

Using the same reasoning for the two masses to move together the maximum applied force could be

$$F = \mu_s (m_t + m_b) g$$

ANALYZE a) Substituting the value of μ_s found above the maximum horizontal force has a magnitude

$$F = \mu_s (m_t + m_b) g = 0.31 (4.0 \text{ kg} + 5.0 \text{ kg}) (9.8 \text{ m/s}^2) = 27$$

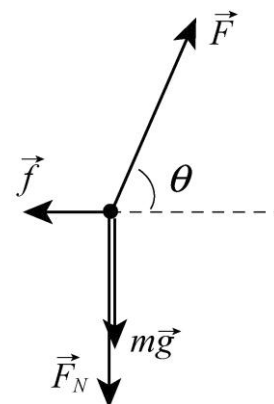
b) The maximum acceleration is

$$a_{\text{max}} = \frac{F}{m_t + m_b} = \mu_s g = 0.31 (9.8 \text{ m/s}^2) = 3.0 \text{ m/s}^2.$$

LEARN Slipping will occur if the applied force exceeds 27.3 N. In the absence of friction ($\mu_s = 0$) between the two blocks any amount of force could cause the top block to slip.

62. The free body diagram for the stone is shown to the right with \vec{F} being the force applied to the stone, \vec{F}_N the downward normal force of the ceiling on the stone, $m\vec{g}$ the force of gravity and \vec{f} the force of friction. We take the x direction to be horizontal to the right and the y direction to be up. The equations for the x and the y components of the force according to Newton's second law are

$$\begin{aligned} F_x &= F \cos \theta - f = ma \\ F_y &= F \sin \theta - F_N - mg = 0 \end{aligned}$$



so $f = \mu_k F_N$ and the second equation gives $F_N = F \sin \theta - mg$ which yields $f = \mu_k (F \sin \theta - mg)$. This expression is substituted for f in the first equation to obtain

$$F \cos \theta - \mu_k (F \sin \theta - mg) = ma.$$

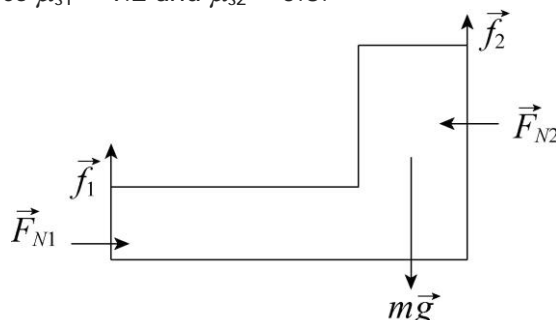
or $a = 0$ the force is

$$F = \frac{-\mu_k mg}{\cos \theta - \mu_k \sin \theta}.$$

With $\mu_k = 0.65$, $m = 5.0 \text{ kg}$ and $\theta = 70^\circ$ we obtain $F = 118 \text{ N}$.

63. a) The free body diagram for the person shown as an irregularly shaped block is shown below. The force that she exerts on the rock slabs is not directly shown (since the diagram should only show forces exerted on her), but it is related by Newton's third law) to the normal forces \vec{F}_{N1} and \vec{F}_{N2} exerted horizontally by the slabs onto her shoes and

back respectively. We will show in part b that $F_{N1} = F_{N2}$ so that there is no ambiguity in saying that the magnitude of her push is F_{N2} . The total upward force due to maximum static friction is $\vec{f} = \vec{f}_1 + \vec{f}_2$ where $f_1 = \mu_{s1}F_{N1}$ and $f_2 = \mu_{s2}F_{N2}$. The problem gives the values $\mu_{s1} = 1.2$ and $\mu_{s2} = 0.8$.



(b) We apply Newton's second law to the x and y axes with x rightward and y upward and there is no acceleration in either direction.

$$\begin{aligned} F_{N1} - F_{N2} &= 0 \\ f_1 + f_2 - mg &= 0 \end{aligned}$$

The first equation tells us that the normal forces are equal $F_{N1} = F_{N2} = F_N$. Consequently from 6.1

$$\begin{aligned} f_1 &= \mu_{s1}F_N \\ f_2 &= \mu_{s2}F_N \end{aligned}$$

We conclude that

$$f_1 = \left(\frac{\mu_{s1}}{\mu_{s2}} \right) f_2.$$

Therefore $f_1 + f_2 - mg = 0$ leads to

$$\left(\frac{\mu_{s1}}{\mu_{s2}} + 1 \right) f_2 = mg$$

which with $m = 49 \text{ kg}$ yields $f_2 = 192 \text{ N}$. From this we find $F_N = f_2 / \mu_{s2} = 240 \text{ N}$. This is equal to the magnitude of the push exerted by the rock climber.

From the above calculation we find $f_1 = \mu_{s1}F_N = 288 \text{ N}$ which amounts to a fraction

$$\frac{f_1}{W} = \frac{288}{(49)(9.8)} = 0.60$$

or 60% of her weight.

64. a The upward force exerted by the car on the passenger is equal to the downward force of gravity $W = 500$ on the passenger. So the *net* force does not have a vertical contribution; it only has the contribution from the horizontal force which is necessary for maintaining the circular motion. Thus $|\vec{F}_{\text{net}}| = F = 210$.

b Using 6.18 we have

$$v = \sqrt{\frac{FR}{m}} = \sqrt{\frac{210 \times 470 \text{ m}}{51.0 \text{ kg}}} = 44.0 \text{ m/s}.$$

65. The layer of ice has a mass of

$$m_{\text{ice}} = (917 \text{ kg/m}^3) (400 \text{ m} \times 500 \text{ m} \times 0.0040 \text{ m}) = 7.34 \times 10^5 \text{ kg}.$$

This added to the mass of the hundred stones at 20 kg each comes to $m = 7.36 \times 10^5 \text{ kg}$.

a Setting $F = D$ for drag force we use 6.14 to find the wind speed v along the ground which actually is relative to the moving stone but we assume the stone is moving slowly enough that this does not invalidate the result

$$v = \sqrt{\frac{\mu_k mg}{4C_{\text{ice}} \rho A_{\text{ice}}}} = \sqrt{\frac{(0.10)(7.36 \times 10^5 \text{ kg})(9.8 \text{ m/s}^2)}{4(0.002)(1.21 \text{ kg/m}^3)(400 \times 500 \text{ m}^2)}} = 19 \text{ m/s} \approx 69 \text{ km/h}.$$

b Doubling our previous result we find the reported speed to be 139 km/h.

c The result is reasonable for storm winds. Category 5 hurricane has speeds on the order of $2.6 \times 10^2 \text{ m/s}$.

66. Note that since no static friction coefficient is mentioned we assume f_s is not relevant to this computation. We apply Newton's second law to each block's x axis which for m_1 is positive rightward and for m_2 is positive downhill

$$\begin{aligned} T - f_k &= m_1 a \\ m_2 g \sin \theta - T &= m_2 a \end{aligned}$$

Adding the equations we obtain the acceleration

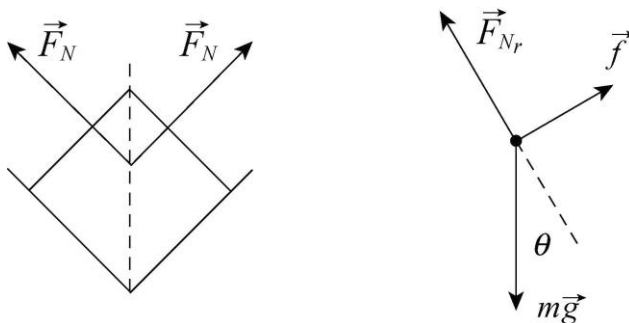
$$a = \frac{m_2 g \sin \theta - f_k}{m_1 + m_2}$$

or $f_k = \mu_k F_N = \mu_k m_1 g$ we obtain

$$a = \frac{3.0 \text{ kg } 9.8 \text{ m/s}^2 \sin 30^\circ - 0.25 (3.0 \text{ kg} + 2.0 \text{ kg}) 9.8 \text{ m/s}^2}{3.0 \text{ kg} + 2.0 \text{ kg}} = 1.96 \text{ m/s}^2.$$

Returning this value to either of the above two equations we find $T = 8.8 \text{ N}$.

67. Each side of the trough exerts a normal force on the crate. The first diagram shows the view looking in to and across a cross section.



The net force is along the dashed line. Since each of the normal forces makes an angle of 45° with the dashed line, the magnitude of the resultant normal force is given by

$$F_{Nr} = 2F_N \cos 45^\circ = \sqrt{2}F_N.$$

The second diagram is the free body diagram for the crate (from a “side” view, similar to that shown in the first picture in Fig. 6-51). The force of gravity has magnitude mg where m is the mass of the crate and the magnitude of the force of friction is denoted by f .

We take the x direction to be down the incline and y to be in the direction of \vec{F}_{Nr} . Then the x and the y components of Newton’s second law are

$$\begin{aligned} x \quad & mg \sin \theta - f = ma \\ y \quad & F_{Nr} - mg \cos \theta = 0. \end{aligned}$$

Since the crate is moving, each side of the trough exerts a force of kinetic friction, so the total frictional force has magnitude

$$f = 2\mu_k F_N = 2\mu_k F_{Nr} / \sqrt{2} = \sqrt{2}\mu_k F_{Nr}$$

Combining this expression with $F_{Nr} = mg \cos \theta$ and substituting into the x component equation we obtain

$$mg \sin \theta - \sqrt{2}mg \cos \theta = ma.$$

Therefore $a = g \sin \theta - \sqrt{2}\mu_k g \cos \theta$.

68. A block to be on the verge of sliding out means that the force of static friction is acting “down the bank” (in the sense explained in the problem statement with maximum

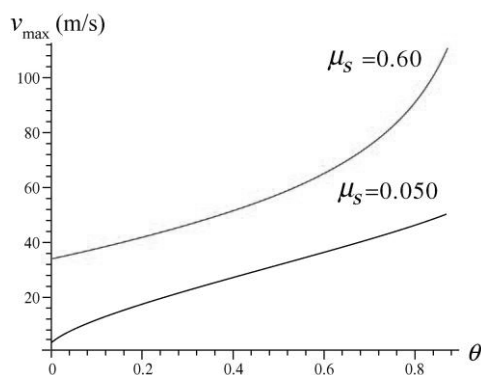
possible magnitude. We first consider the vector sum \vec{F} of the maximum static friction force and the normal force. Due to the facts that they are perpendicular and their magnitudes are simply proportional (6.1) we find \vec{F} is at angle ϕ measured from the vertical such that $\phi = \theta_s$ here $\tan \theta_s = \mu_s$ compare with (6.13) and θ is the bank angle as stated in the problem. So the vector sum of \vec{F} and the vertically downward pull mg of gravity must be equal to the horizontal centripetal force mv^2/R which leads to a surprisingly simple relationship

$$\tan \phi = \frac{mv^2/R}{mg} = \frac{v^2}{Rg}.$$

Writing this as an expression for the maximum speed we have

$$v_{\max} = \sqrt{Rg \tan \theta + \tan^{-1} \mu_s} = \sqrt{\frac{Rg \tan \theta + \mu_s}{1 - \mu_s \tan \theta}}$$

(b) The graph is shown below with θ in radians



(c) Either estimating from the graph $\mu_s = 0.60$ upper curve or calculated it more carefully leads to $v = 41.3 \text{ m/s} = 149 \text{ km/h}$ when $\theta = 10^\circ = 0.175 \text{ radian}$.

(d) Similarly for $\mu_s = 0.050$ the lower curve we find $v = 21.2 \text{ m/s} = 76.2 \text{ km/h}$ when $\theta = 10^\circ = 0.175 \text{ radian}$.

69. For simplicity we denote the 70° angle as θ and the magnitude of the push 80 N as P . The vertical forces on the block are the downward normal force exerted on it by the ceiling, the downward pull of gravity of magnitude mg and the vertical component of \vec{P} which is upward with magnitude $P \sin \theta$. Since there is no acceleration in the vertical direction we must have

$$F_N = P \sin \theta - mg$$

in which case the leftward pointed kinetic friction has magnitude

$$f_k = \mu_k P \sin \theta - mg.$$

hoosing x rightward, Newton's second law leads to

$$P \cos \theta - f_k = ma \Rightarrow a = \frac{P \cos \theta - \mu_k P \sin \theta - mg}{m}$$

which yields $a = 3.4 \text{ m s}^{-2}$ when $\mu_k = 0.40$ and $m = 5.0 \text{ kg}$.

70. a. We note that R , the horizontal distance from the bob to the axis of rotation, is the circumference of the circular path divided by 2π ; therefore $R = 0.94 / 2\pi = 0.15 \text{ m}$. The angle that the cord makes with the horizontal is not easily found

$$\theta = \cos^{-1} R/L = \cos^{-1} 0.15 \text{ m}/0.90 \text{ m} = 80^\circ.$$

The vertical component of the force of tension in the string is $T \sin \theta$ and must equal the downward pull of gravity mg . Thus

$$T = \frac{mg}{\sin \theta} = 0.40 \text{ N}.$$

Note that we are using T for tension, not for the period.

b. The horizontal component of that tension must supply the centripetal force mv^2/R . So we have $T \cos \theta = mv^2/R$. This gives speed $v = 0.49 \text{ m/s}$. This divided into the circumference gives the time for one revolution $0.94 / 0.49 = 1.9 \text{ s}$.

71. a. To be “on the verge of sliding” means the applied force is equal to the maximum possible force of static friction $f_{s \text{ max}} = \mu_s mg$ in this case

$$f_{s \text{ max}} = \mu_s mg = 35.3 \text{ N}.$$

b. In this case the applied force \vec{F} indirectly decreases the maximum possible value of friction since its y component causes a reduction in the normal force as well as directly opposing the friction force itself because of its x component. The normal force turns out to be

$$F_N = mg - F \sin \theta$$

here $\theta = 60^\circ$ so that the horizontal equation (the x application of Newton's second law) becomes

$$F \cos \theta - f_{s \text{ max}} = F \cos \theta - \mu_s mg - F \sin \theta = 0 \Rightarrow F = 39.7 \text{ N}.$$

c. If the applied force \vec{F} indirectly increases the maximum possible value of friction since its y component causes a reduction in the normal force as well as directly opposing the friction force itself because of its x component. The normal force in this case turns out to be

$$F_N = mg - F \sin \theta$$

here $\theta = 60^\circ$ so that the horizontal equation becomes

$$F \cos \theta - f_s = ma = F \cos \theta - \mu_s (mg - F \sin \theta) = 0 \Rightarrow F = 320 \text{ N}.$$

72. With $\theta = 40^\circ$, we apply Newton's second law to the "downhill" direction:

$$mg \sin \theta - f = ma$$

$$f = f_k = \mu_k F_N = \mu_k (mg \cos \theta)$$

using Eq. 6.12, thus

$$a = 0.75 \text{ m/s}^2 = g \sin \theta - \mu_k \cos \theta$$

determines the coefficient of kinetic friction $\mu_k = 0.74$.

73. a With $\theta = 60^\circ$, we apply Newton's second law to the "downhill" direction:

$$mg \sin \theta - f = ma$$

$$f = f_k = \mu_k F_N = \mu_k mg \cos \theta.$$

thus

$$a = g \sin \theta - \mu_k \cos \theta = 7.5 \text{ m/s}^2.$$

b The direction of the acceleration \vec{a} is down the slope.

c Now the friction force is in the "downhill" direction (which is our positive direction) so that we obtain

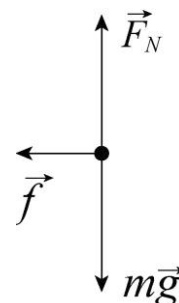
$$a = g \sin \theta + \mu_k \cos \theta = 9.5 \text{ m/s}^2.$$

d The direction is down the slope.

74. The free body diagram for the puck is shown on the right. \vec{F}_N is the normal force of the ice on the puck, \vec{f} is the force of friction in the $-x$ direction, and $m\vec{g}$ is the force of gravity.

a The horizontal component of Newton's second law gives $-f = ma$ and constant acceleration kinematics (Table 2.1) can be used to find the acceleration.

Since the final velocity is zero, $v^2 = v_0^2 + 2ax$ leads to $a = -v_0^2 / 2x$. This is substituted into the Newton's law equation to obtain



$$f = \frac{mv_0^2}{2x} = \frac{(0.110 \text{ kg})(6.0 \text{ m/s})^2}{2(15 \text{ m})} = 0.13 \text{ N}.$$

(b) The vertical component of Newton's second law gives $F_N - mg = 0$ so $F_N = mg$ which implies using Eq. 6-2 $f = \mu_k mg$. We solve for the coefficient

$$\mu_k = \frac{f}{mg} = \frac{0.13 \text{ N}}{(0.110 \text{ kg})(9.8 \text{ m/s}^2)} = 0.12.$$

75. We may treat all 25 cars as a single object of mass $m = 25 \times 5.0 \times 10^4 \text{ kg}$ and when the speed is $30 \text{ km/h} = 8.3 \text{ m/s}$ subject to a friction force equal to

$$f = 25 \times 250 \times 8.3 = 5.2 \times 10^4 \text{ N}.$$

(a) Along the level track, this object experiences a "forward" force T exerted by the locomotive so that Newton's second law leads to

$$T - f = ma \Rightarrow T = 5.2 \times 10^4 + 1.25 \times 10^6 (0.20) = 3.0 \times 10^5 \text{ N}.$$

(b) The free body diagram is shown next with θ as the angle of the incline. The x direction (which is the only direction to which we will be applying Newton's second law) is uphill (to the upper right in our sketch). Thus we obtain

$$T - f - mg \sin \theta = ma$$

here we set $a = 0$ implied by the problem statement and solve for the angle. We obtain $\theta = 1.2^\circ$.

76. An excellent discussion and equation development related to this problem is given in Sample Problem – "Friction, applied force at an angle." Using the result we obtain

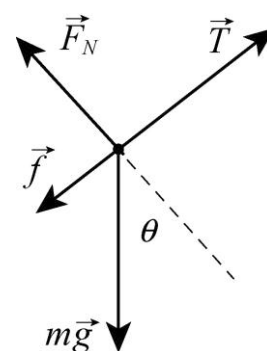
$$\theta = \tan^{-1} \mu_s = \tan^{-1} 0.50 = 27^\circ$$

which implies that the angle through which the slope should be *reduced* is

$$\phi = 45^\circ - 27^\circ \approx 18^\circ.$$

77. We make use of Eq. 6-16 which yields

$$\sqrt{\frac{2mg}{C\rho\pi R^2}} = \sqrt{\frac{2(6)(9.8)}{1.6(1.2\pi)(0.03)^2}} = 147 \text{ m/s}.$$



78. a The coefficient of static friction is $\mu_s = \tan \theta_{\text{slip}} = 0.577 \approx 0.58$.

b Using

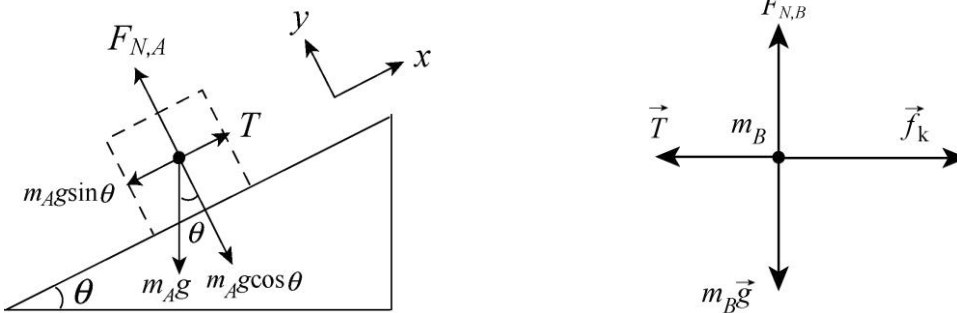
$$mg \sin \theta - f = ma$$

$$f = f_k = \mu_k F_N = \mu_k mg \cos \theta$$

and $a = 2d/t^2$ with $d = 2.5$ m and $t = 4.0$ s we obtain $\mu_k = 0.54$.

79. **THINK** We have two blocks connected by a cord as shown in Fig. 6-56. As block A slides down the frictionless inclined plane it pulls block B , so there's a tension in the cord.

EXPRESS The free body diagrams for blocks A and B are shown below.



Newton's law gives

$$m_A g \sin \theta - T = m_A a$$

for block A where $\theta = 30^\circ$. For block B we have

$$T - f_k = m_B a$$

so the frictional force is given by $f_k = \mu_k F_{N,B} = \mu_k m_B g$. The equations allow us to solve for the tension T and the acceleration a .

ANALYZE a Combining the above equations to solve for T we obtain

$$T = \frac{m_A m_B}{m_A + m_B} (\sin \theta + \mu_k) g = \frac{4.0 \text{ kg} \cdot 2.0 \text{ kg}}{4.0 \text{ kg} + 2.0 \text{ kg}} (\sin 30^\circ + 0.50) 9.80 \text{ m/s}^2 = 13 \text{ N}.$$

b Similarly the acceleration of the two block system is

$$a = \left(\frac{m_A \sin \theta - \mu_k m_B}{m_A + m_B} \right) g = \frac{4.0 \text{ kg} \sin 30^\circ - 0.50 \cdot 2.0 \text{ kg}}{4.0 \text{ kg} + 2.0 \text{ kg}} 9.80 \text{ m/s}^2 = 1.6 \text{ m/s}^2.$$

LEARN In the case where $\theta = 90^\circ$ and $\mu_k = 0$ we have

$$T = \frac{m_A m_B}{m_A + m_B} g \quad a = \frac{m_A}{m_A + m_B} g$$

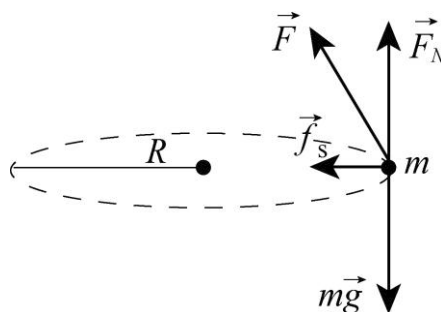
which correspond to the simple problem – “Block on table, block hanging,” discussed in chapter 5.

80. We use $D = \frac{1}{2} C \rho A v^2$ where ρ is the air density A is the cross sectional area of the missile v is the speed of the missile and C is the drag coefficient. The area is given by $A = \pi R^2$ where $R = 0.265$ m is the radius of the missile. Thus

$$D = \frac{1}{2} (0.75) (1.2 \text{ kg/m}^3) \pi (0.265 \text{ m})^2 (250 \text{ m/s})^2 = 6.2 \times 10^3 \text{ N}$$

81. **THINK** How can a cyclist move in a circle? It is the force of friction that provides the centripetal force required for the circular motion.

EXPRESS The free body diagram is shown below. The magnitude of the acceleration of the cyclist as it moves along the horizontal circular path is given by v^2/R where v is the speed of the cyclist and R is the radius of the curve.



The horizontal component of Newton's second law is $f_s = mv^2/R$ where f_s is the static friction exerted horizontally by the ground on the tires. Similarly, if F_N is the vertical force of the ground on the bicycle and m is the mass of the bicycle and rider, the vertical component of Newton's second law leads to $F_N = mg = 833 \text{ N}$.

ANALYZE a The frictional force is $f_s = \frac{mv^2}{R} = \frac{(85.0 \text{ kg})(9.00 \text{ m/s})^2}{25.0 \text{ m}} = 275 \text{ N}$.

b Since the frictional force f_s and F_N the normal force exerted by the road are perpendicular to each other, the magnitude of the force exerted by the ground on the bicycle is

$$F = \sqrt{f_s^2 + F_N^2} = \sqrt{275^2 + 833^2} = 877 \text{ N}$$

LEARN The force exerted by the ground on the bicycle is at an angle $\theta = \tan^{-1} \frac{275}{833} = 18.3^\circ$ with respect to the vertical axis.

82. At the top of the hill the vertical forces on the car are the upward normal force exerted by the ground and the downward pull of gravity. Designating y downward and we have

$$mg - F_N = \frac{mv^2}{R}$$

from Newton's second law. To find the greatest speed without leaving the hill, we set $F_N = 0$ and solve for v

$$v = \sqrt{gR} = \sqrt{9.8 \text{ m/s}^2 \cdot 250 \text{ m}} = 49.5 \text{ m/s} = 49.5 \cdot \frac{3600}{1000} \text{ km/h} = 178 \text{ km/h}.$$

83. a. The push to get it moving must be at least as big as $f_{s \max} = \mu_s F_N$. With $F_N = mg$ in this case which equals $0.51 \cdot 165 = 84.2$.

b. While in motion constant velocity (zero acceleration) is maintained if the push is equal to the kinetic friction force $f_k = \mu_k F_N = \mu_k mg = 52.8$.

c. We note that the mass of the crate is $165/9.8 = 16.8 \text{ kg}$. The acceleration using the push from part a is

$$a = \frac{84.2 - 52.8}{16.8 \text{ kg}} \approx 1.87 \text{ m/s}^2.$$

84. a. The x component of \vec{F} tries to move the crate while its y component indirectly contributes to the inhibiting effects of friction by increasing the normal force. Newton's second law implies

$$x \text{ direction } F \cos \theta - f_s = 0$$

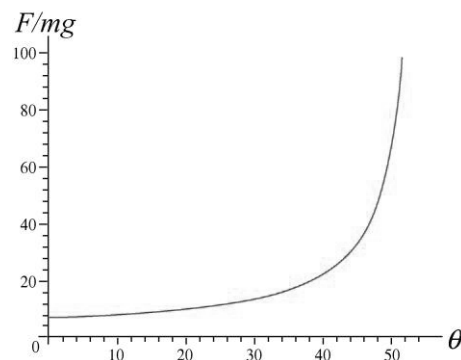
$$y \text{ direction } F_N - F \sin \theta - mg = 0.$$

To be "on the verge of sliding" means $f_s = f_{s \max} = \mu_s F_N$. Solving these equations for F actually for the ratio of F to mg yields

$$\frac{F}{mg} = \frac{\mu_s}{\cos \theta - \mu_s \sin \theta}.$$

This is plotted on the right (θ in degrees).

b. The denominator of our expression for F/mg vanishes when



$$\cos \theta - \mu_s \sin \theta = 0 \Rightarrow \theta_{\text{inf}} = \tan^{-1} \left(\frac{1}{\mu_s} \right)$$

or $\mu_s = 0.70$ we obtain $\theta_{\text{inf}} = \tan^{-1} \left(\frac{1}{\mu_s} \right) = 55^\circ$.

c Reducing the coefficient means increasing the angle by the condition in part b.

d or $\mu_s = 0.60$ we have $\theta_{\text{inf}} = \tan^{-1} \left(\frac{1}{\mu_s} \right) = 59^\circ$.

85. The car is in “danger of sliding” down when

$$\mu_s = \tan \theta = \tan 35.0^\circ = 0.700.$$

This value represents a 3.4% decrease from the given 0.725 value.

86. a The tension will be the greatest at the lowest point of the swing. Note that there is no substantive difference between the tension T in this problem and the normal force F_N in Sample Problem – “Vertical circular loop, Diavolo.” Eq. 6-19 of that Sample Problem examines the situation at the top of the circular path where F_N is the least and rewriting that for the bottom of the path leads to

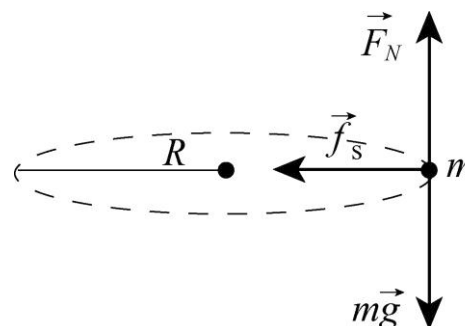
$$T = mg + mv^2/r$$

here F_N is at its greatest value.

b At the breaking point $T = 33 \text{ N} = mg + mv^2/r$ here $m = 0.26 \text{ kg}$ and $r = 0.65 \text{ m}$. Solving for the speed we find that the cord should break when the speed at the lowest point reaches 8.73 m/s .

87. **THINK** The car is making a turn on an unbanked curve. Friction is what provides the centripetal force needed for this circular motion.

EXPRESS The free body diagram is shown to the right. The mass of the car is $m = 10700 \text{ kg}$ $9.80 \text{ kg} = 1.09 \times 10^3 \text{ kg}$. We choose “inward” (horizontally toward the center of the circular path) as the positive direction. The normal force is $F_N = mg$ in this situation and the required frictional force is $f_s = mv^2/R$.



ANALYZE a With a speed of $v = 13.4 \text{ m/s}$ and a radius $R = 61 \text{ m}$, Newton’s second law (using Eq. 6-18) leads to

$$f_s = \frac{mv^2}{R} = \frac{1.09 \times 10^3 \text{ kg } 13.4 \text{ m s}^{-2}}{61.0 \text{ m}} = 3.21 \times 10^3 \text{ N}$$

b. The maximum possible static friction is found to be

$$f_{s \text{ max}} = \mu_s mg = (0.35)(10700 \text{ N}) = 3.75 \times 10^3 \text{ N}$$

using Eq. 6.1. We see that the static friction found in part (a) is less than this, so the car rolls without skidding and successfully negotiates the curve.

LEARN From the above expressions we see that with a coefficient of friction μ_s the maximum speed of the car negotiating a curve of radius R is $v_{\text{max}} = \sqrt{\mu_s g R}$. So in this case the car can go up to a maximum speed of

$$v_{\text{max}} = \sqrt{0.35 \cdot 9.8 \text{ m s}^{-2} \cdot 61 \text{ m}} = 14.5 \text{ m s}^{-1}$$

without skidding.

88. For the $m_2 = 1.0 \text{ kg}$ block, application of Newton's laws result in

$$\begin{aligned} F \cos \theta - T - f_k &= m_2 a & \text{x axis} \\ F_N - F \sin \theta - m_2 g &= 0 & \text{y axis} \end{aligned}$$

Since $f_k = \mu_k F_N$, these equations can be combined into an equation to solve for a

$$F \cos \theta - \mu_k \sin \theta - T - \mu_k m_2 g = m_2 a$$

Similarly, but without the applied push, we analyze the $m_1 = 2.0 \text{ kg}$ block

$$\begin{aligned} T - f'_k &= m_1 a & \text{x axis} \\ F'_N - m_1 g &= 0 & \text{y axis} \end{aligned}$$

Since $f'_k = \mu_k F'_N$, the equations can be combined

$$T - \mu_k m_1 g = m_1 a$$

Subtracting the two equations for a and solving for the tension, we obtain

$$T = \frac{m_1 \cos \theta - \mu_k \sin \theta}{m_1 + m_2} F = \frac{2.0 \text{ kg } \cos 35^\circ - 0.20 \sin 35^\circ}{2.0 \text{ kg} + 1.0 \text{ kg}} 20 \text{ N} = 9.4 \text{ N}$$

89. **THINK** In order to move a filing cabinet, the force applied must be able to overcome the frictional force.

EXPRESS We apply Newton's second law (as $F_{\text{push}} - f = ma$). If we find the applied force F_{push} to be less than $f_{s, \text{ma}}$, the maximum static frictional force, our conclusion would then be "no, the cabinet does not move" (which means a is actually 0 and the frictional force is simply $f = F_{\text{push}}$). On the other hand, if we obtain $a > 0$ then the cabinet moves so $f = f_k$. In our case, $F_{\text{push}} = 222 \text{ N}$ and $f_{s, \text{ma}} = 378 \text{ N}$. Since $F_{\text{push}} < f_{s, \text{ma}}$, the cabinet does not move and the frictional force is simply $f = F_{\text{push}} = 222 \text{ N}$.

$$f_{s, \text{ma}} = \mu_s F_N = \mu_s mg = 0.68 \cdot 556 \text{ N} = 378 \text{ N}.$$

and the kinetic frictional force is

$$f_k = \mu_k F_N = \mu_k mg = 0.56 \cdot 556 \text{ N} = 311 \text{ N}.$$

ANALYZE a. Here we find $F_{\text{push}} = 222 \text{ N}$ and $f_{s, \text{ma}} = 378 \text{ N}$. Since $F_{\text{push}} < f_{s, \text{ma}}$, the cabinet does not move.

b. Here we find $F_{\text{push}} = 334 \text{ N}$ and $f_{s, \text{ma}} = 378 \text{ N}$. Since $F_{\text{push}} < f_{s, \text{ma}}$, the cabinet does not move.

c. Here we have $F_{\text{push}} = 311 \text{ N}$ and $f_{s, \text{ma}} = 378 \text{ N}$. Since $F_{\text{push}} < f_{s, \text{ma}}$, the cabinet does not move.

d. Here we have $F_{\text{push}} = 311 \text{ N}$ and $f_{s, \text{ma}} = 378 \text{ N}$. Since $F_{\text{push}} < f_{s, \text{ma}}$, the cabinet does not move.

e. The cabinet moves in c and d.

LEARN In summary, in order to make the cabinet move, the minimum applied force is equal to the maximum static frictional force $f_{s, \text{ma}}$.

90. Analysis of forces in the horizontal direction: here there can be no acceleration, so $F = F_N$. The magnitude of the normal force is 60 N . The maximum possible static friction force is therefore $\mu_s F_N = 33 \text{ N}$ and the kinetic friction force, when applicable, is $\mu_k F_N = 23 \text{ N}$.

a. In this case $\vec{P} = 34 \text{ N}$ up and to the right. Assuming \vec{f} points down then Newton's second law for the y leads to

$$P - mg - f = ma.$$

If we assume $f = f_s$ and $a = 0$ we obtain $f = 34 - 22 = 12 \text{ N}$. This is less than $f_{s, \text{ma}}$ which shows the consistency of our assumption. The answer is $\vec{f}_s = 12 \text{ N}$ down.

b In this case $\vec{P} = 12$ up and. The above equation with the same assumptions as in part a leads to $f = 12 - 22 = -10$. Thus $f_s < f_{s, \text{max}}$ justifying our assumption that the block is stationary but its negative value tells us that our initial assumption about the direction of \vec{f} is incorrect in this case. Thus the answer is $\vec{f}_s = 10$ up.

c In this case $\vec{P} = 48$ up and. The above equation with the same assumptions as in part a leads to $f = 48 - 22 = 26$. Thus we again have $f_s < f_{s, \text{max}}$ and our answer is $\vec{f}_s = 26$ down.

d In this case $\vec{P} = 62$ up and. The above equation with the same assumptions as in part a leads to $f = 62 - 22 = 40$ which is larger than $f_{s, \text{max}}$ invalidating our assumptions. Therefore we take $f = f_k$ and $a \neq 0$ in the above equation if we wished to find the value of a we could find it to be positive as we should expect. The answer is $\vec{f}_k = 23$ down.

e In this case $\vec{P} = 10$ down and. The above equation but with P replaced with $-P$ with the same assumptions as in part a leads to $f = -10 - 22 = -32$. Thus we have $f_s < f_{s, \text{max}}$ justifying our assumption that the block is stationary but its negative value tells us that our initial assumption about the direction of \vec{f} is incorrect in this case. Thus the answer is $\vec{f}_s = 32$ up.

f In this case $\vec{P} = 18$ down and. The above equation but with P replaced with $-P$ with the same assumptions as in part a leads to $f = -18 - 22 = -40$ which is larger in absolute value than $f_{s, \text{max}}$ invalidating our assumptions. Therefore we take $f = f_k$ and $a \neq 0$ in the above equation if we wished to find the value of a we could find it to be negative as we should expect. The answer is $\vec{f}_k = 23$ up.

g The block moves up the incline in case d where $a > 0$.

h The block moves down the incline in case f where $a < 0$.

i The frictional force \vec{f}_s is directed down in cases a, c and d.

91. THINK Whether the block is sliding down or up the incline there is a frictional force in the opposite direction of the motion.

EXPRESS The free body diagram for the first part of this problem when the block is sliding downhill with zero acceleration is shown next.

Newton's second law gives

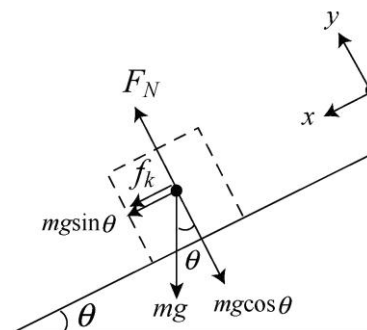
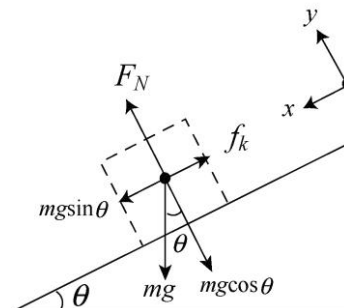
$$\begin{aligned}mg \sin \theta - f_k &= mg \sin \theta - \mu_k F_N = ma_x = 0 \\mg \cos \theta - F_N &= ma_y = 0\end{aligned}$$

These two equations can be combined to give

$$\mu_k = \tan \theta.$$

Now for the second part of the problem with the block projected uphill the friction direction is reversed (see figure to the right). Newton's second law for the uphill motion and 6.12 leads to

$$\begin{aligned}mg \sin \theta + f_k &= mg \sin \theta + \mu_k F_N = ma_x \\mg \cos \theta - F_N &= ma_y = 0\end{aligned}$$



Note that by our convention $a_x > 0$ means that the acceleration is downhill and therefore the speed of the block will decrease as it moves up the incline.

ANALYZE Using $\mu_k = \tan \theta$ and $F_N = mg \cos \theta$ we find the x component of the acceleration to be

$$a_x = g \sin \theta + \frac{\mu_k F_N}{m} = g \sin \theta + \frac{\tan \theta \cdot mg \cos \theta}{m} = 2g \sin \theta.$$

The distance the block travels before coming to a stop can be found by using 2.16 $v_f^2 = v_0^2 - 2a_x \Delta x$ which yields

$$\Delta x = \frac{v_0^2}{2a_x} = \frac{v_0^2}{2 \cdot 2g \sin \theta} = \frac{v_0^2}{4g \sin \theta}.$$

One usually expects $\mu_s > \mu_k$ (see the discussion in Section 6.1). The “angle of repose” is the minimum angle necessary for a stationary block to start sliding downhill; it is $\mu_s = \tan \theta_{\text{repose}}$. Therefore we expect $\theta_{\text{repose}} > \theta$ found in part a. Consequently when the block comes to rest the incline is not steep enough to cause it to start slipping downhill again.

LEARN An alternative way to see that the block will not slide downhill again is to note that the downhill force of gravitation is not large enough to overcome the force of friction i.e. $mg \sin \theta = f_k < f_{s \text{ max}}$.

92. Consider that the car is “on the verge of sliding out” – meaning that the force of static friction is acting “down the bank” (or “downhill” from the point of view of an ant on the banked curve) with maximum possible magnitude. We first consider the vector sum \vec{F} of the maximum static friction force and the normal force. Due to the facts that they are perpendicular and their magnitudes are simply proportional, we find \vec{F} is at angle ϕ measured from the vertical such that $\phi = \theta$ where $\tan \theta_s = \mu_s$ compare with 6.613 and θ is the bank angle. So the vector sum of \vec{F} and the vertically downward pull mg of gravity must be equal to the horizontal centripetal force mv^2/R which leads to a surprisingly simple relationship

$$\tan \phi = \frac{mv^2/R}{mg} = \frac{v^2}{Rg}.$$

Writing this as an expression for the maximum speed we have

$$v_{\text{ma}} = \sqrt{Rg \tan \theta + \tan^{-1} \mu_s} = \sqrt{\frac{Rg \tan \theta + \mu_s}{1 - \mu_s \tan \theta}}.$$

a We note that the given speed is in units roughly 17 m/s. If we do not want the cars to “depend” on the static friction to keep from sliding out (that is, if we want the component “down the bank” of gravity to be sufficient), then we can set $\mu_s = 0$ in the above expression and obtain $v = \sqrt{Rg \tan \theta}$. With $R = 150$ m this leads to $\theta = 11^\circ$.

b If however the curve is not banked so $\theta = 0$ then the above expression becomes

$$v = \sqrt{Rg \tan \tan^{-1} \mu_s} = \sqrt{Rg \mu_s}$$

solving this for the coefficient of static friction $\mu_s = 0.19$.

93. (a) The box doesn’t move until $t = 2.8$ s which is when the applied force \vec{F} reaches a magnitude of $F = 1.8(2.8) = 5.0$ implying therefore that $f_{s \text{ ma}} = 5.0$. Analysis of the vertical forces on the block leads to the observation that the normal force magnitude equals the weight $F_N = mg = 15$. Thus

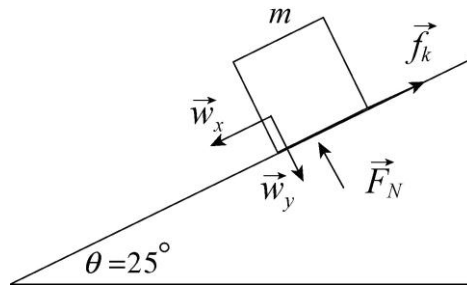
$$\mu_s = f_{s \text{ ma}} / F_N = 0.34.$$

(b) We apply Newton’s second law to the horizontal x axis positive in the direction of motion

$$F - f_k = ma \Rightarrow 1.8t - f_k = (15)(1.2t - 2.4)$$

thus we find $f_k = 3.6$. Therefore $\mu_k = f_k / F_N = 0.24$.

94. In the figure below $m = 140/9.8 = 14.3$ kg is the mass of the child. We use \vec{w}_x and \vec{w}_y as the components of the gravitational pull of earth on the block. Their magnitudes are $w_x = mg \sin \theta$ and $w_y = mg \cos \theta$.



a. With the x axis directed up along the incline so that $a = -0.86 \text{ m/s}^2$, Newton's second law leads to

$$f_k - 140 \sin 25^\circ = m(-0.86)$$

which yields $f_k = 47$ N. We also apply Newton's second law to the y axis perpendicular to the incline surface where the acceleration component is zero

$$F_N - 140 \cos 25^\circ = 0 \Rightarrow F_N = 127 \text{ N}.$$

hence $\mu_k = f_k / F_N = 0.37$.

b. Returning to our first equation in part a we see that if the downhill component of the weight force were insufficient to overcome static friction the child could not slide at all. Therefore we require $140 \sin 25^\circ \leq f_{s \max} = \mu_s F_N$ which leads to $\tan 25^\circ \leq 0.47 \mu_s$.

The minimum value of μ_s equals μ_k and is more subtle reference to 6.1 is recommended. If μ_k exceeded μ_s then static friction would be overcome as the incline is raised then it should start to move – which is impossible if f_k is large enough to cause deceleration. The bounds on μ_s are therefore given by $0.47 \leq \mu_s \leq 0.37$.

95. a. The x component of \vec{F} contributes to the motion of the crate while its y component indirectly contributes to the inhibiting effects of friction by increasing the normal force. Along the y direction we have $F_N - F \cos \theta - mg = 0$ and along the x direction we have $F \sin \theta - f_k = 0$ since it is not accelerating according to the problem.

Also 6.2 gives $f_k = \mu_k F_N$. Solving these equations for F yields

$$F = \frac{\mu_k mg}{\sin \theta - \mu_k \cos \theta}.$$

b. When $\theta < \theta_0 = \tan^{-1} \mu_s$ F will not be able to move the mop head.

96. (a) The distance traveled in one revolution is $2\pi R = 2\pi(4.6 \text{ m}) = 29 \text{ m}$. The constant speed is consequently $v = 29 \text{ m} / 30 \text{ s} = 0.96 \text{ m/s}$.

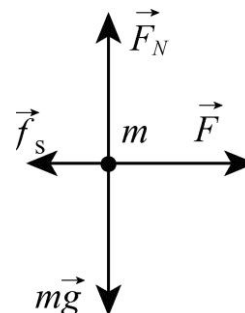
(b) Newton's second law (using Eq. 6.17 for the magnitude of the acceleration) leads to

$$f_s = m \left(\frac{v^2}{R} \right) = m(0.20)$$

in units. Noting that $F_N = mg$ in this situation, the maximum possible static friction is $f_{s \text{ max}} = \mu_s mg$ using Eq. 6.1. Equating this with $f_s = m(0.20)$, we find the mass m cancels and we obtain $\mu_s = 0.20 / 9.8 = 0.021$.

97. **THINK** In this problem a force is applied to accelerate a box. From the distance traveled and the speed at that instant we can calculate the coefficient of kinetic friction between the box and the floor.

EXPRESS The free body diagram is shown to the right. We adopt the familiar axes with x rightward and y upward and refer to the 85 N horizontal push of the worker as F and assume it to be rightward. Applying Newton's second law to the x axis and y axis respectively produces



$$F - f_k = ma_x \quad F_N - mg = 0.$$

On the other hand, using Eq. 2.16, $v^2 = v_0^2 + 2a_x \Delta x$, we find the acceleration to be

$$a_x = \frac{v^2 - v_0^2}{2\Delta x} = \frac{1.0 \text{ m/s}^2 - 0}{2(1.4 \text{ m})} = 0.357 \text{ m/s}^2.$$

The above equations can be combined to give μ_k .

ANALYZE Using $f_k = \mu_k F_N$, we find the coefficient of kinetic friction between the box and the floor to be

$$\mu_k = \frac{f_k}{F_N} = \frac{F - ma_x}{mg} = \frac{85 \text{ N} - 40 \text{ kg}(0.357 \text{ m/s}^2)}{40 \text{ kg}(9.8 \text{ m/s}^2)} = 0.18.$$

LEARN In general, the acceleration can be written as $a_x = (F - \mu_k mg) / m$. We see that the smaller the value of μ_k , the greater the acceleration. In the limit $\mu_k = 0$, we simply have $a_x = F / m$.

98. We resolve this horizontal force into appropriate components.

(a) Applying Newton's second law to the x directed uphill and y directed away from the incline surface we obtain

$$F \cos \theta - f_k - mg \sin \theta = ma$$

$$F_N - F \sin \theta - mg \cos \theta = 0.$$

Since $f_k = \mu_k F_N$ these equations lead to

$$a = \frac{F}{m} \cos \theta - \mu_k \sin \theta - g \sin \theta + \mu_k \cos \theta$$

which yields $a = -2.1 \text{ m/s}^2$ or $a = 2.1 \text{ m/s}^2$ for $\mu_k = 0.30$, $F = 50$ and $m = 5.0 \text{ kg}$.

(b) The direction of \vec{a} is down the plane.

(c) With $v_0 = 4.0 \text{ m/s}$ and $v = 0$, Eq. 2-16 gives $\Delta x = -\frac{4.0 \text{ m/s}^2}{2(-2.1 \text{ m/s}^2)} = 3.9 \text{ m}$.

(d) We expect $\mu_s \geq \mu_k$ otherwise an object started into motion would immediately start decelerating before it gained any speed. In the minimal expectation case where $\mu_s = 0.30$ the maximum possible downhill static friction is using Eq. 6-1

$$f_{s \text{ max}} = \mu_s F_N = \mu_s (F \sin \theta + mg \cos \theta)$$

which turns out to be 21 N. But in order to have no acceleration along the x axis we must have

$$f_s = F \cos \theta - mg \sin \theta = 10$$

the fact that this is positive reinforces our suspicion that \vec{f}_s points downhill. Since the f_s needed to remain at rest is less than $f_{s \text{ max}}$ then it stays at that location.

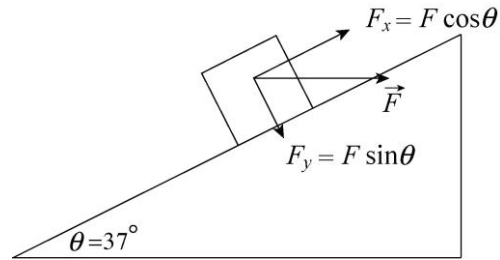
99. (a) We note that $F_N = mg$ in this situation so

$$f_{s \text{ max}} = \mu_s mg = 0.52 (11 \text{ kg})(9.8 \text{ m/s}^2) = 56 \text{ N}.$$

Consequently the horizontal force \vec{F} needed to initiate motion must be at minimum slightly more than 56 N.

(b) Analyzing vertical forces when \vec{F} is at non zero θ yields

$$F \sin \theta + F_N = mg \Rightarrow f_{s \text{ max}} = \mu_s (mg - F \sin \theta).$$



o the horizontal component of \vec{F} needed to initiate motion must be at minimum slightly more than this so

$$F \cos \theta = \mu_s mg - F \sin \theta \Rightarrow F = \frac{\mu_s mg}{\cos \theta + \mu_s \sin \theta}$$

hich yields $F = 59$ hen $\theta = 60^\circ$.

c e no set $\theta = -60^\circ$ and obtain

$$F = \frac{0.52 \cdot 11 \text{ kg} \cdot 9.8 \text{ m/s}^2}{\cos -60^\circ + 0.52 \sin -60^\circ} = 1.1 \times 10^3 \text{ N}.$$

100. a f the skier covers a distance L during time t ith ero initial speed and a constant acceleration a then $L = at^2/2$ hich gives the acceleration a_1 for the first old pair of skis

$$a_1 = \frac{2L}{t_1^2} = \frac{2(200 \text{ m})}{(61 \text{ s})^2} = 0.11 \text{ m/s}^2.$$

b he acceleration a_2 for the second ne pair is

$$a_2 = \frac{2L}{t_2^2} = \frac{2(200 \text{ m})}{(42 \text{ s})^2} = 0.23 \text{ m/s}^2.$$

c he net force along the slope acting on the skier of mass m is

$$F_{\text{net}} = mg \sin \theta - f_k = mg(\sin \theta - \mu_k \cos \theta) = ma$$

hich e solve for μ_{k1} for the first pair of skis

$$\mu_{k1} = \tan \theta - \frac{a_1}{g \cos \theta} = \tan 3.0^\circ - \frac{0.11 \text{ m/s}^2}{9.8 \text{ m/s}^2 \cos 3.0^\circ} = 0.041$$

d or the second pair e have

$$\mu_{k2} = \tan \theta - \frac{a_2}{g \cos \theta} = \tan 3.0^\circ - \frac{0.23 \text{ m/s}^2}{9.8 \text{ m/s}^2 \cos 3.0^\circ} = 0.029.$$

101. If we choose “downhill” positive, then Newton’s law gives

$$mg \sin \theta - f_k = ma$$

for the sliding child. o using . 6 12

$$f_k = \mu_k F_N = \mu_k m g$$

so we obtain $a = g \sin \theta - \mu_k \cos \theta = -0.5 \text{ m/s}^2$ note that the problem gives the direction of the acceleration vector as uphill even though the child is sliding downhill so it is a deceleration. With $\theta = 35^\circ$ we solve for the coefficient and find $\mu_k = 0.76$.

102. a our x direction is horizontal and is chosen as we also do with y so that the components of the 100 force \vec{F} are non negative. thus $F_x = F \cos \theta = 100$ which the textbook denotes F_h in this problem.

b since there is no vertical acceleration, application of Newton's second law in the y direction gives

$$F_N + F_y = mg \Rightarrow F_N = mg - F \sin \theta$$

here $m = 25.0 \text{ kg}$. this yields $F_N = 245$ in this case $\theta = 0^\circ$.

c o $F_x = F_h = F \cos \theta = 86.6$ for $\theta = 30.0^\circ$.

d nd $F_N = mg - F \sin \theta = 195$.

e we find $F_x = F_h = F \cos \theta = 50.0$ for $\theta = 60.0^\circ$.

f nd $F_N = mg - F \sin \theta = 158$.

g the condition for the chair to slide is

$$F_x > f_{s \text{ ma}} = \mu_s F_N \quad \text{here } \mu_s = 0.42.$$

or $\theta = 0^\circ$ we have

$$F_x = 100 < f_{s \text{ ma}} = 0.42 \cdot 245 = 103$$

so the crate remains at rest.

h or $\theta = 30.0^\circ$ we find $F_x = 86.6 > f_{s \text{ ma}} = 0.42 \cdot 195 = 81.9$ so the crate slides.

i or $\theta = 60^\circ$ we get $F_x = 50.0 < f_{s \text{ ma}} = 0.42 \cdot 158 = 66.4$ which means the crate must remain at rest.

103. a the intuitive conclusion that the tension is greatest at the bottom of the swing is certainly supported by application of Newton's second law there:

$$T - mg = \frac{mv^2}{R} \Rightarrow T = m \left(g + \frac{v^2}{R} \right)$$

here $g = 9.8 \text{ m/s}^2$ has been used. Increasing the speed eventually leads to the tension at the bottom of the circle reaching that breaking value of 40 N .

b Solving the above equation for the speed we find

$$v = \sqrt{R \left(\frac{T}{m} - g \right)} = \sqrt{0.91 \text{ m} \left(\frac{40}{0.37 \text{ kg}} - 9.8 \text{ m/s}^2 \right)}$$

which yields $v = 9.5 \text{ m/s}$.

104. a The component of the weight along the incline with downhill understood as the positive direction is $mg \sin \theta$ here $m = 630 \text{ kg}$ and $\theta = 10.2^\circ$. With $f = 62.0 \text{ N}$, Newton's second law leads to $mg \sin \theta - f = ma$ which yields $a = 1.64 \text{ m/s}^2$. Using $s = 215 \text{ m}$ we have

$$80.0 \text{ m} = \left(6.20 \frac{\text{m}}{\text{s}} \right) t + \frac{1}{2} \left(1.64 \frac{\text{m}}{\text{s}^2} \right) t^2.$$

This is solved using the quadratic formula. The positive root is $t = 6.80 \text{ s}$.

b Running through the calculation of part a with $f = 42.0 \text{ N}$ instead of $f = 62 \text{ N}$ results in $t = 6.76 \text{ s}$.

105. Except for replacing f_s with f_k Fig. 6-5 in the textbook is appropriate. With that figure in mind we choose uphill as the x direction. Applying Newton's second law to the x axis we have

$$f_k - W \sin \theta = ma \quad \text{here } m = \frac{W}{g}$$

and here $W = 40 \text{ N}$, $a = 0.80 \text{ m/s}^2$ and $\theta = 25^\circ$. Thus we find $f_k = 20 \text{ N}$. Along the y axis we have

$$\sum \vec{F}_y = 0 \Rightarrow F_N = W \cos \theta$$

so that $\mu_k = f_k / F_N = 0.56$.

Chapter

1. **THINK** As the proton is being accelerated its speed increases and so does its kinetic energy.

EXPRESS To calculate the speed of the proton at a later time we use the equation $v^2 = v_0^2 + 2a\Delta x$ from Table 2-1. The change in kinetic energy is then equal to

$$\Delta K = \frac{1}{2}m(v_f^2 - v_i^2).$$

ANALYZE With $\Delta x = 3.5 \text{ cm} = 0.035 \text{ m}$ and $a = 3.6 \times 10^{15} \text{ m/s}^2$ we find the proton speed to be

$$v = \sqrt{v_0^2 + 2a\Delta x} = \sqrt{(2.4 \times 10^7 \text{ m/s})^2 + 2(3.6 \times 10^{15} \text{ m/s}^2)(0.035 \text{ m})} = 2.9 \times 10^7 \text{ m/s}.$$

b The initial kinetic energy is

$$K_i = \frac{1}{2}mv_0^2 = \frac{1}{2}(1.67 \times 10^{-27} \text{ kg})(2.4 \times 10^7 \text{ m/s})^2 = 4.8 \times 10^{-13} \text{ J}$$

and the final kinetic energy is

$$K_f = \frac{1}{2}mv^2 = \frac{1}{2}(1.67 \times 10^{-27} \text{ kg})(2.9 \times 10^7 \text{ m/s})^2 = 6.9 \times 10^{-13} \text{ J}.$$

Thus the change in kinetic energy is

$$\Delta K = K_f - K_i = 6.9 \times 10^{-13} \text{ J} - 4.8 \times 10^{-13} \text{ J} = 2.1 \times 10^{-13} \text{ J}.$$

LEARN The change in kinetic energy can be rewritten as

$$\Delta K = \frac{1}{2}m(v_f^2 - v_i^2) = \frac{1}{2}m(2a\Delta x) = ma\Delta x = F\Delta x = W$$

which according to the work-kinetic energy theorem is simply the work done on the particle.

2. With speed $v = 11200 \text{ m s}^{-1}$ we find

$$K = \frac{1}{2}mv^2 = \frac{1}{2} (2.9 \times 10^5 \text{ kg}) (11200 \text{ m s}^{-1})^2 = 1.8 \times 10^{13} \text{ J}.$$

3. a The change in kinetic energy for the meteorite would be

$$\Delta K = K_f - K_i = -K_i = -\frac{1}{2}m_i v_i^2 = -\frac{1}{2}(4 \times 10^6 \text{ kg})(15 \times 10^3 \text{ m s}^{-1})^2 = -5 \times 10^{14} \text{ J}$$

or $\Delta K = 5 \times 10^{14} \text{ J}$. The negative sign indicates that kinetic energy is lost.

- b The energy loss in units of megatons of TNT would be

$$-\Delta K = (5 \times 10^{14} \text{ J}) \left(\frac{1 \text{ megaton}}{4.2 \times 10^{15} \text{ J}} \right) = 0.1 \text{ megaton}.$$

- c The number of bombs N that the meteorite impact would correspond to is found by noting that megaton = 1000 kilotons and setting up the ratio

$$N = \frac{0.1 \times 1000 \text{ kiloton}}{13 \text{ kiloton}} = 8.$$

4. a We set up the ratio

$$\frac{50 \text{ km}}{1 \text{ km}} = \left(\frac{E}{1 \text{ megaton}} \right)^{1/3}$$

and find $E = 50^3 \approx 1 \times 10^5$ megatons of TNT.

- b We note that 15 kilotons is equivalent to 0.015 megatons. Dividing the result from part a by 0.013 yields about ten million 10^7 bombs.

5. We denote the mass of the father as m and his initial speed v_i . The initial kinetic energy of the father is

$$K_i = \frac{1}{2} K_{\text{son}}$$

and his final kinetic energy when his speed is $v_f = v_i + 1.0 \text{ m s}^{-1}$ is $K_f = K_{\text{son}}$. We use these relations along with $v_f = v_i + 1.0$ in our solution.

- a We see from the above that $K_i = \frac{1}{2} K_f$ which with units understood leads to

$$\frac{1}{2}mv_i^2 = \frac{1}{2} \left[\frac{1}{2}m (v_i + 1.0 \text{ m/s})^2 \right].$$

The mass cancels and we find a second degree equation for v_i : $\frac{1}{2}v_i^2 - v_i - \frac{1}{2} = 0$. The positive root from the quadratic formula yields $v_i = 2.4 \text{ m/s}$.

b. From the first relation above ($K_i = \frac{1}{2}K_{\text{son}}$) we have

$$\frac{1}{2}mv_i^2 = \frac{1}{2} \left(\frac{1}{2}m (2v_i)^2 \right)$$

and after canceling m and one factor of $1/2$ are led to $v_{\text{son}} = 2v_i = 4.8 \text{ m/s}$.

6. We apply the equation $x(t) = x_0 + v_0t + \frac{1}{2}at^2$ found in Table 2.1. Since at $t = 0 \text{ s}$ $x_0 = 0$ and $v_0 = 12 \text{ m/s}$ the equation becomes in unit of meters

$$x(t) = 12t + \frac{1}{2}at^2.$$

With $x = 10 \text{ m}$ when $t = 1.0 \text{ s}$ the acceleration is found to be $a = -4.0 \text{ m/s}^2$. The fact that $a < 0$ implies that the bead is decelerating. Thus the position is described by $x(t) = 12t - 2.0t^2$. Differentiating x with respect to t then yields

$$v(t) = \frac{dx}{dt} = 12 - 4.0t.$$

Indeed at $t = 3.0 \text{ s}$ $v(t) = 3.0 = 0$ and the bead stops momentarily. The speed at $t = 1.0 \text{ s}$ is $v(t) = 12 - 4.0 = 8.0 \text{ m/s}$ and the corresponding kinetic energy is

$$K = \frac{1}{2}mv^2 = \frac{1}{2} (1.8 \times 10^{-2} \text{ kg}) (8.0 \text{ m/s})^2 = 7.1 \text{ J}.$$

7. Since this involves constant acceleration motion we can apply the equations of Table 2.1 such as $x = v_0t + \frac{1}{2}at^2$ here $x_0 = 0$. We choose to analyze the third and fifth points obtaining

$$0.2 \text{ m} = v_0 (1.0 \text{ s}) + \frac{1}{2}a (1.0 \text{ s})^2$$

$$0.8 \text{ m} = v_0 (2.0 \text{ s}) + \frac{1}{2}a (2.0 \text{ s})^2.$$

Simultaneous solution of the equations leads to $v_0 = 0$ and $a = 0.40 \text{ m/s}^2$. We now have two ways to finish the problem. One is to compute force from $F = ma$ and then obtain the work from Eq. 7-7. The other is to find ΔK as a way of computing W in accordance with Eq. 7-10. In this latter approach we find the velocity at $t = 2.0 \text{ s}$ from $v = v_0 + at$ so $v = 0.80 \text{ m/s}$. Thus

$$W = \Delta K = \frac{1}{2} (3.0 \text{ kg}) (0.80 \text{ m/s})^2 = 0.96 \text{ J}.$$

8. Using Eqs. 7-8 and 7-3 we find the work done by the water on the ice block

$$W = \vec{F} \cdot \vec{d} = [210 \text{ N} \hat{i} - 150 \text{ N} \hat{j}] \cdot [15 \text{ m} \hat{i} - 12 \text{ m} \hat{j}] = 210 \text{ N} (15 \text{ m}) + (-150 \text{ N}) (-12 \text{ m}) \\ = 5.0 \times 10^3 \text{ J}.$$

9. By the work-kinetic energy theorem

$$W = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \frac{1}{2} (2.0 \text{ kg}) (6.0 \text{ m/s}^2 - 4.0 \text{ m/s}^2) = 20 \text{ J}.$$

We note that the *directions* of \vec{v}_f and \vec{v}_i play no role in the calculation.

10. Equation 7-8 readily yields

$$W = F_x \Delta x + F_y \Delta y = (2.0 \text{ N} \cos 100^\circ) (3.0 \text{ m}) + (2.0 \text{ N} \sin 100^\circ) (4.0 \text{ m}) = 6.8 \text{ J}.$$

11. Using the work-kinetic energy theorem we have

$$\Delta K = W = \vec{F} \cdot \vec{d} = Fd \cos \phi.$$

In addition $F = 12 \text{ N}$ and $d = \sqrt{(2.00 \text{ m})^2 + (-4.00 \text{ m})^2 + (3.00 \text{ m})^2} = 5.39 \text{ m}$.

a. If $\Delta K = +30.0 \text{ J}$ then

$$\phi = \cos^{-1} \left(\frac{\Delta K}{Fd} \right) = \cos^{-1} \left(\frac{30.0}{(12.0 \text{ N})(5.39 \text{ m})} \right) = 62.3^\circ.$$

b. If $\Delta K = -30.0 \text{ J}$ then

$$\phi = \cos^{-1} \left(\frac{\Delta K}{Fd} \right) = \cos^{-1} \left(\frac{-30.0}{(12.0 \text{ N})(5.39 \text{ m})} \right) = 118^\circ.$$

12. a. From Eq. 7-6 $F = W/x = 3.00 \text{ N}$ this is the slope of the graph.

b. Equation 7.10 yields $K = K_i$, $W = 3.00 - 6.00 = -9.00$ J.

13. We choose x as the direction of motion so \vec{a} and \vec{F} are negative valued.

(a) Newton's second law readily yields $\vec{F} = (85 \text{ kg})(-2.0 \text{ m/s}^2)$ so that

$$F = |\vec{F}| = 1.7 \times 10^2 \text{ N}.$$

b. From Eq. 2.16 with $v = 0$ we have

$$0 = v_0^2 + 2a\Delta x \Rightarrow \Delta x = -\frac{(37 \text{ m/s})^2}{2(-2.0 \text{ m/s}^2)} = 3.4 \times 10^2 \text{ m}.$$

Alternatively, this can be worked using the work-energy theorem.

c. Since \vec{F} is opposite to the direction of motion so the angle ϕ between \vec{F} and $\vec{d} = \Delta x$ is 180° then Eq. 7.7 gives the work done as $W = -F\Delta x = -5.8 \times 10^4$ J.

(d) In this case, Newton's second law yields $\vec{F} = (85 \text{ kg})(-4.0 \text{ m/s}^2)$ so that $F = |\vec{F}| = 3.4 \times 10^2$ N.

e. From Eq. 2.16 we now have

$$\Delta x = -\frac{(37 \text{ m/s})^2}{2(-4.0 \text{ m/s}^2)} = 1.7 \times 10^2 \text{ m}.$$

f. The force \vec{F} is again opposite to the direction of motion so the angle ϕ is again 180° so that Eq. 7.7 leads to $W = -F\Delta x = -5.8 \times 10^4$ J. The fact that this agrees with the result of part c provides insight into the concept of work.

14. The forces are all constant so the total work done by them is given by $W = F_{\text{net}}\Delta x$ where F_{net} is the magnitude of the net force and Δx is the magnitude of the displacement. We add the three vectors finding the x and y components of the net force

$$F_{\text{net},x} = -F_1 - F_2 \sin 50.0^\circ + F_3 \cos 35.0^\circ = -3.00 - 4.00 \sin 35.0^\circ + 10.0 \cos 35.0^\circ = 2.13$$

$$F_{\text{net},y} = -F_2 \cos 50.0^\circ + F_3 \sin 35.0^\circ = -4.00 \cos 50.0^\circ + 10.0 \sin 35.0^\circ = 3.17$$

The magnitude of the net force is

$$F_{\text{net}} = \sqrt{F_{\text{net},x}^2 + F_{\text{net},y}^2} = \sqrt{2.13^2 + 3.17^2} = 3.82 \text{ N}.$$

the work done by the net force is

$$W = F_{\text{net}} d = (3.82 \text{ N})(4.00 \text{ m}) = 15.3 \text{ J}.$$

here we have used the fact that $\vec{d} \parallel \vec{F}_{\text{net}}$ which follows from the fact that the canister started from rest and moved horizontally under the action of horizontal forces — the resultant effect of which is expressed by \vec{F}_{net} .

15. a. The forces are constant so the work done by any one of them is given by $W = \vec{F} \cdot \vec{d}$ where \vec{d} is the displacement. Since \vec{F}_1 is in the direction of the displacement so

$$W_1 = F_1 d \cos \phi_1 = (5.00 \text{ N})(3.00 \text{ m}) \cos 0^\circ = 15.0 \text{ J}.$$

Since \vec{F}_2 makes an angle of 120° with the displacement so

$$W_2 = F_2 d \cos \phi_2 = (9.00 \text{ N})(3.00 \text{ m}) \cos 120^\circ = -13.5 \text{ J}.$$

Since \vec{F}_3 is perpendicular to the displacement so

$$W_3 = F_3 d \cos \phi_3 = 0 \text{ since } \cos 90^\circ = 0.$$

The net work done by the three forces is

$$W = W_1 + W_2 + W_3 = 15.0 \text{ J} - 13.5 \text{ J} + 0 = +1.50 \text{ J}.$$

b. If no other forces do work on the box its kinetic energy increases by 1.50 J during the displacement.

16. The change in kinetic energy can be written as

$$\Delta K = \frac{1}{2} m (v_f^2 - v_i^2) = \frac{1}{2} m (2a\Delta x) = ma\Delta x$$

here we have used $v_f^2 = v_i^2 + 2a\Delta x$ from Table 2.1. From the figure we see that $\Delta K = 0 - 30 \text{ J} = -30 \text{ J}$ when $\Delta x = +5 \text{ m}$. The acceleration can then be obtained as

$$a = \frac{\Delta K}{m\Delta x} = \frac{-30 \text{ J}}{(8.0 \text{ kg})(5.0 \text{ m})} = -0.75 \text{ m/s}^2.$$

The negative sign indicates that the mass is decelerating. From the figure we also see that when $x = 5 \text{ m}$ the kinetic energy becomes zero implying that the mass comes to rest momentarily. Thus

$$v_0^2 = v^2 - 2a\Delta x = 0 - 2(-0.75 \text{ m/s}^2)(5.0 \text{ m}) = 7.5 \text{ m}^2/\text{s}^2$$

or $v_0 = 2.7 \text{ m/s}$. The speed of the object when $x = -3.0 \text{ m}$ is

$$v = \sqrt{v_0^2 + 2a\Delta x} = \sqrt{7.5 \text{ m}^2/\text{s}^2 + 2(-0.75 \text{ m/s}^2)(-3.0 \text{ m})} = \sqrt{12} \text{ m/s} = 3.5 \text{ m/s}.$$

17. THINK The helicopter does work to lift the astronaut upward against gravity. The work done on the astronaut is converted to the kinetic energy of the astronaut.

EXPRESS We use \vec{F} to denote the upward force exerted by the cable on the astronaut. The force of the cable is upward and the force of gravity is mg downward. Furthermore the acceleration of the astronaut is $a = g/10$ upward. According to Newton's second law the force is given by

$$F - mg = ma \Rightarrow F = m(g + a) = \frac{11}{10}mg$$

in the same direction as the displacement. On the other hand the force of gravity has magnitude $F_g = mg$ and is opposite in direction to the displacement.

ANALYZE a) Since the force of the cable \vec{F} and the displacement \vec{d} are in the same direction the work done by \vec{F} is

$$W_F = Fd = \frac{11mgd}{10} = \frac{11(72 \text{ kg})(9.8 \text{ m/s}^2)(15 \text{ m})}{10} = 1.164 \times 10^4 \approx 1.2 \times 10^4 \text{ J}.$$

b) Since the work done by gravity is

$$W_g = -F_g d = -mgd = -(72 \text{ kg})(9.8 \text{ m/s}^2)(15 \text{ m}) = -1.058 \times 10^4 \approx -1.1 \times 10^4 \text{ J}.$$

c) The total work done is the sum of the two works

$$W_{\text{net}} = W_F + W_g = 1.164 \times 10^4 - 1.058 \times 10^4 = 1.06 \times 10^3 \approx 1.1 \times 10^3 \text{ J}.$$

Since the astronaut started from rest the work kinetic energy theorem tells us that this is her final kinetic energy.

d) Since $K = \frac{1}{2}mv^2$ her final speed is $v = \sqrt{\frac{2K}{m}} = \sqrt{\frac{2(1.06 \times 10^3 \text{ J})}{72 \text{ kg}}} = 5.4 \text{ m/s}.$

LEARN For a general upward acceleration a the net work done is

$$W_{\text{net}} = W_F + W_g = Fd - F_g d = m(g + a)d - mgd = mad.$$

Since $W_{\text{net}} = \Delta K = mv^2/2$ by the work kinetic energy theorem the speed of the astronaut could be $v = \sqrt{2ad}$ which is independent of the mass of the astronaut. In our case $v = \sqrt{2(9.8 \text{ m/s}^2)(10.15 \text{ m})} = 5.4 \text{ m/s}$ which agrees with that calculated in d.

18. In both cases there is no acceleration so the lifting force is equal to the weight of the object.

a. Equation 7.8 leads to $W = \vec{F} \cdot \vec{d} = 360 \text{ k} \cdot 0.10 \text{ m} = 36 \text{ kJ}$.

b. In this case we find $W = 4000 \cdot 0.050 \text{ m} = 2.0 \times 10^2 \text{ J}$.

19. Equation 7.15 applies but the wording of the problem suggests that it is only necessary to examine the contribution from the rope (which would be the “ W_a ” term in Eq. 7.15)

$$W_a = -50 \cdot 0.50 \text{ m} = -25 \text{ J}$$

the minus sign arises from the fact that the pull from the rope is anti parallel to the direction of motion of the block. Thus the kinetic energy could have been 25 J greater if the rope had not been attached given the same displacement.

20. From the figure one may write the kinetic energy in units of J as a function of x as

$$K = K_s - 20x = 40 - 20x.$$

Since $W = \Delta K = \vec{F}_x \cdot \Delta x$ the component of the force along the x axis is $F_x = dK/dx = -20 \text{ N}$. The normal force on the block is $F_N = F_y$ which is related to the gravitational force by

$$mg = \sqrt{F_x^2 + F_y^2}.$$

Note that F_N points in the opposite direction of the component of the gravitational force. With an initial kinetic energy $K_s = 40.0 \text{ J}$ and $v_0 = 4.00 \text{ m/s}$ the mass of the block is

$$m = \frac{2K_s}{v_0^2} = \frac{2(40.0)}{(4.00 \text{ m/s})^2} = 5.00 \text{ kg}.$$

Thus the normal force is

$$F_y = \sqrt{(mg)^2 - F_x^2} = \sqrt{(5.0 \text{ kg} \cdot 9.8 \text{ m/s}^2)^2 - (20)^2} = 44.7 \text{ N} \approx 45 \text{ N}.$$

21. **THINK** In this problem the cord is doing work on the block so that it does not undergo free fall.

EXPRESS We use F to denote the magnitude of the force of the cord on the block. This force is upward and opposite to the force of gravity which has magnitude $F_g = Mg$ to prevent the block from undergoing free fall. The acceleration is $\vec{a} = g/4$ downward. Taking the downward direction to be positive, then Newton's second law yields

$$\vec{F}_{\text{net}} = m\vec{a} \Rightarrow Mg - F = M\left(\frac{g}{4}\right)$$

so $F = 3Mg/4$ in the opposite direction of the displacement. On the other hand the force of gravity $F_g = mg$ is in the same direction to the displacement.

ANALYZE (a) Since the displacement is downward, the work done by the cord's force is using Eq. 7.7

$$W_F = -Fd = -\frac{3}{4}Mgd.$$

(b) Similarly the work done by the force of gravity is $W_g = F_g d = Mgd$.

(c) The total work done on the block is simply the sum of the two works

$$W_{\text{net}} = W_F + W_g = -\frac{3}{4}Mgd + Mgd = \frac{1}{4}Mgd.$$

Since the block starts from rest we use Eq. 7.15 to conclude that this $(Mgd/4)$ is the block's kinetic energy K at the moment it has descended the distance d .

(d) With $K = \frac{1}{2}Mv^2$ the speed is

$$v = \sqrt{\frac{2K}{M}} = \sqrt{\frac{2(Mgd/4)}{M}} = \sqrt{\frac{gd}{2}}$$

at the moment the block has descended the distance d .

LEARN For a general downward acceleration a the force exerted by the cord is $F = m(g - a)$ so that the net work done on the block is $W_{\text{net}} = F_{\text{net}}d = mad$. The speed of the block after falling a distance d is $v = \sqrt{2ad}$. In the special case where the block hangs still $a = 0$, $F = mg$ and $v = 0$. In our case $a = g/4$ and $v = \sqrt{2(g/4)d} = \sqrt{gd/2}$ which agrees with that calculated in (d).

22. We use d to denote the magnitude of the spelunker's displacement during each stage. The mass of the spelunker is $m = 80.0$ kg. The work done by the lifting force is denoted W_i here $i = 1, 2, 3$ for the three stages. We apply the work-energy theorem (7.17–15).

a. For stage 1 $W_1 - mgd = \Delta K_1 = \frac{1}{2}mv_1^2$ here $v_1 = 5.00$ m/s. This gives

$$W_1 = mgd + \frac{1}{2}mv_1^2 = (80.0 \text{ kg})(9.80 \text{ m/s}^2)(10.0 \text{ m}) + \frac{1}{2}(80.0 \text{ kg})(5.00 \text{ m/s})^2 = 8.84 \times 10^3 \text{ J}.$$

b. For stage 2 $W_2 - mgd = \Delta K_2 = 0$ which leads to

$$W_2 = mgd = (80.0 \text{ kg})(9.80 \text{ m/s}^2)(10.0 \text{ m}) = 7.84 \times 10^3 \text{ J}.$$

c. For stage 3 $W_3 - mgd = \Delta K_3 = -\frac{1}{2}mv_1^2$. We obtain

$$W_3 = mgd - \frac{1}{2}mv_1^2 = (80.0 \text{ kg})(9.80 \text{ m/s}^2)(10.0 \text{ m}) - \frac{1}{2}(80.0 \text{ kg})(5.00 \text{ m/s})^2 = 6.84 \times 10^3 \text{ J}.$$

23. The fact that the applied force \vec{F}_a causes the block to move up a frictionless ramp at a constant speed implies that there is no net change in the kinetic energy $\Delta K = 0$. Thus the work done by \vec{F}_a must be equal to the negative work done by gravity $W_a = -W_g$. Since the block is displaced vertically upward by $h = 0.150$ m we have

$$W_a = +mgh = (3.00 \text{ kg})(9.80 \text{ m/s}^2)(0.150 \text{ m}) = 4.41 \text{ J}.$$

24. a. Using notation common to many vector-capable calculators we have from (7.78) $W = \text{dot}(20.0, 0, 0 - 3.00, 9.8, 0.500) \angle 30.0 = 1.31 \text{ J}$, where “dot” stands for dot product.

b. (7.10) along with (7.1) then leads to $v = \sqrt{2(1.31 \text{ J})/3.00 \text{ kg}} = 0.935 \text{ m/s}$.

25. a. The net upward force is given by

$$F + F_N - (m + M)g = (m + M)a$$

here $m = 0.250$ kg is the mass of the cheese, $M = 900$ kg is the mass of the elevator cab, F is the force from the cable, and $F_N = 3.00$ N is the normal force on the cheese. In the cheese alone we have

$$F_N - mg = ma \Rightarrow a = \frac{3.00 \text{ N} - (0.250 \text{ kg})(9.80 \text{ m/s}^2)}{0.250 \text{ kg}} = 2.20 \text{ m/s}^2.$$

thus the force from the cable is $F = (m + M)a + mg - F_N = 1.08 \times 10^4$ and the work done by the cable on the cab is

$$W = Fd_1 = 1.80 \times 10^4 \text{ J} \quad 2.40 \text{ m} = 2.59 \times 10^4 \text{ J}.$$

b. If $W = 92.61 \text{ kJ}$ and $d_2 = 10.5 \text{ m}$ the magnitude of the normal force is

$$F_N = (m + M)g - \frac{W}{d_2} = 0.250 \text{ kg} + 900 \text{ kg} \cdot 9.80 \text{ m/s}^2 - \frac{9.261 \times 10^4}{10.5 \text{ m}} = 2.45 \text{ kN}.$$

26. We make use of Eqs. 7-25 and 7-28 since the block is stationary before and after the displacement. The work done by the applied force can be written as

$$W_a = -W_s = \frac{1}{2}k(x_f^2 - x_i^2).$$

The spring constant is $k = 80 \text{ N/cm} = 8.0 \times 10^3 \text{ N/m}$. With $W_a = 4.0 \text{ J}$ and $x_i = -2.0 \text{ cm}$ we have

$$x_f = \pm \sqrt{\frac{2W_a}{k} + x_i^2} = \pm \sqrt{\frac{2(4.0 \text{ J})}{8.0 \times 10^3 \text{ N/m}} + (-0.020 \text{ m})^2} = \pm 0.049 \text{ m} = \pm 4.9 \text{ cm}.$$

27. From Eqs. 7-25 we see that the work done by the spring force is given by

$$W_s = \frac{1}{2}k(x_i^2 - x_f^2).$$

The fact that 360 J of force must be applied to pull the block to $x = 4.0 \text{ cm}$ implies that the spring constant is

$$k = \frac{360 \text{ J}}{4.0 \text{ cm}} = 90 \text{ J/cm} = 9.0 \times 10^3 \text{ N/m}.$$

a. When the block moves from $x_i = +5.0 \text{ cm}$ to $x = +3.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (9.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - 0.030 \text{ m}^2) = 7.2 \text{ J}.$$

b. Moving from $x_i = +5.0 \text{ cm}$ to $x = -3.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (9.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - (-0.030 \text{ m})^2) = 7.2 \text{ J}.$$

c Moving from $x_i = +5.0$ cm to $x = -5.0$ cm we have

$$W_s = \frac{1}{2} (9.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - -0.050 \text{ m}^2) = 0 \text{ J}.$$

d Moving from $x_i = +5.0$ cm to $x = -9.0$ cm we have

$$W_s = \frac{1}{2} (9.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - -0.090 \text{ m}^2) = -25 \text{ J}.$$

28. The spring constant is $k = 100 \text{ N/m}$ and the maximum elongation is $x_i = 5.00 \text{ m}$.
 sing . 7 25 With $x_f = 0$ the work is found to be

$$W = \frac{1}{2} k x_i^2 = \frac{1}{2} (100 \text{ N/m}) (5.00 \text{ m})^2 = 1.25 \times 10^3 \text{ J}.$$

29. The work done by the spring force is given by . 7 25 $W_s = \frac{1}{2} k (x_i^2 - x_f^2)$. The
 spring constant k can be deduced from the figure which shows the amount of work done
 to pull the block from 0 to $x = 3.0$ cm. The parabola $W_a = kx^2/2$ contains (0, 0), (2.0 cm,
 0.40 J) and (3.0 cm, 0.90 J). Thus we may infer from the data that $k = 2.0 \times 10^3 \text{ N/m}$.

a When the block moves from $x_i = +5.0$ cm to $x = +4.0$ cm we have

$$W_s = \frac{1}{2} (2.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - 0.040 \text{ m}^2) = 0.90 \text{ J}.$$

b Moving from $x_i = +5.0$ cm to $x = -2.0$ cm we have

$$W_s = \frac{1}{2} (2.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - -0.020 \text{ m}^2) = 2.1 \text{ J}.$$

c Moving from $x_i = +5.0$ cm to $x = -5.0$ cm we have

$$W_s = \frac{1}{2} (2.0 \times 10^3 \text{ N/m}) (0.050 \text{ m}^2 - -0.050 \text{ m}^2) = 0 \text{ J}.$$

30. Hooke's law and the work done by a spring is discussed in the chapter. We apply the
 work kinetic energy theorem in the form of $\Delta K = W_a + W_s$ to the points in the figure at x
 $= 1.0 \text{ m}$ and $x = 2.0 \text{ m}$, respectively. The "applied" work W_a is that due to the constant
 force \vec{P} .

$$4 = P(1.0 \text{ m}) - \frac{1}{2}k(1.0 \text{ m})^2$$

$$0 = P(2.0 \text{ m}) - \frac{1}{2}k(2.0 \text{ m})^2.$$

a simultaneous solution leads to $P = 8.0 \text{ N}$.

b similarly we find $k = 8.0 \text{ N/m}$.

31. **THINK** The applied force varies with x so an integration is required to calculate the work done on the body.

EXPRESS As the body moves along the x axis from $x_i = 3.0 \text{ m}$ to $x_f = 4.0 \text{ m}$ the work done by the force is

$$W = \int_{x_i}^{x_f} F_x dx = \int_{x_i}^{x_f} -6x dx = -3x_f^2 - x_i^2 = -3(4.0^2 - 3.0^2) = -21 \text{ J}.$$

According to the work kinetic energy theorem this gives the change in the kinetic energy

$$W = \Delta K = \frac{1}{2}m(v_f^2 - v_i^2)$$

here v_i is the initial velocity at x_i and v_f is the final velocity at x_f . Given v_i we can readily calculate v_f .

ANALYZE a The work kinetic theorem yields

$$v_f = \sqrt{\frac{2W}{m} + v_i^2} = \sqrt{\frac{2(-21 \text{ J})}{2.0 \text{ kg}} + (8.0 \text{ m/s})^2} = 6.6 \text{ m/s}.$$

b The velocity of the particle is $v_f = 5.0 \text{ m/s}$ when it is at $x = x_f$. The work kinetic energy theorem is used to solve for x_f . The net work done on the particle is $W = -3(x_f^2 - x_i^2)$ so the theorem leads to

$$W = \Delta K \Rightarrow -3(x_f^2 - x_i^2) = \frac{1}{2}m(v_f^2 - v_i^2).$$

thus

$$x_f = \sqrt{-\frac{m}{6}(v_f^2 - v_i^2) + x_i^2} = \sqrt{-\frac{2.0 \text{ kg}}{6}((5.0 \text{ m/s})^2 - (8.0 \text{ m/s})^2) + (3.0 \text{ m})^2} = 4.7 \text{ m}.$$

LEARN Since $x_f > x_i$, $W = -3(x_f^2 - x_i^2) < 0$ i.e. the work done by the force is negative.

From the work kinetic energy theorem this implies $\Delta K < 0$. Hence the speed of the particle will continue to decrease as it moves in the x direction.

32. The work done by the spring force is given by Eq. 7-25 $W_s = \frac{1}{2}k(x_i^2 - x_f^2)$. Since $F_x = -kx$ the slope in Fig. 7-37 corresponds to the spring constant k . Its value is given by $k = 80 \text{ N/m} = 8.0 \times 10^3 \text{ N/m}$.

a. When the block moves from $x_i = +8.0 \text{ cm}$ to $x = +5.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (8.0 \times 10^3 \text{ N/m}) (0.080 \text{ m}^2 - 0.050 \text{ m}^2) = 15.6 \text{ J} \approx 16 \text{ J}.$$

b. Moving from $x_i = +8.0 \text{ cm}$ to $x = -5.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (8.0 \times 10^3 \text{ N/m}) (0.080 \text{ m}^2 - (-0.050 \text{ m})^2) = 15.6 \text{ J} \approx 16 \text{ J}.$$

c. Moving from $x_i = +8.0 \text{ cm}$ to $x = -8.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (8.0 \times 10^3 \text{ N/m}) (0.080 \text{ m}^2 - (-0.080 \text{ m})^2) = 0 \text{ J}.$$

d. Moving from $x_i = +8.0 \text{ cm}$ to $x = -10.0 \text{ cm}$ we have

$$W_s = \frac{1}{2} (8.0 \times 10^3 \text{ N/m}) (0.080 \text{ m}^2 - (-0.10 \text{ m})^2) = -14.4 \text{ J} \approx -14 \text{ J}.$$

33. a. This is a situation where Eq. 7-28 applies so we have

$$Fx = \frac{1}{2}kx^2 \Rightarrow 3.0 \text{ N} x = \frac{1}{2} (50 \text{ N/m}) x^2$$

which other than the trivial root gives $x = 3.0/25 \text{ m} = 0.12 \text{ m}$.

b. The work done by the applied force is $W_a = Fx = (3.0 \text{ N})(0.12 \text{ m}) = 0.36 \text{ J}$.

c. Eq. 7-28 immediately gives $W_s = -W_a = -0.36 \text{ J}$.

d. With $K_f = K$ considered variable and $K_i = 0$, Eq. 7-27 gives $K = Fx - \frac{1}{2}kx^2$. We take the derivative of K with respect to x and set the resulting expression equal to zero in order to find the position x_c that corresponds to a maximum value of K

$$x_c = \frac{F}{k} = (3.0/50 \text{ m}) = 0.060 \text{ m}.$$

We note that x_c is also the point where the applied and spring forces “balance.”

at x_c we find $K = K_{\text{ma}} = 0.090$.

34. According to the graph the acceleration a varies linearly with the coordinate x . We may write $a = \alpha x$ where α is the slope of the graph. Numerically

$$\alpha = \frac{20 \text{ m/s}^2}{8.0 \text{ m}} = 2.5 \text{ s}^{-2}.$$

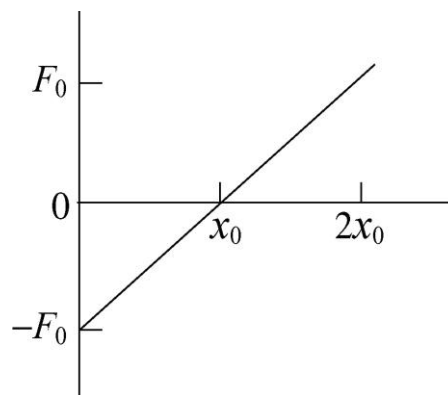
The force on the brick is in the positive x direction and, according to Newton's second law its magnitude is given by $F = ma = m\alpha x$. If x_f is the final coordinate the work done by the force is

$$W = \int_0^{x_f} F dx = m\alpha \int_0^{x_f} x dx = \frac{m\alpha}{2} x_f^2 = \frac{10 \text{ kg}}{2} \cdot 2.5 \text{ s}^{-2} \cdot 8.0 \text{ m}^2 = 8.0 \times 10^2 \text{ J}.$$

35. **THINK** We have an applied force that varies with x . An integration is required to calculate the work done on the particle.

EXPRESS Given a one dimensional force $F(x)$ the work done is simply equal to the area under the curve $W = \int_{x_i}^{x_f} F(x) dx$.

ANALYZE In the plot of $F(x)$ is shown to the right. We take x_0 to be positive. The work is negative as the object moves from $x = 0$ to $x = x_0$ and positive as it moves from $x = x_0$ to $x = 2x_0$.



Since the area of a triangle is $\frac{1}{2} \text{ base} \times \text{altitude}$, the work done from $x = 0$ to $x = x_0$ is $W_1 = -\frac{1}{2} x_0 F_0$ and the work done from $x = x_0$ to $x = 2x_0$ is

$$W_2 = \frac{1}{2} (2x_0 - x_0) F_0 = \frac{1}{2} x_0 F_0$$

The total work is the sum of the two

$$W = W_1 + W_2 = -\frac{1}{2} F_0 x_0 + \frac{1}{2} F_0 x_0 = 0.$$

b. The integral for the work is

$$W = \int_0^{2x_0} F_0 \left(\frac{x}{x_0} - 1 \right) dx = F_0 \left(\frac{x^2}{2x_0} - x \right) \Bigg|_0^{2x_0} = 0.$$

LEARN If the particle starts out at $x = 0$ with an initial speed v_i with a negative work $W_1 = -\frac{1}{2} F_0 x_0 < 0$ its speed at $x = x_0$ will decrease to

$$v = \sqrt{v_i^2 + \frac{2W_1}{m}} = \sqrt{v_i^2 - \frac{F_0 x_0}{m}} < v_i$$

but return to v_i again at $x = 2x_0$ with a positive work $W_2 = F_0 x_0$ $W_2 > 0$.

36. From Fig. 7-32, we see that the “area” in the graph is equivalent to the work done. Finding that area in terms of rectangular length \times width and triangular $\frac{1}{2}$ base \times height areas we obtain

$$W = W_{0 < x < 2} + W_{2 < x < 4} + W_{4 < x < 6} + W_{6 < x < 8} = 20 + 10 + 0 - 5 = 25 \text{ J}.$$

37. a We first multiply the vertical axis by the mass so that it becomes a graph of the applied force. Now, adding the triangular and rectangular “areas” in the graph (for $0 \leq x \leq 4$ gives 42 J for the work done.

b Counting the “areas” under the axis as negative contributions, we find (for $0 \leq x \leq 7$) the work to be 30 J at $x = 7.0$ m.

c And at $x = 9.0$ m the work is 12 J.

d Equation 7-10 along with Fig. 7-1 leads to speed $v = 6.5$ m/s at $x = 4.0$ m. Returning to the original graph where a is plotted we note that since it started from rest it has received acceleration a up to this point only in the $+x$ direction and consequently must have a velocity vector pointing in the $+x$ direction at $x = 4.0$ m.

e Also using the result of part b and Fig. 7-10 along with Fig. 7-1 we find the speed is 5.5 m/s at $x = 7.0$ m. Although it has experienced some deceleration during the $0 \leq x \leq 7$ interval its velocity vector still points in the $+x$ direction.

f Finally using the result of part c and Fig. 7-10 along with Fig. 7-1 we find its speed $v = 3.5$ m/s at $x = 9.0$ m. It certainly has experienced a significant amount of deceleration during the $0 \leq x \leq 9$ interval nonetheless its velocity vector *still* points in the $+x$ direction.

38. a Using the work kinetic energy theorem

$$K_f = K_i + \int_0^{2.0} (2.5 - x^2) dx = 0 + 2.5(2.0) - \frac{1}{3}(2.0)^3 = 2.3 \text{ J}.$$

b For a variable end point we have K_f as a function of x which could be differentiated to find the extremum value but we recognize that this is equivalent to solving $F = 0$ for x

$$F = 0 \Rightarrow 2.5 - x^2 = 0.$$

thus K is extremized at $x = \sqrt{2.5} \approx 1.6$ m and we obtain

$$K_f = K_i + \int_0^{\sqrt{2.5}} (2.5 - x^2) dx = 0 + 2.5 \sqrt{2.5} - \frac{1}{3} \sqrt{2.5}^3 = 2.6 \text{ J}.$$

Recalling our answer for part (a) it is clear that this extreme value is a maximum.

39. As the body moves along the x axis from $x_i = 0$ m to $x_f = 3.00$ m the work done by the force is

$$\begin{aligned} W &= \int_{x_i}^{x_f} F_x dx = \int_{x_i}^{x_f} (cx - 3.00x^2) dx = \left(\frac{c}{2} x^2 - x^3 \right)_0^3 = \frac{c}{2} (3.00)^2 - (3.00)^3 \\ &= 4.50c - 27.0. \end{aligned}$$

Moreover $W = \Delta K = 11.0 - 20.0 = -9.00$ from the work kinetic energy theorem. Thus

$$4.50c - 27.0 = -9.00$$

or $c = 4.00$ N/m.

40. Using $\int_0^{1.25} e^{-4x^2} dx$ we find

$$W = \int_{0.25}^{1.25} e^{-4x^2} dx = 0.21$$

Here the result has been obtained numerically. Any modern calculators have that capability as well as most math software packages that a great many students have access to.

41. We choose to work this using $\int_0^{10} (3.0 - 8.0t + 3.0t^2) dt$ the work kinetic energy theorem. To find the initial and final kinetic energies we need the speeds so

$$v = \frac{dx}{dt} = 3.0 - 8.0t + 3.0t^2$$

in m/s. Thus the initial speed is $v_i = 3.0$ m/s and the speed at $t = 4$ s is $v_f = 19$ m/s. The change in kinetic energy for the object of mass $m = 3.0$ kg is therefore

$$\Delta K = \frac{1}{2} m (v_f^2 - v_i^2) = 528 \text{ J}$$

which we round off to two figures and using the work kinetic energy theorem conclude that the work done is $W = 5.3 \times 10^2$ J.

42. We solve the problem using the work kinetic energy theorem which states that the change in kinetic energy is equal to the work done by the applied force $\Delta K = W$. In our

problem the work done is $W = Fd$ here F is the tension in the cord and d is the length of the cord pulled as the cart slides from x_1 to x_2 . From the figure we have

$$d = \sqrt{x_1^2 + h^2} - \sqrt{x_2^2 + h^2} = \sqrt{3.00 \text{ m}^2 + 1.20 \text{ m}^2} - \sqrt{1.00 \text{ m}^2 + 1.20 \text{ m}^2} \\ = 3.23 \text{ m} - 1.56 \text{ m} = 1.67 \text{ m}$$

which yields $\Delta K = Fd = 25.0 \text{ N} \cdot 1.67 \text{ m} = 41.7 \text{ J}$.

43. **THINK** This problem deals with the power and work done by a constant force.

EXPRESS The power done by a constant force F is given by $P = Fv$ and the work done by F from time t_1 to time t_2 is

$$W = \int_{t_1}^{t_2} P \, dt = \int_{t_1}^{t_2} Fv \, dt$$

Since F is the magnitude of the net force the magnitude of the acceleration is $a = F/m$. Thus if the initial velocity is $v_0 = 0$ then the velocity of the body as a function of time is given by $v = v_0 + at = F/m \, t$. Substituting the expression for v into the equation above the work done during the time interval t_1 to t_2 becomes

$$W = \int_{t_1}^{t_2} F^2/m \, t \, dt = \frac{F^2}{2m} (t_2^2 - t_1^2).$$

ANALYZE a. For $t_1 = 0$ and $t_2 = 1.0 \text{ s}$ $W = \frac{1}{2} \left(\frac{5.0^2}{15 \text{ kg}} \right) 1.0 \text{ s}^2 - 0 = 0.83 \text{ J}$.

b. For $t_1 = 1.0 \text{ s}$ and $t_2 = 2.0 \text{ s}$ $W = \frac{1}{2} \left(\frac{5.0^2}{15 \text{ kg}} \right) 2.0 \text{ s}^2 - 1.0 \text{ s}^2 = 2.5 \text{ J}$.

c. For $t_1 = 2.0 \text{ s}$ and $t_2 = 3.0 \text{ s}$ $W = \frac{1}{2} \left(\frac{5.0^2}{15 \text{ kg}} \right) 3.0 \text{ s}^2 - 2.0 \text{ s}^2 = 4.2 \text{ J}$.

d. Substituting $v = F/m \, t$ into $P = Fv$ we obtain $P = F^2 t/m$ for the power at any time t . At the end of the third second the instantaneous power is

$$P = \left(\frac{5.0^2}{15 \text{ kg}} 3.0 \text{ s} \right) = 5.0 \text{ W}.$$

LEARN The work done here is quadratic in t . Therefore from the definition $P = dW/dt$ for the instantaneous power we see that P increases linearly with t .

44. a Since constant speed implies $\Delta K = 0$ we require $W_a = -W_g$ by 7.15. Since W_g is the same in both cases (same height and same path) then $W_a = 9.0 \times 10^2$ just as it is in the first case.

b Since the speed of 1.0 m/s is constant then 8.0 meters is traveled in 8.0 seconds. Using 7.42 and noting that average power is *the* power when the work is being done at a steady rate we have

$$P = \frac{W}{\Delta t} = \frac{900}{8.0 \text{ s}} = 1.1 \times 10^2 \text{ W}.$$

c Since the speed of 2.0 m/s is constant 8.0 meters is traveled in 4.0 seconds. Using 7.42 with *average power* replaced by *power* we have

$$P = \frac{W}{\Delta t} = \frac{900}{4.0 \text{ s}} = 225 \text{ W} \approx 2.3 \times 10^2 \text{ W}.$$

45. **THINK** The block is pulled at a constant speed by a force directed at some angle with respect to the direction of motion. The quantity we're interested in is the power, or the time rate at which work is done by the applied force.

EXPRESS The power associated with force \vec{F} is given by $P = \vec{F} \cdot \vec{v} = Fv \cos \phi$ where \vec{v} is the velocity of the object on which the force acts and ϕ is the angle between \vec{F} and \vec{v} .

ANALYZE With $F = 122 \text{ N}$, $v = 5.0 \text{ m/s}$ and $\phi = 37.0^\circ$ we find the power to be

$$P = Fv \cos \phi = (122 \text{ N})(5.0 \text{ m/s}) \cos 37.0^\circ = 4.9 \times 10^2 \text{ W}.$$

LEARN From the expression $P = Fv \cos \phi$ we see that the power is at a maximum when \vec{F} and \vec{v} are in the same direction ($\phi = 0$) and is zero when they are perpendicular to each other. In addition, we're told that the block moves at a constant speed so $\Delta K = 0$ and the net work done on it must also be zero by the work-kinetic energy theorem. Thus the applied force here must be compensating another force (e.g. friction) for the net rate to be zero.

46. Recognizing that the force in the cable must equal the total weight since there is no acceleration we employ 7.47

$$P = Fv \cos \theta = mg \left(\frac{\Delta x}{\Delta t} \right)$$

Here we have used the fact that $\theta = 0^\circ$ (both the force of the cable and the elevator's motion are upward). Thus

$$P = 3.0 \times 10^3 \text{ kg} \cdot 9.8 \text{ m/s}^2 \left(\frac{210 \text{ m}}{23 \text{ s}} \right) = 2.7 \times 10^5 \text{ W}.$$

47. a. Equation 7.8 yields

$$\begin{aligned} W &= F_x \Delta x + F_y \Delta y + F_z \Delta z \\ &= (2.00 \text{ N})(7.5 \text{ m} - 0.50 \text{ m}) + (4.00 \text{ N})(12.0 \text{ m} - 0.75 \text{ m}) + (6.00 \text{ N})(7.2 \text{ m} - 0.20 \text{ m}) \\ &= 101 \text{ J} \approx 1.0 \times 10^2 \text{ J}. \end{aligned}$$

b. Dividing this result by 12 s (see Eq. 7.42) yields $P = 8.4 \text{ W}$.

48. a. Since the force exerted by the spring on the mass is zero when the mass passes through the equilibrium position of the spring, the rate at which the spring is doing work on the mass at this instant is also zero.

b. The rate is given by $P = \vec{F} \cdot \vec{v} = -Fv$ (here the minus sign corresponds to the fact that \vec{F} and \vec{v} are anti-parallel to each other). The magnitude of the force is given by

$$F = kx = (500 \text{ N/m})(0.10 \text{ m}) = 50 \text{ N}.$$

While v is obtained from conservation of energy for the spring-mass system

$$E = K + U = 10 \text{ J} = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = \frac{1}{2}(0.30 \text{ kg})v^2 + \frac{1}{2}(500 \text{ N/m})(0.10 \text{ m})^2$$

which gives $v = 7.1 \text{ m/s}$. Thus

$$P = -Fv = -(50 \text{ N})(7.1 \text{ m/s}) = -3.5 \times 10^2 \text{ W}.$$

49. **THINK** We have a loaded elevator moving upward at a constant speed. The forces involved are gravitational force on the elevator, gravitational force on the counterweight, and the force by the motor via cable.

EXPRESS The total work is the sum of the work done by gravity on the elevator, the work done by gravity on the counterweight, and the work done by the motor on the system

$$W = W_e + W_c + W_m.$$

Since the elevator moves at constant velocity, its kinetic energy does not change and according to the work-kinetic energy theorem the total work done is zero, i.e., $W = \Delta K = 0$.

ANALYZE The elevator moves *upward* through 54 m, so the work done by gravity on it is

$$W_e = -m_e g d = -1200 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 54 \text{ m} = -6.35 \times 10^5 \text{ J}.$$

The counterweight moves *downward* the same distance so the work done by gravity on it is

$$W_c = m_c g d = 950 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 54 \text{ m} = 5.03 \times 10^5 \text{ J}.$$

Since $W = 0$ the work done by the motor on the system is

$$W_m = -W_e - W_c = 6.35 \times 10^5 \text{ J} - 5.03 \times 10^5 \text{ J} = 1.32 \times 10^5 \text{ J}.$$

This work is done in a time interval of $\Delta t = 3.0 \text{ min} = 180 \text{ s}$ so the power supplied by the motor to lift the elevator is

$$P = \frac{W_m}{\Delta t} = \frac{1.32 \times 10^5 \text{ J}}{180 \text{ s}} = 7.4 \times 10^2 \text{ W}.$$

LEARN In general the work done by the motor is $W_m = (m_e - m_c)gd$. When the counterweight mass balances the total mass $m_c = m_e$ no work is required by the motor.

50. a Using Eqs. 7.48 and 7.323 we obtain

$$P = \vec{F} \cdot \vec{v} = 4.0 \text{ N}(-2.0 \text{ m/s}) + 9.0 \text{ N}(4.0 \text{ m/s}) = 28 \text{ W}.$$

b We again use Eqs. 7.48 and 7.323 but with a one component velocity $\vec{v} = v\hat{i}$.

$$P = \vec{F} \cdot \vec{v} \Rightarrow -12 \text{ W} = -2.0 \text{ N} \cdot v.$$

which yields $v = 6 \text{ m/s}$.

51. (a) The object's displacement is

$$\vec{d} = \vec{d}_f - \vec{d}_i = -8.00 \text{ m} \hat{i} + 6.00 \text{ m} \hat{j} + 2.00 \text{ m} \hat{k}.$$

thus Eqs. 7.8 gives

$$W = \vec{F} \cdot \vec{d} = 3.00 \text{ N}(-8.00 \text{ m}) + 7.00 \text{ N}(6.00 \text{ m}) + 7.00 \text{ N}(2.00 \text{ m}) = 32.0 \text{ J}.$$

b The average power is given by Eqs. 7.42

$$P_{\text{avg}} = \frac{W}{t} = \frac{32.0 \text{ J}}{4.00 \text{ s}} = 8.00 \text{ W}.$$

c The distance from the coordinate origin to the initial position is

$$d_i = \sqrt{3.00 \text{ m}^2 + -2.00 \text{ m}^2 + 5.00 \text{ m}^2} = 6.16 \text{ m}$$

and the magnitude of the distance from the coordinate origin to the final position is

$$d_f = \sqrt{-5.00 \text{ m}^2 + 4.00 \text{ m}^2 + 7.00 \text{ m}^2} = 9.49 \text{ m}.$$

their scalar dot product is

$$\vec{d}_i \cdot \vec{d}_f = 3.00 \text{ m} \cdot -5.00 \text{ m} + -2.00 \text{ m} \cdot 4.00 \text{ m} + 5.00 \text{ m} \cdot 7.00 \text{ m} = 12.0 \text{ m}^2.$$

thus the angle between the two vectors is

$$\phi = \cos^{-1} \left(\frac{\vec{d}_i \cdot \vec{d}_f}{d_i d_f} \right) = \cos^{-1} \left(\frac{12.0}{6.16 \cdot 9.49} \right) = 78.2^\circ.$$

52. According to the problem statement the power of the car is

$$P = \frac{dW}{dt} = \frac{d}{dt} \left(\frac{1}{2} mv^2 \right) = mv \frac{dv}{dt} = \text{constant}.$$

the condition implies $dt = mvdv/P$ which can be integrated to give

$$\int_0^T dt = \int_0^{v_T} \frac{mvdv}{P} \Rightarrow T = \frac{mv_T^2}{2P}$$

here v_T is the speed of the car at $t = T$. On the other hand the total distance traveled can be written as

$$L = \int_0^T v dt = \int_0^{v_T} v \frac{mvdv}{P} = \frac{m}{P} \int_0^{v_T} v^2 dv = \frac{mv_T^3}{3P}.$$

By using the expression for L and substituting the expression for T we obtain

$$L^2 = \left(\frac{mv_T^3}{3P} \right)^2 = \frac{8P}{9m} \left(\frac{mv_T^2}{2P} \right)^3 = \frac{8PT^3}{9m}$$

which implies that

$$PT^3 = \frac{9}{8} mL^2 = \text{constant}.$$

Differentiating the above equation gives $dPT^3 + 3PT^2 dT = 0$ or $dT = -\frac{T}{3P} dP$.

53. a Noting that the x component of the third force is $F_{3x} = 4.00 \cos 60^\circ$ we apply Eq. 7-8 to the problem

$$W = 5.00 - 1.00 + 4.00 \cos 60^\circ (0.20 \text{ m}) = 1.20 \text{ J}.$$

b Equation 7-10 along with Eq. 7-1 then yields $v = \sqrt{2W/m} = 1.10 \text{ m/s}$.

54. From Eq. 7-32, we see that the “area” in the graph is equivalent to the work done. We find the area in terms of rectangular length \times width and triangular $\frac{1}{2}$ base \times height areas and use the work-kinetic energy theorem appropriately. The initial point is taken to be $x = 0$ where $v_0 = 4.0 \text{ m/s}$.

a With $K_i = \frac{1}{2}mv_0^2 = 16 \text{ J}$ we have

$$K_3 - K_0 = W_{0 < x < 1} + W_{1 < x < 2} + W_{2 < x < 3} = -4.0 \text{ J}$$

so that K_3 the kinetic energy when $x = 3.0 \text{ m}$ is found to be equal to 12 J.

b With units understood we write $W_{3 < x < x_f}$ as $F_x \Delta x = -4.0 \text{ J}$ for $x_f - 3.0 \text{ m}$ and apply the work-kinetic energy theorem

$$\begin{aligned} K_{x_f} - K_3 &= W_{3 < x < x_f} \\ K_{x_f} - 12 &= -4 \text{ J} \quad x_f - 3.0 \end{aligned}$$

so that the requirement $K_{x_f} = 8.0 \text{ J}$ leads to $x_f = 4.0 \text{ m}$.

c As long as the work is positive the kinetic energy grows. The graph shows this situation to hold until $x = 1.0 \text{ m}$. At that location the kinetic energy is

$$K_1 = K_0 + W_{0 < x < 1} = 16 \text{ J} + 2.0 \text{ J} = 18 \text{ J}.$$

55. **THINK** A horse is doing work to pull a cart at a constant speed. We’d like to know the work done during a time interval and the corresponding average power.

EXPRESS The horse pulls with a force \vec{F} . As the cart moves through a displacement \vec{d} the work done by \vec{F} is $W = \vec{F} \cdot \vec{d} = Fd \cos \phi$ where ϕ is the angle between \vec{F} and \vec{d} .

ANALYZE a In 10 min the cart moves a distance

$$d = v\Delta t = \left(6.0 \frac{\text{mi}}{\text{h}}\right) \left(\frac{5280 \text{ ft}}{1 \text{ mi}}\right) \left(\frac{10 \text{ min}}{60 \text{ min/h}}\right) = 5280 \text{ ft}$$

so that Eq. 7-7 yields

$$W = Fd \cos \phi = 40 \text{ lb} \cdot 5280 \text{ ft} \cdot \cos 30^\circ = 1.8 \times 10^5 \text{ ft} \cdot \text{lb}.$$

b The average power is given by Eq. 7-42. With $\Delta t = 10 \text{ min} = 600 \text{ s}$ we obtain

$$P_{\text{avg}} = \frac{W}{\Delta t} = \frac{1.8 \times 10^5 \text{ ft} \cdot \text{lb}}{600 \text{ s}} = 305 \text{ ft} \cdot \text{lb/s}$$

which using the conversion factor $1 \text{ hp} = 550 \text{ ft} \cdot \text{lb/s}$ found on the inside back cover converts to $P_{\text{avg}} = 0.55 \text{ hp}$.

LEARN The average power can also be calculated by using Eq. 7-48 $P_{\text{avg}} = Fv \cos \phi$.

Converting the speed to $v = 6.0 \text{ mi/h} \left(\frac{5280 \text{ ft}}{3600 \text{ s}} \right) = 8.8 \text{ ft/s}$ we get

$$P_{\text{avg}} = Fv \cos \phi = 40 \text{ lb} \cdot 8.8 \text{ ft/s} \cdot \cos 30^\circ = 305 \text{ ft} \cdot \text{lb/s} = 0.55 \text{ hp}$$

which agrees with that found in (b).

56. The acceleration is constant so we may use the equations in Table 2-1. We choose the direction of motion as x and note that the displacement is the same as the distance traveled in this problem. We designate the force assumed singular along the x direction acting on the $m = 2.0 \text{ kg}$ object as F .

a With $v_0 = 0$, Eq. 2-11 leads to $a = v/t$, and Eq. 2-17 gives $\Delta x = \frac{1}{2}vt$. Newton's second law yields the force $F = ma$. Equation 7-8 then gives the work

$$W = F\Delta x = m \left(\frac{v}{t} \right) \left(\frac{1}{2}vt \right) = \frac{1}{2}mv^2$$

as we expect from the work-kinetic energy theorem. With $v = 10 \text{ m/s}$ this yields $W = 1.0 \times 10^2 \text{ J}$.

b Instantaneous power is defined in Eq. 7-48. With $t = 3.0 \text{ s}$ we find

$$P = Fv = m \left(\frac{v}{t} \right) v = 67 \text{ W}.$$

c The velocity at $t' = 1.5 \text{ s}$ is $v' = at' = 5.0 \text{ m/s}$. Thus $P' = Fv' = 33 \text{ W}$.

57. a To hold the crate at equilibrium in the final situation \vec{F} must have the same magnitude as the horizontal component of the rope's tension $T \sin \theta$ here θ is the angle between the rope in the final position and vertical

$$\theta = \sin^{-1}\left(\frac{4.00}{12.0}\right) = 19.5^\circ.$$

At the vertical component of the tension supports against the weight $T \cos \theta = mg$. Thus the tension is

$$T = 230 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cos 19.5^\circ = 2391$$

and $F = 2391 \sin 19.5^\circ = 797$.

An alternative approach based on drawing a vector triangle of forces in the final situation provides a quick solution.

b Since there is no change in kinetic energy the net work on it is zero.

c The work done by gravity is $W_g = \vec{F}_g \cdot \vec{d} = -mgh$ here $h = L(1 - \cos \theta)$ is the vertical component of the displacement. With $L = 12.0 \text{ m}$ we obtain $W_g = -1547$ which should be rounded to three significant figures -1.55 kJ .

d The tension vector is everywhere perpendicular to the direction of motion so its work is zero since $\cos 90^\circ = 0$.

e The implication of the previous three parts is that the work due to \vec{F} is $-W_g$ so the net work turns out to be zero. Thus $W_F = -W_g = 1.55 \text{ kJ}$.

f Since \vec{F} does not have constant magnitude we cannot expect 7.8 to apply.

58. a The force of the worker on the crate is constant so the work it does is given by $W_F = \vec{F} \cdot \vec{d} = Fd \cos \phi$ here \vec{F} is the force \vec{d} is the displacement of the crate and ϕ is the angle between the force and the displacement. Here $F = 210$, $d = 3.0 \text{ m}$ and $\phi = 20^\circ$. Thus

$$W_F = 210 \cdot 3.0 \text{ m} \cos 20^\circ = 590.$$

b The force of gravity is downward and perpendicular to the displacement of the crate. The angle between this force and the displacement is 90° and $\cos 90^\circ = 0$ so the work done by the force of gravity is zero.

c The normal force of the floor on the crate is also perpendicular to the displacement so the work done by this force is also zero.

d These are the only forces acting on the crate so the total work done on it is 590 .

59. The work done by the applied force \vec{F}_a is given by $W = \vec{F}_a \cdot \vec{d} = F_a d \cos \phi$. From the figure we see that $W = 25$ when $\phi = 0$ and $d = 5.0$ cm. This yields the magnitude of \vec{F}_a

$$F_a = \frac{W}{d} = \frac{25}{0.050 \text{ m}} = 5.0 \times 10^2 \text{ N}.$$

a. For $\phi = 64^\circ$ we have $W = F_a d \cos \phi = (5.0 \times 10^2 \text{ N})(0.050 \text{ m}) \cos 64^\circ = 11 \text{ J}$.

b. For $\phi = 147^\circ$ we have $W = F_a d \cos \phi = (5.0 \times 10^2 \text{ N})(0.050 \text{ m}) \cos 147^\circ = -21 \text{ J}$.

60. a. In the work kinetic energy theorem we include both the work due to an applied force W_a and work done by gravity W_g in order to find the latter quantity.

$$\Delta K = W_a + W_g \Rightarrow 30 \text{ J} = 100 \text{ J} + (1.8 \text{ m}) \cos 180^\circ W_g$$

leading to $W_g = 2.1 \times 10^2 \text{ J}$.

b. The value of W_g obtained in part a still applies since the height and the path of the child remain the same so $\Delta K = W_g = 2.1 \times 10^2 \text{ J}$.

61. One approach is to assume a “path” from \vec{r}_i to \vec{r}_f and do the line integral accordingly. Another approach is to simply use Eq. 7.36 which we demonstrate

$$W = \int_{x_i}^{x_f} F_x dx + \int_{y_i}^{y_f} F_y dy = \int_2^{-4} 2x dx + \int_3^{-3} 3 dy$$

with units understood. Thus we obtain $W = 12 \text{ J} - 18 \text{ J} = -6 \text{ J}$.

62. a. The compression of the spring is $d = 0.12$ m. The work done by the force of gravity acting on the block is by Eq. 7.12

$$W_1 = mgd = (0.25 \text{ kg})(9.8 \text{ m/s}^2)(0.12 \text{ m}) = 0.29 \text{ J}.$$

b. The work done by the spring is by Eq. 7.26

$$W_2 = -\frac{1}{2}kd^2 = -\frac{1}{2}(250 \text{ N/m})(0.12 \text{ m})^2 = -1.8 \text{ J}.$$

c. The speed v_i of the block just before it hits the spring is found from the work kinetic energy theorem Eq. 7.15

$$\Delta K = 0 - \frac{1}{2}mv_i^2 = W_1 + W_2$$

which yields

$$v_i = \sqrt{\frac{-2(W_1 + W_2)}{m}} = \sqrt{\frac{-2(0.29 - 1.8)}{0.25 \text{ kg}}} = 3.5 \text{ m/s}.$$

and if we instead had $v_i' = 7 \text{ m/s}$ we reverse the above steps and solve for d' . Recalling the theorem used in part (c) we have

$$0 - \frac{1}{2}mv_i'^2 = W_1' + W_2' = mgd' - \frac{1}{2}kd'^2$$

which choosing the positive root leads to

$$d' = \frac{mg + \sqrt{m^2g^2 + mkv_i'^2}}{k}$$

which yields $d = 0.23 \text{ m}$. In order to obtain this result we have used more digits in our intermediate results than are shown above so $v_i = \sqrt{12.048} \text{ m/s} = 3.471 \text{ m/s}$ and $v_i' = 6.942 \text{ m/s}$.

63. THINK The crate is being pushed up a frictionless inclined plane. The forces involved are gravitational force on the crate, normal force on the crate, and the force applied by the worker.

EXPRESS The work done by a force \vec{F} on an object as it moves through a displacement \vec{d} is $W = \vec{F} \cdot \vec{d} = Fd \cos \phi$ where ϕ is the angle between \vec{F} and \vec{d} .

ANALYZE a. The applied force is parallel to the inclined plane. Thus using Eq. 7.6 the work done on the crate by the worker's applied force is

$$W_a = Fd \cos 0^\circ = (209 \text{ N})(1.50 \text{ m}) \approx 314 \text{ J}.$$

b. Using Eq. 7.12 we find the work done by the gravitational force to be

$$\begin{aligned} W_g &= F_g d \cos 90^\circ + 25^\circ = mgd \cos 115^\circ \\ &= (25.0 \text{ kg})(9.8 \text{ m/s}^2)(1.50 \text{ m}) \cos 115^\circ \\ &\approx -155 \text{ J}. \end{aligned}$$

c. The angle between the normal force and the direction of motion remains 90° at all times so the work it does is zero

$$W_N = F_N d \cos 90^\circ = 0.$$

d The total work done on the crate is the sum of all three works

$$W = W_a + W_g + W_N = 314 \text{ J} + (-158 \text{ J}) + 0 \text{ J} = 156 \text{ J}.$$

LEARN By work kinetic energy theorem if the crate is initially at rest $K_i = 0$ then its kinetic energy after having moved 1.50 m up the incline could be $K_f = W = 156 \text{ J}$ and the speed of the crate at that instant is

$$v = \sqrt{2K_f/m} = \sqrt{2(156 \text{ J})/25.0 \text{ kg}} = 3.56 \text{ m/s}.$$

64. a The force \vec{F} of the incline is a combination of normal and friction force which is serving to “cancel” the tendency of the box to fall downward (due to its 19.6 N weight). Thus $\vec{F} = mg$ upward. In this part of the problem the angle ϕ between the belt and \vec{F} is 80° . From Fig. 7-47 we have

$$P = Fv \cos \phi = (19.6 \text{ N})(0.50 \text{ m/s}) \cos 80^\circ = 1.7 \text{ J/s}.$$

b For the angle between the belt and \vec{F} is 90° so that $P = 0$.

c In this part the angle between the belt and \vec{F} is 100° so that

$$P = (19.6 \text{ N})(0.50 \text{ m/s}) \cos 100^\circ = -1.7 \text{ J/s}.$$

65. There is no acceleration so the lifting force is equal to the weight of the object. We note that the person's pull \vec{F} is equal in magnitude to the tension in the cord.

a As indicated in the *hint* tension contributes twice to the lifting of the canister $2T = mg$. Since $|\vec{F}| = T$ we find $|\vec{F}| = 98 \text{ N}$.

b To rise 0.020 m the two segments of the cord (see Fig. 7-47) must shorten by that amount. Thus the amount of string pulled down at the left end (this is the magnitude of \vec{d} , the downward displacement of the hand) is $d = 0.040 \text{ m}$.

c Since at the left end both \vec{F} and \vec{d} are downward then Fig. 7-7 leads to

$$W = \vec{F} \cdot \vec{d} = (98 \text{ N})(0.040 \text{ m}) = 3.9 \text{ J}.$$

d Since the force of gravity \vec{F}_g with magnitude mg is opposite to the displacement $\vec{d}_c = 0.020 \text{ m}$ up of the canister Fig. 7-7 leads to

$$W = \vec{F}_g \cdot \vec{d}_c = -196 \text{ N} \cdot 0.020 \text{ m} = -3.9 \text{ J}.$$

This is consistent with Eq. 7-15 since there is no change in kinetic energy.

66. After converting the speed $v = 120 \text{ km/h} = 33.33 \text{ m/s}$ we find

$$K = \frac{1}{2}mv^2 = \frac{1}{2}(1200 \text{ kg})(33.33 \text{ m/s})^2 = 6.67 \times 10^5 \text{ J}.$$

67. **THINK** In this problem we have packages hung from the spring. The amount of stretching can be determined from Hooke's law.

EXPRESS According to Hooke's law, the spring force is given by

$$F_x = -k(x - x_0) = -k\Delta x$$

where Δx is the displacement from the equilibrium position. Thus the first two situations in Fig. 7-48 can be written as

$$\begin{aligned} -110 \text{ N} &= -k(40 \text{ mm} - x_0) \\ -240 \text{ N} &= -k(60 \text{ mm} - x_0) \end{aligned}$$

The two equations allow us to solve for k , the spring constant, as well as x_0 , the relaxed position when no mass is hung.

ANALYZE a. The two equations can be added to give

$$-240 \text{ N} - 110 \text{ N} = k(60 \text{ mm} - 40 \text{ mm})$$

which yields $k = 6.5 \text{ N/mm}$. Substituting the result into the first equation we find

$$x_0 = 40 \text{ mm} - \frac{110 \text{ N}}{k} = 40 \text{ mm} - \frac{110 \text{ N}}{6.5 \text{ N/mm}} = 23 \text{ mm}.$$

b. Using the results from part (a) to analyze that last picture we find the weight to be

$$W = k(30 \text{ mm} - x_0) = 6.5 \text{ N/mm}(30 \text{ mm} - 23 \text{ mm}) = 45 \text{ N}.$$

LEARN An alternative method to calculate W in the third picture is to note that since the amount of stretching is proportional to the weight hung we have $\frac{W}{W'} = \frac{\Delta x}{\Delta x'}$. Applying this relation to the second and the third pictures the weight W is

$$W = \left(\frac{\Delta x_3}{\Delta x_2} \right) W_2 = \left(\frac{30 \text{ mm} - 23 \text{ mm}}{60 \text{ mm} - 23 \text{ mm}} \right) 240 = 45$$

in agreement with the result shown in (b).

68. Since $\phi = 77^\circ$ we have $W = Fd \cos \phi = 1504 \text{ J}$. Then by the work kinetic energy theorem we find the kinetic energy $K_f = K_i + W = 0 + 1504 \text{ J}$. The answer is therefore 1.5 kJ .

69. The total weight is $100 \times 660 \text{ N} = 6.60 \times 10^4 \text{ N}$ and the words “raises ... at constant speed” imply zero acceleration, so the lift force is equal to the total weight. Thus

$$P = Fv = 6.60 \times 10^4 \text{ N} \times 150 \text{ m} / 60.0 \text{ s} = 1.65 \times 10^5 \text{ W}$$

70. With units understood, $W = 4.0 \times 3.0 - c \times 2.0 = 12 - 2c$.

a. If $W = 0$ then $c = 6.0 \text{ J}$.

b. If $W = 17 \text{ J}$ then $c = -2.5 \text{ J}$.

c. If $W = -18 \text{ J}$ then $c = 15 \text{ J}$.

71. Since $\phi = 78^\circ$ we find

$$W = \vec{F} \cdot \vec{d} = F \cos \theta \hat{i} + F \sin \theta \hat{j} \cdot x \hat{i} + y \hat{j} = Fx \cos \theta + Fy \sin \theta$$

here $x = 2.0 \text{ m}$, $y = -4.0 \text{ m}$, $F = 10 \text{ N}$ and $\theta = 150^\circ$. Thus we obtain $W = -37 \text{ J}$. Note that the given mass value 2.0 kg is not used in the computation.

72. a. $\phi = 10^\circ$ along with $\phi = 1^\circ$ and $\phi = 7^\circ$ leads to

$$v_f = 2 \frac{d}{m} F \cos \theta^{1/2} = \cos \theta^{1/2}$$

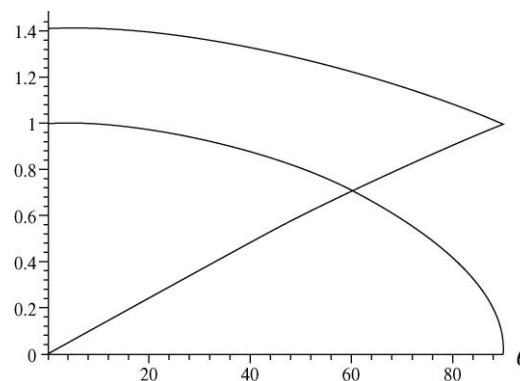
here we have substituted $F = 2.0 \text{ N}$, $m = 4.0 \text{ kg}$ and $d = 1.0 \text{ m}$.

b. With $v_i = 1$ those same steps lead to $v_f = 1 - \cos \theta^{1/2}$.

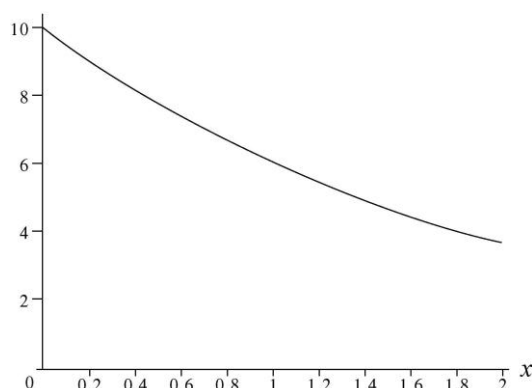
c. Replacing θ with $180^\circ - \theta$ and still using $v_i = 1$ we find

$$v_f = 1 - \cos 180^\circ - \theta^{1/2} = 1 - \cos \theta^{1/2}$$

d The graphs are shown on the right. Note that as θ is increased in parts a and b the force provides less and less of a positive acceleration whereas in part c the force provides less and less of a deceleration as its θ value increases. The highest curve which slowly decreases from 1.4 to 1 is the curve for part b the other decreasing curve starting at 1 and ending at 0 is for part a. The rising curve is for part c it is equal to 1 here $\theta = 90^\circ$.



73. a The plot of the function with units understood is shown below.



estimating the area under the curve allows for a range of answers. Estimates from 11 to 14 are typical.

b Evaluating the work analytically using 7.32 we have

$$W = \int_0^2 10e^{-x^2} dx = -20e^{-x^2} \Big|_0^2 = 12.6 \approx 13.$$

74. a Using 7.8 and units we find

$$W = \vec{F} \cdot \vec{d} = 2\hat{i} - 4\hat{j} \cdot 8\hat{i} + c\hat{j} = 16 - 4c$$

which if equal zero implies $c = 16/4 = 4$ m.

b If $W = 0$ then $16 - 4c$ which implies $c = 4$ m.

c If $W = 0$ then $16 - 4c$ which implies $c = 4$ m.

75. **THINK** Power must be supplied in order to lift the elevator with load upward at a constant speed.

EXPRESS For the elevator load system to move upward at a constant speed (zero acceleration) the applied force F must exactly balance the gravitational force on the system i.e. $F = F_g = (m_{\text{elev}} + m_{\text{load}})g$. The power required can then be calculated using Eq. 17-48 $P = Fv$.

ANALYZE With $m_{\text{elev}} = 4500 \text{ kg}$, $m_{\text{load}} = 1800 \text{ kg}$ and $v = 3.80 \text{ m/s}$ we find the power to be

$$P = Fv = (m_{\text{elev}} + m_{\text{load}})gv = (4500 \text{ kg} + 1800 \text{ kg})(9.8 \text{ m/s}^2)(3.80 \text{ m/s}) = 235 \text{ kW}.$$

LEARN The power required is proportional to the speed at which the system moves: the greater the speed the greater the power that must be supplied.

76. (a) The component of the force of gravity exerted on the ice block of mass m along the incline is $mg \sin \theta$ where $\theta = \sin^{-1}(0.91/1.5)$ gives the angle of inclination for the inclined plane. Since the ice block slides down with uniform velocity the worker must exert a force \vec{F} “uphill” with a magnitude equal to $mg \sin \theta$. Consequently

$$F = mg \sin \theta = (45 \text{ kg})(9.8 \text{ m/s}^2) \left(\frac{0.91 \text{ m}}{1.5 \text{ m}} \right) = 2.7 \times 10^2 \text{ N}.$$

(b) Since the “downhill” displacement is opposite to \vec{F} the work done by the worker is

$$W_1 = -(2.7 \times 10^2 \text{ N})(1.5 \text{ m}) = -4.0 \times 10^2 \text{ J}.$$

(c) Since the displacement has a vertically downward component of magnitude 0.91 m in the same direction as the force of gravity we find the work done by gravity to be

$$W_2 = (45 \text{ kg})(9.8 \text{ m/s}^2)(0.91 \text{ m}) = 4.0 \times 10^2 \text{ J}.$$

(d) Since \vec{F}_N is perpendicular to the direction of motion of the block and $\cos 90^\circ = 0$ the work done by the normal force is $W_3 = 0$ by Eq. 7-7.

(e) The resultant force \vec{F}_{net} is zero since there is no acceleration. Thus its work is zero as can be checked by adding the above results $W_1 + W_2 + W_3 = 0$.

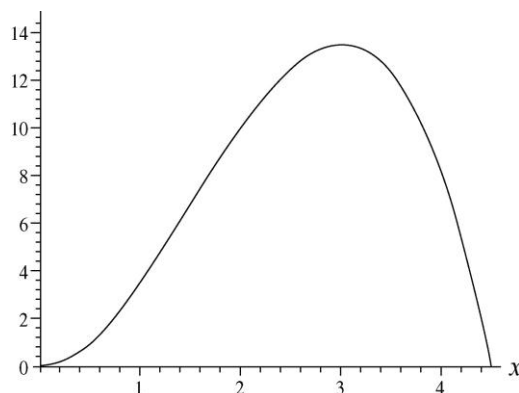
77. (a) To estimate the area under the curve between $x = 1 \text{ m}$ and $x = 3 \text{ m}$ (which should yield the value for the work done), one can try “counting squares” (or half squares or thirds of squares between the curve and the axis). Estimates between 5 and 8 are typical for this crude procedure.

b Equation 7.32 gives

$$\int_1^3 \frac{a}{x^2} dx = \frac{a}{3} - \frac{a}{1} = -6$$

here $a = -9 \text{ m}^2$ is given in the problem statement.

78. a Using Eq. 7.32 the work becomes $W = \frac{9}{2}x^2 - x^3$ units understood. The plot is shown below



b We see from the graph that its peak value occurs at $x = 3.00 \text{ m}$. This can be verified by taking the derivative of W and setting it equal to zero or simply by noting that this is where the force vanishes.

c The maximum value is $W = \frac{9}{2} (3.00)^2 - (3.00)^3 = 13.50$.

d We see from the graph or from our analytic expression that $W = 0$ at $x = 4.50 \text{ m}$.

e The case is at rest when $v = 0$. Since $W = \Delta K = mv^2/2$ the condition implies $W = 0$. This happens at $x = 4.50 \text{ m}$.

79. **THINK** A block sliding in the x direction is slowed down by a steady wind in the $-x$ direction. The problem involves graphical analysis.

EXPRESS Fig. 7.51 represents $x(t)$ the position of the lunch box as a function of time. It is convenient to fit the curve to a concave downward parabola

$$x(t) = \frac{1}{10}t(10-t) = t - \frac{1}{10}t^2.$$

By taking one and two derivatives we find the velocity and acceleration to be

$$v(t) = \frac{dx}{dt} = 1 - \frac{t}{5} \text{ in m/s} \quad a = \frac{d^2x}{dt^2} = -\frac{1}{5} = -0.2 \text{ in m/s}^2.$$

he equations imply that the initial speed of the ball is $v_i = v_0 = 1.0 \text{ m/s}$ and the constant force by the hand is

$$F = ma = (2.0 \text{ kg})(-0.2 \text{ m/s}^2) = -0.40 \text{ N}.$$

he corresponding work is given by units understood

$$W(t) = F \cdot x(t) = -0.40t(10 - t).$$

he initial kinetic energy of the lunch ball is

$$K_i = \frac{1}{2}mv_i^2 = \frac{1}{2}(2.0 \text{ kg})(1.0 \text{ m/s})^2 = 1.0 \text{ J}.$$

With $\Delta K = K_f - K_i = W$ the kinetic energy at a later time is given by in units

$$K(t) = K_i + W = 1 - 0.40t(10 - t)$$

ANALYZE a When $t = 1.0 \text{ s}$ the above expression gives

$$K(1 \text{ s}) = 1 - 0.40(1)(10 - 1) = 1 - 0.36 = 0.64 \approx 0.6$$

here the second significant figure is not to be taken too seriously.

b At $t = 5.0 \text{ s}$ the above method gives $K(5.0 \text{ s}) = 1 - 0.40(5)(10 - 5) = 1 - 1 = 0$.

c The work done by the force from the hand from $t = 1.0 \text{ s}$ to $t = 5.0 \text{ s}$ is

$$W = K(5.0) - K(1.0 \text{ s}) = 0 - 0.6 \approx -0.6 \text{ J}.$$

LEARN The result in c can also be obtained by evaluating $W(t) = -0.40t(10 - t)$ directly at $t = 5.0 \text{ s}$ and $t = 1.0 \text{ s}$ and subtracting

$$W(5) - W(1) = -0.40(5)(10 - 5) - [-0.40(1)(10 - 1)] = -1 - (-0.36) = -0.64 \approx -0.6 \text{ J}.$$

Note that at $t = 5.0 \text{ s}$ $K = 0$ the ball comes to a stop and then reverses its direction subsequently with x decreasing.

80. The problem indicates that units are understood so the result of 0.723 is in joules. One numerically using features available on many modern calculators the result is roughly 0.47 J . For the interested student it might be worthwhile to quote the “exact” answer (in terms of the “error function”):

$$\int_{.15}^{1.2} e^{2x^2} dx = \sqrt{2\pi} \operatorname{erf} 6\sqrt{2} \cdot 5 - \operatorname{erf} 3\sqrt{2} \cdot 20 \quad .$$

81. a The work done by the spring force is $W_s = \frac{1}{2}k(x_i^2 - x_f^2)$. By energy conservation when the block is at $x_f = 0$ the energy stored in the spring is completely converted to the kinetic energy of the block $W_s = K = \frac{1}{2}mv^2$. Solving for v we obtain

$$\frac{1}{2}k(x_i^2 - x_f^2) = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{\frac{k}{m}}x_i = \sqrt{\frac{500 \text{ N/m}}{4.00 \text{ kg}}}(0.300 \text{ m}) = 3.35 \text{ m/s}.$$

b The work done by the spring is

$$W_s = \frac{1}{2}kx_i^2 = \frac{1}{2}(500 \text{ N/m})(0.300 \text{ m})^2 = 22.5 \text{ J}.$$

c The instantaneous power due to the spring can be written as

$$P = Fv = kx \sqrt{\frac{k}{m}(x_i^2 - x^2)}$$

At the release point x_i the power is zero.

d Similarly at $x = 0$ we also have $P = 0$.

e The position where the power is maximum can be found by differentiating P with respect to x setting $dP/dx = 0$

$$\frac{dP}{dx} = \frac{k^2(x_i^2 - 2x^2)}{\sqrt{\frac{k}{m}(x_i^2 - x^2)}} = 0$$

which gives $x = \frac{x_i}{\sqrt{2}} = \frac{0.300 \text{ m}}{\sqrt{2}} = 0.212 \text{ m}.$

82. (a) Applying Newton's second law to the x directed uphill and y normal to the inclined plane gives

$$\begin{aligned} F - mg \sin \theta &= ma \\ F_N - mg \cos \theta &= 0. \end{aligned}$$

The second equation allows us to solve for the angle the inclined plane makes with the horizontal

$$\theta = \cos^{-1}\left(\frac{F_N}{mg}\right) = \cos^{-1}\left(\frac{13.41}{4.00 \text{ kg} \cdot 9.8 \text{ m/s}^2}\right) = 70.0^\circ$$

From the equation for the acceleration find the acceleration of the block to be

$$a = \frac{F}{m} - g \sin \theta = \frac{50}{4.00 \text{ kg}} - 9.8 \text{ m/s}^2 \sin 70.0^\circ = 3.29 \text{ m/s}^2$$

Using the kinematic equation $v^2 = v_0^2 + 2ad$ the speed of the block when $d = 3.00 \text{ m}$ is

$$v = \sqrt{2ad} = \sqrt{2(3.29 \text{ m/s}^2)(3.00 \text{ m})} = 4.44 \text{ m/s}$$

83. a. The work done by the spring force with spring constant $k = 1800 \text{ N/m}$ is

$$W_s = \frac{1}{2}k(x_i^2 - x_f^2) = -\frac{1}{2}kx_f^2 = -\frac{1}{2}(1800 \text{ N/m})(7.60 \times 10^{-3} \text{ m})^2 = -5.20 \times 10^{-2} \text{ J}$$

b. For $x'_f = 2x_f$ the work done by the spring force is $W'_s = -\frac{1}{2}kx_f'^2 = -\frac{1}{2}k(2x_f)^2$ so the additional work done is

$$\Delta W = W'_s - W_s = -\frac{1}{2}k(2x_f)^2 - \left(-\frac{1}{2}kx_f^2\right) = -\frac{3}{2}kx_f^2 = 3W_s = 3(-5.20 \times 10^{-2} \text{ J}) = -0.156 \text{ J}$$

84. a. The displacement of the object is

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1 = (-4.10\hat{i} + 3.30\hat{j} + 5.40\hat{k}) - (2.70\hat{i} - 2.90\hat{j} + 5.50\hat{k}) = -6.80\hat{i} + 6.20\hat{j} - 0.10\hat{k}$$

The work done by $\vec{F} = 2.00\hat{i} + 9.00\hat{j} + 5.30\hat{k}$ is in units

$$W = \vec{F} \cdot \Delta \vec{r} = (2.00\hat{i} + 9.00\hat{j} + 5.30\hat{k}) \cdot (-6.80\hat{i} + 6.20\hat{j} - 0.10\hat{k}) = 41.7 \text{ J}$$

b. The average power due to the force during the time interval is

$$P = \frac{W}{\Delta t} = \frac{41.7 \text{ J}}{2.10 \text{ s}} = 19.8 \text{ W}$$

c. The magnitudes of the position vectors are in units

$$r_1 = |\vec{r}_1| = \sqrt{(2.70)^2 + (-2.90)^2 + (5.50)^2} = 6.78$$

$$r_2 = |\vec{r}_2| = \sqrt{(-4.10)^2 + (3.30)^2 + (5.40)^2} = 7.54$$

and their dot product is

$$\begin{aligned}\vec{r}_1 \cdot \vec{r}_2 &= 2.70\hat{i} - 2.90\hat{j} + 5.50\hat{k} \cdot -4.10\hat{i} + 3.30\hat{j} + 5.40\hat{k} \\ &= 2.70(-4.10) + (-2.90)(3.30) + 5.50(5.40) = 9.06\end{aligned}$$

Since $\vec{r}_1 \cdot \vec{r}_2 = r_1 r_2 \cos \theta$ the angle between \vec{r}_1 and \vec{r}_2 is

$$\theta = \cos^{-1} \left(\frac{\vec{r}_1 \cdot \vec{r}_2}{r_1 r_2} \right) = \cos^{-1} \left(\frac{9.06}{6.78 \cdot 7.54} \right) = 79.8^\circ$$

85. The work done by the force is in units

$$W = \vec{F} \cdot \vec{d} = -5.00\hat{i} + 5.00\hat{j} + 4.00\hat{k} \cdot 2.00\hat{i} + 2.00\hat{j} + 7.00\hat{k} = 28$$

By energy conservation $W = \Delta K = \frac{1}{2} m v_f^2 - v_i^2$. Thus the final speed of the particle is

$$v_f = \sqrt{v_i^2 + \frac{2W}{m}} = \sqrt{4.00 \text{ m/s}^2 + \frac{2 \cdot 28}{2.00 \text{ kg}}} = 6.63 \text{ m/s}.$$

Chapter

1. **THINK** A compressed spring stores potential energy. This exercise explores the relationship between the energy stored and the spring constant.

EXPRESS The potential energy stored by the spring is given by $U = kx^2/2$ where k is the spring constant and x is the displacement of the end of the spring from its position when the spring is in equilibrium. Thus the spring constant is $k = 2U/x^2$.

ANALYZE Substituting $U = 25$ and $x = 7.5 \text{ m} = 0.075 \text{ cm}$ into the above expression we find the spring constant to be

$$k = \frac{2U}{x^2} = \frac{2(25)}{(0.075 \text{ m})^2} = 8.9 \times 10^3 \text{ N/m}.$$

LEARN The spring constant k has units N/m . The quantity provides a measure of stiffness of the spring: for a given x the greater the value of k the greater the potential energy U .

2. We use 7.12 for W_g and 7.89 for U .

a The displacement between the initial point and A is horizontal so $\phi = 90.0^\circ$ and $W_g = 0$ since $\cos 90.0^\circ = 0$.

b The displacement between the initial point and B has a vertical component of $h/2$ downward same direction as \vec{F}_g so we obtain

$$W_g = \vec{F}_g \cdot \vec{d} = \frac{1}{2} mgh = \frac{1}{2} (825 \text{ kg})(9.80 \text{ m/s}^2)(42.0 \text{ m}) = 1.70 \times 10^5 \text{ J}.$$

c The displacement between the initial point and C has a vertical component of h downward same direction as \vec{F}_g so we obtain

$$W_g = \vec{F}_g \cdot \vec{d} = mgh = (825 \text{ kg})(9.80 \text{ m/s}^2)(42.0 \text{ m}) = 3.40 \times 10^5 \text{ J}.$$

d With the reference position at C we obtain

$$U_B = \frac{1}{2} mgh = \frac{1}{2} (825 \text{ kg})(9.80 \text{ m/s}^2)(42.0 \text{ m}) = 1.70 \times 10^5 \text{ J}.$$

e. Similarly we find

$$U_A = mgh = 825 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 42.0 \text{ m} = 3.40 \times 10^5 \text{ J}.$$

f. If the answers are proportional to the mass of the object, if the mass is doubled all answers are doubled.

3. a. Noting that the vertical displacement is $10.0 \text{ m} - 1.50 \text{ m} = 8.50 \text{ m}$ down and same direction as \vec{F}_g , 7.12 yields

$$W_g = mgd \cos \phi = 2.00 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 8.50 \text{ m} \cos 0^\circ = 167 \text{ J}.$$

b. One approach which is fairly trivial is to use 7.81 but we feel it is instructive to instead calculate this as ΔU here $U = mgy$ with up and understood to be the y direction. The result is

$$\Delta U = mg(y_f - y_i) = 2.00 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 1.50 \text{ m} - 10.0 \text{ m} = -167 \text{ J}.$$

c. In part b we used the fact that $U_i = mgy_i = 196 \text{ J}$.

d. In part b we also used the fact $U_f = mgy_f = 29 \text{ J}$.

e. The computation of W_g does not use the new information that $U = 100 \text{ J}$ at the ground so we again obtain $W_g = 167 \text{ J}$.

f. As a result of 7.81 we must again find $\Delta U = -W_g = -167 \text{ J}$.

g. With this new information that $U_0 = 100 \text{ J}$ here $y = 0$ we have

$$U_i = mgy_i \quad U_0 = 296 \text{ J}.$$

h. With this new information that $U_0 = 100 \text{ J}$ here $y = 0$ we have

$$U_f = mgy_f \quad U_0 = 129 \text{ J}.$$

We can check part f by subtracting the new U_i from this result.

4. a. The only force that does work on the ball is the force of gravity; the force of the rod is perpendicular to the path of the ball and so does no work. In going from its initial position to the lowest point on its path the ball moves vertically through a distance equal to the length L of the rod so the work done by the force of gravity is

$$W = mgL = 0.341 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 0.452 \text{ m} = 1.51 \text{ J}.$$

b In going from its initial position to the highest point on its path the ball moves vertically through a distance equal to L but this time the displacement is up and opposite the direction of the force of gravity. The work done by the force of gravity is

$$W = -mgL = - (0.341 \text{ kg}) (9.80 \text{ m/s}^2) (0.452 \text{ m}) = -1.51 \text{ J}.$$

c The final position of the ball is at the same height as its initial position. The displacement is horizontal perpendicular to the force of gravity. The force of gravity does no work during this displacement.

d The force of gravity is conservative. The change in the gravitational potential energy of the ball-Earth system is the negative of the work done by gravity

$$\Delta U = -mgL = - (0.341 \text{ kg}) (9.80 \text{ m/s}^2) (0.452 \text{ m}) = -1.51 \text{ J}$$

as the ball goes to the lowest point.

e Continuing this line of reasoning we find

$$\Delta U = +mgL = (0.341 \text{ kg}) (9.80 \text{ m/s}^2) (0.452 \text{ m}) = 1.51 \text{ J}$$

as it goes to the highest point.

f Continuing this line of reasoning we have $\Delta U = 0$ as it goes to the point at the same height.

g The change in the gravitational potential energy depends only on the initial and final positions of the ball not on its speed anywhere. The change in the potential energy is the *same* since the initial and final positions are the same.

5. **THINK** As the ice flake slides down the frictionless bowl its potential energy changes due to the work done by the gravitational force.

EXPRESS The force of gravity is constant so the work it does is given by $W = \vec{F} \cdot \vec{d}$ where \vec{F} is the force and \vec{d} is the displacement. The force is vertically downward and has magnitude mg where m is the mass of the flake so this reduces to $W = mgh$ where h is the height from which the flake falls. The force of gravity is conservative so the change in gravitational potential energy of the flake-Earth system is the negative of the work done $\Delta U = -W$.

ANALYZE As the ice flake falls a distance $h = r = 22.0 \text{ cm} = 0.22 \text{ m}$. Therefore the work done by gravity is

$$W = mgr = (2.00 \times 10^{-3} \text{ kg}) (9.8 \text{ m/s}^2) (22.0 \times 10^{-2} \text{ m}) = 4.31 \times 10^{-3} \text{ J}.$$

- b The change in gravitational potential energy is $\Delta U = -W = -4.31 \times 10^{-3}$.
- c The potential energy when the flake is at the top is greater than when it is at the bottom by ΔU . If $U = 0$ at the bottom then $U = 4.31 \times 10^{-3}$ at the top.
- d If $U = 0$ at the top then $U = -4.31 \times 10^{-3}$ at the bottom.
- e All the answers are proportional to the mass of the flake. If the mass is doubled all answers are doubled.

LEARN While the potential energy depends on the reference point location where $U = 0$ the change in potential energy ΔU does not. In both c and d we find $\Delta U = -4.31 \times 10^{-3}$.

6. We use 3.712 for W_g and 3.89 for U .

a The displacement between the initial point and Q has a vertical component of $h - R$ downward and same direction as \vec{F}_g so with $h = 5R$ we obtain

$$W_g = \vec{F}_g \cdot \vec{d} = 4mgR = 4(3.20 \times 10^{-2} \text{ kg})(9.80 \text{ m/s}^2)(0.12 \text{ m}) = 0.15 \text{ J}.$$

b The displacement between the initial point and the top of the loop has a vertical component of $h - 2R$ downward and same direction as \vec{F}_g so with $h = 5R$ we obtain

$$W_g = \vec{F}_g \cdot \vec{d} = 3mgR = 3(3.20 \times 10^{-2} \text{ kg})(9.80 \text{ m/s}^2)(0.12 \text{ m}) = 0.11 \text{ J}.$$

c With $y = h = 5R$ at P we find

$$U = 5mgR = 5(3.20 \times 10^{-2} \text{ kg})(9.80 \text{ m/s}^2)(0.12 \text{ m}) = 0.19 \text{ J}.$$

d With $y = R$ at Q we have

$$U = mgR = (3.20 \times 10^{-2} \text{ kg})(9.80 \text{ m/s}^2)(0.12 \text{ m}) = 0.038 \text{ J}.$$

e With $y = 2R$ at the top of the loop we find

$$U = 2mgR = 2(3.20 \times 10^{-2} \text{ kg})(9.80 \text{ m/s}^2)(0.12 \text{ m}) = 0.075 \text{ J}.$$

f The new information $v_i \neq 0$ is not involved in any of the preceding computations the above results are unchanged.

7. The main challenge for students in this type of problem seems to be working out the trigonometry in order to obtain the height of the ball relative to the low point of the

sing $h = L - L \cos \theta$ for angle θ measured from vertical as shown in fig. 8.34. Since this relation which we will not derive here since we have found this to be most easily illustrated at the blackboard is established then the principal results of this problem follow from 8.7.12 for W_g and 8.8.9 for U .

a The vertical component of the displacement vector is downward with magnitude h so we obtain

$$\begin{aligned} W_g &= \vec{F}_g \cdot \vec{d} = mgh = mgL(1 - \cos \theta) \\ &= 5.00 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 2.00 \text{ m} (1 - \cos 30^\circ) = 13.1 \text{ J} \end{aligned}$$

b From 8.8.1 we have $\Delta U = -W_g = -mgL(1 - \cos \theta) = -13.1 \text{ J}$.

c With $y = h$ 8.8.9 yields $U = mgL(1 - \cos \theta) = 13.1 \text{ J}$.

d As the angle increases we intuitively see that the height h increases and less obviously from the mathematics we see that $\cos \theta$ decreases so that $1 - \cos \theta$ increases so the answers to parts a and c increase and the absolute value of the answer to part b also increases.

8. a The force of gravity is constant so the work it does is given by $W = \vec{F} \cdot \vec{d}$ where \vec{F} is the force and \vec{d} is the displacement. The force is vertically downward and has magnitude mg where m is the mass of the snowball. The expression for the work reduces to $W = mgh$ where h is the height through which the snowball drops. Thus

$$W = mgh = 1.50 \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 12.5 \text{ m} = 184 \text{ J}$$

b The force of gravity is conservative so the change in the potential energy of the snowball-earth system is the negative of the work it does $\Delta U = -W = -184 \text{ J}$.

c The potential energy when it reaches the ground is less than the potential energy when it is fired by ΔU so $U = -184 \text{ J}$ when the snowball hits the ground.

9. We use 8.8.17 representing the conservation of mechanical energy which neglects friction and other dissipative effects.

a In problem 9.2 we found $U_A = mgh$ with the reference position at C . Referring again to fig. 8.29 we see that this is the same as U_0 which implies that $K_A = K_0$ and thus that

$$v_A = v_0 = 17.0 \text{ m/s}$$

b In the solution to problem 9.2 we also found $U_B = mgh/2$. In this case we have

$$K_0 + U_0 = K_B + U_B$$

$$\frac{1}{2}mv_0^2 + mgh = \frac{1}{2}mv_B^2 + mg\left(\frac{h}{2}\right)$$

which leads to

$$v_B = \sqrt{v_0^2 + gh} = \sqrt{17.0 \text{ m s}^{-2} + 9.80 \text{ m s}^{-2} \cdot 42.0 \text{ m}} = 26.5 \text{ m s}.$$

c Similarly $v_C = \sqrt{v_0^2 + 2gh} = \sqrt{17.0 \text{ m s}^{-2} + 2 \cdot 9.80 \text{ m s}^{-2} \cdot 42.0 \text{ m}} = 33.4 \text{ m s}.$

(d) To find the “final” height, we set $K_f = 0$. In this case we have

$$K_0 + U_0 = K_f + U_f$$

$$\frac{1}{2}mv_0^2 + mgh = 0 + mgh_f$$

which yields $h_f = h + \frac{v_0^2}{2g} = 42.0 \text{ m} + \frac{17.0 \text{ m s}^{-2}}{2 \cdot 9.80 \text{ m s}^{-2}} = 56.7 \text{ m}.$

It is evident that the above results do not depend on mass. Thus a different mass for the coaster must lead to the same results.

10. We use 8.17 representing the conservation of mechanical energy which neglects friction and other dissipative effects.

a In the solution to problem 9.3 to which this problem refers we found $U_i = mgy_i = 196$ and $U_f = mgy_f = 29.0$ assuming the reference position is at the ground. Since $K_i = 0$ in this case we have

$$0 + 196 = K_f + 29.0$$

which gives $K_f = 167$ and thus leads to $v = \sqrt{\frac{2K_f}{m}} = \sqrt{\frac{2 \cdot 167}{2.00 \text{ kg}}} = 12.9 \text{ m s}.$

b If we proceed algebraically through the calculation in part a we find $K_f = -\Delta U = mgh$ here $h = y_i - y_f$ and is positive valued. Thus

$$v = \sqrt{\frac{2K_f}{m}} = \sqrt{2gh}$$

as we might also have derived from the equations of table 2.1 particularly 2.16. The fact that the answer is independent of mass means that the answer to part b is identical to that of part a that is $v = 12.9 \text{ m s}.$

c If $K_i \neq 0$ then we find $K_f = mgh + K_i$ here K_i is necessarily positive valued. This represents a larger value for K_f than in the previous parts and thus leads to a larger value for v .

11. **THINK** As the ice flake slides down the frictionless bowl its potential energy decreases discussed in problem 8.5. By conservation of mechanical energy its kinetic energy must increase.

EXPRESS If K_i is the kinetic energy of the flake at the edge of the bowl K_f is its kinetic energy at the bottom U_i is the gravitational potential energy of the flake-earth system with the flake at the top and U_f is the gravitational potential energy with it at the bottom then

$$K_f + U_f = K_i + U_i.$$

Making the potential energy to be zero at the bottom of the bowl then the potential energy at the top is $U_i = mgr$ here $r = 0.220$ m is the radius of the bowl and m is the mass of the flake. $K_i = 0$ since the flake starts from rest. Since the problem asks for the speed at the bottom we write $K_f = mv^2/2$.

ANALYZE a Energy conservation leads to

$$K_f + U_f = K_i + U_i \Rightarrow \frac{1}{2}mv^2 + 0 = 0 + mgr.$$

The speed is $v = \sqrt{2gr} = 2.08$ m/s.

b Since the expression for speed is $v = \sqrt{2gr}$ which does not contain the mass of the flake the speed would be the same 2.08 m/s regardless of the mass of the flake.

c The final kinetic energy is given by $K_f = K_i + U_i - U_f$. If K_i is greater than before then K_f will also be greater. This means the final speed of the flake is greater.

LEARN The mechanical energy conservation principle can also be expressed as $\Delta E_{\text{mech}} = \Delta K + \Delta U = 0$ which implies $\Delta K = -\Delta U$ i.e. the increase in kinetic energy is equal to the negative of the change in potential energy.

12. We use 8.18 representing the conservation of mechanical energy. We choose the reference position for computing U to be at the ground below the cliff it is also regarded as the “final” position in our calculations.

a Using 8.9 the initial potential energy is given by $U_i = mgh$ here $h = 12.5$ m and $m = 1.50$ kg. Thus we have

$$K_i + U_i = K_f + U_f$$

$$\frac{1}{2}mv_i^2 + mgh = \frac{1}{2}mv^2 + 0$$

which leads to the speed of the snow ball at the instant before striking the ground

$$v = \sqrt{\frac{2}{m} \left(\frac{1}{2}mv_i^2 + mgh \right)} = \sqrt{v_i^2 + 2gh}$$

here $v_i = 14.0 \text{ m/s}$ is the magnitude of its initial velocity not just one component of it. thus we find $v = 21.0 \text{ m/s}$.

but as noted above v_i is the magnitude of its initial velocity and not just one component of it therefore there is no dependence on launch angle. the answer is again 21.0 m/s .

it is evident that the result for v in part (a) does not depend on mass. thus changing the mass of the snow ball does not change the result for v .

13. **THINK** As the marble moves vertically up and its gravitational potential energy increases. this energy comes from the release of elastic potential energy stored in the spring.

EXPRESS We take the reference point for gravitational potential energy to be at the position of the marble when the spring is compressed. the gravitational potential energy when the marble is at the top of its motion is $U_g = mgh$. On the other hand the energy stored in the spring is $U_s = kx^2/2$. Applying mechanical energy conservation principle allows us to solve the problem.

ANALYZE (a) the height of the highest point is $h = 20 \text{ m}$. With initial gravitational potential energy set to zero we find

$$\Delta U_g = mgh = 5.0 \times 10^{-3} \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 20 \text{ m} = 0.98 \text{ J}.$$

(b) Since the kinetic energy is zero at the release point and at the highest point then conservation of mechanical energy implies $\Delta U_g + \Delta U_s = 0$ where ΔU_s is the change in the spring's elastic potential energy. therefore $\Delta U_s = -\Delta U_g = -0.98 \text{ J}$.

(c) We take the spring potential energy to be zero when the spring is relaxed. then our result in the previous part implies that its initial potential energy is $U_s = 0.98 \text{ J}$. this must be $\frac{1}{2}kx^2$ where k is the spring constant and x is the initial compression. consequently

$$k = \frac{2U_s}{x^2} = \frac{0.98}{(0.080 \text{ m})^2} = 3.1 \times 10^2 \text{ N/m} = 3.1 \text{ kN/m}.$$

LEARN In general the marble has both kinetic and potential energies

$$\frac{1}{2}kx^2 = \frac{1}{2}mv^2 + mgy$$

At the maximum height $y_{\text{max}} = h$, $v = 0$ and $mgh = \frac{1}{2}kx^2$ or $h = \frac{kx^2}{2mg}$.

14. We use 8.18 representing the conservation of mechanical energy which neglects friction and other dissipative effects.

a. The change in potential energy is $\Delta U = mgL$ as it goes to the highest point. Thus we have

$$\begin{aligned}\Delta K + \Delta U &= 0 \\ K_{\text{top}} - K_0 + mgL &= 0\end{aligned}$$

which upon requiring $K_{\text{top}} = 0$ gives $K_0 = mgL$ and thus leads to

$$v_0 = \sqrt{\frac{2K_0}{m}} = \sqrt{2gL} = \sqrt{2 \cdot 9.80 \text{ m/s}^2 \cdot 0.452 \text{ m}} = 2.98 \text{ m/s}.$$

b. We also found in problem 9.4 that the potential energy change is $\Delta U = -mgL$ in going from the initial point to the lowest point the bottom. Thus

$$\begin{aligned}\Delta K + \Delta U &= 0 \\ K_{\text{bottom}} - K_0 - mgL &= 0\end{aligned}$$

which with $K_0 = mgL$ leads to $K_{\text{bottom}} = 2mgL$. Therefore

$$v_{\text{bottom}} = \sqrt{\frac{2K_{\text{bottom}}}{m}} = \sqrt{4gL} = \sqrt{4 \cdot 9.80 \text{ m/s}^2 \cdot 0.452 \text{ m}} = 4.21 \text{ m/s}.$$

c. Since there is no change in height going from initial point to the rightmost point then $\Delta U = 0$ which implies $\Delta K = 0$. Consequently the speed is the same as that it has initially

$$v_{\text{right}} = v_0 = 2.98 \text{ m/s}.$$

d. It is evident from the above manipulations that the results do not depend on mass. Thus a different mass for the ball must lead to the same results.

15. **THINK** The truck with failed brakes is moving up an escape ramp. In order for it to come to a complete stop all of its kinetic energy must be converted into gravitational potential energy.

EXPRESS We ignore any work done by friction. In units the initial speed of the truck just before entering the escape ramp is $v_i = 130 \frac{1000}{3600} = 36.1 \text{ m/s}$. When the truck comes to a stop its kinetic and potential energies are $K_f = 0$ and $U_f = mgh$. We apply mechanical energy conservation to solve the problem.

ANALYZE Energy conservation implies $K_f + U_f = K_i + U_i$. With $U_i = 0$ and

$$K_i = \frac{1}{2}mv_i^2 \quad \text{we obtain}$$

$$\frac{1}{2}mv_i^2 + 0 = 0 + mgh \Rightarrow h = \frac{v_i^2}{2g} = \frac{36.1^2 \text{ m}^2/\text{s}^2}{2 \cdot 9.8 \text{ m/s}^2} = 66.5 \text{ m}.$$

If L is the minimum length of the ramp then $L \sin \theta = h$ or $L \sin 15^\circ = 66.5 \text{ m}$ so that $L = 66.5 \text{ m} / \sin 15^\circ = 257 \text{ m}$. That is the ramp must be about $2.6 \times 10^2 \text{ m}$ long if friction is negligible.

b The minimum length is $L = \frac{h}{\sin \theta} = \frac{v_i^2}{2g \sin \theta}$ which does not depend on the mass of the truck. Thus the answer remains the same if the mass is reduced.

c If the speed is decreased then h and L both decrease note that h is proportional to the square of the speed and that L is proportional to h .

LEARN The greater the speed of the truck the longer the ramp required. This length can be shortened considerably if the friction between the tires and the ramp surface is factored in.

16. We place the reference position for evaluating gravitational potential energy at the relaxed position of the spring. We use x for the spring's compression measured positively downward so $x = 0$ means it is compressed.

a With $x = 0.190 \text{ m}$, 7.26 gives

$$W_s = -\frac{1}{2}kx^2 = -7.22 \approx -7.2$$

for the work done by the spring force. Using Newton's third law we see that the work done on the spring is 7.2 J .

b As noted above $W_s = -7.2 \text{ J}$.

c Energy conservation leads to

$$K_i + U_i = K_f + U_f \Rightarrow 0 + mgh_0 = \frac{1}{2}kx^2 - mgx$$

which with $m = 0.70 \text{ kg}$ yields $h_0 = 0.86 \text{ m}$.

and with a new value for the height $h'_0 = 2h_0 = 1.72 \text{ m}$ we solve for a new value of x using the quadratic formula taking its positive root so that $x \geq 0$.

$$mgh'_0 = -mgx + \frac{1}{2}kx^2 \Rightarrow x = \frac{mg + \sqrt{(mg)^2 + 2mgkh'_0}}{k}$$

which yields $x = 0.26 \text{ m}$.

17. at Q the block which is in circular motion at that point experiences a centripetal acceleration v^2/R leftward. We find v^2 from energy conservation

$$K_P + U_P = K_Q + U_Q$$

$$0 + mgh = \frac{1}{2}mv^2 + mgR$$

using the fact that $h = 5R$ we find $mv^2 = 8mgR$. Thus the horizontal component of the net force on the block at Q is

$$F = mv^2/R = 8mg = 8(0.032 \text{ kg})(9.8 \text{ m/s}^2) = 2.5 \text{ N}.$$

The direction is to the left in the same direction as \vec{a} .

b. The downward component of the net force on the block at Q is the downward force of gravity

$$F = mg = 0.032 \text{ kg}(9.8 \text{ m/s}^2) = 0.31 \text{ N}.$$

c. To barely make the top of the loop the centripetal force there must equal the force of gravity

$$\frac{mv_t^2}{R} = mg \Rightarrow mv_t^2 = mgR.$$

This requires a different value of h than that as used above.

$$K_P + U_P = K_t + U_t$$

$$0 + mgh = \frac{1}{2}mv_t^2 + mgh_t$$

$$mgh = \frac{1}{2}mgR + mg(2R)$$

Consequently $h = 2.5R = 2.5(0.12 \text{ m}) = 0.30 \text{ m}$.

and the normal force F_N for speeds v_t greater than \sqrt{gR} which are the only possibilities for non-zero F_N — see the solution in the previous part — obeys

$$F_N = \frac{mv_t^2}{R} - mg$$

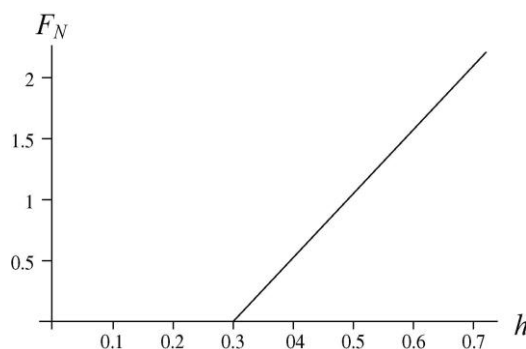
from the conservation of energy. Since v_t^2 is related to h by energy conservation

$$K_p + U_p = K_t + U_t \Rightarrow gh = \frac{1}{2}v_t^2 + 2gR$$

then the normal force as a function for h so long as $h \geq 2.5R$ — see the solution in the previous part — becomes

$$F_N = \frac{2mgh}{R} - 5mg.$$

Thus the graph for $h \geq 2.5R = 0.30$ m consists of a straight line of positive slope $2mg/R$ which can be set to some convenient values for graphing purposes. Note that for $h \leq 2.5R$ the normal force is zero.



18. We use Eq. 8.18 representing the conservation of mechanical energy. The reference position for computing U is the lowest point of the swing; it is also regarded as the “final” position in our calculations.

and the potential energy is $U = mgL(1 - \cos \theta)$ at the position shown in Fig. 8.34 which we consider to be the initial position. Thus we have

$$\begin{aligned} K_i + U_i &= K_f + U_f \\ 0 + mgL(1 - \cos \theta) &= \frac{1}{2}mv^2 + 0 \end{aligned}$$

which leads to

$$v = \sqrt{\frac{2mgL(1 - \cos \theta)}{m}} = \sqrt{2gL(1 - \cos \theta)}.$$

ugging in $L = 2.00 \text{ m}$ and $\theta = 30.0^\circ$ we find $v = 2.29 \text{ m/s}$.

It is evident that the result for v does not depend on mass. Thus a different mass for the ball must not change the result.

19. We convert to SI units and choose up and as the y direction. Also the relaxed position of the top end of the spring is the origin so the initial compression of the spring defining an equilibrium situation between the spring force and the force of gravity is $y_0 = -0.100 \text{ m}$ and the additional compression brings it to the position $y_1 = -0.400 \text{ m}$.

a When the stone is in the equilibrium $a = 0$ position Newton's second law becomes

$$\begin{aligned}\vec{F}_{\text{net}} &= m\vec{a} \\ F_{\text{spring}} - mg &= 0 \\ -k(-0.100) - (8.00)(9.8) &= 0\end{aligned}$$

here Hooke's law (Eq. 7.21) has been used. This leads to a spring constant equal to $k = 784 \text{ N/m}$.

b With the additional compression and release the acceleration is no longer zero and the stone will start moving up and turning some of its elastic potential energy stored in the spring into kinetic energy. The amount of elastic potential energy at the moment of release is using Eq. 8.11

$$U = \frac{1}{2}ky_1^2 = \frac{1}{2}(784 \text{ N/m})(-0.400)^2 = 62.7 \text{ J}.$$

c Its maximum height y_2 is beyond the point that the stone separates from the spring entering free fall motion. As usual it is characterized by having momentarily zero speed. If we choose the y_1 position as the reference position in computing the gravitational potential energy then

$$\begin{aligned}K_1 + U_1 &= K_2 + U_2 \\ 0 + \frac{1}{2}ky_1^2 &= 0 + mgh\end{aligned}$$

here $h = y_2 - y_1$ is the height above the release point. Thus mgh the gravitational potential energy is seen to be equal to the previous answer 62.7 J and we proceed with the solution in the next part.

d We find $h = ky_1^2/2mg = 0.800 \text{ m}$ or 80.0 cm.

20. a We take the reference point for gravitational energy to be at the lowest point of the string. Let θ be the angle measured from vertical. Then the height y of the pendulum "bob" (the object at the end of the pendulum, which in this problem is the stone) is given by $L(1 - \cos\theta) = y$. Hence the gravitational potential energy is

$$mgy = mgL(1 - \cos\theta).$$

When $\theta = 0$ the string is at its lowest point. We are told that its speed is 8.0 m/s ; its kinetic energy there is therefore 64 J . Using $\theta = 60^\circ$, its mechanical energy is

$$E_{\text{mech}} = \frac{1}{2}mv^2 = mgL(1 - \cos\theta).$$

Energy conservation (since there is no friction) requires that this be equal to 64 J . Solving for the speed, we find $v = 5.0 \text{ m/s}$.

But we now set the above expression again equal to 64 J , with θ being the unknown, but with zero speed, which gives the condition for the maximum point, or “turning point” that it reaches. This leads to $\theta_{\text{max}} = 79^\circ$.

As observed in our solution to part (a), the total mechanical energy is 64 J .

21. We use Eq. 8-18 representing the conservation of mechanical energy, which neglects friction and other dissipative effects. The reference position for computing U (and height h) is the lowest point of the swing; it is also regarded as the “final” position in our calculations.

A careful examination of the figure leads to the trigonometric relation $h = L - L \cos\theta$. When the angle is measured from vertical as shown, thus the gravitational potential energy is $U = mgL(1 - \cos\theta_0)$ at the position shown in Fig. 8-34, the initial position. Thus we have

$$\begin{aligned} K_0 + U_0 &= K_f + U_f \\ \frac{1}{2}mv_0^2 + mgL(1 - \cos\theta_0) &= \frac{1}{2}mv^2 + 0 \end{aligned}$$

which leads to

$$\begin{aligned} v &= \sqrt{\frac{2}{m} \left[\frac{1}{2}mv_0^2 + mgL(1 - \cos\theta_0) \right]} = \sqrt{v_0^2 + 2gL(1 - \cos\theta_0)} \\ &= \sqrt{(8.00 \text{ m/s})^2 + 2(9.80 \text{ m/s}^2)(1.25 \text{ m})(1 - \cos 40^\circ)} = 8.35 \text{ m/s}. \end{aligned}$$

But we look for the initial speed required to barely reach the horizontal position — described by $v_h = 0$ and $\theta = 90^\circ$ or $\theta = -90^\circ$ if one prefers, but since $\cos(-\phi) = \cos\phi$ the sign of the angle is not a concern.

$$\begin{aligned} K_0 + U_0 &= K_h + U_h \\ \frac{1}{2}mv_0^2 + mgL(1 - \cos\theta_0) &= 0 + mgL \end{aligned}$$

which yields

$$v_0 = \sqrt{2gL \cos\theta_0} = \sqrt{2(9.80 \text{ m/s}^2)(1.25 \text{ m}) \cos 40^\circ} = 4.33 \text{ m/s}.$$

For the cord to remain straight then the centripetal force at the top must be at least equal to gravitational force

$$\frac{mv_t^2}{r} = mg \Rightarrow mv_t^2 = mgL$$

Here we recognize that $r = L$. We plug this into the expression for the kinetic energy at the top where $\theta = 180^\circ$.

$$K_0 + U_0 = K_t + U_t$$

$$\frac{1}{2}mv_0^2 + mgL(1 - \cos\theta_0) = \frac{1}{2}mv_t^2 + mg(1 - \cos 180^\circ)$$

$$\frac{1}{2}mv_0^2 + mgL(1 - \cos\theta_0) = \frac{1}{2}mgL + mg(2L)$$

which leads to

$$v_0 = \sqrt{gL(3 + 2\cos\theta_0)} = \sqrt{9.80 \text{ m/s}^2 \cdot 1.25 \text{ m} \cdot 3 + 2\cos 40^\circ} = 7.45 \text{ m/s}.$$

the more initial potential energy there is the less initial kinetic energy there needs to be in order to reach the positions described in parts b and c. Increasing θ_0 amounts to increasing U_0 so we see that a greater value of θ_0 leads to smaller results for v_0 in parts b and c.

22. From chapter 4 we know the height h of the skier's jump can be found from $v_y^2 = 0 = v_{0,y}^2 - 2gh$ where $v_{0,y} = v_0 \sin 28^\circ$ is the upward component of the skier's "launch velocity." To find v_0 we use energy conservation.

a. The skier starts at rest $y = 20 \text{ m}$ above the point of "launch" so energy conservation leads to

$$mgy = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{2gy} = 20 \text{ m/s}$$

which becomes the initial speed v_0 for the launch. Hence the above equation relating h to v_0 yields

$$h = \frac{(v_0 \sin 28^\circ)^2}{2g} = 4.4 \text{ m}.$$

b. We see that all reference to mass cancels from the above computations so a new value for the mass will yield the same result as before.

23. As the string reaches its lowest point its original potential energy $U = mgL$ measured relative to the lowest point is converted into kinetic energy. Thus

$$mgL = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{2gL}.$$

With $L = 1.20 \text{ m}$ we obtain $v = \sqrt{2gL} = \sqrt{2(9.80 \text{ m/s}^2)(1.20 \text{ m})} = 4.85 \text{ m/s}.$

But in this case the total mechanical energy is shared between kinetic $\frac{1}{2}mv_b^2$ and potential $mg y_b$. We note that $y_b = 2r$ here $r = L - d = 0.450 \text{ m}$. Energy conservation leads to

$$mgL = \frac{1}{2}mv_b^2 + mg y_b$$

which yields $v_b = \sqrt{2gL - 2g(2r)} = 2.42 \text{ m/s}.$

24. We denote m as the mass of the block, $h = 0.40 \text{ m}$ as the height from which it dropped (measured from the relaxed position of the spring) and x as the compression of the spring (measured downward) so that it yields a positive value. Our reference point for the gravitational potential energy is the initial position of the block. The block drops a total distance $h + x$ and the final gravitational potential energy is $-mg(h + x)$. The spring potential energy is $\frac{1}{2}kx^2$ in the final situation and the kinetic energy is zero both at the beginning and end. Since energy is conserved

$$K_i + U_i = K_f + U_f$$

$$0 = -mg(h + x) + \frac{1}{2}kx^2$$

which is a second degree equation in x . Using the quadratic formula its solution is

$$x = \frac{mg \pm \sqrt{(mg)^2 + 2mghk}}{k}.$$

So $mg = 19.6$, $h = 0.40 \text{ m}$ and $k = 1960 \text{ N/m}$ and we choose the positive root so that $x > 0$.

$$x = \frac{19.6 + \sqrt{19.6^2 + 2(19.6)(0.40)(1960)}}{1960} = 0.10 \text{ m}.$$

25. Since time does not directly enter into the energy formulations we return to Chapter 4 or Table 2.1 in Chapter 2 to find the change of height during this $t = 6.0 \text{ s}$ flight.

$$\Delta y = v_{0y}t - \frac{1}{2}gt^2$$

This leads to $\Delta y = -32 \text{ m}$. Therefore $\Delta U = mg\Delta y = -318 \text{ J} \approx -3.2 \times 10^2 \text{ J}.$

26. a With energy in joules and length in meters we have

$$\Delta U = U(x) - U(0) = -\int_0^x (6x' - 12) dx'.$$

herefore with $U(0) = 27$ we obtain $U(x)$ written simply as U by integrating and rearranging

$$U = 27 + 12x - 3x^2.$$

b We can maximize the above function by working through the $dU/dx = 0$ condition or we can treat this as a force equilibrium situation — which is the approach we show.

$$F = 0 \Rightarrow 6x_{eq} - 12 = 0$$

thus $x_{eq} = 2.0$ m and the above expression for the potential energy becomes $U = 39$ J.

c Using the quadratic formula or using the polynomial solver on an appropriate calculator we find the negative value of x for which $U = 0$ to be $x = -1.6$ m.

d Similarly we find the positive value of x for which $U = 0$ to be $x = 5.6$ m.

27. a To find out whether or not the vine breaks it is sufficient to examine it at the moment when it swings through the lowest point — which is when the vine — if it didn't break — would have the greatest tension. Choosing upward positive Newton's second law leads to

$$T - mg = m \frac{v^2}{r}$$

here $r = 18.0$ m and $m = W/g = 688/9.8 = 70.2$ kg. We find the v^2 from energy conservation where the reference position for the potential energy is at the lowest point.

$$mgh = \frac{1}{2}mv^2 \Rightarrow v^2 = 2gh$$

here $h = 3.20$ m. Combining these results we have

$$T = mg + m \frac{2gh}{r} = mg \left(1 + \frac{2h}{r} \right)$$

which yields 933 N. Thus the vine does not break.

b Rounding to an appropriate number of significant figures we see the maximum tension is roughly 9.3×10^2 N.

28. From the slope of the graph we find the spring constant

$$k = \frac{\Delta F}{\Delta x} = 0.10 \text{ N/cm} = 10 \text{ N/m}.$$

a. Equating the potential energy of the compressed spring to the kinetic energy of the cork at the moment of release we have

$$\frac{1}{2} kx^2 = \frac{1}{2} mv^2 \Rightarrow v = x \sqrt{\frac{k}{m}}$$

which yields $v = 2.8 \text{ m/s}$ for $m = 0.0038 \text{ kg}$ and $x = 0.055 \text{ m}$.

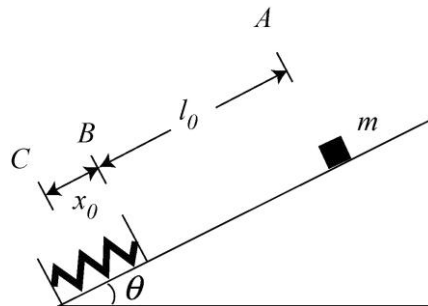
b. The new scenario involves some potential energy at the moment of release. With $d = 0.015 \text{ m}$ energy conservation becomes

$$\frac{1}{2} kx^2 = \frac{1}{2} mv^2 + \frac{1}{2} kd^2 \Rightarrow v = \sqrt{\frac{k}{m}(x^2 - d^2)}$$

which yields $v = 2.7 \text{ m/s}$.

29. **THINK** As the block slides down the inclined plane it compresses the spring then stops momentarily before sliding back up again.

EXPRESS We refer to its starting point as A the point where it first comes into contact with the spring as B and the point where the spring is compressed by $x_0 = 0.055 \text{ m}$ as C see the figure below. Point C is our reference point for computing gravitational potential energy. Elastic potential energy of the spring is zero when the spring is relaxed.



Information given in the second sentence allows us to compute the spring constant. From Hooke's law we find

$$k = \frac{F}{x} = \frac{270}{0.02 \text{ m}} = 1.35 \times 10^4 \text{ N/m}.$$

The distance between points A and B is l_0 and we note that the total sliding distance $l_0 + x_0$ is related to the initial height h_A of the block measured relative to C by $\sin \theta = \frac{h_A}{l_0 + x_0}$ where the incline angle θ is 30° .

ANALYZE a Mechanical energy conservation leads to

$$K_A + U_A = K_C + U_C \Rightarrow 0 + mgh_A = \frac{1}{2}kx_0^2$$

which yields

$$h_A = \frac{kx_0^2}{2mg} = \frac{1.35 \times 10^4 \text{ N/m} \cdot 0.055 \text{ m}^2}{2 \cdot 12 \text{ kg} \cdot 9.8 \text{ m/s}^2} = 0.174 \text{ m}.$$

therefore the total distance traveled by the block before coming to a stop is

$$l_0 + x_0 = \frac{h_A}{\sin 30^\circ} = \frac{0.174 \text{ m}}{\sin 30^\circ} = 0.347 \text{ m} \approx 0.35 \text{ m}.$$

b From this result we find $l_0 = x_0 = 0.347 \text{ m} - 0.055 \text{ m} = 0.292 \text{ m}$ which means that the block has descended a vertical distance

$$\Delta y = h_A - h_B = l_0 \sin \theta = 0.292 \text{ m} \sin 30^\circ = 0.146 \text{ m}$$

in sliding from point A to point B . Thus using 8.18 we have

$$0 + mgh_A = \frac{1}{2}mv_B^2 + mgh_B \Rightarrow \frac{1}{2}mv_B^2 = mg \Delta y$$

which yields $v_B = \sqrt{2g \Delta y} = \sqrt{2 \cdot 9.8 \text{ m/s}^2 \cdot 0.146 \text{ m}} = 1.69 \text{ m/s} \approx 1.7 \text{ m/s}.$

LEARN Energy is conserved in the process. The total energy of the block at position B is

$$E_B = \frac{1}{2}mv_B^2 + mgh_B = \frac{1}{2} \cdot 12 \text{ kg} \cdot (1.69 \text{ m/s})^2 + 12 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 0.028 \text{ m} = 20.4 \text{ J}$$

which is equal to the elastic potential energy in the spring

$$\frac{1}{2}kx_0^2 = \frac{1}{2} \cdot 1.35 \times 10^4 \text{ N/m} \cdot 0.055 \text{ m}^2 = 20.4 \text{ J}.$$

30. We take the original height of the block to be the $y = 0$ reference level and observe that in general the height of the block when the block has moved a distance d downhill is $y = -d \sin 40^\circ$.

a Using the conservation of energy we have

$$K_i + U_i = K + U \Rightarrow 0 + 0 = \frac{1}{2}mv^2 + mgy + \frac{1}{2}kd^2.$$

herefore with $d = 0.10$ m we obtain $v = 0.81$ m/s.

b We look for a value of $d \neq 0$ such that $K = 0$.

$$K_i + U_i = K + U \Rightarrow 0 + 0 = 0 + mgy + \frac{1}{2}kd^2.$$

thus we obtain $mgd \sin 40^\circ = \frac{1}{2}kd^2$ and find $d = 0.21$ m.

c The uphill force is caused by the spring Hooke's law and has magnitude $kd = 25.2$ N. The downhill force is the component of gravity $mg \sin 40^\circ = 12.6$ N. Thus the net force on the block is $25.2 - 12.6 = 12.6$ N uphill with

$$a = F/m = 12.6 / 2.0 \text{ kg} = 6.3 \text{ m/s}^2.$$

d The acceleration is up the incline.

31. The reference point for the gravitational potential energy U_g and height h is at the block when the spring is maximally compressed. When the block is moving to its highest point it is first accelerated by the spring later it separates from the spring and finally reaches a point where its speed v_f is momentarily zero. The x axis is along the incline pointing uphill so x_0 for the initial compression is negative valued its origin is at the relaxed position of the spring. We use SI units so $k = 1960$ N/m and $x_0 = -0.200$ m.

a The elastic potential energy is $\frac{1}{2}kx_0^2 = 39.2$ J.

b Since initially $U_g = 0$ the change in U_g is the same as its final value mgh here $m = 2.00$ kg. That this must equal the result in part a is made clear in the steps shown in the next part. Thus $\Delta U_g = U_g = 39.2$ J.

c The principle of mechanical energy conservation leads to

$$K_0 + U_0 = K_f + U_f$$

$$0 + \frac{1}{2}kx_0^2 = 0 + mgh$$

which yields $h = 2.00$ m. The problem asks for the distance *along the incline* so we have $d = h \sin 30^\circ = 4.00$ m.

32. The work required is the change in the gravitational potential energy as a result of the chain being pulled onto the table. Dividing the hanging chain into a large number of infinitesimal segments each of length dy we note that the mass of a segment is $m/L dy$ and the change in potential energy of a segment when it is a distance y below the table top is

$$dU = (m/L) g y dy = - (m/L) g y dy$$

since y is negative valued we have y up and the origin is at the tabletop. The total potential energy change is

$$\Delta U = -\frac{mg}{L} \int_{-L/4}^0 y dy = \frac{1}{2} \frac{mg}{L} (L/4)^2 = mgL/32.$$

The work required to pull the chain onto the table is therefore

$$W = \Delta U = mgL/32 = (0.012 \text{ kg})(9.8 \text{ m/s}^2)(0.28 \text{ m})/32 = 0.0010 \text{ J}.$$

33. If heights h are measured from the lower end of the incline which is our reference position for computing gravitational potential energy mgh . Our x axis is along the incline with x being uphill so spring compression corresponds to $x = 0$ and its origin being at the relaxed end of the spring. The height that corresponds to the canister's initial position with spring compressed amount $x = 0.200$ m is given by $h_1 = D + x \sin \theta$ where $\theta = 37^\circ$.

a. Energy conservation leads to

$$K_1 + U_1 = K_2 + U_2 \Rightarrow 0 + mg(D + x \sin \theta) + \frac{1}{2} kx^2 = \frac{1}{2} mv_2^2 + mgD \sin \theta$$

which yields using the data $m = 2.00$ kg and $k = 170$ N/m

$$v_2 = \sqrt{2gx \sin \theta + kx^2/m} = 2.40 \text{ m/s}.$$

b. In this case energy conservation leads to

$$\begin{aligned} K_1 + U_1 &= K_3 + U_3 \\ 0 + mg(D + x \sin \theta) + \frac{1}{2} kx^2 &= \frac{1}{2} mv_3^2 + 0 \end{aligned}$$

which yields $v_3 = \sqrt{2g(D + x \sin \theta) + kx^2/m} = 4.19 \text{ m/s}.$

34. Let \vec{F}_N be the normal force of the ice on him and m is his mass. The net inward force is $mg \cos \theta - F_N$ and according to the second law this must be equal to mv^2/R where v is the speed of the boy. At the point where the boy leaves the ice $F_N = 0$ so $g \cos \theta = v^2/R$. We wish to find his speed. If the gravitational potential energy is taken to be zero when he is at the top of the ice mound then his potential energy at the time shown is

$$U = -mgR(1 - \cos \theta).$$

He starts from rest and his kinetic energy at the time shown is $\frac{1}{2}mv^2$. Thus conservation of energy gives

$$0 = \frac{1}{2}mv^2 - mgR(1 - \cos \theta)$$

or $v^2 = 2gR(1 - \cos \theta)$. We substitute this expression into the equation developed from the second law to obtain $g \cos \theta = 2g(1 - \cos \theta)$. This gives $\cos \theta = 2/3$. The height of the boy above the bottom of the mound is

$$h = R \cos \theta = \frac{2}{3}R = \frac{2}{3}(13.8 \text{ m}) = 9.20 \text{ m}.$$

35. a. The final elastic potential energy is

$$U = \frac{1}{2}kx^2 = \frac{1}{2}(431 \text{ N/m})(0.210 \text{ m})^2 = 9.50 \text{ J}.$$

Ultimately this must come from the original gravitational energy in the system mgy (where we are measuring y from the lowest “elevation” reached by the block, so

$$y = d \sin 30^\circ.$$

thus

$$mg(d \sin 30^\circ) = 9.50 \quad \Rightarrow \quad d = 0.396 \text{ m}.$$

b. The block is still accelerating due to the component of gravity along the incline $mg \sin 30^\circ$ for a few moments after coming into contact with the spring (which exerts the Hooke’s law force kx), until the Hooke’s law force is strong enough to cause the block to begin decelerating. This point is reached when

$$kx = mg \sin 30^\circ$$

which leads to $x = 0.0364 \text{ m} = 3.64 \text{ cm}$ this is long before the block finally stops 36.0 cm before it stops.

36. The distance the marble travels is determined by its initial speed and the methods of chapter 4 and the initial speed is determined using energy conservation by the original compression of the spring. We denote h as the height of the table and x as the horizontal

distance to the point where the marble lands. Then $x = v_0 t$ and $h = \frac{1}{2}gt^2$ (since the vertical component of the marble's "launch velocity" is zero). From these we find $x = v_0 \sqrt{2h/g}$. We note from this that the distance to the landing point is directly proportional to the initial speed. We denote v_{01} be the initial speed of the first shot and $D_1 = 2.20 - 0.27 \text{ m} = 1.93 \text{ m}$ be the horizontal distance to its landing point similarly v_{02} is the initial speed of the second shot and $D = 2.20 \text{ m}$ is the horizontal distance to its landing spot. Then

$$\frac{v_{02}}{v_{01}} = \frac{D}{D_1} \Rightarrow v_{02} = \frac{D}{D_1} v_{01}$$

When the spring is compressed an amount ℓ the elastic potential energy is $\frac{1}{2}k\ell^2$. When the marble leaves the spring its kinetic energy is $\frac{1}{2}mv_0^2$. Mechanical energy is conserved $\frac{1}{2}mv_0^2 = \frac{1}{2}k\ell^2$ and we see that the initial speed of the marble is directly proportional to the original compression of the spring. If ℓ_1 is the compression for the first shot and ℓ_2 is the compression for the second then $v_{02} = (\ell_2/\ell_1)v_{01}$. Relating this to the previous result we obtain

$$\ell_2 = \frac{D}{D_1} \ell_1 = \left(\frac{2.20 \text{ m}}{1.93 \text{ m}} \right) 1.10 \text{ cm} = 1.25 \text{ cm}.$$

37. Consider a differential element of length dx at a distance x from one end (the end that remains stuck) of the cord. As the cord turns vertical its change in potential energy is given by

$$dU = -\lambda dx gx$$

here $\lambda = m/h$ is the mass unit length and the negative sign indicates that the potential energy decreases. Integrating over the entire length we obtain the total change in the potential energy

$$\Delta U = \int dU = -\int_0^h \lambda gx dx = -\frac{1}{2} \lambda gh^2 = -\frac{1}{2} mgh.$$

With $m = 15 \text{ g}$ and $h = 25 \text{ cm}$ we have $\Delta U = -0.018 \text{ J}$.

38. In this problem the mechanical energy (the sum of K and U) remains constant as the particle moves.

a) Since mechanical energy is conserved $U_B + K_B = U_A + K_A$ the kinetic energy of the particle in region A ($3.00 \text{ m} \leq x \leq 4.00 \text{ m}$) is

$$K_A = U_B - U_A + K_B = 12.0 - 9.00 + 4.00 = 7.00 \text{ J}.$$

With $K_A = mv_A^2/2$ the speed of the particle at $x = 3.5 \text{ m}$ (within region A) is

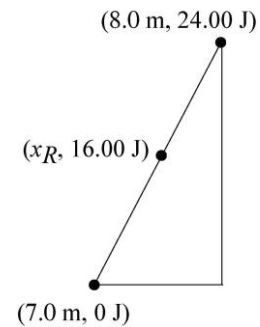
$$v_A = \sqrt{\frac{2K_A}{m}} = \sqrt{\frac{2 \cdot 7.00}{0.200 \text{ kg}}} = 8.37 \text{ m/s.}$$

b At $x = 6.5 \text{ m}$, $U = 0$ and $K = U_B + K_B = 12.0 + 4.00 = 16.0$ by mechanical energy conservation. Therefore the speed at this point is

$$v = \sqrt{\frac{2K}{m}} = \sqrt{\frac{2 \cdot 16.0}{0.200 \text{ kg}}} = 12.6 \text{ m/s.}$$

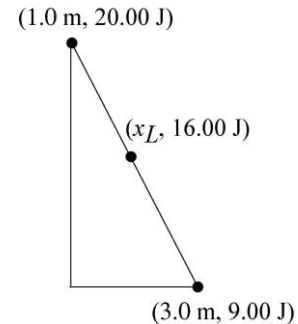
c At the turning point the speed of the particle is zero. Let the position of the right turning point be x_R . From the figure shown on the right we find x_R to be

$$\frac{16.00 - 0}{x_R - 7.00 \text{ m}} = \frac{24.00 - 16.00}{8.00 \text{ m} - x_R} \Rightarrow x_R = 7.67 \text{ m.}$$



d Let the position of the left turning point be x_L . From the figure shown we find x_L to be

$$\frac{16.00 - 20.00}{x_L - 1.00 \text{ m}} = \frac{9.00 - 16.00}{3.00 \text{ m} - x_L} \Rightarrow x_L = 1.73 \text{ m.}$$



39. From the figure we see that at $x = 4.5 \text{ m}$ the potential energy is $U_1 = 15$. If the speed is $v = 7.0 \text{ m/s}$ then the kinetic energy is

$$K_1 = mv^2/2 = 0.90 \text{ kg} \cdot (7.0 \text{ m/s})^2/2 = 22.$$

The total energy is $E_1 = U_1 + K_1 = 15 + 22 = 37$.

a At $x = 1.0 \text{ m}$ the potential energy is $U_2 = 35$. By energy conservation we have $K_2 = 2.0$. This means that the particle can reach there with a corresponding speed

$$v_2 = \sqrt{\frac{2K_2}{m}} = \sqrt{\frac{2 \cdot 2.0}{0.90 \text{ kg}}} = 2.1 \text{ m/s.}$$

b The force acting on the particle is related to the potential energy by the negative of the slope

$$F_x = -\frac{\Delta U}{\Delta x}$$

From the figure we have $F_x = -\frac{35 - 15}{2 \text{ m} - 4 \text{ m}} = +10$.

c Since the magnitude $F_x > 0$ the force points in the x direction.

d At $x = 7.0 \text{ m}$ the potential energy is $U_3 = 45$ which exceeds the initial total energy E_1 . Thus the particle can never reach there. At the turning point the kinetic energy is zero. Between $x = 5$ and 6 m the potential energy is given by

$$U(x) = 15 + 30(x - 5) \quad 5 \leq x \leq 6.$$

Thus the turning point is found by solving $37 = 15 + 30(x - 5)$ which yields $x = 5.7 \text{ m}$.

e At $x = 5.0 \text{ m}$ the force acting on the particle is

$$F_x = -\frac{\Delta U}{\Delta x} = -\frac{45 - 15}{6 - 5 \text{ m}} = -30$$
 .

The magnitude is $F_x = 30$.

f The fact that $F_x < 0$ indicated that the force points in the $-x$ direction.

40. a The force at the equilibrium position $r = r_e$ is

$$F = -\frac{dU}{dr} \bigg|_{r=r_e} = 0 \Rightarrow -\frac{12A}{r_e^{13}} + \frac{6B}{r_e^7} = 0$$

which leads to the result

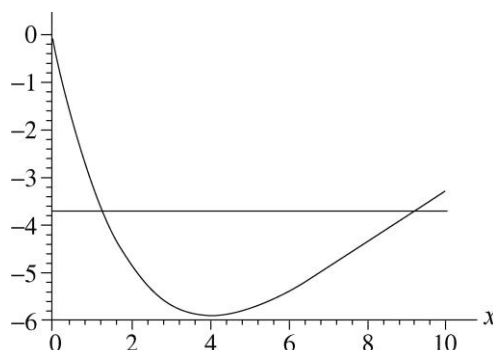
$$r_e = \left(\frac{2A}{B} \right)^{\frac{1}{6}} = 1.12 \left(\frac{A}{B} \right)^{\frac{1}{6}}.$$

b This defines a minimum in the potential energy curve as can be verified either by a graph or by taking another derivative and verifying that it is concave up and at this point which means that for values of r slightly smaller than r_e the slope of the curve is negative so the force is positive repulsive .

c And for values of r slightly larger than r_e the slope of the curve must be positive so the force is negative attractive .

41. a The energy at $x = 5.0 \text{ m}$ is $E = K + U = 2.0 - 5.7 = -3.7$.

b plot of the potential energy curve units understood and the energy E the horizontal line is shown for $0 \leq x \leq 10$ m.



c the problem asks for a graphical determination of the turning points which are the points on the curve corresponding to the total energy computed in part a. The result for the smallest turning point determined to be honest by more careful means is $x = 1.3$ m.

d and the result for the largest turning point is $x = 9.1$ m.

e since $K = E - U$ then maximizing K involves finding the minimum of U . Graphical determination suggests that this occurs at $x = 4.0$ m which plugs into the expression $E - U = -3.7 - (-4xe^{-x/4})$ to give $K = 2.16 \approx 2.2$ J. Alternatively one can measure from the graph from the minimum of the U curve up to the level representing the total energy E and thereby obtain an estimate of K at that point.

f As mentioned in the previous part the minimum of the U curve occurs at $x = 4.0$ m.

g The force understood to be in newtons follows from the potential energy using $F = -dU/dx$. 8.20 and Appendix if students are unfamiliar with such derivatives.

$$F = \frac{dU}{dx} = (4 - x)e^{-x/4}$$

h This revisits the considerations of parts d and e since we are returning to the minimum of $U(x)$ — but now with the advantage of having the analytic result of part g. We see that the location that produces $F = 0$ is exactly $x = 4.0$ m.

42. Since the velocity is constant $\vec{a} = 0$ and the horizontal component of the worker's push $F \cos \theta$ where $\theta = 32^\circ$ must equal the friction force magnitude $f_k = \mu_k F_N$. Also the vertical forces must cancel implying

$$W_{\text{applied}} = 8.0 \times 0.70 \text{ m} = 5.6$$

which is solved to find $F = 71$ N.

a The work done on the block by the worker is using 7.7

$$W = Fd \cos \theta = (71)(9.2 \text{ m}) \cos 32^\circ = 5.6 \times 10^2 \text{ J}.$$

b Since $f_k = \mu_k mg = F \sin \theta$ we find $\Delta E_{\text{th}} = f_k d = 60(9.2 \text{ m}) = 5.6 \times 10^2 \text{ J}.$

43. a Using 7.8 we have $W_{\text{applied}} = 8.0(0.70 \text{ m}) = 5.6 \text{ J}.$

b Using 8.31 the thermal energy generated is $\Delta E_{\text{th}} = f_k d = 5.0(0.70 \text{ m}) = 3.5 \text{ J}.$

44. a The work is $W = Fd = 35.0(3.00 \text{ m}) = 105 \text{ J}.$

b The total amount of energy that has gone to thermal forms is see 8.31 and 6.2

$$\Delta E_{\text{th}} = \mu_k mgd = 0.600(4.00 \text{ kg})(9.80 \text{ m/s}^2)(3.00 \text{ m}) = 70.6 \text{ J}.$$

If 40.0 J has gone to the block then $70.6 - 40.0 = 30.6 \text{ J}$ has gone to the floor.

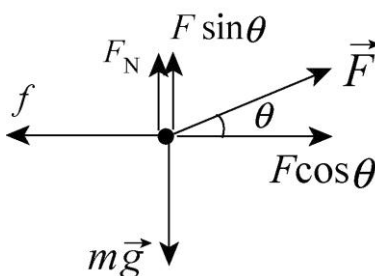
c Much of the work (105 J) has been “wasted” due to the 70.6 J of thermal energy generated but there still remains $105 - 70.6 = 34.4 \text{ J}$ that has gone into increasing the kinetic energy of the block. It has not gone into increasing the potential energy of the block because the floor is presumed to be horizontal.

45. **THINK** Work is done against friction while pulling a block along the floor at a constant speed.

EXPRESS Place the x axis along the path of the block and the y axis normal to the floor. The free body diagram is shown below. The x and the y component of the tension second law are

$$\begin{aligned} x & F \cos \theta - f = 0 \\ y & F_N - F \sin \theta - mg = 0 \end{aligned}$$

where m is the mass of the block F is the force exerted by the rope f is the magnitude of the kinetic friction force and θ is the angle between that force and the horizontal.



he work done on the block by the force in the rope is $W = Fd \cos \theta$. Similarly the increase in thermal energy of the block floor system due to the frictional force is given by
 $\Delta E_{\text{th}} = fd$.

ANALYZE a substituting the values given we find the work done on the block by the rope's force to be

$$W = Fd \cos \theta = 7.68 \text{ N} \cdot 4.06 \text{ m} \cos 15.0^\circ = 30.1 \text{ J}.$$

b the increase in thermal energy is $\Delta E_{\text{th}} = fd = 7.42 \text{ N} \cdot 4.06 \text{ m} = 30.1 \text{ J}$.

c we can use Newton's second law of motion to obtain the frictional and normal forces then use $\mu_k = f/F_N$ to obtain the coefficient of friction. The x component of Newton's law gives

$$f = F \cos \theta = 7.68 \text{ N} \cos 15.0^\circ = 7.42 \text{ N}.$$

Similarly the y component yields

$$F_N = mg - F \sin \theta = 3.57 \text{ kg} \cdot 9.8 \text{ m/s}^2 - 7.68 \text{ N} \sin 15.0^\circ = 33.0 \text{ N}.$$

thus the coefficient of kinetic friction is

$$\mu_k = \frac{f}{F_N} = \frac{7.42}{33.0} = 0.225.$$

LEARN In this problem the block moves at a constant speed so that $\Delta K = 0$ i.e. no change in kinetic energy. The work done by the external force is converted into thermal energy of the system $W = \Delta E_{\text{th}}$.

46. We work this using English units with $g = 32 \text{ ft/s}^2$ but for consistency we convert the weight to pounds

$$mg = 9.0 \text{ lb} \cdot \left(\frac{1 \text{ lb}}{16 \text{ lb}} \right) = 0.56 \text{ lb}$$

which implies $m = 0.018 \text{ lb} \cdot \text{s}^2/\text{ft}$ which can be phrased as 0.018 slug as explained in Appendix D. And we convert the initial speed to feet per second

$$v_i = 81.8 \text{ mi/h} \cdot \left(\frac{5280 \text{ ft/mi}}{3600 \text{ s/h}} \right) = 120 \text{ ft/s}$$

or a more "direct" conversion from Appendix D can be used. Equation 8.30 provides $\Delta E_{\text{th}} = -\Delta E_{\text{mec}}$ for the energy "lost" in the sense of this problem. Thus

$$\Delta E_{\text{th}} = \frac{1}{2} m v_i^2 - v_f^2 + mg y_i - y_f = \frac{1}{2} (0.018 \text{ kg}) (120^2 - 110^2) + 0 = 20 \text{ ft} \cdot \text{lb}.$$

47. We use SI units so $m = 0.075 \text{ kg}$. Equation 8.33 provides $\Delta E_{\text{th}} = -\Delta E_{\text{mec}}$ for the energy “lost” in the sense of this problem. Thus,

$$\begin{aligned} \Delta E_{\text{th}} &= \frac{1}{2} m v_i^2 - v_f^2 + mg y_i - y_f \\ &= \frac{1}{2} (0.075 \text{ kg}) (12 \text{ m/s})^2 - (10.5 \text{ m/s})^2 + (0.075 \text{ kg}) (9.8 \text{ m/s}^2) (1.1 \text{ m} - 2.1 \text{ m}) \\ &= 0.53 \text{ J}. \end{aligned}$$

48. We use Eq. 8.31 to obtain $\Delta E_{\text{th}} = f_k d = (10 \text{ N}) (5.0 \text{ m}) = 50 \text{ J}$ and Eq. 8.7 to get

$$W = Fd = (2.0 \text{ N}) (5.0 \text{ m}) = 10 \text{ J}.$$

Similarly, Eq. 8.31 gives

$$\begin{aligned} W &= \Delta K + \Delta U + \Delta E_{\text{th}} \\ 10 &= 35 + \Delta U + 50 \end{aligned}$$

which yields $\Delta U = -75 \text{ J}$. Using Eq. 8.1 then the work done by gravity is $W = -\Delta U = 75 \text{ J}$.

49. **THINK** As the bear slides down the tree its gravitational potential energy is converted into both kinetic energy and thermal energy.

EXPRESS We take the initial gravitational potential energy to be $U_i = mgL$ where L is the length of the tree and final gravitational potential energy at the bottom to be $U_f = 0$. To solve this problem we note that the changes in the mechanical and thermal energies must sum to zero.

ANALYZE a. Substituting the values given the change in gravitational potential energy is

$$\Delta U = U_f - U_i = -mgL = -(25 \text{ kg}) (9.8 \text{ m/s}^2) (12 \text{ m}) = -2.9 \times 10^3 \text{ J}.$$

b. The final speed is $v_f = 5.6 \text{ m/s}$. Therefore the kinetic energy is

$$K_f = \frac{1}{2} m v_f^2 = \frac{1}{2} (25 \text{ kg}) (5.6 \text{ m/s})^2 = 3.9 \times 10^2 \text{ J}.$$

c. The change in thermal energy is $\Delta E_{\text{th}} = fL$ where f is the magnitude of the average frictional force. Therefore from $\Delta E_{\text{th}} + \Delta K + \Delta U = 0$ we find f to be

$$f = -\frac{\Delta K + \Delta U}{L} = -\frac{3.9 \times 10^2 \text{ J} - 2.9 \times 10^3 \text{ J}}{12 \text{ m}} = 2.1 \times 10^2 \text{ N}.$$

LEARN In this problem no external work is done to the bear. therefore

$$W = \Delta E_{\text{th}} + \Delta E_{\text{mech}} = \Delta E_{\text{th}} + \Delta K + \Delta U = 0$$

which implies $\Delta K = -\Delta U - \Delta E_{\text{th}} = -\Delta U - fL$. Thus $\Delta E_{\text{th}} = fL$ can be interpreted as the additional change (decrease) in kinetic energy due to frictional force.

50. Equation 8.33 provides $\Delta E_{\text{th}} = -\Delta E_{\text{mec}}$ for the energy “lost” in the sense of this problem. Thus

$$\begin{aligned}\Delta E_{\text{th}} &= \frac{1}{2} m (v_i^2 - v_f^2) + mg (y_i - y_f) \\ &= \frac{1}{2} (60 \text{ kg}) (24 \text{ m/s}^2 - 22 \text{ m/s}^2) + (60 \text{ kg}) (9.8 \text{ m/s}^2) (14 \text{ m}) \\ &= 1.1 \times 10^4 \text{ J}.\end{aligned}$$

That the angle of 25° is nowhere used in this calculation is indicative of the fact that energy is a scalar quantity.

51. a. The initial potential energy is

$$U_i = mgy_i = (520 \text{ kg}) (9.8 \text{ m/s}^2) (300 \text{ m}) = 1.53 \times 10^6 \text{ J}$$

here y is upward and $y = 0$ at the bottom so that $U_f = 0$.

b. Since $f_k = \mu_k F_N = \mu_k mg \cos \theta$ we have $\Delta E_{\text{th}} = f_k d = \mu_k mg d \cos \theta$ from Eq. 8.31. On the hillside surface of length $d = 500 \text{ m}$ is treated as an hypotenuse of a 3-4-5 triangle so $\cos \theta = x/d$ where $x = 400 \text{ m}$. Therefore

$$\Delta E_{\text{th}} = \mu_k mg d \frac{x}{d} = \mu_k mg x = (0.25) (520) (9.8) (400) = 5.1 \times 10^5 \text{ J}.$$

c. Using Eq. 8.31 with $W = 0$ we find

$$K_f = K_i + U_i - U_f - \Delta E_{\text{th}} = 0 + 1.53 \times 10^6 - 0 - 5.1 \times 10^5 = 1.02 \times 10^6 \text{ J}.$$

d. From $K_f = mv^2/2$ we obtain $v = 63 \text{ m/s}$.

52. a. An appropriate picture (once friction is included) for this problem is Figure 8.3 in the textbook. We apply Eq. 8.31 $\Delta E_{\text{th}} = f_k d$ and relate initial kinetic energy K_i to the resting potential energy U_r .

$$K_i + U_i = f_k d + K_r + U_r \Rightarrow 20.0 - 0 = f_k d - 0 - \frac{1}{2} kd^2$$

here $f_k = 10.0$ and $k = 400$ N/m. We solve the equation for d using the quadratic formula or by using the polynomial solver on an appropriate calculator with $d = 0.292$ m being the only positive root.

b We apply Eq. 8.31 again and relate U_r to the second kinetic energy K_s it has at the unstretched position.

$$K_r + U_r = f_k d + K_s + U_s \Rightarrow \frac{1}{2} k d^2 = f_k d + K_s = 0$$

Using the result from part (a) this yields $K_s = 14.2$ J.

53. (a) The vertical forces acting on the block are the normal force upward and the force of gravity downward. Since the vertical component of the block's acceleration is zero, Newton's second law requires $F_N = mg$ where m is the mass of the block. Thus $f = \mu_k F_N = \mu_k mg$. The increase in thermal energy is given by $\Delta E_{th} = f d = \mu_k mg D$ where D is the distance the block moves before coming to rest. Using Eq. 8.29 we have

$$\Delta E_{th} = (0.25)(3.5 \text{ kg})(9.8 \text{ m/s}^2)(7.8 \text{ m}) = 67 \text{ J}.$$

b The block has its maximum kinetic energy K_{ma} just as it leaves the spring and enters the region where friction acts. Therefore the maximum kinetic energy equals the thermal energy generated in bringing the block back to rest: 67 J.

c The energy that appears as kinetic energy is originally in the form of potential energy in the compressed spring. Thus $K_{ma} = U_i = \frac{1}{2} k x^2$ where k is the spring constant and x is the compression. Thus

$$x = \sqrt{\frac{2 K_{ma}}{k}} = \sqrt{\frac{2(67 \text{ J})}{640 \text{ N/m}}} = 0.46 \text{ m}.$$

54. (a) Using the force analysis shown in Chapter 6 we find the normal force $F_N = mg \cos \theta$ where $mg = 267$ N which means

$$f_k = \mu_k F_N = \mu_k mg \cos \theta.$$

Using Eq. 8.31 yields

$$\Delta E_{th} = f_k d = \mu_k mg d \cos \theta = (0.10)(267)(6.1) \cos 20^\circ = 1.5 \times 10^2 \text{ J}.$$

b The potential energy change is

$$\Delta U = mg(-d \sin \theta) = 267(-6.1 \text{ m} \sin 20^\circ) = -5.6 \times 10^2 \text{ J}.$$

the initial kinetic energy is

$$K_i = \frac{1}{2}mv_i^2 = \frac{1}{2}\left(\frac{267}{9.8\text{ m s}^2}\right) 0.457\text{ m s}^2 = 2.8 \text{ J}$$

herefore using Eq. 8-33 with $W = 0$ the final kinetic energy is

$$K_f = K_i - \Delta U - \Delta E_{\text{th}} = 2.8 - (-5.6 \times 10^2) - 1.5 \times 10^2 = 4.1 \times 10^2 \text{ J}$$

Consequently the final speed is $v_f = \sqrt{2K_f/m} = 5.5 \text{ m/s}$.

55. a. With $x = 0.075 \text{ m}$ and $k = 320 \text{ N/m}$, Eq. 7-26 yields $W_s = -\frac{1}{2}kx^2 = -0.90 \text{ J}$. For later reference this is equal to the negative of ΔU .

b. Analyzing forces we find $F_N = mg$ which means $f_k = \mu_k F_N = \mu_k mg$. With $d = x$, Eq. 8-31 yields

$$\Delta E_{\text{th}} = f_k d = \mu_k mgx = 0.25(2.5)(9.8)(0.075) = 0.46 \text{ J}$$

c. Equation 8-33 with $W = 0$ indicates that the initial kinetic energy is

$$K_i = \Delta U + \Delta E_{\text{th}} = 0.90 + 0.46 = 1.36 \text{ J}$$

which leads to $v_i = \sqrt{2K_i/m} = 1.0 \text{ m/s}$.

56. Energy conservation as expressed by Eq. 8-33 with $W = 0$ leads to

$$\begin{aligned} \Delta E_{\text{th}} &= K_i - K_f + U_i - U_f \Rightarrow f_k d = 0 - 0 + \frac{1}{2}kx^2 - 0 \\ \Rightarrow \mu_k mgd &= \frac{1}{2}(200 \text{ N})(0.15 \text{ m})^2 \Rightarrow \mu_k(2.0 \text{ kg})(9.8 \text{ m/s}^2)(0.75 \text{ m}) = 2.25 \end{aligned}$$

which yields $\mu_k = 0.15$ as the coefficient of kinetic friction.

57. Since the valley is frictionless the only reason for the speed being less when it reaches the higher level is the gain in potential energy $\Delta U = mgh$ where $h = 1.1 \text{ m}$.

Sliding along the rough surface of the higher level the block finally stops since its remaining kinetic energy has turned to thermal energy $\Delta E_{\text{th}} = f_k d = \mu mgd$ where $\mu = 0.60$. Thus, Eq. 8-33 with $W = 0$ provides us with an equation to solve for the distance d

$$K_i = \Delta U + \Delta E_{\text{th}} = mg(h + \mu d)$$

here $K_i = mv_i^2/2$ and $v_i = 6.0 \text{ m/s}$. Dividing by mass and rearranging we obtain

$$d = \frac{v_i^2}{2\mu g} - \frac{h}{\mu} = 1.2 \text{ m.}$$

58. This can be worked entirely by the methods of chapters 2–6 but we will use energy methods in as many steps as possible.

For part (a) a force analysis of the style done in chapter 6 will find the normal force has magnitude $F_N = mg \cos \theta$ where $\theta = 40^\circ$ which means $f_k = \mu_k F_N = \mu_k mg \cos \theta$ where $\mu_k = 0.15$. Thus Eq. 8.31 yields

$$\Delta E_{\text{th}} = f_k d = \mu_k mgd \cos \theta.$$

Also elementary trigonometry leads us to conclude that $\Delta U = mgd \sin \theta$. Eq. 8.33 with $W = 0$ and $K_f = 0$ provides an equation for determining d

$$K_i = \Delta U + \Delta E_{\text{th}}$$

$$\frac{1}{2}mv_i^2 = mgd(\sin \theta + \mu_k \cos \theta)$$

where $v_i = 1.4 \text{ m/s}$. Dividing by mass and rearranging we obtain

$$d = \frac{v_i^2}{2g(\sin \theta + \mu_k \cos \theta)} = 0.13 \text{ m.}$$

For part (b) note that we know where on the incline it stops $d' = 0.13 + 0.55 = 0.68 \text{ m}$ from the bottom. We can use Eq. 8.33 again with $W = 0$ and now with $K_i = 0$ to describe the final kinetic energy at the bottom

$$K_f = -\Delta U - \Delta E_{\text{th}}$$

$$\frac{1}{2}mv^2 = mgd'(\sin \theta - \mu_k \cos \theta)$$

which — after dividing by the mass and rearranging — yields

$$v = \sqrt{2gd'(\sin \theta - \mu_k \cos \theta)} = 2.7 \text{ m/s.}$$

For part (c) in part (a) it is clear that d increases if μ_k decreases — both mathematically since it is a positive term in the denominator and intuitively less friction — less energy “lost”). In part (b) there are two terms in the expression for v that imply that it should increase if μ_k were smaller: the increased value of $d' = d_0 + d$ and that last factor $\sin \theta - \mu_k \cos \theta$, which indicates that less is being subtracted from $\sin \theta$ when μ_k is less so the factor itself increases in value.

59. a) The maximum height reached is h . The thermal energy generated by air resistance as the stone rises to this height is $\Delta E_{th} = fh$ by 8.31. Use energy conservation in the form of 8.33 with $W = 0$

$$K_f + U_f + \Delta E_{th} = K_i + U_i$$

and we take the potential energy to be zero at the throwing point (ground level). The initial kinetic energy is $K_i = \frac{1}{2}mv_0^2$ the initial potential energy is $U_i = 0$ the final kinetic energy is $K_f = 0$ and the final potential energy is $U_f = wh$ here $w = mg$ is the weight of the stone. Thus $wh + fh = \frac{1}{2}mv_0^2$ and we solve for the height

$$h = \frac{mv_0^2}{2(w+f)} = \frac{v_0^2}{2g(1+f/w)}.$$

Numerically we have with $m = 5.29 \times 9.80 \text{ m/s}^2 = 0.54 \text{ kg}$

$$h = \frac{20.0 \text{ m/s}^2}{2 \times 9.80 \text{ m/s}^2 \times 1 + 0.265 \times 5.29} = 19.4 \text{ m}.$$

b) We notice that the force of the air is downward on the trip up and upward on the trip down since it is opposite to the direction of motion. Over the entire trip the increase in thermal energy is $\Delta E_{th} = 2fh$. The final kinetic energy is $K_f = \frac{1}{2}mv^2$ here v is the speed of the stone just before it hits the ground. The final potential energy is $U_f = 0$. Thus using 8.31 with $W = 0$ we find

$$\frac{1}{2}mv^2 + 2fh = \frac{1}{2}mv_0^2.$$

We substitute the expression found for h to obtain

$$\frac{2fv_0^2}{2g(1+f/w)} = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2$$

which leads to

$$v^2 = v_0^2 - \frac{2fv_0^2}{mg(1+f/w)} = v_0^2 - \frac{2fv_0^2}{w(1+f/w)} = v_0^2 \left(1 - \frac{2f}{w+f} \right) = v_0^2 \frac{w-f}{w+f}$$

here w was substituted for mg and some algebraic manipulations were carried out. Therefore

$$v = v_0 \sqrt{\frac{w-f}{w+f}} = 20.0 \text{ m/s} \sqrt{\frac{5.29 - 0.265}{5.29 + 0.265}} = 19.0 \text{ m/s}.$$

60. We look for the distance along the incline d which is related to the height ascended by $\Delta h = d \sin \theta$. By a force analysis of the style done in Chapter 6 we find the normal force has magnitude $F_N = mg \cos \theta$, which means $f_k = \mu_k mg \cos \theta$. Thus, with $W = 0$ leads to

$$\begin{aligned} 0 &= K_f - K_i + \Delta U + \Delta E_{\text{th}} \\ &= 0 - K_i + mgd \sin \theta + \mu_k mgd \cos \theta \end{aligned}$$

which leads to

$$d = \frac{K_i}{mg(\sin \theta + \mu_k \cos \theta)} = \frac{128}{(4.0)(9.8)(\sin 30^\circ + 0.30 \cos 30^\circ)} = 4.3 \text{ m}.$$

61. Before the launch the mechanical energy is $\Delta E_{\text{mech } 0} = 0$. At the maximum height h where the speed of the beetle vanishes the mechanical energy is $\Delta E_{\text{mech } 1} = mgh$. The change of the mechanical energy is related to the external force by

$$\Delta E_{\text{mech}} = \Delta E_{\text{mech } 1} - \Delta E_{\text{mech } 0} = mgh = F_{\text{avg}} d \cos \phi$$

here F_{avg} is the average magnitude of the external force on the beetle.

a. From the above equation we have

$$F_{\text{avg}} = \frac{mgh}{d \cos \phi} = \frac{4.0 \times 10^{-6} \text{ kg} \cdot 9.80 \text{ m/s}^2 \cdot 0.30 \text{ m}}{7.7 \times 10^{-4} \text{ m} \cdot \cos 0^\circ} = 1.5 \times 10^{-2} \text{ N}.$$

b. Dividing the above result by the mass of the beetle we obtain

$$a = \frac{F_{\text{avg}}}{m} = \frac{h}{d \cos \phi} g = \frac{0.30 \text{ m}}{7.7 \times 10^{-4} \text{ m} \cdot \cos 0^\circ} g = 3.8 \times 10^2 g.$$

62. We will refer to the point where it first encounters the “rough region” as point C . This is the point at a height h above the reference level. From 8.17 we find the speed it has at point C to be

$$v_C = \sqrt{v_A^2 - 2gh} = \sqrt{8.0^2 - 2(9.8)(2.0)} = 4.980 \approx 5.0 \text{ m/s}.$$

Thus we see that its kinetic energy right at the beginning of its “rough slide” (heading uphill towards B) is

$$K_C = \frac{1}{2} m (4.980 \text{ m/s})^2 = 12.4 \text{ mJ}$$

(with SI units understood). Note that we “carry along” the mass (as if it were a known quantity as we will see it will cancel out shortly). Using .8.37 and .6.2 with $F_N = mg \cos \theta$ and $y = d \sin \theta$ we note that if $d > L$ the block does not reach point B this kinetic energy will turn entirely into thermal and potential energy

$$K = mgy - f_k d \Rightarrow 12.4m = mgd \sin \theta - \mu_k mgd \cos \theta.$$

With $\mu_k = 0.40$ and $\theta = 30^\circ$ we find $d = 1.49$ m which is greater than L given in the problem as 0.75 m so our assumption that $d < L$ is incorrect. What is its kinetic energy as it reaches point B the calculation is similar to the above but with d replaced by L and the final v^2 term being the unknown instead of assumed zero

$$\frac{1}{2} m v^2 = K_C - mgL \sin \theta - \mu_k mgL \cos \theta.$$

this determines the speed with which it arrives at point B

$$\begin{aligned} v_B &= \sqrt{v_C^2 - 2gL \sin \theta + \mu_k \cos \theta} \\ &= \sqrt{4.98 \text{ m/s}^2 - 2(9.80 \text{ m/s}^2)(0.75 \text{ m}) \sin 30^\circ + 0.4 \cos 30^\circ} = 3.5 \text{ m/s}. \end{aligned}$$

63. We observe that the last line of the problem indicates that static friction is not to be considered a factor in this problem. The friction force of magnitude $f = 4400$ mentioned in the problem is kinetic friction and as mentioned is constant and directed up the incline and the thermal energy change associated with it is $\Delta E_{th} = fd$.8.31 here $d = 3.7$ m in part a but will be replaced by x the spring compression in part b.

a With $W = 0$ and the reference level for computing $U = mgy$ set at the top of the inclined spring .8.33 leads to

$$U_i = K + \Delta E_{th} \Rightarrow v = \sqrt{2d \left(g - \frac{f}{m} \right)}$$

which yields $v = 7.4$ m/s for $m = 1800$ kg.

b We again utilize .8.33 with $W = 0$ now relating its kinetic energy at the moment it makes contact with the spring to the system energy at the bottom most point. Using the same reference level for computing $U = mgy$ as we did in part a we end up with gravitational potential energy equal to $mg(-x)$ at that bottom most point where the spring with spring constant $k = 1.5 \times 10^5$ /m is fully compressed.

$$K = mg(-x) + \frac{1}{2} kx^2 + fx$$

here $K = \frac{1}{2}mv^2 = 4.9 \times 10^4$ using the speed found in part a. Using the abbreviation $\xi = mg - f = 1.3 \times 10^4$ the quadratic formula yields

$$x = \frac{\xi \pm \sqrt{\xi^2 + 2kK}}{k} = 0.90 \text{ m}$$

here we have taken the positive root.

c We relate the energy at the bottom most point to that of the highest point of rebound a distance d' above the relaxed position of the spring. We assume $d' \ll x$. We now use the bottom most point as the reference level for computing gravitational potential energy.

$$\frac{1}{2}kx^2 = mgd' + fd' \Rightarrow d' = \frac{kx^2}{2(mg + f)} = 2.8 \text{ m}.$$

d The non conservative force 8.1 is friction and the energy term associated with it is the one that keeps track of the total distance traveled whereas the potential energy terms coming as they do from conservative forces depend on positions — but not on the paths that led to them. We assume the elevator comes to final rest at the equilibrium position of the spring with the spring compressed an amount d_e given by

$$mg = kd_e \Rightarrow d_e = \frac{mg}{k} = 0.12 \text{ m}.$$

In this part we use that final rest point as the reference level for computing gravitational potential energy so the original $U = mgy$ becomes $mg(d_e - d)$. In that final position then the gravitational energy is zero and the spring energy is $\frac{1}{2}kd_e^2$. Thus 8.33 becomes

$$mg(d_e + d) = \frac{1}{2}kd_e^2 + fd_{\text{total}}$$

$$(1800)(9.8)(0.12 + 3.7) = \frac{1}{2}(1.5 \times 10^5)(0.12)^2 + (4400)d_{\text{total}}$$

which yields $d_{\text{total}} = 15 \text{ m}$.

64. In the absence of friction we have a simple conversion as it moves along the inclined ramps of energy between the kinetic form 8.7.1 and the potential form 8.8.9. Along the horizontal plateaus however there is friction that causes some of the kinetic energy to dissipate in accordance with 8.8.31 along with 8.6.2 here $\mu_k = 0.50$ and $F_N = mg$ in this situation. Thus after it slides down a vertical distance d it has gained $K = \frac{1}{2}mv^2 = mgd$ some of which $\Delta E_{\text{th}} = \mu_k mgd$ is dissipated so that the value of kinetic energy at the end of the first plateau just before it starts descending towards the lowest plateau is

$$K = mgd - \mu_k mgd = \frac{1}{2} mgd .$$

On its descent to the lowest plateau it gains $mgd/2$ more kinetic energy but as it slides across it “loses” $\mu_k mgd/2$ of it. Therefore as it starts its climb up the right ramp it has kinetic energy equal to

$$K = \frac{1}{2} mgd + \frac{1}{2} mgd - \frac{1}{2} \mu_k mgd = \frac{3}{4} mgd .$$

Setting this equal to . 8 9 to find the height to which it climbs we get $H = d$. Thus the block momentarily stops on the inclined ramp at the right at a height of

$$H = 0.75d = 0.75 \cdot 40 \text{ cm} = 30 \text{ cm}$$

measured from the lowest plateau.

65. The initial and final kinetic energies are zero and we set up energy conservation in the form of . 8 33 with $W = 0$ according to our assumptions. Certainly it can only come to a permanent stop somewhere in the flat part but the question is whether this occurs during its first pass through going right and/or its second pass through going left and/or its third pass through going right and again and so on. If it occurs during its first pass through then the thermal energy generated is $\Delta E_{\text{th}} = f_k d$ here $d \leq L$ and $f_k = \mu_k mg$. If it occurs during its second pass through then the total thermal energy is $\Delta E_{\text{th}} = \mu_k mg L + d$ here we again use the symbol d for how far through the level area it goes during that last pass so $0 \leq d \leq L$. Generalizing to the n^{th} pass through we see that

$$\Delta E_{\text{th}} = \mu_k mg (n-1)L + d .$$

In this way we have

$$mgh = \mu_k mg ((n-1)L + d)$$

which simplifies when $h = L/2$ is inserted to

$$\frac{d}{L} = 1 + \frac{1}{2\mu_k} - n .$$

The first two terms give $1 + 1/2\mu_k = 3.5$ so that the requirement $0 \leq d/L \leq 1$ demands that $n = 3$. We arrive at the conclusion that $d/L = \frac{1}{2}$ or

$$d = \frac{1}{2} L = \frac{1}{2} \cdot 40 \text{ cm} = 20 \text{ cm}$$

and that this occurs on its third pass through the flat region.

66. a Equation 8.9 gives $U = mgh = (3.2 \text{ kg})(9.8 \text{ m/s}^2)(3.0 \text{ m}) = 94 \text{ J}$.

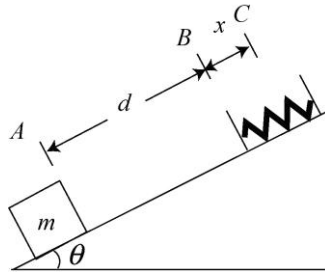
b The mechanical energy is conserved so $K = 94 \text{ J}$.

c The speed from solving 8.7.1 is

$$v = \sqrt{2K/m} = \sqrt{2(94 \text{ J})/(32 \text{ kg})} = 7.7 \text{ m/s}.$$

67. **THINK** As the block is projected up the inclined plane its kinetic energy is converted into gravitational potential energy and elastic potential energy of the spring. The block compresses the spring stopping momentarily before sliding back down again.

EXPRESS Let A be the starting point and the reference point for computing gravitational potential energy $U_A = 0$. The block first comes into contact with the spring at B . The spring is compressed by an additional amount x at C as shown in the figure below.



By energy conservation $K_A + U_A = K_B + U_B = K_C + U_C$. Note that

$$U = U_g + U_s = mgy + \frac{1}{2}kx^2$$

i.e. the total potential energy is the sum of gravitational potential energy and elastic potential energy of the spring.

ANALYZE At the instant when $x_C = 0.20 \text{ m}$ the vertical height is

$$y_C = d + x_C \sin \theta = 0.60 \text{ m} + 0.20 \text{ m} \sin 40^\circ = 0.514 \text{ m}.$$

Applying energy conservation principle gives

$$K_A + U_A = K_C + U_C \Rightarrow 16 \text{ J} + 0 = K_C + mgy_C + \frac{1}{2}kx_C^2$$

from which we obtain

$$\begin{aligned}
 K_C &= K_A - mgy_C - \frac{1}{2}kx_C^2 \\
 &= 16 \text{ J} - 1.0 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 0.514 \text{ m} - \frac{1}{2} \cdot 200 \text{ N/m} \cdot (0.20 \text{ m})^2 = 6.96 \text{ J} \approx 7.0 \text{ J}.
 \end{aligned}$$

b At the instant when $x'_C = 0.40 \text{ m}$ the vertical height is

$$y'_C = d + x'_C \sin \theta = 0.60 \text{ m} + 0.40 \text{ m} \sin 40^\circ = 0.64 \text{ m}.$$

Applying energy conservation principle we have $K'_A + U'_A = K'_C + U'_C$. Since $U'_A = 0$ the initial kinetic energy that gives $K'_C = 0$ is

$$\begin{aligned}
 K'_A &= U'_C = mgy'_C + \frac{1}{2}kx_C'^2 \\
 &= 1.0 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 0.64 \text{ m} + \frac{1}{2} \cdot 200 \text{ N/m} \cdot (0.40 \text{ m})^2 \\
 &= 22 \text{ J}.
 \end{aligned}$$

LEARN Comparing the results found in a and b we see that more kinetic energy is required to move the block higher in the inclined plane to achieve a greater spring compression.

68. a At the point of maximum height where $y = 140 \text{ m}$ the vertical component of velocity vanishes but the horizontal component remains that it has when it is launched if we neglect air friction. Its kinetic energy at that moment is

$$K = \frac{1}{2}(0.55 \text{ kg})v_x^2.$$

Also its potential energy with the reference level chosen at the level of the cliff edge at that moment is $U = mgy = 755 \text{ J}$. Thus by mechanical energy conservation

$$K = K_i - U = 1550 - 755 \Rightarrow v_x = \sqrt{\frac{2(1550 - 755)}{0.55}} = 54 \text{ m/s}.$$

b As mentioned $v_x = v_{ix}$ so that the initial kinetic energy

$$K_i = \frac{1}{2}m(v_{ix}^2 + v_{iy}^2)$$

can be used to find v_{iy} . We obtain $v_{iy} = 52 \text{ m/s}$.

c Applying Eq. 2-16 to the vertical direction with y up and we have

$$v_y^2 = v_{iy}^2 - 2g\Delta y \Rightarrow 65 \text{ m s}^{-2} = 52 \text{ m s}^{-2} - 2(9.8 \text{ m s}^{-2})\Delta y$$

which yields $\Delta y = -76 \text{ m}$. The minus sign tells us it is below its launch point.

69. **THINK** The two blocks are connected by a cord. As block B falls, block A moves up the incline.

EXPRESS If the larger mass, block B ($m_B = 2.0 \text{ kg}$) falls a vertical distance $d = 0.25 \text{ m}$, then the smaller mass, blocks A ($m_A = 1.0 \text{ kg}$) must increase its height by $h = d \sin 30^\circ$. The change in gravitational potential energy is

$$\Delta U = -m_B g d + m_A g h.$$

By mechanical energy conservation, $\Delta E_{\text{mech}} = \Delta K + \Delta U = 0$, the change in kinetic energy of the system is $\Delta K = -\Delta U$.

ANALYZE Since the initial kinetic energy is zero, the final kinetic energy is

$$\begin{aligned} K_f &= \Delta K = m_B g d - m_A g h = m_B g d - m_A g d \sin \theta \\ &= (m_B - m_A \sin \theta) g d = (2.0 \text{ kg} - 1.0 \text{ kg} \sin 30^\circ)(9.8 \text{ m s}^{-2})(0.25 \text{ m}) \\ &= 3.7 \text{ J}. \end{aligned}$$

LEARN From the above expression, we see that in the special case where $m_B = m_A \sin \theta$, the two-block system could remain stationary. On the other hand, if $m_A \sin \theta > m_B$, block A will slide down the incline with block B moving vertically upward.

70. We use conservation of mechanical energy; the mechanical energy must be the same at the top of the swing as it is initially. The tension's second law is used to find the speed, and hence the kinetic energy at the top. Here the tension force T of the string and the force of gravity are both downward toward the center of the circle. We notice that the radius of the circle is $r = L - d$, so the law can be written

$$T + mg = mv^2 / (L - d)$$

Here v is the speed and m is the mass of the ball. When the ball passes the highest point with the least possible speed, the tension is zero. Then

$$mg = m \frac{v^2}{L - d} \Rightarrow v = \sqrt{g(L - d)}.$$

We take the gravitational potential energy of the ball-earth system to be zero when the ball is at the bottom of its swing. Then the initial potential energy is mgL . The initial kinetic energy is zero since the ball starts from rest. The final potential energy at the top of the swing is $2mg(L-d)$ and the final kinetic energy is $\frac{1}{2}mv^2 = \frac{1}{2}mg(L-d)$ using the above result for v . Conservation of energy yields

$$mgL = 2mg(L-d) + \frac{1}{2}mg(L-d) \Rightarrow d = 3L/5.$$

With $L = 1.20 \text{ m}$ we have $d = 0.60 \times 1.20 \text{ m} = 0.72 \text{ m}$.

Notice that if d is greater than this value, so the highest point is lower than the speed of the ball is greater as it reaches that point and the ball passes the point. If d is less, the ball cannot go around. Thus the value we found for d is a lower limit.

71. THINK As the block slides down the frictionless incline, its gravitational potential energy is converted to kinetic energy, so the speed of the block increases.

EXPRESS By energy conservation $K_A + U_A = K_B + U_B$. Thus the change in kinetic energy as the block moves from points A to B is

$$\Delta K = K_B - K_A = -\Delta U = -U_B - U_A.$$

In both circumstances we have the same potential energy change. Thus $\Delta K_1 = \Delta K_2$.

ANALYZE With $\Delta K_1 = \Delta K_2$ the speed of the block at the second time is given by

$$\frac{1}{2}mv_{B1}^2 - \frac{1}{2}mv_{A1}^2 = \frac{1}{2}mv_{B2}^2 - \frac{1}{2}mv_{A2}^2$$

or

$$v_{B2} = \sqrt{v_{B1}^2 - v_{A1}^2 + v_{A2}^2} = \sqrt{2.60 \text{ m/s}^2 - 2.00 \text{ m/s}^2 + 4.00 \text{ m/s}^2} = 4.33 \text{ m/s}.$$

LEARN The speed of the block at A is greater the second time $v_{A2} > v_{A1}$. This can happen if the block slides down from a higher position with greater initial gravitational potential energy.

72. a We take the gravitational potential energy of the skier-earth system to be zero when the skier is at the bottom of the peaks. The initial potential energy is $U_i = mgH$ where m is the mass of the skier and H is the height of the higher peak. The final potential energy is $U_f = mgh$ where h is the height of the lower peak. The skier initially has a kinetic energy of $K_i = 0$ and the final kinetic energy is $K_f = \frac{1}{2}mv^2$ where v is the speed of the skier at the top of the lower peak. The normal force of the slope on the skier does no work and friction is negligible, so mechanical energy is conserved.

$$U_i + K_i = U_f + K_f \Rightarrow mgH = mgh + \frac{1}{2}mv^2.$$

thus

$$v = \sqrt{2g(H-h)} = \sqrt{2(9.8 \text{ m/s}^2)(850 \text{ m} - 750 \text{ m})} = 44 \text{ m/s}.$$

b We recall from analyzing objects sliding down inclined planes that the normal force of the slope on the skier is given by $F_N = mg \cos \theta$ where θ is the angle of the slope from the horizontal 30° for each of the slopes shown. The magnitude of the force of friction is given by $f = \mu_k F_N = \mu_k mg \cos \theta$. The thermal energy generated by the force of friction is $fd = \mu_k mgd \cos \theta$ where d is the total distance along the path. Since the skier gets to the top of the lower peak with no kinetic energy, the increase in thermal energy is equal to the decrease in potential energy. That is $\mu_k mgd \cos \theta = mg(H-h)$. Consequently

$$\mu_k = \frac{H-h}{d \cos \theta} = \frac{850 \text{ m} - 750 \text{ m}}{3.2 \times 10^3 \text{ m} \cos 30^\circ} = 0.036.$$

73. **THINK** As the cube is pushed across the floor, both the thermal energies of floor and the cube increase because of friction.

EXPRESS By law of conservation of energy, we have $W = \Delta E_{\text{mech}} + \Delta E_{\text{th}}$ for the floor-cube system. Since the speed is constant, $\Delta K = 0$. 8-33 is an application of the energy conservation concept, implies

$$W = \Delta E_{\text{mech}} + \Delta E_{\text{th}} = \Delta E_{\text{th}} = \Delta E_{\text{th, cube}} + \Delta E_{\text{th, floor}}.$$

ANALYZE With $W = (15 \text{ N})(3.0 \text{ m}) = 45 \text{ J}$ and we are told that $\Delta E_{\text{th, cube}} = 20 \text{ J}$, then we conclude that $\Delta E_{\text{th, floor}} = 25 \text{ J}$.

LEARN The applied work here has all been converted into thermal energies of the floor and the cube. The amount of thermal energy transferred to a material depends on its thermal properties as we shall discuss in Chapter 18.

74. We take her original elevation to be the $y = 0$ reference level and observe that the top of the hill must consequently have $y_A = R(1 - \cos 20^\circ) = 1.2 \text{ m}$ where R is the radius of the hill. The mass of the skier is $m = 600 \text{ kg}$. $(9.8 \text{ m/s}^2) = 61 \text{ kg}$.

a Applying energy conservation, 8-17 we have

$$K_B + U_B = K_A + U_A \Rightarrow K_B + 0 = K_A + mgy_A.$$

Since $K_B = \frac{1}{2}(61 \text{ kg})(8.0 \text{ m/s})^2$, we obtain $K_A = 1.2 \times 10^3 \text{ J}$. Thus we find the speed at the hilltop is

$$v_A = \sqrt{\frac{2K_A}{m}} = \sqrt{\frac{2 \cdot 1.2 \times 10^3}{61 \text{ kg}}} = 6.4 \text{ m/s}.$$

One might wish to check that the skier stays in contact with the hill — which is indeed the case here. For instance at A we find $v^2/r \approx 2 \text{ m/s}^2$ which is considerably less than g .

b With $K_A = 0$ we have

$$K_B + U_B = K_A + U_A \Rightarrow K_B + 0 = 0 + mgy_A$$

which yields $K_B = 724$ and the corresponding speed is

$$v_B = \sqrt{\frac{2K_B}{m}} = \sqrt{\frac{2 \cdot 724}{61 \text{ kg}}} = 4.9 \text{ m/s}.$$

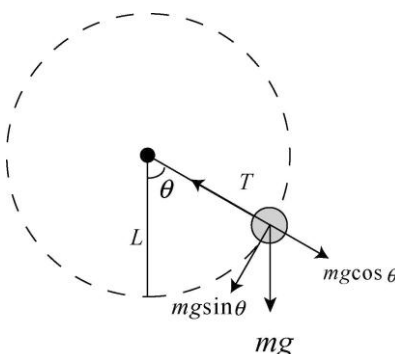
c Expressed in terms of mass we have

$$K_B + U_B = K_A + U_A \Rightarrow \frac{1}{2}mv_B^2 + mgy_B = \frac{1}{2}mv_A^2 + mgy_A.$$

Thus the mass m cancels and we observe that solving for speed does not depend on the value of mass or height.

75. **THINK** This problem deals with pendulum motion. The kinetic and potential energies of the ball attached to the rod change with position but the mechanical energy remains conserved throughout the process.

EXPRESS Let L be the length of the pendulum. The connection between angle θ measured from vertical and height h measured from the lowest point which is our choice of reference position in computing the gravitational potential energy mgh is given by $h = L(1 - \cos \theta)$.



The free body diagram is shown above. The initial height is at $h_1 = 2L$ and at the lowest point we have $h_2 = 0$. The total mechanical energy is conserved throughout.

ANALYZE a Initially the ball is at $h_1 = 2L$ with $K_1 = 0$ and $U_1 = mgh_1 = mg \cdot 2L$. At the lowest point $h_2 = 0$ we have $K_2 = \frac{1}{2}mv_2^2$ and $U_2 = 0$. Using energy conservation in the form of Eq. 8.17 leads to

$$K_1 + U_1 = K_2 + U_2 \Rightarrow 0 + 2mgL = \frac{1}{2}mv_2^2 + 0$$

this leads to $v_2 = 2\sqrt{gL}$. With $L = 0.62 \text{ m}$ we have

$$v_2 = 2\sqrt{9.8 \text{ m/s}^2 \cdot 0.62 \text{ m}} = 4.9 \text{ m/s}.$$

b At the lowest point the ball is in circular motion with the center of the circle above it so $\vec{a} = v^2/r$ up and here $r = L$. Newton's second law leads to

$$T - mg = m \frac{v^2}{r} \Rightarrow T = m \left(g + \frac{4gL}{L} \right) = 5mg.$$

With $m = 0.092 \text{ kg}$ the tension is $T = 4.5 \text{ N}$.

c The pendulum is now started with zero speed at $\theta_i = 90^\circ$ that is $h_i = L$ and we look for an angle θ such that $T = mg$. When the ball is moving through a point at angle θ as can be seen from the free body diagram shown above Newton's second law applied to the axis along the rod yields

$$\frac{mv^2}{r} = T - mg \cos \theta = mg(1 - \cos \theta)$$

which since $r = L$ implies $v^2 = gL(1 - \cos \theta)$ at the position we are looking for. Energy conservation leads to

$$\begin{aligned} K_i + U_i &= K + U \\ 0 + mgL &= \frac{1}{2}mv^2 + mgL(1 - \cos \theta) \\ gL &= \frac{1}{2}gL(1 - \cos \theta) + gL(1 - \cos \theta) \end{aligned}$$

here we have divided by mass in the last step. Simplifying we obtain

$$\theta = \cos^{-1} \left(\frac{1}{3} \right) = 71^\circ.$$

d Since the angle found in c is independent of the mass the result remains the same if the mass of the ball is changed.

LEARN At a given angle θ with respect to the vertical the tension in the rod is

$$T = m \left(\frac{v^2}{r} + g \cos \theta \right)$$

The tangential acceleration $a_t = g \sin \theta$ is what causes the speed and therefore the kinetic energy to change with time. Nonetheless mechanical energy is conserved.

76. a The table shows that the force is 3.0 N while the displacement is in the x direction $\vec{d} = 3.0 \text{ m i}$ and it is -3.0 N while the displacement is in the $-x$ direction. Using 7.8 for each part of the trip and adding the results we find the work done is 18 J. This is not a conservative force field if it had been then the net work done would have been zero since it returned to where it started.

b This however is a conservative force field as can be easily verified by calculating that the net work done here is zero.

c The two integrations that need to be performed are each of the form $\int 2x \, dx$ so that we are adding two equivalent terms where each equals x^2 evaluated at $x = 4$ minus its value at $x = 1$. Thus the work done is $2(4^2 - 1^2) = 30 \text{ J}$.

d This is another conservative force field as can be easily verified by calculating that the net work done here is zero.

e The forces in b and d are conservative.

77. **THINK** This problem involves graphical analyses. From the graph of potential energy as a function of position the conservative force can be deduced.

EXPRESS The connection between the potential energy function $U(x)$ and the conservative force $F(x)$ is given by 8.22 $F(x) = -dU/dx$. A positive slope of $U(x)$ at a point means that $F(x)$ is negative and vice versa.

ANALYZE a The force at $x = 2.0 \text{ m}$ is

$$F = -\frac{dU}{dx} \approx -\frac{\Delta U}{\Delta x} = -\frac{U(x=4 \text{ m}) - U(x=1 \text{ m})}{4.0 \text{ m} - 1.0 \text{ m}} = -\frac{-17.5 \text{ J} - (-2.8 \text{ J})}{4.0 \text{ m} - 1.0 \text{ m}} = 4.9 \text{ N}.$$

b Since the slope of $U(x)$ at $x = 2.0 \text{ m}$ is negative the force points in the x direction but there is some uncertainty in reading the graph which makes the last digit not very significant.

c At $x = 2.0 \text{ m}$ we estimate the potential energy to be

$$U_{x=2.0 \text{ m}} \approx U_{x=1.0 \text{ m}} + (-4.9 \text{ J/m}) (1.0 \text{ m}) = -7.7 \text{ J}.$$

thus the total mechanical energy is

$$E = K + U = \frac{1}{2}mv^2 + U = \frac{1}{2}(2.0 \text{ kg})(-1.5 \text{ m/s})^2 + (-7.7 \text{ J}) = -5.5 \text{ J}.$$

Again there is some uncertainty in reading the graph which makes the last digit not very significant. At that level -5.5 J on the graph we find two points where the potential energy curve has that value — at $x \approx 1.5 \text{ m}$ and $x \approx 13.5 \text{ m}$. Therefore the particle remains in the region $1.5 \text{ m} \leq x \leq 13.5 \text{ m}$. The left boundary is at $x = 1.5 \text{ m}$.

d From the above results the right boundary is at $x = 13.5 \text{ m}$.

e At $x = 7.0 \text{ m}$ we read $U \approx -17.5 \text{ J}$. Thus if its total energy calculated in the previous part is $E \approx -5.5 \text{ J}$ then we find

$$\frac{1}{2}mv^2 = E - U \approx 12 \text{ J} \Rightarrow v = \sqrt{\frac{2}{m}(E - U)} \approx 3.5 \text{ m/s}$$

Here there is certainly room for disagreement on that last digit for the reasons cited above.

LEARN Since the total mechanical energy is negative the particle is bounded by the potential with its motion confined to the region $1.5 \text{ m} \leq x \leq 13.5 \text{ m}$. At the turning points 1.5 m and 13.5 m kinetic energy is zero and the particle is momentarily at rest.

78. a Since the speed of the crate of mass m increases from 0 to 1.20 m/s relative to the factory ground the kinetic energy supplied to it is

$$K = \frac{1}{2}mv^2 = \frac{1}{2}(300 \text{ kg})(1.20 \text{ m/s})^2 = 216 \text{ J}.$$

b The magnitude of the kinetic frictional force is

$$f = \mu F_N = \mu mg = (0.400)(300 \text{ kg})(9.8 \text{ m/s}^2) = 1.18 \times 10^3 \text{ N}.$$

c Let the distance the crate moved relative to the conveyor belt before it stops slipping be d . Then from $\frac{1}{2}mv^2 = 2fd = 2fmd$ we find

$$\Delta E_{\text{th}} = fd = \frac{1}{2}mv^2 = K.$$

thus the total energy that must be supplied by the motor is

$$W = K + \Delta E_{\text{th}} = 2K = 2(216 \text{ J}) = 432 \text{ J}.$$

and the energy supplied by the motor is the work W it does on the system and must be greater than the kinetic energy gained by the crate computed in part (b). This is due to the fact that part of the energy supplied by the motor is being used to compensate for the energy dissipated ΔE_{th} while it is slipping.

79. THINK As the car slides down the incline due to the presence of frictional force some of its mechanical energy is converted into thermal energy.

EXPRESS The incline angle is $\theta = 5.0^\circ$. Thus the change in height between the car's highest and lowest points is $\Delta y = -50 \text{ m} \sin \theta = -4.4 \text{ m}$. We take the lowest point the car's final reported location to correspond to the $y = 0$ reference level. The change in potential energy is given by $\Delta U = mg\Delta y$.

As for the kinetic energy we first convert the speeds to SI units $v_0 = 8.3 \text{ m/s}$ and $v = 11.1 \text{ m/s}$. The change in kinetic energy is $\Delta K = \frac{1}{2}m(v_f^2 - v_i^2)$. The total change in mechanical energy is $\Delta E_{\text{mech}} = \Delta K + \Delta U$.

ANALYZE After substituting the values given we find ΔE_{mech} to be

$$\begin{aligned}\Delta E_{\text{mech}} &= \Delta K + \Delta U = \frac{1}{2}m(v_f^2 - v_i^2) + mg\Delta y \\ &= \frac{1}{2}(1500 \text{ kg})[11.1^2 \text{ m}^2/\text{s}^2 - 8.3^2 \text{ m}^2/\text{s}^2] + (1500 \text{ kg})(9.8 \text{ m/s}^2)(-4.4 \text{ m}) \\ &= -23940 \text{ J} \approx -2.4 \times 10^4 \text{ J}\end{aligned}$$

That is, the mechanical energy decreases due to friction by $2.4 \times 10^4 \text{ J}$.

Using $\mu_k = 0.831$ and $\mu_s = 0.833$ we find $\Delta E_{\text{th}} = f_k d = -\Delta E_{\text{mech}}$. With $d = 50 \text{ m}$ we solve for f_k and obtain

$$f_k = \frac{-\Delta E_{\text{mech}}}{d} = \frac{-(-2.4 \times 10^4 \text{ J})}{50 \text{ m}} = 4.8 \times 10^2 \text{ N}.$$

LEARN The amount of mechanical energy lost is proportional to the frictional force. In the absence of friction mechanical energy would have been conserved.

80. We note that in one second the block slides $d = 1.34 \text{ m}$ up the incline which means its height increase is $h = d \sin \theta$ where

$$\theta = \tan^{-1}\left(\frac{30}{40}\right) = 37^\circ.$$

e also note that the force of kinetic friction in this inclined plane problem is $f_k = \mu_k mg \cos \theta$ here $\mu_k = 0.40$ and $m = 1400$ kg. thus using . 8 31 and . 8 33 we find

$$W = mgh + f_k d = mgd(\sin \theta + \mu_k \cos \theta)$$

or $W = 1.69 \times 10^4$ for this one second interval. thus the power associated with this is

$$P = \frac{1.69 \times 10^4}{1 \text{ s}} = 1.69 \times 10^4 \approx 1.7 \times 10^4 \text{ .}$$

81. a the remark in the problem statement that the forces can be associated with potential energies is illustrated as follows the work from $x = 3.00$ m to $x = 2.00$ m is

$$W = F_2 \Delta x = 5.00 \text{ N} (-1.00 \text{ m}) = -5.00 \text{ J}$$

so the potential energy at $x = 2.00$ m is $U_2 = 5.00$ J.

b so it is evident from the problem statement that $E_{\text{ma}} = 14.0$ J so the kinetic energy at $x = 2.00$ m is

$$K_2 = E_{\text{ma}} - U_2 = 14.0 - 5.00 = 9.00 \text{ J .}$$

c the work from $x = 2.00$ m to $x = 0$ is $W = F_1 \Delta x = 3.00 \text{ N} (-2.00 \text{ m}) = -6.00$ J so the potential energy at $x = 0$ is

$$U_0 = 6.00 \text{ J} \quad U_2 = 6.00 \text{ J} - 5.00 \text{ J} = 1.00 \text{ J .}$$

d similar reasoning to that presented in part a then gives

$$K_0 = E_{\text{ma}} - U_0 = 14.0 - 1.00 = 13.0 \text{ J .}$$

e the work from $x = 8.00$ m to $x = 11.0$ m is $W = F_3 \Delta x = -4.00 \text{ N} (3.00 \text{ m}) = -12.0$ J so the potential energy at $x = 11.0$ m is $U_{11} = 12.0$ J.

f the kinetic energy at $x = 11.0$ m is therefore

$$K_{11} = E_{\text{ma}} - U_{11} = 14.0 - 12.0 = 2.00 \text{ J .}$$

g so we have $W = F_4 \Delta x = -1.00 \text{ N} (1.00 \text{ m}) = -1.00$ J so the potential energy at $x = 12.0$ m is

$$U_{12} = 1.00 \text{ J} \quad U_{11} = 1.00 \text{ J} + 12.0 \text{ J} = 13.0 \text{ J .}$$

h thus the kinetic energy at $x = 12.0$ m is

$$K_{12} = E_{\text{ma}} - U_{12} = 14.0 - 13.0 = 1.00 \text{ J}.$$

i There is no work done in this interval from $x = 12.0 \text{ m}$ to $x = 13.0 \text{ m}$ so the answers are the same as in part g $U_{12} = 13.0 \text{ J}$.

here is no work done in this interval from $x = 12.0 \text{ m}$ to $x = 13.0 \text{ m}$ so the answers are the same as in part h $K_{12} = 1.00 \text{ J}$.

k Although the plot is not shown here, it would look like a “potential well” with piecewise sloping sides from $x = 0$ to $x = 2$ units understood the graph of U is a decreasing line segment from 11 to 5 and from $x = 2$ to $x = 3$ it then heads down to zero where it stays until $x = 8$ here it starts increasing to a value of 12 at $x = 11$ and then in another positive slope line segment it increases to a value of 13 at $x = 12$. For $x > 12$ its value does not change (this is the “top of the well”).

l The particle can be thought of as “falling” down the $0 < x < 3$ slopes of the well gaining kinetic energy as it does so and certainly is able to reach $x = 5$. Since $U = 0$ at $x = 5$ then its initial potential energy 11 J has completely converted to kinetic energy $K = 11.0 \text{ J}$.

m This is not sufficient to climb up and out of the well on the large x side $x > 8$ but does allow it to reach a “height” of 11 J at $x = 10.8 \text{ m}$. As discussed in section 8.5 this is a “turning point” of the motion.

n Next it “falls” back down and rises back up the small x slope until it comes back to its original position. Studying this more carefully when it is momentarily stopped at $x = 10.8 \text{ m}$ it is accelerated to the left by the force \vec{F}_3 it gains enough speed as a result that it eventually is able to return to $x = 0$ where it stops again.

82. a At $x = 5.00 \text{ m}$ the potential energy is zero and the kinetic energy is

$$K = \frac{1}{2} mv^2 = \frac{1}{2} (2.00 \text{ kg}) (3.45 \text{ m/s})^2 = 11.9 \text{ J}.$$

The total energy therefore is great enough to reach the point $x = 0$ where $U = 11.0 \text{ J}$ with a little “left over” ($11.9 \text{ J} - 11.0 \text{ J} = 0.9025 \text{ J}$). This is the kinetic energy at $x = 0$ which means the speed there is

$$v = \sqrt{2(0.9025 \text{ J}) / 2 \text{ kg}} = 0.950 \text{ m/s}.$$

It has not come to a stop therefore so it has not encountered a turning point.

b The total energy 11.9 J is equal to the potential energy in the scenario where it is initially moving right and at $x = 10.9756 \approx 11.0 \text{ m}$. This point may be found by interpolation or simply by using the work-kinetic energy theorem

$$K_f = K_i + W = 0 \Rightarrow 11.9025 - 4d = 0 \Rightarrow d = 2.9756 \approx 2.98$$

When added to $x = 8.00$ the point where F_3 begins to act gives the correct result. This provides a turning point for the particle's motion.

83. THINK Energy is transferred from an external agent to the block so that its speed continues to increase.

EXPRESS According to 8.25 the work done by the external force is $W = \Delta E_{\text{mech}} = \Delta K + \Delta U$. When there is no change in potential energy $\Delta U = 0$ the expression simplifies to

$$W = \Delta E_{\text{mech}} = \Delta K = \frac{1}{2} m v_f^2 - v_i^2.$$

The average power or average rate of work done is given by $P_{\text{avg}} = W / \Delta t$.

ANALYZE a Substituting the values given the change in mechanical energy is

$$\Delta E_{\text{mech}} = \Delta K = \frac{1}{2} m v_f^2 - v_i^2 = \frac{1}{2} (15 \text{ kg}) (30 \text{ m/s})^2 - (10 \text{ m/s})^2 = 6000 \text{ J} = 6.0 \times 10^3 \text{ J}$$

b From the above we have $W = 6.0 \times 10^3 \text{ J}$. Also from chapter 2 we know that $\Delta t = \Delta v / a = 10 \text{ s}$. Thus using 7.42 the average rate at which energy is transferred to the block is

$$P_{\text{avg}} = \frac{W}{\Delta t} = \frac{6.0 \times 10^3 \text{ J}}{10.0 \text{ s}} = 600 \text{ W}.$$

c and d The constant applied force is $F = ma = 30 \text{ N}$ and clearly in the direction of motion so 7.48 provides the results for instantaneous power

$$P = \vec{F} \cdot \vec{v} = \begin{cases} 300 & \text{for } v = 10 \text{ m/s} \\ 900 & \text{for } v = 30 \text{ m/s} \end{cases}$$

LEARN The average of these two values found in c and d agrees with the result in part b. Note that the expression for the instantaneous rate used above can be derived from

$$P = \frac{dW}{dt} = \frac{d}{dt} \left(\frac{1}{2} m v^2 \right) = m \vec{v} \cdot \frac{d\vec{v}}{dt} = m \vec{v} \cdot \vec{a} = \vec{F} \cdot \vec{v}$$

84. a To stretch the spring an external force equal in magnitude to the force of the spring but opposite to its direction is applied. Since a spring stretched in the positive x direction exerts a force in the negative x direction the applied force must be $F = 52.8x + 38.4x^2$ in the x direction. The work it does is

$$W = \int_{0.50}^{1.00} 52.8x + 38.4x^2 \, dx = \left(\frac{52.8}{2}x^2 + \frac{38.4}{3}x^3 \right) \bigg|_{0.50}^{1.00} = 31.0 \, \text{J}.$$

b The spring does 31.0 J of work and this must be the increase in the kinetic energy of the particle. Its speed is then

$$v = \sqrt{\frac{2K}{m}} = \sqrt{\frac{2(31.0 \, \text{J})}{2.17 \, \text{kg}}} = 5.35 \, \text{m/s}.$$

c The force is conservative since the work it does as the particle goes from any point x_1 to any other point x_2 depends only on x_1 and x_2 not on details of the motion between x_1 and x_2 .

85. **THINK** This problem deals with the concept of hydroelectric generator – kinetic energy of water can be converted into electrical energy.

EXPRESS By energy conservation the change in kinetic energy of water in one second is

$$\Delta K = -\Delta U = mgh = \rho Vgh = (10^3 \, \text{kg/m}^3)(1200 \, \text{m}^3)(9.8 \, \text{m/s}^2)(100 \, \text{m}) = 1.176 \times 10^9 \, \text{J}.$$

Only 3/4 of this amount is transferred to electrical energy.

ANALYZE The power generation is assumed constant so average power is the same as instantaneous power is

$$P_{\text{avg}} = \frac{\Delta K}{t} = \frac{1.176 \times 10^9 \, \text{J}}{1.0 \, \text{s}} = 1.176 \times 10^9 \, \text{W}.$$

LEARN Hydroelectricity is the most widely used renewable energy; it accounts for almost 20% of the world's electricity supply.

86. a At B the speed is from Eq. 17

$$v = \sqrt{v_0^2 + 2gh_1} = \sqrt{7.0 \, \text{m/s}^2 + 2(9.8 \, \text{m/s}^2)(6.0 \, \text{m})} = 13 \, \text{m/s}.$$

a Here what matters is the difference in heights between A and C

$$v = \sqrt{v_0^2 + 2g(h_1 - h_2)} = \sqrt{7.0 \, \text{m/s}^2 + 2(9.8 \, \text{m/s}^2)(4.0 \, \text{m})} = 11.29 \, \text{m/s} \approx 11 \, \text{m/s}.$$

c Using the result from part b we see that its kinetic energy right at the beginning of its “rough slide” (heading horizontally toward D) is $\frac{1}{2}mv^2 = 63.7 \, \text{J}$ (with units understood). Note that we “carry along” the mass (as if it were a known quantity);

as we will see it will cancel out shortly. Using $\mu_k = 0.831$ and $\mu_s = 0.62$ with $F_N = mg$ we note that this kinetic energy will turn entirely into thermal energy

$$63.7m = \mu_k mgd$$

if $d < L$. With $\mu_k = 0.70$ we find $d = 9.3$ m which is indeed less than L given in the problem as 12 m. We conclude that the block stops before passing out of the “rough” region and thus does not arrive at point D .

87. THINK We have a ball attached to a rod that moves in a vertical circle. The total mechanical energy of the system is conserved.

EXPRESS Let position A be the reference point for potential energy $U_A = 0$. The total mechanical energies at A , B and C are

$$\begin{aligned} E_A &= \frac{1}{2}mv_A^2 + U_A = \frac{1}{2}mv_0^2 \\ E_B &= \frac{1}{2}mv_B^2 + U_B = \frac{1}{2}mv_B^2 - mgL \\ E_D &= \frac{1}{2}mv_D^2 + U_D = mgL \end{aligned}$$

here $v_D = 0$. The problem can be analyzed by applying energy conservation $E_A = E_B = E_D$.

ANALYZE a The condition $E_A = E_D$ gives

$$\frac{1}{2}mv_0^2 = mgL \Rightarrow v_0 = \sqrt{2gL}$$

b To find the tension in the rod when the ball passes through B we first calculate the speed at B . Since $E_B = E_D$ we find

$$\frac{1}{2}mv_B^2 - mgL = mgL$$

or $v_B = \sqrt{4gL}$. The direction of the centripetal acceleration is up and at that moment as is the tension force. Thus, Newton's second law gives

$$T - mg = \frac{mv_B^2}{r} = \frac{m \cdot 4gL}{L} = 4mg$$

or $T = 5mg$.

c The difference in height between C and D is L , so the “loss” of mechanical energy which goes into thermal energy is $-mgL$.

d the difference in height between B and D is $2L$, so the total “loss” of mechanical energy which all goes into thermal energy is $-2mgL$.

LEARN An alternative way to calculate the energy loss in d is to note that

$$E'_B = \frac{1}{2}mv_B'^2 + U_B = 0 - mgL = -mgL$$

which gives

$$\Delta E = E'_B - E_A = -mgL - mgL = -2mgL.$$

88. a the initial kinetic energy is $K_i = \frac{1}{2}(1.5)(3)^2 = 6.75$.

b the work of gravity is the negative of its change in potential energy. At the highest point all of K_i has converted into U if we neglect air friction so we conclude the work of gravity is -6.75 .

c and we conclude that $\Delta U = 6.75$.

d the potential energy there is $U_f = U_i + \Delta U = 6.75$.

e if $U_f = 0$ then $U_i = U_f - \Delta U = -6.75$.

f since $mg\Delta y = \Delta U$ we obtain $\Delta y = 0.459$ m .

89. a any mechanical energy conversation the kinetic energy as it reaches the floor which we choose to be the $U = 0$ level is the sum of the initial kinetic and potential energies

$$K = K_i + U_i = \frac{1}{2} (2.50 \text{ kg}) (3.00 \text{ m/s})^2 + (2.50 \text{ kg}) (9.80 \text{ m/s}^2) (4.00 \text{ m}) = 109 \text{ J}.$$

or later use we note that the speed with which it reaches the ground is

$$v = \sqrt{2K/m} = 9.35 \text{ m/s}.$$

b when the drop in height is 2.00 m instead of 4.00 m the kinetic energy is

$$K = \frac{1}{2} (2.50 \text{ kg}) (3.00 \text{ m/s})^2 + (2.50 \text{ kg}) (9.80 \text{ m/s}^2) (2.00 \text{ m}) = 60.3 \text{ J}.$$

c simple way to approach this is to imagine the can being *launched* from the ground at $t = 0$ with a speed 9.35 m/s see above and calculate the height and speed at $t = 0.200$ s using 2.15 and 2.11

$$y = 9.35 \text{ m/s} \cdot 0.200 \text{ s} - \frac{1}{2} (9.80 \text{ m/s}^2) (0.200 \text{ s})^2 = 1.67 \text{ m}$$

$$v = 9.35 \text{ m/s} - (9.80 \text{ m/s}^2) (0.200 \text{ s}) = 7.39 \text{ m/s}.$$

the kinetic energy is $K = \frac{1}{2} (2.50 \text{ kg}) (7.39 \text{ m/s})^2 = 68.2 \text{ J}.$

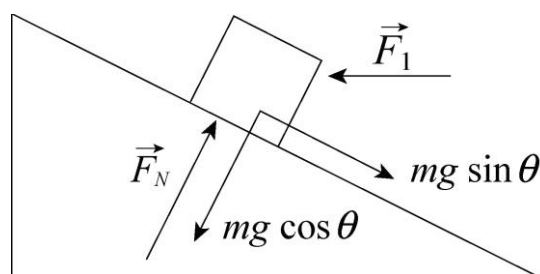
d the gravitational potential energy is

$$U = mgy = (2.5 \text{ kg}) (9.8 \text{ m/s}^2) (1.67 \text{ m}) = 41.0 \text{ J}.$$

90. The free body diagram for the trunk is shown below. The x and y applications of Newton's second law provide the equations

$$F_1 \cos \theta - f_k - mg \sin \theta = ma$$

$$F_N - F_1 \sin \theta - mg \cos \theta = 0.$$



a the trunk is moving up the incline at constant velocity so $a = 0$. Since $f_k = \mu_k F_N$, we solve for the push force F_1 and obtain

$$F_1 = \frac{mg(\sin \theta + \mu_k \cos \theta)}{\cos \theta - \mu_k \sin \theta}.$$

The work done by the push force \vec{F}_1 as the trunk is pushed through a distance ℓ up the inclined plane is therefore

$$\begin{aligned} W_1 &= F_1 \ell \cos \theta = \frac{(mg \ell \cos \theta)(\sin \theta + \mu_k \cos \theta)}{\cos \theta - \mu_k \sin \theta} \\ &= \frac{(50 \text{ kg})(9.8 \text{ m/s}^2)(6.0 \text{ m})(\cos 30^\circ)(\sin 30^\circ + (0.20) \cos 30^\circ)}{\cos 30^\circ - (0.20) \sin 30^\circ} \\ &= 2.2 \times 10^3 \text{ J}. \end{aligned}$$

b the increase in the gravitational potential energy of the trunk is

$$\Delta U = mg\ell \sin \theta = 50 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 6.0 \text{ m} \sin 30^\circ = 1.5 \times 10^3 \text{ J}.$$

Since the speed and therefore the kinetic energy of the trunk is unchanged, Eq. 8.33 leads to

$$W_1 = \Delta U + \Delta E_{\text{th}}.$$

Thus, using more precise numbers than are shown above, the increase in thermal energy generated by the kinetic friction is $2.24 \times 10^3 \text{ J} - 1.47 \times 10^3 \text{ J} = 7.7 \times 10^2 \text{ J}$. An alternate way to this result is to use $\Delta E_{\text{th}} = f_k \ell$ (Eq. 8.31).

91. The initial height of the $2M$ block shown in Fig. 8.69 is the $y = 0$ level in our computations of its value of U_g . As that block drops, the spring stretches accordingly. Also, the kinetic energy K_{sys} is evaluated for the *system* that is, for a total moving mass of $3M$.

a. The conservation of energy (Eq. 8.17) leads to

$$K_i + U_i = K_{\text{sys}} + U_{\text{sys}} \Rightarrow 0 + 0 = K_{\text{sys}} + 2Mg(-0.090) + \frac{1}{2}k(0.090)^2.$$

Thus, with $M = 2.0 \text{ kg}$, we obtain $K_{\text{sys}} = 2.7 \text{ J}$.

b. The kinetic energy of the $2M$ block represents a fraction of the total kinetic energy

$$\frac{K_{2M}}{K_{\text{sys}}} = \frac{2M v^2 / 2}{3M v^2 / 2} = \frac{2}{3}.$$

Therefore, $K_{2M} = \frac{2}{3} \cdot 2.7 \text{ J} = 1.8 \text{ J}$.

c. Here, we let $y = -d$ and solve for d .

$$K_i + U_i = K_{\text{sys}} + U_{\text{sys}} \Rightarrow 0 + 0 = 0 + 2Mg(-d) + \frac{1}{2}kd^2.$$

Thus, with $M = 2.0 \text{ kg}$, we obtain $d = 0.39 \text{ m}$.

92. By energy conservation, $mgh = mv^2/2$, the speed of the volcanic ash is given by $v = \sqrt{2gh}$. In our present problem, the height is related to the distance on the $\theta = 10^\circ$ slope, $d = 920 \text{ m}$, by the trigonometric relation $h = d \sin \theta$. Thus

$$v = \sqrt{2 \cdot 9.8 \text{ m/s}^2 \cdot 920 \text{ m} \sin 10^\circ} = 56 \text{ m/s}.$$

93. a. The assumption is that the slope of the bottom of the slide is horizontal like the ground. A useful analogy is that of the pendulum of length $R = 12 \text{ m}$ that is pulled

leftward to an angle θ corresponding to being at the top of the slide at height $h = 4.0$ m and released so that the pendulum swings to the lowest point zero height gaining speed $v = 6.2$ m/s. Exactly as we could analyze the trigonometric relations in the pendulum problem we find

$$h = R(1 - \cos\theta) \Rightarrow \theta = \cos^{-1}\left(1 - \frac{h}{R}\right) = 48^\circ$$

or 0.84 radians. The slide representing a circular arc of length $s = R\theta$ is therefore 12 m $0.84 = 10$ m long.

b To find the magnitude f of the frictional force we use Eq. 8.31 with $W = 0$

$$\begin{aligned} 0 &= \Delta K + \Delta U + \Delta E_{\text{th}} \\ &= \frac{1}{2}mv^2 - mgh + fs \end{aligned}$$

so that with $m = 25$ kg we obtain $f = 49$ N.

c The assumption is no longer that the slope of the bottom of the slide is horizontal but rather that the slope of the top of the slide is vertical and 12 m to the left of the center of curvature. Returning to the pendulum analogy this corresponds to releasing the pendulum from horizontal at $\theta_1 = 90^\circ$ measured from vertical and taking a snapshot of its motion a few moments later when it is at angle θ_2 with speed $v = 6.2$ m/s. The difference in height between these two positions is just as we could figure for the pendulum of length R

$$\Delta h = R(1 - \cos\theta_2) - R(1 - \cos\theta_1) = -R\cos\theta_2$$

here we have used the fact that $\cos\theta_1 = 0$. Thus with $\Delta h = -4.0$ m we obtain $\theta_2 = 70.5^\circ$ which means the arc subtends an angle of $\Delta\theta = 19.5^\circ$ or 0.34 radians. Multiplying this by the radius gives a slide length of $s' = 4.1$ m.

d We again find the magnitude f' of the frictional force by using Eq. 8.31 with $W = 0$

$$\begin{aligned} 0 &= \Delta K + \Delta U + \Delta E_{\text{th}} \\ &= \frac{1}{2}mv^2 - mgh + f's' \end{aligned}$$

so that we obtain $f' = 1.2 \times 10^2$ N.

94. We use $P = Fv$ to compute the force

$$F = \frac{P}{v} = \frac{92 \times 10^6}{(32.5 \text{ knot}) \left(1.852 \frac{\text{km/h}}{\text{knot}}\right) \left(\frac{1000 \text{ m/km}}{3600 \text{ s/h}}\right)} = 5.5 \times 10^6 \text{ N}$$

95. This can be worked entirely by the methods of chapters 2–6 but we will use energy methods in as many steps as possible.

By a force analysis in the style of chapter 6 we find the normal force has magnitude $F_N = mg \cos \theta$ where $\theta = 39^\circ$ which means $f_k = \mu_k mg \cos \theta$ where $\mu_k = 0.28$. Thus 8.31 yields

$$\Delta E_{\text{th}} = f_k d = \mu_k mgd \cos \theta.$$

So elementary trigonometry leads us to conclude that $\Delta U = -mgd \sin \theta$ where $d = 3.7 \text{ m}$. Since $K_i = 0$ 8.33 with $W = 0$ indicates that the final kinetic energy is

$$K_f = -\Delta U - \Delta E_{\text{th}} = mgd (\sin \theta - \mu_k \cos \theta)$$

which leads to the speed at the bottom of the ramp

$$v = \sqrt{\frac{2K_f}{m}} = \sqrt{2gd (\sin \theta - \mu_k \cos \theta)} = 5.5 \text{ m/s}.$$

b This speed begins its horizontal motion where $f_k = \mu_k mg$ and $\Delta U = 0$. It slides a distance d' before it stops. According to 8.31 with $W = 0$

$$\begin{aligned} 0 &= \Delta K + \Delta U + \Delta E_{\text{th}} \\ &= 0 - \frac{1}{2}mv^2 + 0 + \mu_k mgd' \\ &= -\frac{1}{2}(2gd (\sin \theta - \mu_k \cos \theta)) + \mu_k gd' \end{aligned}$$

here we have divided by mass and substituted from part a in the last step. Therefore

$$d' = \frac{d(\sin \theta - \mu_k \cos \theta)}{\mu_k} = 5.4 \text{ m}.$$

c We see from the algebraic form of the results above that the answers do not depend on mass. A 90 kg crate should have the same speed at the bottom and sliding distance across the floor to the extent that the friction relations in chapter 6 are accurate. Interestingly since g does not appear in the relation for d' the sliding distance could seem to be the same if the experiment were performed on Mars.

96. a The loss of the initial $K = \frac{1}{2}mv^2 = \frac{1}{2}(70 \text{ kg})(10 \text{ m/s})^2$ is 3500 J or 3.5 kJ.

b This is dissipated as thermal energy $\Delta E_{\text{th}} = 3500 \text{ J} = 3.5 \text{ kJ}$.

97. . 8 33 gives $mgy_f = K_i + mgy_i - \Delta E_{th}$ or

$$0.50 \text{ kg } 9.8 \text{ m/s}^2 (0.80 \text{ m}) = \frac{1}{2} (0.50 \text{ kg}) (4.00 \text{ m/s})^2 + 0.50 \text{ kg } 9.8 \text{ m/s}^2 (0) - \Delta E_{th}$$

which yields $\Delta E_{th} = 4.00 - 3.92 = 0.080 \text{ J}$.

98. Since the period T is $2.5 \text{ rev/s}^{-1} = 0.40 \text{ s}$ then . 4 33 leads to $v = 3.14 \text{ m/s}$. The frictional force has magnitude using . 6 2

$$f = \mu_k F_N = (0.320)(180 \text{ N}) = 57.6 \text{ N}$$

The power dissipated by the friction must be equal to that supplied by the motor so . 7 48 gives $P = (57.6 \text{ N})(3.14 \text{ m/s}) = 181 \text{ W}$.

99. To swim at constant velocity the swimmer must push back against the water with a force of 110 N . Relative to him the water is going at 0.22 m/s toward his rear in the same direction as his force. Using . 7 48 his power output is obtained

$$P = \vec{F} \cdot \vec{v} = Fv = (110 \text{ N})(0.22 \text{ m/s}) = 24 \text{ W}$$

100. The initial kinetic energy of the automobile of mass m moving at speed v_i is $K_i = \frac{1}{2}mv_i^2$ here $m = 16400/9.8 = 1673 \text{ kg}$. Using . 8 31 and . 8 33 this relates to the effect of friction force f in stopping the auto over a distance d by $K_i = fd$ here the road is assumed level so $\Delta U = 0$. With

$$v_i = (113 \text{ km/h}) = (113 \text{ km/h}) \left(\frac{1000 \text{ m}}{1 \text{ km}} \right) \left(\frac{1 \text{ h}}{3600 \text{ s}} \right) = 31.4 \text{ m/s}$$

we obtain

$$d = \frac{K_i}{f} = \frac{mv_i^2}{2f} = \frac{(1673 \text{ kg})(31.4 \text{ m/s})^2}{2(8230 \text{ N})} = 100 \text{ m}$$

101. With the potential energy reference level set at the point of throwing we have with units understood

$$\Delta E = mgh - \frac{1}{2}mv_0^2 = m \left((9.8)(8.1) - \frac{1}{2}(14)^2 \right)$$

which yields $\Delta E = -12 \text{ J}$ for $m = 0.63 \text{ kg}$. This “loss” of mechanical energy is presumably due to air friction.

102. As the internal energy the climber must convert to gravitational potential energy is

$$\Delta U = mgh = (90 \text{ kg})(9.80 \text{ m/s}^2)(8850 \text{ m}) = 7.8 \times 10^6 \text{ J}.$$

b The number of candy bars this corresponds to is

$$N = \frac{7.8 \times 10^6 \text{ J}}{1.25 \times 10^6 \text{ J/bar}} \approx 6.2 \text{ bars}.$$

103. a The acceleration of the sprinter is using Eq. 2-15

$$a = \frac{2\Delta x}{t^2} = \frac{(2)(7.0 \text{ m})}{(1.6 \text{ s})^2} = 5.47 \text{ m/s}^2.$$

Consequently the speed at $t = 1.6 \text{ s}$ is $v = at = (5.47 \text{ m/s}^2)(1.6 \text{ s}) = 8.8 \text{ m/s}$. Alternatively, Eq. 2-17 could be used.

b The kinetic energy of the sprinter of weight w and mass $m = w/g$ is

$$K = \frac{1}{2}mv^2 = \frac{1}{2}\left(\frac{w}{g}\right)v^2 = \frac{1}{2}(670 \text{ N} / 9.8 \text{ m/s}^2)(8.8 \text{ m/s})^2 = 2.6 \times 10^3 \text{ J}.$$

c The average power is

$$P_{\text{avg}} = \frac{\Delta K}{\Delta t} = \frac{2.6 \times 10^3 \text{ J}}{1.6 \text{ s}} = 1.6 \times 10^3 \text{ W}.$$

104. From Eq. 8-6 we find U with units understood

$$U(\xi) = - \int_0^\xi (-3x - 5x^2) dx = \frac{3}{2}\xi^2 + \frac{5}{3}\xi^3.$$

a Using the above formula we obtain $U(2) \approx 19 \text{ J}$.

b When its speed is $v = 4 \text{ m/s}$ its mechanical energy is $\frac{1}{2}mv^2 + U(5)$. This must equal the energy at the origin

$$\frac{1}{2}mv^2 + U(5) = \frac{1}{2}mv_0^2 + U(0)$$

so that the speed at the origin is

$$v_0 = \sqrt{v^2 + \frac{2}{m}(U(5) - U(0))}.$$

Thus with $U(5) = 246 \text{ J}$, $U(0) = 0$ and $m = 20 \text{ kg}$ we obtain $v_0 = 6.4 \text{ m/s}$.

c Our original formula for U is changed to

$$U(x) = -8 + \frac{3}{2}x^2 + \frac{5}{3}x^3$$

in this case. Therefore $U(2) = 11$ J. But we still have $v_0 = 6.4$ m/s since that calculation only depended on the difference of potential energy values specifically $U(5) - U(0)$ J.

105. a Resolving the gravitational force into components and applying Newton's second law as well as $\Sigma F = ma$ we find

$$F_{\text{machine}} - mg \sin \theta - \mu_k mg \cos \theta = ma.$$

In the situation described in the problem we have $a = 0$ so

$$F_{\text{machine}} = mg \sin \theta + \mu_k mg \cos \theta = 372 \text{ N}.$$

Thus the work done by the machine is $F_{\text{machine}}d = 744 \text{ J} = 7.4 \times 10^2 \text{ J}$.

b The thermal energy generated is $\mu_k mg \cos \theta d = 240 \text{ J} = 2.4 \times 10^2 \text{ J}$.

106. a At the highest point the velocity $v = v_x$ is purely horizontal and is equal to the horizontal component of the launch velocity see section 4.6 $v_{0x} = v_0 \cos \theta$ here $\theta = 30^\circ$ in this problem. Equation 8.17 relates the kinetic energy at the highest point to the launch kinetic energy

$$K_0 = mgy + \frac{1}{2}mv^2 = \frac{1}{2}mv_{0x}^2 + \frac{1}{2}mv_{0y}^2$$

With $y = 1.83$ m. Since the $mv_{0x}^2/2$ term on the left hand side cancels the $mv^2/2$ term on the right hand side this yields $v_{0y} = \sqrt{2gy} \approx 6$ m/s. With $v_{0y} = v_0 \sin \theta$ we obtain

$$v_0 = 11.98 \text{ m/s} \approx 12 \text{ m/s}.$$

b Energy conservation including now the energy stored elastically in the spring. Equation 8.11 also applies to the motion along the incline through a distance d that corresponds to a vertical height increase of $d \sin \theta$

$$\frac{1}{2}kd^2 = K_0 - mgd \sin \theta \Rightarrow d = 0.11 \text{ m}.$$

107. The work done by \vec{F} is the negative of its potential energy change see section 8.6 so $U_B = U_A - 25 = 15$ J.

108. a We assume his mass is between $m_1 = 50$ kg and $m_2 = 70$ kg corresponding to a weight between 110 lb and 154 lb. His increase in gravitational potential energy is therefore in the range

$$m_1gh \leq \Delta U \leq m_2gh \Rightarrow 2 \times 10^5 \leq \Delta U \leq 3 \times 10^5$$

in units here $h = 443$ m.

b The problem only asks for the amount of internal energy that converts into gravitational potential energy so this result is the same as in part a. But if we were to consider his *total* internal energy “output” much of which converts to heat we can expect that external climb is quite different from taking the stairs.

109. a We implement .8.37 as

$$K_f = K_i - mgy_i - f_k d = 0 \quad 60 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 4.0 \text{ m} - 0 = 2.35 \times 10^3 \text{ J}$$

b So it applies with a non-zero thermal term

$$K_f = K_i - mgy_i - f_k d = 0 \quad 60 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 4.0 \text{ m} - 500 \cdot 4.0 \text{ m} = 352 \text{ J}$$

110. We take the bottom of the incline to be the $y = 0$ reference level. The incline angle is $\theta = 30^\circ$. The distance along the incline d measured from the bottom is related to height y by the relation $y = d \sin \theta$.

a Using the conservation of energy we have

$$K_0 + U_0 = K_{\text{top}} + U_{\text{top}} \Rightarrow \frac{1}{2}mv_0^2 + 0 = 0 + mgy$$

With $v_0 = 5.0$ m/s. This yields $y = 1.3$ m from which we obtain $d = 2.6$ m.

b An analysis of forces in the manner of chapter 6 reveals that the magnitude of the friction force is $f_k = \mu_k mg \cos \theta$. So we write .8.33 as

$$\begin{aligned} K_0 + U_0 &= K_{\text{top}} + U_{\text{top}} + f_k d \\ \frac{1}{2}mv_0^2 + 0 &= 0 + mgy + f_k d \\ \frac{1}{2}mv_0^2 &= mgd \sin \theta + \mu_k mgd \cos \theta \end{aligned}$$

which — upon canceling the mass and rearranging — provides the result for d

$$d = \frac{v_0^2}{2g(\mu_k \cos \theta + \sin \theta)} = 1.5 \text{ m}.$$

c The thermal energy generated by friction is $f_k d = \mu_k mgd \cos \theta = 26 \text{ J}$.

d The slide back down from the height $y = 1.5 \sin 30^\circ$ is also described by Eq. 8-33. With ΔE_{th} again equal to 26 J we have

$$K_{\text{top}} + U_{\text{top}} = K_{\text{bot}} + U_{\text{bot}} + f_k d \Rightarrow 0 + mgy = \frac{1}{2}mv_{\text{bot}}^2 + 0 + 26$$

from which we find $v_{\text{bot}} = 2.1 \text{ m/s}$.

111. Equation 8-8 leads directly to $\Delta y = \frac{68000}{9.4 \text{ kg} \cdot 9.8 \text{ m/s}^2} = 738 \text{ m}$.

112. We assume his initial kinetic energy when he jumps is negligible. When his initial gravitational potential energy measured relative to where he momentarily stops is what becomes the elastic potential energy of the stretched net neglecting air friction. Thus

$$U_{\text{net}} = U_{\text{grav}} = mgh$$

here $h = 11.0 \text{ m} + 1.5 \text{ m} = 12.5 \text{ m}$. With $m = 70 \text{ kg}$ we obtain $U_{\text{net}} = 8580 \text{ J}$.

113. We use SI units so $m = 0.030 \text{ kg}$ and $d = 0.12 \text{ m}$.

a Since there is no change in height and we assume no changes in elastic potential energy then $\Delta U = 0$ and we have

$$\Delta E_{\text{mech}} = \Delta K = -\frac{1}{2}mv_0^2 = -3.8 \times 10^3 \text{ J}$$

here $v_0 = 500 \text{ m/s}$ and the final speed is zero.

b By Eq. 8-33 with $W = 0$ we have $\Delta E_{\text{th}} = 3.8 \times 10^3 \text{ J}$ which implies

$$f = \frac{\Delta E_{\text{th}}}{d} = 3.1 \times 10^4 \text{ N}$$

using Eq. 8-31 with f_k replaced by f effectively generalizing that equation to include a greater variety of dissipative forces than just those obeying Eq. 6-2.

114. a The kinetic energy K of the automobile of mass m at $t = 30 \text{ s}$ is

$$K = \frac{1}{2}mv^2 = \frac{1}{2}(1500\text{ kg})\left((72\text{ km/h})\left(\frac{1000\text{ m/km}}{3600\text{ s/h}}\right)\right)^2 = 3.0 \times 10^5 \text{ J}.$$

b The average power required is

$$P_{\text{avg}} = \frac{\Delta K}{\Delta t} = \frac{3.0 \times 10^5}{30\text{ s}} = 1.0 \times 10^4 \text{ W}.$$

c Since the acceleration a is constant the power is $P = Fv = mav = ma \cdot at = ma^2t$ using Eq. 2-11. By contrast from part b the average power is $P_{\text{avg}} = \frac{mv^2}{2t}$ which becomes $\frac{1}{2}ma^2t$ when $v = at$ is again utilized. Thus the instantaneous power at the end of the interval is twice the average power during it

$$P = 2P_{\text{avg}} = (2)(1.0 \times 10^4 \text{ W}) = 2.0 \times 10^4 \text{ W}.$$

115. a The initial kinetic energy is $K_i = \frac{1}{2}(1.5\text{ kg})(20\text{ m/s})^2 = 300 \text{ J}$.

b At the point of maximum height the vertical component of velocity vanishes but the horizontal component remains what it was when it was “shot” (if we neglect air friction). Its kinetic energy at that moment is

$$K = \frac{1}{2}(1.5\text{ kg})[20\text{ m/s} \cos 34^\circ]^2 = 206 \text{ J}.$$

thus $\Delta U = K_i - K = 300 \text{ J} - 206 \text{ J} = 93.8 \text{ J}$.

c Since $\Delta U = mg\Delta y$ we obtain $\Delta y = \frac{93.8\text{ J}}{(1.5\text{ kg})(9.8\text{ m/s}^2)} = 6.38\text{ m}$.

116. a The rate of change of the gravitational potential energy is

$$\frac{dU}{dt} = mg \frac{dy}{dt} = -mg|v| = -(68)(9.8)(59) = -3.9 \times 10^4 \text{ J/s}.$$

thus the gravitational energy is being reduced at the rate of $3.9 \times 10^4 \text{ J/s}$.

b Since the velocity is constant the rate of change of the kinetic energy is zero. Thus the rate at which the mechanical energy is being dissipated is the same as that of the gravitational potential energy $3.9 \times 10^4 \text{ J/s}$.

117. a The effect of sliding friction is described in terms of energy dissipated as shown in Fig. 8-31. We have

$$\Delta E = K + \frac{1}{2}k(0.08)^2 - \frac{1}{2}k(0.10)^2 = -f_k(0.02)$$

where distances are in meters and energies are in joules. With $k = 4000 \text{ N/m}$ and $f_k = 80 \text{ N}$ we obtain $K = 5.6 \text{ J}$.

b In this case we have $d = 0.10 \text{ m}$. Thus

$$\Delta E = K + 0 - \frac{1}{2}k(0.10)^2 = -f_k(0.10)$$

which leads to $K = 12 \text{ J}$.

c We can approach this two ways. One way is to examine the dependence of energy on the variable d

$$\Delta E = K + \frac{1}{2}k(d_0 - d)^2 - \frac{1}{2}kd_0^2 = -f_k d$$

where $d_0 = 0.10 \text{ m}$ and solving for K as a function of d

$$K = -\frac{1}{2}kd^2 + (kd_0)d - f_k d.$$

In this first approach we could work through the $dK/dd = 0$ condition or with the special capabilities of a graphing calculator to obtain the answer $K_{\text{max}} = \frac{1}{2k}(kd_0 - f_k)^2$.

In the second and perhaps easier approach we note that K is maximum where v is maximum — which is where $a = 0 \Rightarrow$ equilibrium of forces. Thus the second approach simply solves for the equilibrium position

$$|F_{\text{spring}}| = f_k \Rightarrow kx = 80.$$

Thus with $k = 4000 \text{ N/m}$ we obtain $x = 0.02 \text{ m}$. But $x = d_0 - d$ so this corresponds to $d = 0.08 \text{ m}$. Then the methods of part a lead to the answer $K_{\text{max}} = 12.8 \text{ J} \approx 13 \text{ J}$.

118. We work this in SI units and convert to horsepower in the last step. Thus

$$v = (80 \text{ km/h}) \left(\frac{1000 \text{ m/km}}{3600 \text{ s/h}} \right) = 22.2 \text{ m/s}.$$

The force F needed to propel the car of weight w and mass $m = w/g$ is found from Newton's second law:

$$F_{\text{net}} = F_p - F = ma = \frac{wa}{g}$$

here $F = 300 + 1.8v^2$ in units. therefore the power required is

$$P = \vec{F}_p \cdot \vec{v} = \left(F + \frac{wa}{g} \right) v = \left(300 + 1.8(22.2)^2 + \frac{(12000)(0.92)}{9.8} \right) (22.2) = 5.14 \times 10^4$$

$$= (5.14 \times 10^4) \left(\frac{1 \text{ hp}}{746} \right) = 69 \text{ hp}.$$

119. **THINK** We apply energy method to analyze the projectile motion of a ball.

EXPRESS We choose the initial position at the ground to be our reference point for calculating the potential energy. The initial energy of the ball is $E_0 = \frac{1}{2}mv_0^2$. At the top of its flight the vertical component of the velocity is zero and the horizontal component neglecting air friction is the same as it was when it was thrown $v_x = v_0 \cos \theta$. At a position h below the ground the energy of the ball is

$$E = K + U = \frac{1}{2}mv^2 - mgh$$

here v is the speed of the ball.

ANALYZE a The kinetic energy of the ball at the top of the flight is

$$K_{\text{top}} = \frac{1}{2}mv_x^2 = \frac{1}{2}m v_0^2 \cos^2 \theta = \frac{1}{2} (0.050 \text{ kg}) (8.0 \text{ m/s})^2 \cos^2 30^\circ = 1.2 \text{ J}.$$

b When the ball is $h = 3.0 \text{ m}$ below the ground by energy conservation we have

$$\frac{1}{2}mv_0^2 = \frac{1}{2}mv^2 - mgh$$

or

$$v = \sqrt{v_0^2 + 2gh} = \sqrt{(8.0 \text{ m/s})^2 + 2(9.8 \text{ m/s}^2)(3.0 \text{ m})} = 11.1 \text{ m/s}.$$

c As can be seen from our expression above $v = \sqrt{v_0^2 + 2gh}$ which is independent of the mass m .

d Similarly the speed v is independent of the initial angle θ .

LEARN Our results demonstrate that the quantity v in the kinetic energy formula is the magnitude of the velocity vector—it does not depend on direction. In addition, mass cancels out in the energy conservation equation so that v is independent of m .

120. a. In the initial situation the elongation is using .8 11

$$x_i = \sqrt{2(1.44)(3200)} = 0.030 \text{ m or } 3.0 \text{ cm}.$$

In the next situation the elongation is only 2.0 cm or 0.020 m so we now have less stored energy relative to what we had initially. Specifically

$$\Delta U = \frac{1}{2}(3200) \text{ m } (0.020 \text{ m})^2 - 1.44 = -0.80 \text{ J}.$$

b. The elastic stored energy for $|x| = 0.020 \text{ m}$ does not depend on whether this represents a stretch or a compression. The answer is the same as in part a: $\Delta U = -0.80 \text{ J}$.

c. Now we have $|x| = 0.040 \text{ m}$ which is greater than x_i so this represents an increase in the potential energy relative to what we had initially. Specifically

$$\Delta U = \frac{1}{2}(3200) \text{ m } (0.040 \text{ m})^2 - 1.44 = 1.12 \text{ J} \approx 1.1 \text{ J}.$$

121. a. With $P = 1.5 \text{ MW} = 1.5 \times 10^6 \text{ W}$ assumed constant and $t = 6.0 \text{ min} = 360 \text{ s}$ the work kinetic energy theorem becomes

$$W = Pt = \Delta K = \frac{1}{2}m(v_f^2 - v_i^2).$$

The mass of the locomotive is then

$$m = \frac{2Pt}{v_f^2 - v_i^2} = \frac{(2)(1.5 \times 10^6 \text{ W})(360 \text{ s})}{(25 \text{ m/s})^2 - (10 \text{ m/s})^2} = 2.1 \times 10^6 \text{ kg}.$$

b. With t arbitrary we use $Pt = \frac{1}{2}m(v^2 - v_i^2)$ to solve for the speed $v = v(t)$ as a function of time and obtain

$$v(t) = \sqrt{v_i^2 + \frac{2Pt}{m}} = \sqrt{(10)^2 + \frac{(2)(1.5 \times 10^6)t}{2.1 \times 10^6}} = \sqrt{100 + 1.5t}$$

in units v in m/s and t in s.

c. The force $F(t)$ as a function of time is

$$F(t) = \frac{P}{v(t)} = \frac{1.5 \times 10^6}{\sqrt{100 + 1.5t}}$$

in units F in and t in s .

d the distance d the train moved is given by

$$d = \int_0^t v(t') dt' = \int_0^{360} \left(100 + \frac{3}{2}t\right)^{1/2} dt = \frac{4}{9} \left(100 + \frac{3}{2}t\right)^{3/2} \bigg|_0^{360} = 6.7 \times 10^3 \text{ m.}$$

122. **THINK** shuffleboard disk is accelerated over some distance by an external force but it eventually comes to rest due to the frictional force.

EXPRESS In the presence of frictional force the work done on a system is $W = \Delta E_{\text{mech}} + \Delta E_{\text{th}}$ here $\Delta E_{\text{mech}} = \Delta K + \Delta U$ and $\Delta E_{\text{th}} = f_k d$. In our situation work has been done by the cue only to the first 2.0 m and not to the subsequent 12 m of distance traveled.

ANALYZE a During the final $d = 12$ m of motion $W = 0$ and we use

$$K_1 + U_1 = K_2 + U_2 + f_k d$$

$$\frac{1}{2}mv^2 + 0 = 0 + 0 + f_k d$$

here $m = 0.42$ kg and $v = 4.2$ m/s. This gives $f_k = 0.31$ N. Therefore the thermal energy change is $\Delta E_{\text{th}} = f_k d = 3.7$ J.

b Using $f_k = 0.31$ N for the entire distance $d_{\text{total}} = 14$ m we obtain

$$\Delta E_{\text{th total}} = f_k d_{\text{total}} = 0.31 \text{ N} \cdot 14 \text{ m} = 4.3 \text{ J}$$

for the thermal energy generated by friction.

c During the initial $d' = 2$ m of motion we have

$$W = \Delta E_{\text{mech}} + \Delta E'_{\text{th}} = \Delta K + \Delta U + f_k d' = \frac{1}{2}mv^2 + 0 + f_k d'$$

which essentially combines Eqs. 8.31 and 8.33. Thus the work done on the disk by the cue is

$$W = \frac{1}{2}mv^2 + f_k d' = \frac{1}{2} (0.42 \text{ kg}) (4.2 \text{ m/s})^2 + 0.31 \text{ N} \cdot 2.0 \text{ m} = 4.3 \text{ J.}$$

LEARN Our answer in c is the same as that in b. This is expected because all the work done becomes thermal energy at the end.

123. The water has gained

$$\Delta K = \frac{1}{2} (10 \text{ kg}) (13 \text{ m/s})^2 - \frac{1}{2} (10 \text{ kg}) (3.2 \text{ m/s})^2 = 794 \text{ J}$$

of kinetic energy and it has lost $\Delta U = (10 \text{ kg}) (9.8 \text{ m/s}^2) (15 \text{ m}) = 1470 \text{ J}$.

The lack of agreement between these two values is presumably due to transfer of energy into thermal forms. The ratio of these values is $0.54 = 54\%$. The mass of the water cancels when we take the ratio so that the assumption stated at the end of the problem $m = 10 \text{ kg}$ is not needed for the final result.

124. a. The integral seen in 8.6 where the value of U at $x = \infty$ is required to vanish is straightforward. The result is $U(x) = -Gm_1m_2/x$.

b. One approach is to use 8.5 which means that we are effectively doing the integral of part a all over again. Another approach is to use our result from part a and thus use 8.1. Either way we arrive at

$$W = \frac{Gm_1m_2}{x_1} - \frac{Gm_1m_2}{x_1+d} = \frac{Gm_1m_2d}{x_1(x_1+d)}.$$

125. a. During one second the decrease in potential energy is

$$-\Delta U = mg(-\Delta y) = (5.5 \times 10^6 \text{ kg}) (9.8 \text{ m/s}^2) (50 \text{ m}) = 2.7 \times 10^9 \text{ J}$$

here y is upward and $\Delta y = y_f - y_i$.

b. The information relating mass to volume is not needed in the computation. $y = 840 \text{ m}$ and the relation $\rho = \text{density}$ the result follows

$$P = 2.7 \times 10^9 \text{ J/s} = 2.7 \times 10^9 \text{ W}.$$

c. One year is equivalent to $24 \times 365.25 = 8766 \text{ h}$ which we write as 8.77 kh . Thus the energy supply rate multiplied by the cost and by the time is

$$(2.7 \times 10^9 \text{ W}) (8.77 \text{ kh}) \left(\frac{1 \text{ cent}}{1 \text{ kWh}} \right) = 2.4 \times 10^{10} \text{ cents} = 2.4 \times 10^8 \text{ dollars}.$$

126. The connection between angle θ measured from vertical and height h measured from the lowest point which is our choice of reference position in computing the

gravitational potential energy is given by $h = L(1 - \cos \theta)$ here L is the length of the pendulum.

a We use energy conservation in the form of 8.17.

$$K_1 + U_1 = K_2 + U_2$$

$$0 + mgL(1 - \cos \theta_1) = \frac{1}{2}mv_2^2 + mgL(1 - \cos \theta_2)$$

With $L = 1.4$ m, $\theta_1 = 30^\circ$ and $\theta_2 = 20^\circ$ we have

$$v_2 = \sqrt{2gL(\cos \theta_2 - \cos \theta_1)} = 1.4 \text{ m/s}.$$

b The maximum speed v_3 is at the lowest point. Our formula for h gives $h_3 = 0$ when $\theta_3 = 0$ as expected. From

$$K_1 + U_1 = K_3 + U_3$$

$$0 + mgL(1 - \cos \theta_1) = \frac{1}{2}mv_3^2 + 0$$

we obtain $v_3 = 1.9$ m/s.

c We look for an angle θ_4 such that the speed there is $v_4 = v_3/3$. To be as accurate as possible we proceed algebraically substituting $v_3^2 = 2gL(1 - \cos \theta_1)$ at the appropriate place and plug numbers in at the end. Energy conservation leads to

$$K_1 + U_1 = K_4 + U_4$$

$$0 + mgL(1 - \cos \theta_1) = \frac{1}{2}mv_4^2 + mgL(1 - \cos \theta_4)$$

$$mgL(1 - \cos \theta_1) = \frac{1}{2}m\frac{v_3^2}{9} + mgL(1 - \cos \theta_4)$$

$$-gL \cos \theta_1 = \frac{1}{2}\frac{2gL(1 - \cos \theta_1)}{9} - gL \cos \theta_4$$

here in the last step we have subtracted out mgL and then divided by m . Thus we obtain

$$\theta_4 = \cos^{-1}\left(\frac{1}{9} + \frac{8}{9}\cos \theta_1\right) = 28.2^\circ \approx 28^\circ.$$

127. Equating the mechanical energy at his initial position as he emerges from the cannon here we set the reference level for computing potential energy to his energy as he lands we obtain

$$K_i = K_f + U_f$$

$$\frac{1}{2}(60\text{ kg})(16\text{ m/s})^2 = K_f + (60\text{ kg})(9.8\text{ m/s}^2)(3.9\text{ m})$$

which leads to $K_f = 5.4 \times 10^3$.

128. a This part is essentially a free fall problem which can be easily done with chapter 2 methods. Instead of choosing energy methods we take $y = 0$ to be the ground level.

$$K_i + U_i = K + U \Rightarrow 0 + mgy_i = \frac{1}{2}mv^2 + 0$$

therefore $v = \sqrt{2gy_i} = 9.2\text{ m/s}$ here $y_i = 4.3\text{ m}$.

b . 8 29 provides $\Delta E_{\text{th}} = f_k d$ for thermal energy generated by the kinetic friction force. we apply . 8 31

$$K_i + U_i = K + U \Rightarrow 0 + mgy_i = \frac{1}{2}mv^2 + 0 + f_k d .$$

with $d = y_i$ $m = 70\text{ kg}$ and $f_k = 500$ this yields $v = 4.8\text{ m/s}$.

129. we want to convert at least in theory the water that falls through $h = 500\text{ m}$ into electrical energy. The problem indicates that in one year a volume of water equal to $A\Delta z$ lands in the form of rain on the country where $A = 8 \times 10^{12}\text{ m}^2$ and $\Delta z = 0.75\text{ m}$. Multiplying this volume by the density $\rho = 1000\text{ kg m}^3$ leads to

$$m_{\text{total}} = \rho A \Delta z = (1000)(8 \times 10^{12})(0.75) = 6 \times 10^{15}\text{ kg}$$

for the mass of rain water. One third of this “falls” to the ocean, so it is $m = 2 \times 10^{15}\text{ kg}$ that we want to use in computing the gravitational potential energy mgh which will turn into electrical energy during the year. Since a year is equivalent to $3.2 \times 10^7\text{ s}$ we obtain

$$P_{\text{avg}} = \frac{(2 \times 10^{15})(9.8)(500)}{3.2 \times 10^7} = 3.1 \times 10^{11} .$$

130. The spring is relaxed at $y = 0$ so the elastic potential energy . 8 11 is $U_{\text{el}} = \frac{1}{2}ky^2$. The total energy is conserved and is zero determined by evaluating it at its initial position. We note that U is the same as ΔU in these manipulations. Thus we have

$$0 = K + U_g + U_e \Rightarrow K = -U_g - U_e$$

here $U_g = mgy = 20y$ with y in meters so that the energies are in joules. We arrange the results in a table

position y	-0.05	-0.10	-0.15	-0.20
K	a 0.75	d 1.0	g 0.75	0
U_g	b -1.0	e -2.0	h -3.0	k -4.0
U_e	c 0.25	f 1.0	i 2.25	l 4.0

131. Let the amount of stretch of the spring be x . For the object to be in equilibrium

$$kx - mg = 0 \Rightarrow x = mg/k.$$

thus the gain in elastic potential energy for the spring is

$$\Delta U_e = \frac{1}{2} kx^2 = \frac{1}{2} k \left(\frac{mg}{k} \right)^2 = \frac{m^2 g^2}{2k}$$

while the loss in the gravitational potential energy of the system is

$$-\Delta U_g = mgx = mg \left(\frac{mg}{k} \right) = \frac{m^2 g^2}{k}$$

which we see by comparing with the previous expression is equal to $2\Delta U_e$. The reason why $|\Delta U_g| \neq \Delta U_e$ is that since the object is slowly lowered an upward external force e.g. due to the hand must have been exerted on the object during the lowering process preventing it from accelerating downward. This force does *negative* work on the object reducing the total mechanical energy of the system.

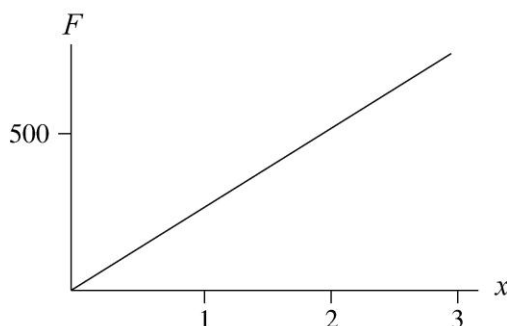
132. (a) The compression is “spring like” so the maximum force relates to the distance x by Hooke’s law

$$F = kx \Rightarrow x = \frac{750}{2.5 \times 10^5} = 0.0030 \text{ m.}$$

(b) The work is what produces the “spring like” potential energy associated with the compression. Thus using 8.11

$$W = \frac{1}{2} kx^2 = \frac{1}{2} (2.5 \times 10^5) (0.0030)^2 = 1.1 \text{ J.}$$

c By Newton's third law the force F exerted by the tooth is equal and opposite to the “spring like” force exerted by the licorice, so the graph of F is a straight line of slope k . We plot F in newtons versus x in millimeters — both are taken as positive.

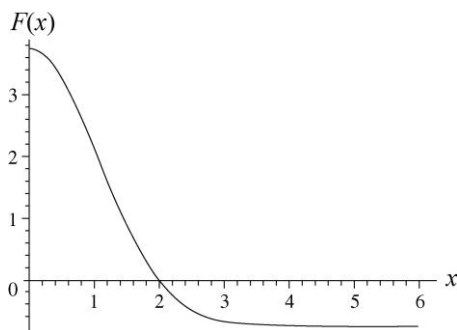


d As mentioned in part b the spring potential energy expression is relevant. Whether or not we can ignore dissipative processes is a deeper question. In other words it seems unlikely that — if the tooth at any moment were to reverse its motion — that the licorice could “spring back” to its original shape. Still, to the extent that $U = \frac{1}{2}kx^2$ applies the graph is a parabola (not shown here) which has its vertex at the origin and is either concave upward or concave downward depending on how one wishes to define the sign of F — the connection being $F = -dU/dx$.

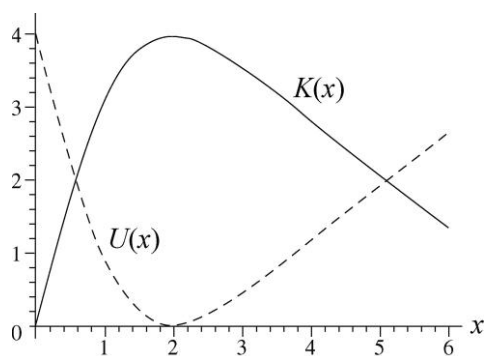
e As a crude estimate the area under the curve is roughly half the area of the entire plotting area $8000 \text{ by } 12 \text{ mm}$. This leads to an approximate work of $\frac{1}{2} 8000 \cdot 0.012 \text{ m} \approx 50 \text{ J}$. Estimates in the range $40 \leq W \leq 50$ are acceptable.

f Certainly dissipative effects dominate this process and we cannot assign it a meaningful potential energy.

133. a The force in units understood from 8.20 is plotted in the graph below.



b The potential energy U and the kinetic energy $K(x)$ are shown in the next. The potential energy curve begins at 4 and drops until about $x = 2$ — the kinetic energy curve is the one that starts at zero and rises until about $x = 2$.



134. The style of reasoning used here is presented in Section 8.5.

a. The horizontal line representing E_1 intersects the potential energy curve at a value of $r \approx 0.07$ nm and seems not to intersect the curve at larger r though this is somewhat unclear since $U(r)$ is graphed only up to $r = 0.4$ nm. Thus if m were propelled towards M from large r with energy E_1 it would “turn around” at 0.07 nm and head back in the direction from which it came.

b. The line representing E_2 has two intersection points $r_1 \approx 0.16$ nm and $r_2 \approx 0.28$ nm with the $U(r)$ plot. Thus if m starts in the region $r_1 < r < r_2$ with energy E_2 it will bounce back and forth between these two points presumably forever.

c. At $r = 0.3$ nm the potential energy is roughly $U = -1.1 \times 10^{-19}$ J.

d. With M and m the kinetic energy is essentially just that of m . Since $E = 1 \times 10^{-19}$ J its kinetic energy is $K = E - U \approx 2.1 \times 10^{-19}$ J.

e. Since force is related to the slope of the curve we must crudely estimate $|F| \approx 1 \times 10^{-9}$ N at this point. The sign of the slope is positive so by Eq. 8.20 the force is negative valued. This is interpreted to mean that the atoms are attracted to each other.

f. Recalling our remarks in the previous part we see that the sign of F is positive meaning it's repulsive for $r < 0.2$ nm.

g. And the sign of F is negative (attractive) for $r > 0.2$ nm.

h. At $r = 0.2$ nm the slope hence F vanishes.

135. The distance traveled up the incline can be calculated using the kinematic equations discussed in Chapter 2

$$v^2 = v_0^2 + 2a\Delta x \rightarrow \Delta x = 200 \text{ m}.$$

This corresponds to an increase in height equal to $y = 200 \text{ m} \sin \theta = 17 \text{ m}$ where $\theta = 5.0^\circ$. We take its initial height to be $y = 0$.

a . 8 24 leads to

$$W_{\text{app}} = \Delta E = \frac{1}{2}m(v^2 - v_0^2) + mgy.$$

herefore $\Delta E = 8.6 \times 10^3$.

b rom the above manipulation e see $W_{\text{app}} = 8.6 \times 10^3$. Iso from hapter 2 e kno that $\Delta t = \Delta v/a = 10$ s. hus using . 7 42

$$P_{\text{avg}} = \frac{W}{\Delta t} = \frac{8.6 \times 10^3}{10} = 860$$

here the ans er has been rounded off from the 856 value that is provided by the calculator .

c and d aking into account the component of gravity along the incline surface the applied force is $ma = mg \sin \theta = 43$ and clearly in the direction of motion so . 7 48 provides the results for instantaneous po er

$$P = \vec{F} \cdot \vec{v} = \begin{cases} 430 & \text{for } v = 10 \text{ m/s} \\ 1300 & \text{for } v = 30 \text{ m/s} \end{cases}$$

here these ans ers have been rounded off from 428 and 1284 respectively . e note that the average of these t o values agrees ith the result in part b .

136. a onservaion of mechanical energy leads to

$$K_i + U_i = K_f + U_f \Rightarrow 0 + \frac{1}{2}ky_i^2 = \frac{1}{2}mv_f^2 + \frac{1}{2}k[y_f - y_i]^2 + mgy_f$$

here $y_i = 0.25$ m is the initial depression of the spring and $y_f - y_i$ is the displacement of the spring from its e uilibrium position hen the block is at y_f . hus the kinetic energy of the block can be ritten as

$$K_f = \frac{1}{2}mv_f^2 = \frac{1}{2}k[y_i^2 - y_f - y_i^2] - mgy_f.$$

or $y_f = 0$ the kinetic energy is $K_f = 0$ as e pected since this corresponds to the initial release point.

b t $y_f = 0.050$ m e have

$$\begin{aligned}
 K_f &= \frac{1}{2}k[y_i^2 - y_f - y_i^2] - mgy_f \\
 &= \frac{1}{2}(620 \text{ N/m})[0.250 \text{ m}^2 - 0.050 \text{ m} - 0.250 \text{ m}^2] - (50 \text{ N})(0.050 \text{ m}) = 4.48 \text{ J}
 \end{aligned}$$

c At $y_f = 0.100 \text{ m}$ we have

$$\begin{aligned}
 K_f &= \frac{1}{2}k[y_i^2 - y_f - y_i^2] - mgy_f \\
 &= \frac{1}{2}(620 \text{ N/m})[0.250 \text{ m}^2 - 0.100 \text{ m} - 0.250 \text{ m}^2] - (50 \text{ N})(0.100 \text{ m}) = 7.40 \text{ J}
 \end{aligned}$$

d Similarly the kinetic energy at $y_f = 0.150 \text{ m}$ is

$$\begin{aligned}
 K_f &= \frac{1}{2}k[y_i^2 - y_f - y_i^2] - mgy_f \\
 &= \frac{1}{2}(620 \text{ N/m})[0.250 \text{ m}^2 - 0.150 \text{ m} - 0.250 \text{ m}^2] - (50 \text{ N})(0.150 \text{ m}) = 8.78 \text{ J}
 \end{aligned}$$

e At $y_f = 0.200 \text{ m}$ the kinetic energy of the block is

$$\begin{aligned}
 K_f &= \frac{1}{2}k[y_i^2 - y_f - y_i^2] - mgy_f \\
 &= \frac{1}{2}(620 \text{ N/m})[0.250 \text{ m}^2 - 0.200 \text{ m} - 0.250 \text{ m}^2] - (50 \text{ N})(0.200 \text{ m}) = 8.60 \text{ J}
 \end{aligned}$$

f The spring returns to its uncompressed state once $y_f \geq y_i$. Since the block becomes detached from the spring beyond that point at its maximum height $K = 0$ and we have

$$\frac{1}{2}ky_i^2 = mgy_{\text{ma}} \Rightarrow y_{\text{ma}} = \frac{ky_i^2}{2mg} = \frac{(620 \text{ N/m})(0.250 \text{ m})^2}{2(50 \text{ N})} = 0.388 \text{ m}.$$